

ECE 260

EXAM I

SOLUTIONS

(FALL 2024)

QUESTION 1

From ①, we have

$$\begin{aligned} v(t) &= 0 \text{ for all } t < 0 \Rightarrow \\ x(t-3)+1 &= 0 \text{ for all } t < 0 \Rightarrow \\ x(t-3) &= -1 \text{ for all } t < 0 \Rightarrow \\ x(t) &= -1 \text{ for all } t+3 < 0 \Rightarrow \\ x(t) &= -1 \text{ for all } t < -3 \end{aligned}$$

Now, we consider ②.

$$w(t) = x(t-2)+1 \text{ is even}$$

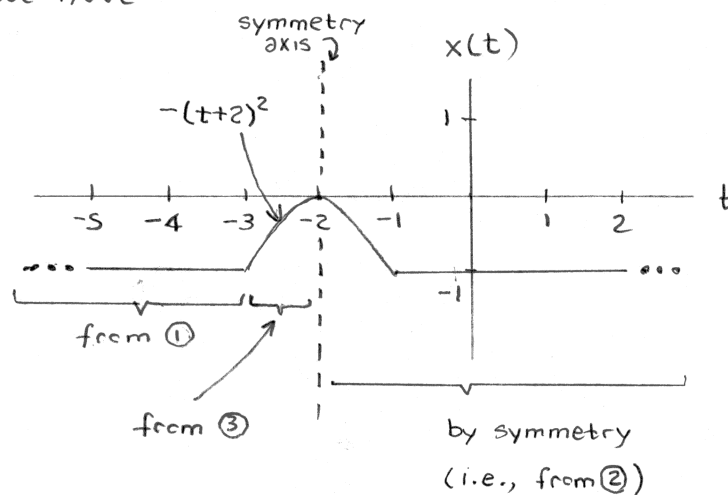
The function w is obtained from x by
time shifting by 2 (i.e., shift right by 2)
amplitude shifting by 1 (i.e., shift up by 1)

Therefore, x is obtained from w by
amplitude shifting by -1 (i.e., shift down by 1)
time shifting by -2 (i.e., shift left by 2)

So, w having a symmetry point at $(0,0)$ implies that x has
a symmetry point at $(0,0)+(-2,-1) = (-2,-1)$.

In other words, x has even-type symmetry about the line $t=-2$.

Thus, we have



$$x(t) = \begin{cases} -(t+2)^2 & -3 \leq t \leq -1 \\ -1 & \text{otherwise} \end{cases}$$

QUESTION 2A

$$\begin{aligned} |H(\omega)| &= \left| \frac{-5}{(-1-j\omega)^4} \right| = \frac{|-5|}{|(-1-j\omega)^4|} = \frac{5}{|-1-j\omega|^4} = \frac{5}{(\sqrt{\omega^2+1})^4} \\ &= \frac{5}{|\omega^2+1|^2} = \frac{5}{(\omega^2+1)^2} \end{aligned}$$

QUESTION 2B

$$\begin{aligned}
 \arg H(\omega) &= \arg \left[\frac{-5}{(-1-j\omega)^4} \right] \\
 &= \arg(-5) - \arg[(-1-j\omega)^4] \\
 &= \pi - 4 \arg(-1-j\omega) \\
 &= \pi - 4 \left[\pi + \arctan\left(\frac{-\omega}{-1}\right) \right] \\
 &= \pi - 4\pi - 4 \arctan(\omega) \\
 &= -3\pi - 4 \arctan(\omega)
 \end{aligned}$$

or more generally,

$$\arg H(\omega) = -4 \arctan(\omega) + (2K+1)\pi \quad \text{for all } K \in \mathbb{Z}$$

QUESTION 3A

$$x(t) = [t][u(t) - u(t-1)] + [2-t][u(t-1) - u(t-2)]$$

$$= tu(t) - tu(t-1) + 2u(t-1) - 2u(t-2) - tu(t-1) + tu(t-2)$$

$$= tu(t) + [-t+2-t]u(t-1) + [-2+t]u(t-2)$$

$$= tu(t) + (2-2t)u(t-1) + (t-2)u(t-2)$$

QUESTION 3B

$$y(t) = \sum_{k=-\infty}^{\infty} x(t-3k)$$

where the formula for x is as determined in part (a)

QUESTION 4A

A system \mathcal{H} is said to be linear if, for all functions x_1 and x_2 and all complex constants a_1 and a_2 , the following holds:

$$\mathcal{H}\{a_1 x_1 + a_2 x_2\} = a_1 \mathcal{H}x_1 + a_2 \mathcal{H}x_2$$

QUESTION 4B

$$\mathcal{H}x(t) = 2x(t) + 3$$

$$\begin{aligned} & \mathcal{H}\{a_1 x_1 + a_2 x_2\}(t) \\ &= 2[a_1 x_1(t) + a_2 x_2(t)] + 3 \\ &= 2a_1 x_1(t) + 2a_2 x_2(t) + 3 \end{aligned}$$

$$\begin{aligned} & a_1 \mathcal{H}x_1(t) + a_2 \mathcal{H}x_2(t) \\ &= a_1[2x_1(t) + 3] + a_2[2x_2(t) + 3] \\ &= 2a_1 x_1(t) + 3a_1 + 2a_2 x_2(t) + 3a_2 \\ &= 2a_1 x_1(t) + 2a_2 x_2(t) + 3(a_1 + a_2) \end{aligned}$$

since $\mathcal{H}\{a_1 x_1 + a_2 x_2\} = a_1 \mathcal{H}x_1 + a_2 \mathcal{H}x_2$ does not hold for all x_1, x_2, a_1 , and a_2 , the system \mathcal{H} is not linear (e.g., this relationship does not hold if $a_1 + a_2 \neq 1$).

QUESTION 5

```
1  function x = func(t)
2      x = ...
3      (0 <= t & t < 3) .* ...
4      (t + 1) .^ 9 .* (t + 2) .^ 7 ./ (t + 3) + ...
5      (3 <= t & t < 6) .* ...
6      sin(pi * t) ./ (t + 1);
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QUESTION 6

$$\mathcal{H}x(t) = Ax^3(t) + B$$

$$x_1(t) = -1, \quad \lambda_1 = -9$$

$$x_2(t) = 2, \quad \lambda_2 = 9$$

Since x_1 is an eigenfunction of \mathcal{H} with eigenvalue λ_1

$$\mathcal{H}x_1 = \lambda_1 x_1 \Rightarrow$$

$$A(-1)^3 + B = (-9)(-1) \Rightarrow$$

$$-A + B = 9 \quad (1)$$

Since x_2 is an eigenfunction of \mathcal{H} with eigenvalue λ_2

$$\mathcal{H}x_2 = \lambda_2 x_2 \Rightarrow$$

$$A(2)^3 + B = (9)(2) \Rightarrow$$

$$8A + B = 18 \quad (2)$$

solving for A and B

$$(1) \rightarrow -A + B = 9 \Rightarrow B = A + 9 \quad (3)$$

$$(2) \rightarrow 8A + B = 18 \Rightarrow 8A + A + 9 = 18 \Rightarrow 9A + 9 = 18 \Rightarrow 9A = 9 \Rightarrow$$

use (3)

$$A = 1$$

$$(3) \rightarrow B = A + 9 = 1 + 9 = 10$$

therefore,

$$A = 1$$

$$B = 10$$