

ECE 260

EXAM 2

SOLUTIONS

(FALL 2023)

QUESTION 1

$$\mathcal{H}x(t) = e^{-at} \int_{-\infty}^t x(v) e^{av} dv, \quad a \in \mathbb{R}$$

PART (A)

$$\begin{aligned} h(t) &= \mathcal{H}\delta(t) \\ &= e^{-at} \int_{-\infty}^t \delta(v) e^{av} dv \\ &= \begin{cases} e^{-at} (1) & t \geq 0 \\ e^{-at} (0) & \text{otherwise} \end{cases} \\ &= \begin{cases} e^{-at} & t \geq 0 \\ 0 & \text{otherwise} \end{cases} \\ &= e^{-at} u(t) \end{aligned}$$

PART (B)

A LTI system with impulse response h is causal if and only if $h(t) = 0$ for all $t < 0$.

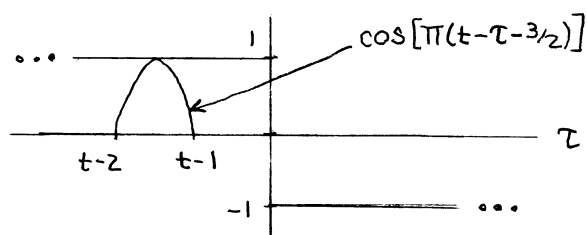
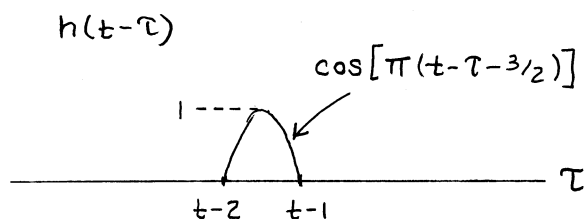
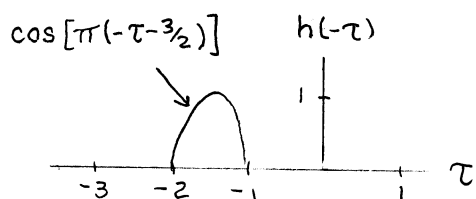
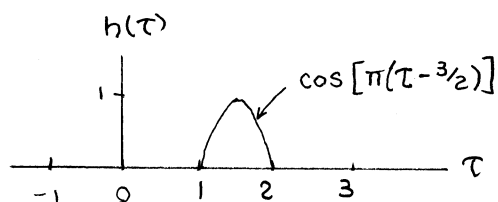
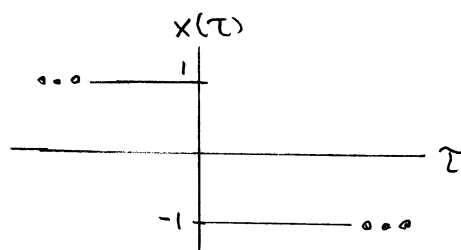
For all a , we have

$$e^{-at} u(t) = 0 \text{ for all } t < 0$$

Since $u(t) = 0$ for all $t < 0$.

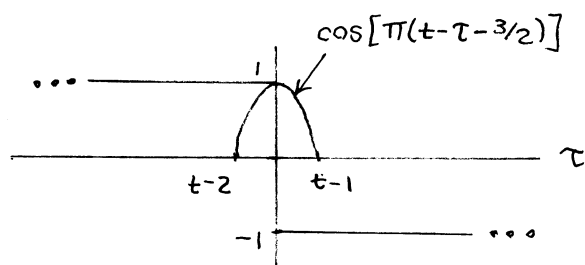
Therefore, \mathcal{H} is causal for all $a \in \mathbb{R}$.

QUESTION 2



$$t-1 < 0 \Rightarrow t < 1$$

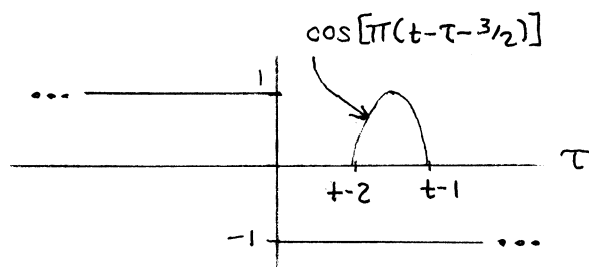
$$x * h(t) = \int_{t-2}^{t-1} \cos[\pi(t-\tau-3/2)] d\tau$$



$$t-2 < 0 \leq t-1 \Rightarrow t < 2 \wedge t \geq 1 \Rightarrow$$

$$1 \leq t < 2$$

$$x * h(t) = \int_{t-2}^0 \cos[\pi(t-\tau-3/2)] d\tau + \int_0^{t-1} -\cos[\pi(t-\tau-3/2)] d\tau$$



$$t-2 \geq 0 \Rightarrow t \geq 2$$

$$x * h(t) = \int_{t-2}^{t-1} -\cos[\pi(t-\tau-3/2)] d\tau$$

$$x * h(t) = \begin{cases} \int_{t-2}^{t-1} \cos[\pi(t-\tau-3/2)] d\tau & t < 1 \\ \int_{t-2}^0 \cos[\pi(t-\tau-3/2)] d\tau + \int_0^{t-1} -\cos[\pi(t-\tau-3/2)] d\tau & 1 \leq t < 2 \\ \int_{t-2}^{t-1} -\cos[\pi(t-\tau-3/2)] d\tau & t \geq 2 \end{cases}$$

QUESTION 3

PART (A)

A LTI system with impulse response h is BIBO stable if and only if $\int_{-\infty}^{\infty} |h(t)| dt < \infty$.

PART (B)

$$h(t) = e^{-a|t|}, \quad a \in \mathbb{R}$$

$$\begin{aligned} \int_{-\infty}^{\infty} |h(t)| dt &= \int_{-\infty}^{\infty} |e^{-a|t|}| dt \\ &= \int_{-\infty}^{\infty} e^{-a|t|} dt \\ &= \int_{-\infty}^0 e^{at} dt + \int_0^{\infty} e^{-at} dt \end{aligned}$$

assuming $a \neq 0$, we have

$$\begin{aligned} \int_{-\infty}^{\infty} |h(t)| dt &= \left[\frac{1}{a} e^{at} \right]_{-\infty}^0 + \left[-\frac{1}{a} e^{-at} \right]_0^{\infty} \\ &= \frac{1}{a} [e^{at}]_{-\infty}^0 - \frac{1}{a} [e^{-at}]_0^{\infty} \\ &= \begin{cases} \frac{1}{a} [1-0] - \frac{1}{a} [0-1] & a > 0 \\ \infty & a < 0 \end{cases} \\ &= \begin{cases} \frac{2}{a} & a > 0 \\ \infty & a < 0 \end{cases} \end{aligned}$$

$$\text{if } a=0, \quad \int_{-\infty}^{\infty} |h(t)| dt = \int_{-\infty}^{\infty} 1 dt = \infty$$

Therefore, \mathcal{H} is BIBO stable if and only if $a > 0$.

QUESTION 4

System \mathcal{H} is LTI; system function $H(s) = e^{2s}$ for all $s \in \mathbb{C}$

$$x(t) = e + \sin(3t)$$

$$\begin{aligned}
 \mathcal{H}x(t) &= \mathcal{H}\{e + \sin(3\bullet)\}(t) \\
 &= \mathcal{H}\left\{e e^{j0\bullet} + \frac{1}{j2} [e^{j3\bullet} - e^{-j3\bullet}]\right\}(t) \quad \text{Euler} \\
 &= \mathcal{H}\left\{e e^{j0\bullet} + \frac{1}{j2} e^{j3\bullet} - \frac{1}{j2} e^{-j3\bullet}\right\}(t) \quad \text{linearity} \\
 &= e \mathcal{H}\{e^{j0\bullet}\}(t) + \frac{1}{j2} \mathcal{H}\{e^{j3\bullet}\}(t) - \frac{1}{j2} \mathcal{H}\{e^{-j3\bullet}\}(t) \\
 &= e H(0) e^{j0t} + \frac{1}{j2} H(j3) e^{j3t} - \frac{1}{j2} H(-j3) e^{-j3t} \quad \text{eigenfunction} \\
 &= e(1)(1) + \frac{1}{j2} (e^{2(j3)}) e^{j3t} - \frac{1}{j2} (e^{2(-j3)}) e^{-j3t} \\
 &= e + \frac{1}{j2} e^{j6} e^{j3t} - \frac{1}{j2} e^{-j6} e^{-j3t} \\
 &= e + \frac{1}{j2} e^{j(3t+6)} - \frac{1}{j2} e^{-j(3t+6)} \\
 &= e + \frac{1}{j2} [e^{j(3t+6)} - e^{-j(3t+6)}] \quad \text{Euler} \\
 &= e + \sin(3t+6) \\
 &= e + \sin[3(t+2)]
 \end{aligned}$$