R Answer (a).

First, we compute $\mathfrak{D}x$ to obtain

$$\mathcal{D}x(t) = \frac{d}{dt}(t^2 + 2t + 1)$$
$$= 2t + 2.$$

So, we have

$$\mathcal{D}x(3t) = 2(3t) + 2$$
$$= 6t + 2.$$

R Answer (b).

First, we give a name v to the anonymous function represented by $x(3\cdot)$. That is, we define v(t) = x(3t). So, we have

$$v(t) = x(3t)$$

$$= (3t)^{2} + 2(3t) + 1$$

$$= 9t^{2} + 6t + 1.$$

So, we have

$$y(t) = \mathcal{D}\lbrace x(3\cdot)\rbrace(t)$$

$$= \mathcal{D}v(t)$$

$$= \frac{d}{dt}(9t^2 + 6t + 1)$$

$$= 18t + 6.$$

R Answer (c).

Let $x_1(t) = 7\cos(35t + 3)$ and $x_2(t) = 5\sin(15t - 2)$. Let T_1 and T_2 denote the fundamental periods of x_1 and x_2 , respectively. We have that

$$T_1 = \frac{2\pi}{35}$$
, $T_2 = \frac{2\pi}{15}$, and $\frac{T_1}{T_2} = \frac{\left(\frac{2\pi}{35}\right)}{\left(\frac{2\pi}{15}\right)} = \frac{2\pi}{35} \left(\frac{15}{2\pi}\right) = \frac{15}{35} = \frac{3}{7}$.

Since $\frac{T_1}{T_2}$ is rational, x is periodic. We have that

$$T = 7T_1 = 3T_2 = 7(\frac{2\pi}{35}) = \frac{2\pi}{5}.$$

R Answer (j).

We are told that the function *x* is such that:

- 1. x(t) = 2 t for 0 < t < 1;
- 2. the function v(t) = x(t) 2 is causal; and
- 3. the function w(t) = x(t+1) is odd.

First, we consider the consequences of v being causal. From the fact that v(t) = x(t) - 2 is causal, we have

$$v(t) = 0$$
 for all $t < 0 \Rightarrow$
 $x(t) - 2 = 0$ for all $t < 0 \Rightarrow$
 $x(t) = 2$ for all $t < 0$.

Now, we consider the consequences of w being odd. Since w(t) = x(t+1) we have

$$x(t) = w(t-1)$$
.

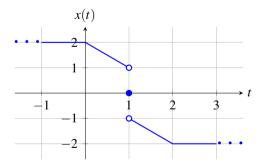
(i.e., x is w shifted to the right by 1). Thus, since w is odd and x is w shifted right by 1, x has odd symmetry about 1. Therefore, x(1) = 0. Next, we determine x(t) for $1 < t \le 2$. This can be deduced either graphically or algebraically. Since a graphical approach is easier, we will use this approach here. (An algebraic approach is presented at the end of this solution.) With a graphical approach, we can simply visualize the consequences of the symmetry in x from a graph of x(t) for $0 \le t < 1$. (See the part of the plot of x(t) below for $0 \le t < 1$, which is known from the information given in the problem statement.) This allows us to deduce that

$$x(t) = -t \text{ for } 1 < t \le 2.$$

Combining the results from above, we conclude

$$x(t) = \begin{cases} 2 & t < 0 \\ 2 - t & 0 \le t < 1 \\ 0 & t = 1 \\ -t & 1 < t \le 2 \\ -2 & t > 2. \end{cases}$$

A plot of *x* is shown in the figure below.



REMARKS ON ALGEBRAIC APPROACH. As mentioned above, the formula for x(t) for $1 < t \le 2$ can also be deduced algebraically (instead of graphically). Now, we will perform this deduction using an algebraic approach. Since x has odd symmetry about 1, we know that

$$x(1+t) = -x(1-t)$$
 for all $t \Rightarrow x(t) = -x(1-(t-1))$ for all $t \Rightarrow x(t) = -x(2-t)$ for all t .

Substituting into the preceding equation for the case that $0 \le t < 1$, we have

$$x(t) = -x(2-t) \text{ for } 0 \le t < 1 \quad \Rightarrow$$

$$x(t) = -[2-(2-t)] \text{ for } 0 \le 2-t < 1 \quad \Rightarrow$$

$$x(t) = -2+2-t \text{ for } 0 \le 2-t < 1 \quad \Rightarrow$$

$$x(t) = -t \text{ for } 1 < t \le 2.$$

(Above, we used that fact that $0 \le 2 - t < 1 \Leftrightarrow 0 \le 2 - t$ and $2 - t < 1 \Leftrightarrow t \le 2$ and $1 < t \Leftrightarrow 1 < t \le 2$.)

R Answer (e).

Let y(t) denote the value of the given expression for a particular value of t. So, we are given

$$y(t) = \int_{t}^{\infty} (\tau^2 + 1) \delta(\tau - 2) d\tau.$$

From the equivalence property of the δ function, we have

$$y(t) = \int_{t}^{\infty} \left[\tau^{2} + 1 \right] \Big|_{\tau=2} \delta(\tau - 2) d\tau$$
$$= \int_{t}^{\infty} (2^{2} + 1) \delta(\tau - 2) d\tau$$
$$= \int_{t}^{\infty} 5\delta(\tau - 2) d\tau$$
$$= 5 \int_{t}^{\infty} \delta(\tau - 2) d\tau.$$

Since $\delta(\cdot - 2)$ has an area of 1 concentrated at the point 2, we have

$$y(t) = \begin{cases} 5(1) & t \le 2 \\ 5(0) & \text{otherwise} \end{cases}$$
$$= \begin{cases} 5 & t \le 2 \\ 0 & \text{otherwise} \end{cases}$$
$$= 5u(2-t).$$

R Answer (b).

We are given the function

$$x(t) = \begin{cases} -e^{t+1} & t < -1\\ t & -1 \le t < 1\\ (t-2)^2 & 1 \le t < 2\\ 0 & \text{otherwise.} \end{cases}$$

We have

$$\begin{split} x(t) &= -e^{t+1}[u(t-[-\infty]) - u(t+1)] + t[u(t+1) - u(t-1)] + (t-2)^2[u(t-1) - u(t-2)] \\ &= -e^{t+1}[1 - u(t+1)] + t[u(t+1) - u(t-1)] + (t-2)^2[u(t-1) - u(t-2)] \\ &= -e^{t+1} + (t+e^{t+1})u(t+1) + [(t-2)^2 - t]u(t-1) - (t-2)^2u(t-2) \\ &= -e^{t+1} + (t+e^{t+1})u(t+1) + [t^2 - 5t + 4]u(t-1) - (t-2)^2u(t-2) \\ &= -e^{t+1} + (t+e^{t+1})u(t+1) + (t-1)(t-4)u(t-1) - (t-2)^2u(t-2). \end{split}$$

R Answer (a).

A system \mathcal{H} is said to be BIBO stable if $\mathcal{H}x$ is bounded for every bounded function x. We have

$$\mathcal{H}x(t) = u(t)x(t)$$
.

Assume that $|x(t)| \le A < \infty$ (i.e., x is bounded). Then, we need to show that this implies that $\mathcal{H}x$ is bounded. Taking the magnitude of both sides of the system equation, we have

$$|\mathcal{H}x(t)| = |u(t)x(t)|$$
$$= |u(t)||x(t)|.$$

Replacing the expressions |u(t)| and |x(t)| in the preceding equation by their upper bounds (of 1 and A, respectively), we obtain the inequality

$$|\mathcal{H}x(t)| \le 1 \cdot A = A.$$

Thus, $|\mathcal{H}x(t)| \le A < \infty$ (i.e., $\mathcal{H}x$ is bounded). Since the boundedness of x implies the boundedness of $\mathcal{H}x$, the system is BIBO stable.

R Answer (b).

We have

$$\mathcal{H}x_1(t) = \int_{-\infty}^t x_1(\tau)d\tau = \frac{1}{2}e^{2t} = \frac{1}{2}x_1(t) \quad \text{and}$$

$$\mathcal{H}x_2(t) = \int_{-\infty}^t x_2(\tau)d\tau = \begin{cases} e^t & t < 0\\ 1 & \text{otherwise.} \end{cases}$$

Therefore, x_1 is an eigenfunction with eigenvalue $\frac{1}{2}$ and x_2 is not an eigenfunction.