

ELEC 260

MIDTERM EXAM 1

SOLUTIONS

Question 1

- (a) ii) even but not odd $x(-t) = 1-t + \cos(-2\pi t) = (1+t) + \cos 2\pi t = x(t)$
- (b) ii) periodic with period 2 $T_1 = 1, T_2 = 2/5, \frac{T_1}{T_2} \notin \mathbb{Q} \Rightarrow T = 2T_1 = 2$
- (c) iii) 0
- (d) iii) insufficient information to determine
- (e) ii) no
- (f) ii) no
- (g) ii) ~~yes~~ no
- (h) i) yes
- (i) ii) no
- (j) iii) delta(t)
- (k) iii) h(t) is absolutely integrable
- (l) i) H_1

QUESTION 2

- (a) To find the poles and zeros of $F(z)$, we rewrite $F(z)$ in factored form. We have

$$F(z) = \frac{z^2 + 5z + 6}{(z-j)(z^4 - z^3)}$$

$$= \frac{(z+2)(z+3)}{(z-j)z^3(z-1)}$$

By inspection, we see that $F(z)$ has the following poles and zeros:

poles

- j (1st order)
- 0 (3rd order)
- 1 (1st order)

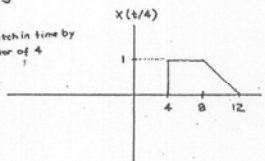
zeros

- -2 (1st order)
- -3 (1st order)

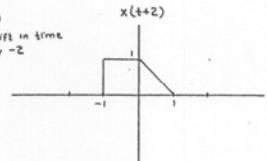
- (b) Since $F(z)$ is a rational function, it is analytic everywhere except at its poles. Therefore, $F(z)$ is analytic everywhere except at $z \in \{j, 0, 1\}$.

QUESTION 3

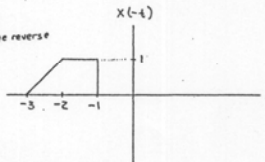
(a) stretch in time by factor of 4



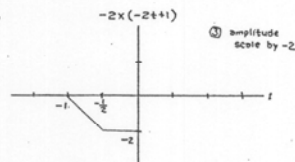
(b) shift in time by -2



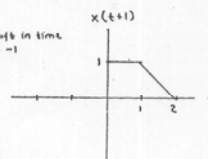
(c) time reverse



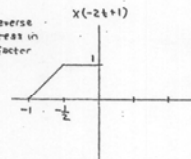
(d)



① shift in time by -1



② time reverse and compress in time by factor of 2



QUESTION 4

We can write

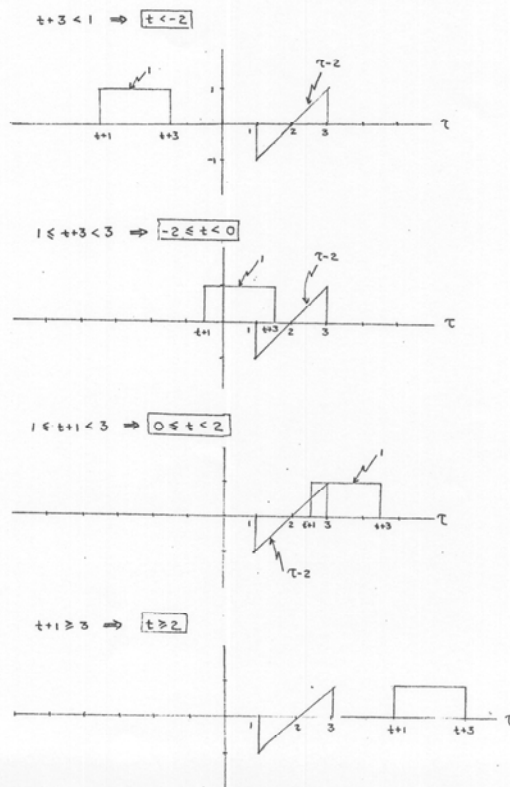
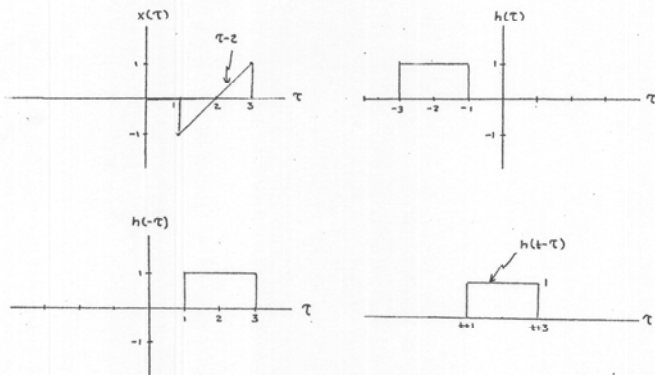
$$\begin{aligned} x(t) &= t[u(t) - u(t-1)] + (2-t)[u(t-1) - u(t-2)] \\ &= t u(t) - t u(t-1) + 2 u(t-1) - 2 u(t-2) \\ &\quad - t u(t-1) + t u(t-2) \\ &= (t) u(t) + (-2t+2) u(t-1) + (t-2) u(t-2) \end{aligned}$$

QUESTION 5

A proof of the commutative property of convolution is provided in the lecture notes.

(See Section 3.3.1 on page 43.)

QUESTION 6



for $t < -2$

$$x(t) * h(t) = 0$$

for $-2 \leq t < 0$

$$\begin{aligned} x(t) * h(t) &= \int_{-1}^{t+3} (1)(\tau-2) d\tau \\ &= \int_{-1}^{t+3} (\tau-2) d\tau \\ &= \left[\frac{1}{2}\tau^2 - 2\tau \right]_{-1}^{t+3} \\ &= \frac{1}{2}(t+3)^2 - 2(t+3) - \left[\frac{1}{2} - 2 \right] \\ &= \frac{1}{2}(t^2 + 6t + 9) - 2t - 6 + \frac{3}{2} \\ &= \frac{1}{2}t^2 + 3t + \frac{9}{2} - 2t - 6 + \frac{3}{2} \\ &= \frac{1}{2}t^2 + t \end{aligned}$$

for $0 \leq t < 2$

$$\begin{aligned} x(t) * h(t) &= \int_{t+1}^3 (1)(\tau-2) d\tau \\ &= \int_{t+1}^3 (\tau-2) d\tau \\ &= \left[\frac{1}{2}\tau^2 - 2\tau \right]_{t+1}^3 \\ &= \frac{9}{2} - 6 - \left[\frac{1}{2}(t+1)^2 - 2(t+1) \right] \\ &= \frac{3}{2} - \frac{1}{2}(t^2 + 2t + 1) + 2(t+1) \\ &= \frac{3}{2} - \frac{1}{2}t^2 - t - \frac{1}{2} + 2t + 2 \\ &= -\frac{1}{2}t^2 + t \end{aligned}$$

for $t \geq 2$

$$x(t) * h(t) = 0$$

$$x(t) * h(t) = \begin{cases} \frac{1}{2}t^2 + t & \text{for } -2 \leq t < 0 \\ -\frac{1}{2}t^2 + t & \text{for } 0 \leq t < 2 \\ 0 & \text{otherwise} \end{cases}$$

QUESTION 7

(a) Suppose that

$$x_1(t) \rightarrow y_1(t)$$

$$x_2(t) \rightarrow y_2(t)$$

$$a_1 x_1(t) + a_2 x_2(t) \rightarrow y_3(t)$$

If for all $a_1, a_2 \in \mathbb{C}$ and all $x_1(t), x_2(t)$ we have

$$y_3(t) = a_1 y_1(t) + a_2 y_2(t), \text{ then the system is linear.}$$

(b) From the system input-output equation, we can write

$$y_1(t) = x_1(t) + 1$$

$$y_2(t) = x_2(t) + 1$$

$$y_3(t) = [a_1 x_1(t) + a_2 x_2(t)] + 1$$

$$= a_1 x_1(t) + a_2 x_2(t) + 1$$

$$a_1 y_1(t) + a_2 y_2(t) = a_1 [x_1(t) + 1] + a_2 [x_2(t) + 1]$$

$$= a_1 x_1(t) + a_2 x_2(t) + a_1 + a_2$$

Thus, we have

$$y_3(t) \neq a_1 y_1(t) + a_2 y_2(t).$$

Therefore, the system is not linear.

QUESTION 8

Let us denote the input to system \mathcal{H}_2 as $v(t)$.

From the block diagram, we have

$$\begin{aligned} v(t) &= x(t) + h_1(t) * x(t) \\ &= [\delta(t) + h_1(t)] * x(t) \end{aligned}$$

$$\begin{aligned} y(t) &= v(t) * h_2(t) + x(t) * h_3(t) \\ &= [\delta(t) + h_1(t)] * x(t) * h_2(t) + x(t) * h_3(t) \\ &= x(t) * [\delta(t) + h_1(t)] * h_2(t) + x(t) * h_3(t) \\ &= x(t) * [(\delta(t) + h_1(t)) * h_2(t) + h_3(t)] \\ &= x(t) * [h_2(t) + h_1(t) * h_2(t) + h_3(t)] \end{aligned}$$

Therefore, the impulse response $h(t)$ of the system is given by

$$h(t) = h_2(t) + h_1(t) * h_2(t) + h_3(t)$$

