

Example 6.24. Consider the periodic function x given by

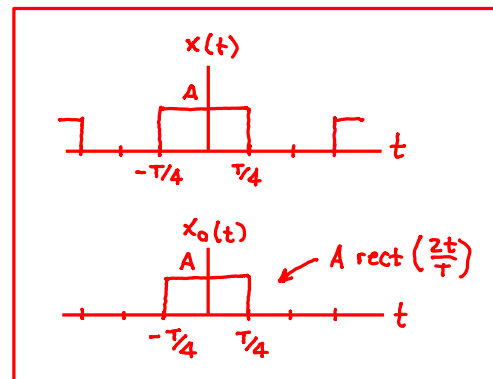
$$x(t) = \sum_{k=-\infty}^{\infty} x_0(t - kT),$$

where a single period of x is given by

$$x_0(t) = A \operatorname{rect}\left(\frac{2t}{T}\right)$$

and A is a real constant. Find the Fourier transform X of the function x .

Solution. From (6.16b), we know that



$$X(\omega) = \sum_{k=-\infty}^{\infty} \omega_0 X_T(k\omega_0) \delta(\omega - k\omega_0)$$

$$X(\omega) = \mathcal{F} \left\{ \sum_{k=-\infty}^{\infty} x_0(t - kT) \right\} (\omega)$$

using (6.16)

$$= \sum_{k=-\infty}^{\infty} \omega_0 X_0(k\omega_0) \delta(\omega - k\omega_0).$$

table of FT pairs

So, we need to find X_0 . Using the linearity property of the Fourier transform and Table 6.2, we have

$$\begin{aligned} X_0(\omega) &= \mathcal{F} \left\{ A \operatorname{rect}\left(\frac{2t}{T}\right) \right\} (\omega) \\ &= A \mathcal{F} \left\{ \operatorname{rect}\left(\frac{2t}{T}\right) \right\} (\omega) \\ &= \frac{AT}{2} \operatorname{sinc}\left(\frac{\omega T}{4}\right). \end{aligned}$$

from definition of x
linearity
FT table

Thus, we have that

$$\begin{aligned} X(\omega) &= \sum_{k=-\infty}^{\infty} \omega_0 \left(\frac{AT}{2} \right) \operatorname{sinc}\left(\frac{k\omega_0 T}{4}\right) \delta(\omega - k\omega_0) \\ &= \sum_{k=-\infty}^{\infty} \pi A \operatorname{sinc}\left(\frac{\pi k}{2}\right) \delta(\omega - k\omega_0). \end{aligned}$$

$\omega_0 = \frac{2\pi}{T}$

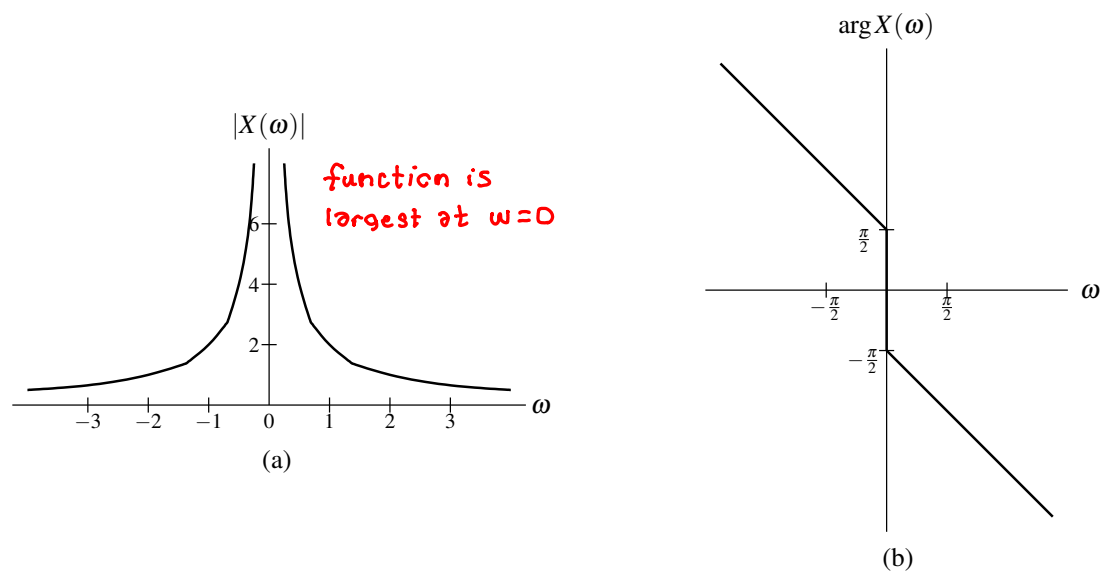


Figure 6.10: Frequency spectrum of the time-shifted signum function. (a) Magnitude spectrum and (b) phase spectrum of x .

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Example 6.34 (Differential equation to frequency response). A LTI system with input x and output y is characterized by the differential equation

$$7y''(t) + 11y'(t) + 13y(t) = 5x'(t) + 3x(t),$$

where x' , y' , and y'' denote the first derivative of x , the first derivative of y , and the second derivative of y , respectively. Find the frequency response H of this system.

Solution. Taking the Fourier transform of the given differential equation, we obtain

$$7(j\omega)^2 Y(\omega) + 11j\omega Y(\omega) + 13Y(\omega) = 5j\omega X(\omega) + 3X(\omega).$$

Rearranging the terms and factoring, we have

$$(-7\omega^2 + 11j\omega + 13)Y(\omega) = (5j\omega + 3)X(\omega).$$

Thus, H is given by

$$\textcircled{1} \quad \frac{Y(\omega)}{X(\omega)} = \frac{5j\omega + 3}{-7\omega^2 + 11j\omega + 13}$$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{5j\omega + 3}{-7\omega^2 + 11j\omega + 13}.$$

$$\textcircled{*} \quad \text{Since system is LTI, } Y(\omega) = X(\omega) H(\omega) \Rightarrow H(\omega) = \frac{Y(\omega)}{X(\omega)}$$