Taking the inverse Fourier transform of both sides of this equation, we obtain

taking inverse FT

$$v_2(t) = \mathcal{F}^{-1}\left\{\frac{2L}{R+j\omega L}\right\}(t)$$

$$= \mathcal{F}^{-1}\left\{\frac{2}{R/L+j\omega}\right\}(t)$$

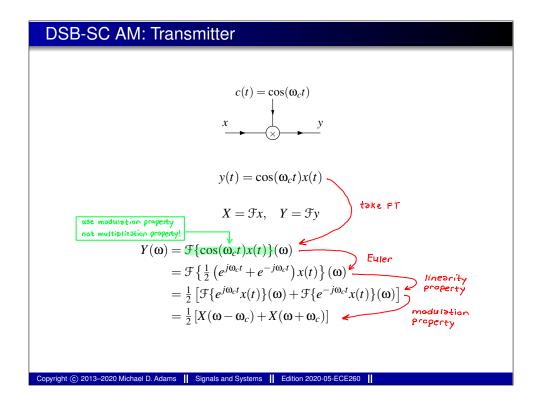
$$= 2\mathcal{F}^{-1}\left\{\frac{1}{R/L+j\omega}\right\}(t).$$
Innearity
$$v_2(t) = 2e^{-(R/L)t}u(t).$$

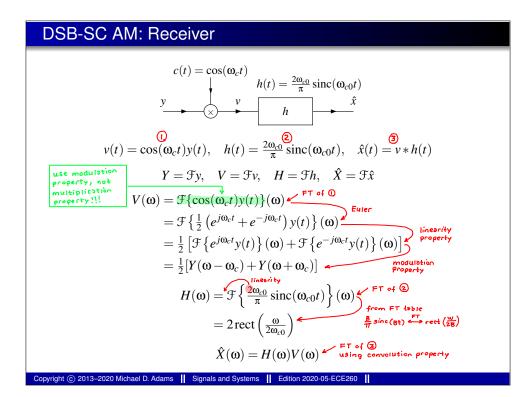
$$v_2(t) = 2e^{-(R/L)t}u(t).$$

Using Table 6.2, we can simplify to obtain

$$e^{-a+u(t)}$$
 $e^{-a+u(t)}$

Thus, we have found the response v_2 to the input $v_1(t) = \operatorname{sgn} t$.





DSB-SC AM: Complete System

$$c(t) = \cos(\omega_c t)$$

$$c(t) = \cos(\omega_c t)$$

$$h(t) = \frac{2\omega_{c0}}{\pi} \operatorname{sinc}(\omega_{c0} t)$$

$$y$$

$$y$$

$$h$$

$$\hat{x}$$

① $Y(\omega) = \frac{1}{2} \left[X(\omega - \omega_c) + X(\omega + \omega_c) \right]^{2}$ from result for transmitter

$$V(\omega) = \frac{1}{2}[Y(\omega - \omega_c) + Y(\omega + \omega_c)]$$

$$= \frac{1}{2} \left[\frac{1}{2} \left[X([\omega - \omega_c] - \omega_c) + X([\omega - \omega_c] + \omega_c) \right] + \frac{1}{2} \left[X([\omega + \omega_c] - \omega_c) + X([\omega + \omega_c] + \omega_c) \right] \right]$$

$$= \frac{1}{2} X(\omega) + \frac{1}{4} X(\omega - 2\omega_c) + \frac{1}{4} X(\omega + 2\omega_c)$$
substitute 0

$$\hat{X}(\omega) = H(\omega)V(\omega) \xrightarrow{\text{from result for receiver}} \\ = H(\omega) \left[\frac{1}{2}X(\omega) + \frac{1}{4}X(\omega - 2\omega_c) + \frac{1}{4}X(\omega + 2\omega_c) \right] \xrightarrow{\text{substitute } 2} \\ = \frac{1}{2}H(\omega)X(\omega) + \frac{1}{4}H(\omega)X(\omega - 2\omega_c) + \frac{1}{4}H(\omega)X(\omega + 2\omega_c) \xrightarrow{\text{multiply}} \\ = \frac{1}{2}\left[2X(\omega) \right] + \frac{1}{4}(0) + \frac{1}{4}(0) \xrightarrow{\text{Simp (itty)}} \xrightarrow{\text{Simp (itty)}} \frac{X(\omega - 2\omega_c) + \frac{1}{4}H(\omega)X(\omega + 2\omega_c)}{\text{(since } \omega_b < \omega_{ec} < 2\omega_c - \omega_b)} \xrightarrow{\text{when } H(\omega) \neq 0} \\ = X(\omega) \xrightarrow{\text{Simp (itty)}}$$

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