

# Computer Communication Networks

## **Medium Access Control**

# Review

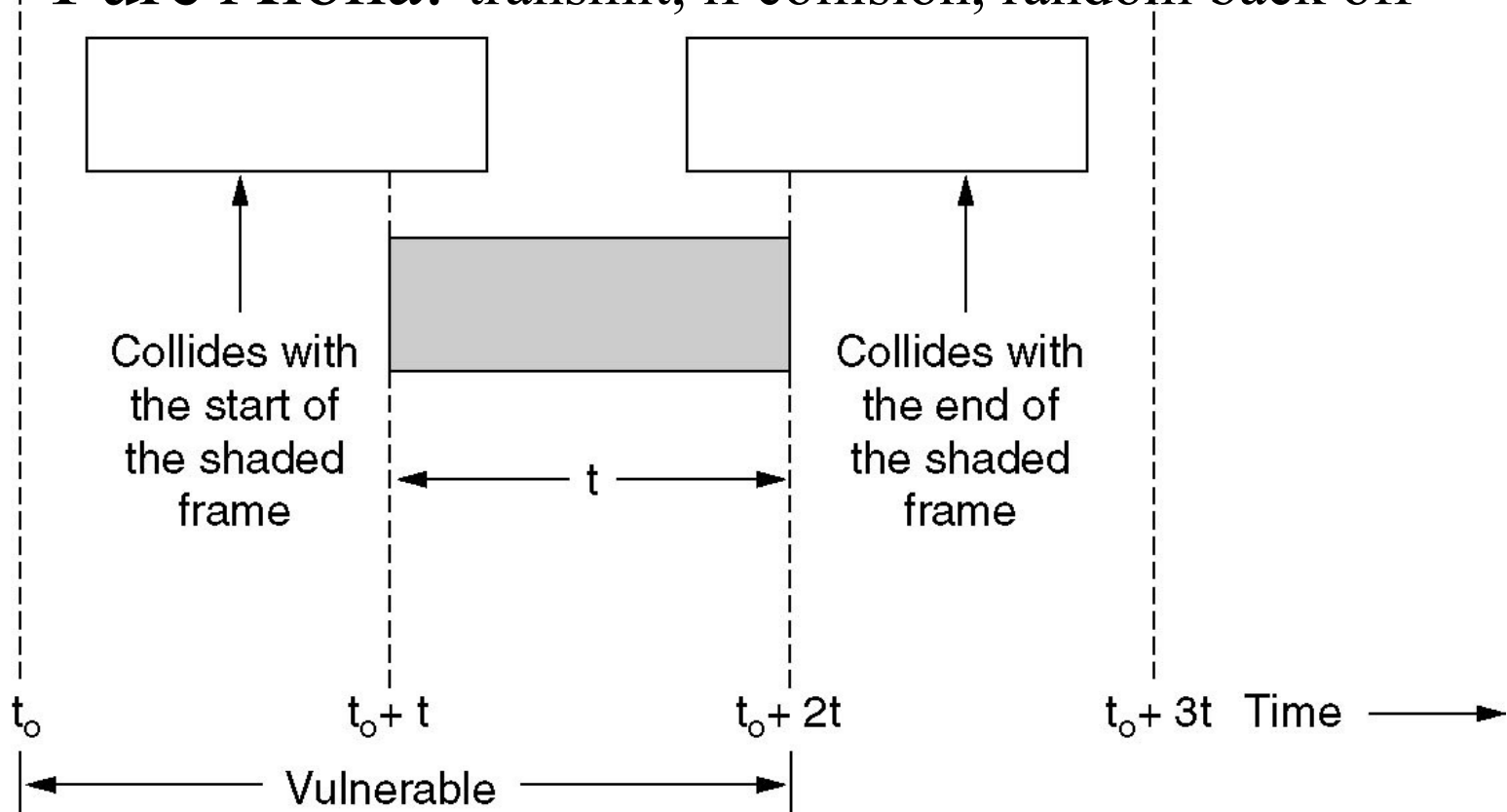
- Link layer
  - framing
  - error control
  - flow control
- How about you have more than one sender and one receiver share a link?

# Medium access control

- Type of links
  - point-to-point link
    - e.g., PPP, switched Ethernet
  - broadcast link (shared medium)
    - e.g., traditional Ethernet, 802.11
    - collision by concurrent transmission
- Medium access
  - deterministic allocation: FDM/TDM/CDM
  - contention-based: ALOHA, CSMA, CSMA/CD

# Aloha

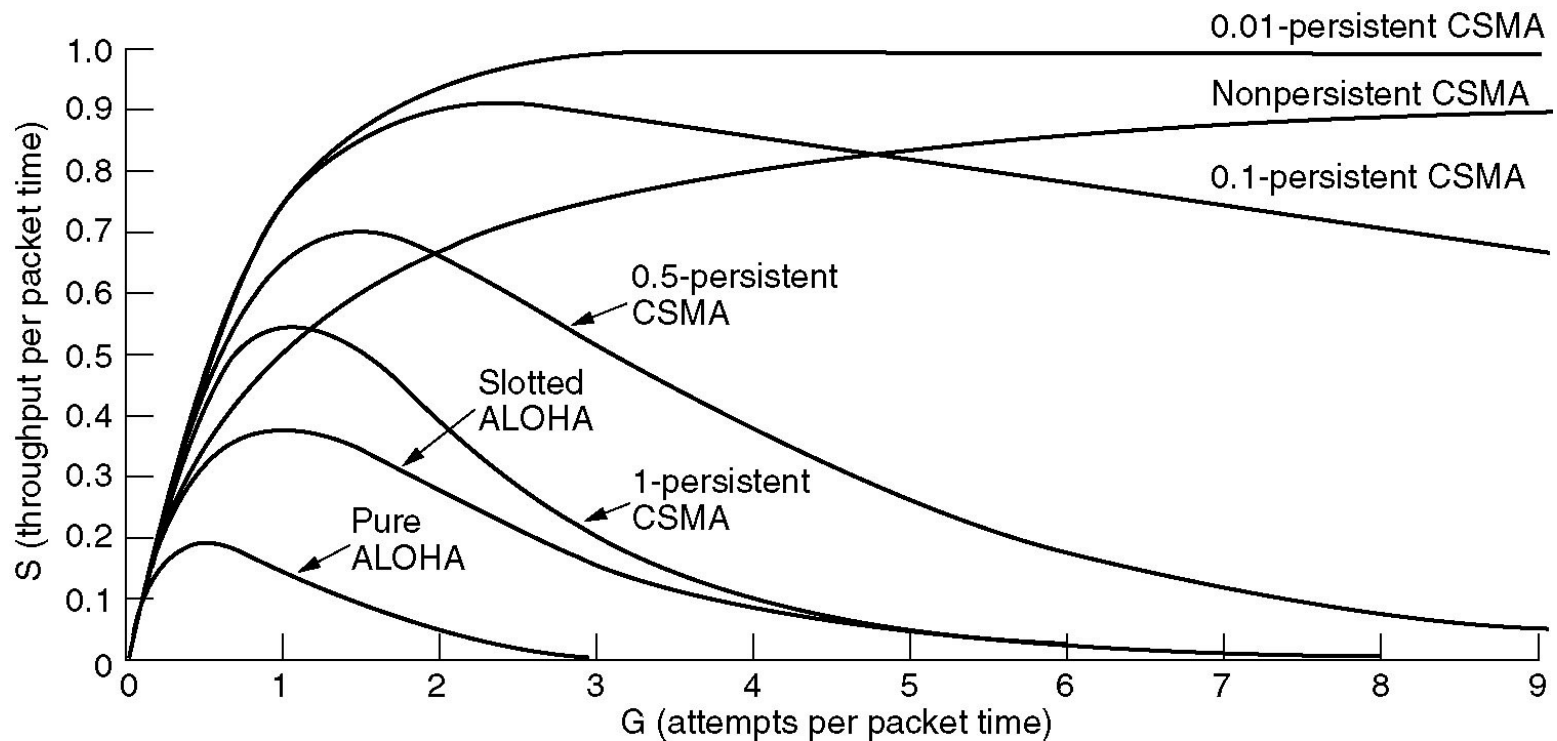
- Pure Aloha: transmit, if collision, random back off



- Slotted Aloha: transmit in next slot, if collision, ...

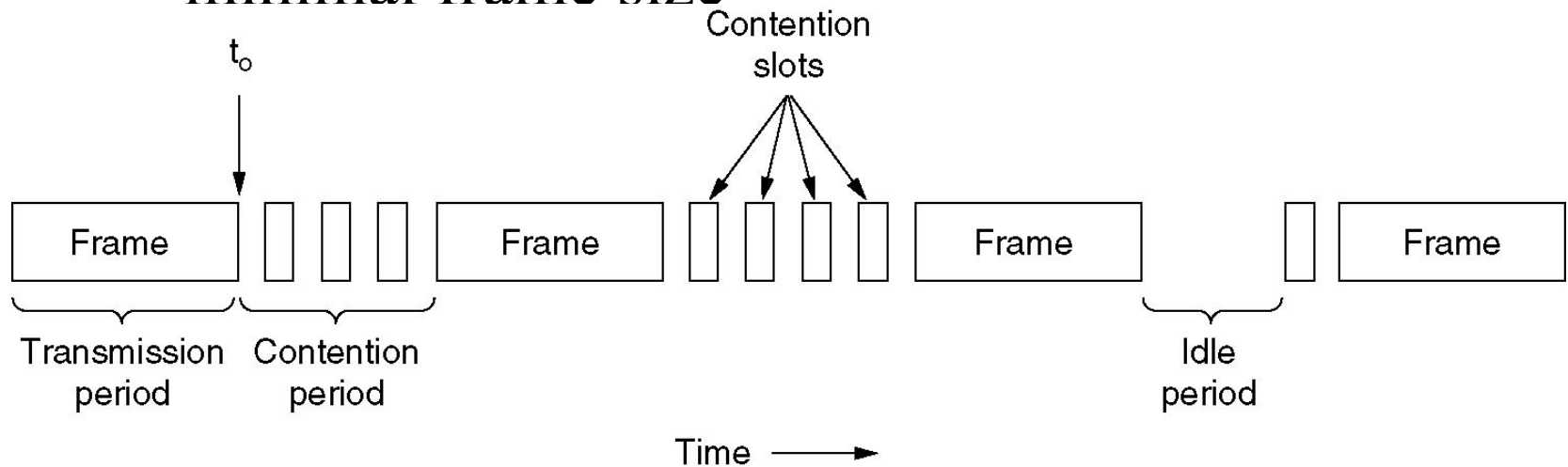
# Carrier sense multiple access

- p-persistent CSMA: if busy, wait; if idle, transmit w/ p
- Non-persistent CSMA: if busy, back-off



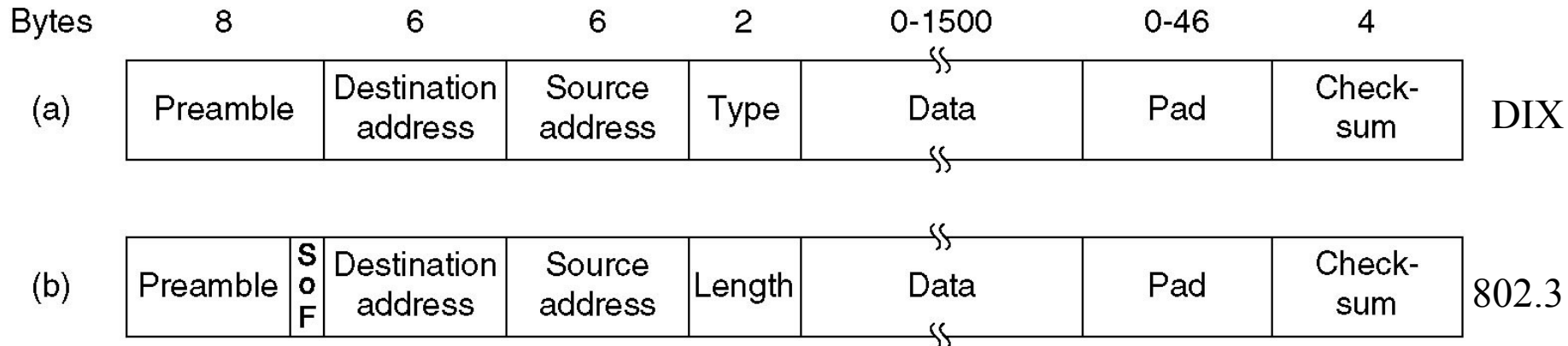
# CSMA/collision detection

- CSMA
- CD: if collision, abort! and back off
  - need: receiving while sending
  - minimal frame size



# Ethernet

- Pervasive!
  - speed: 10Mbps, 100Mbps, 1Gbps, 10Gbps
  - medium: coaxial, twist-pair, fiber
  - topology: bus, tree, star; range: LAN, MAN



# Ethernet frame

- Destination/source addresses (6-byte each)
- Type (2-byte): e.g., 0x0800 (IP)
  - length in 802.3 frame with 802.2 LLC
- Data: 0~1500 bytes
- Pad: 0~46 bytes
  - minimal frame length
- CRC: 4-byte
- CSMA/CD with binary exponential backoff

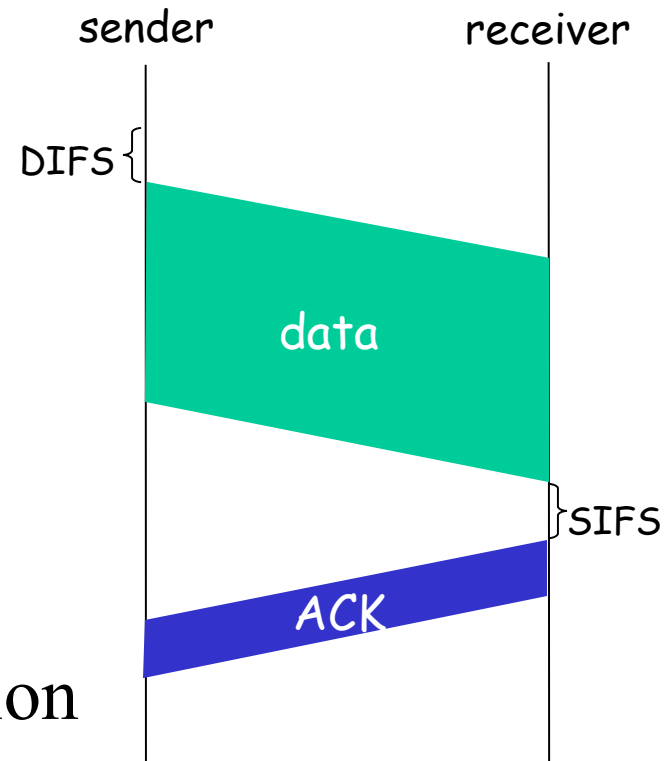


# Wireless LAN

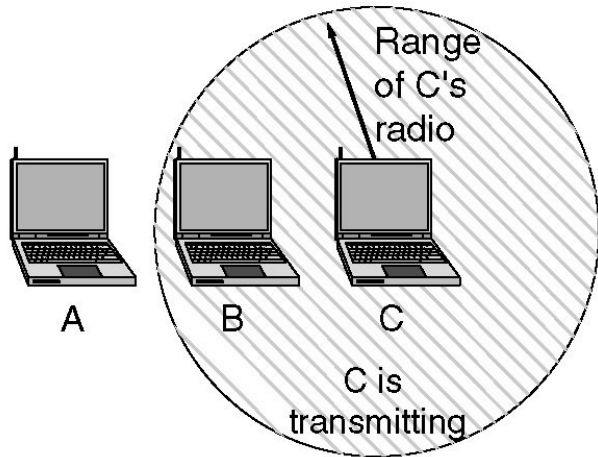
- Very popular!
  - 802.11a: 5GHz, 54Mbps, 30ft
  - 802.11b: 2.4GHz, 11Mbps, 100ft
  - 802.11g: 2.4GHz, 54Mbps, 100ft
  - 802.11n: MIMO, 2.4GHz, 540Mbps
- Infrastructure mode
  - access point
- Ad-hoc mode

# CSMA/CA

- CSMA
- CA: collision avoidance
  - if idle for DIFS, transmit
  - if busy, random backoff
    - count down when idle
    - transmit when count to 0
  - if no ack, collision or corruption
    - exponential backoff
    - CW: contention window

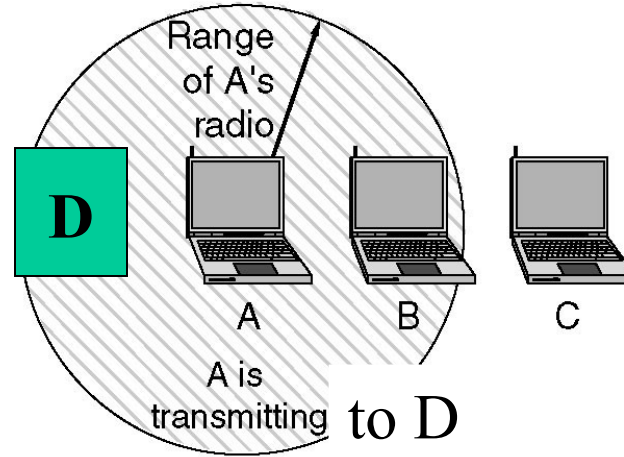


A wants to send to B  
but cannot hear that  
B is busy



(a)

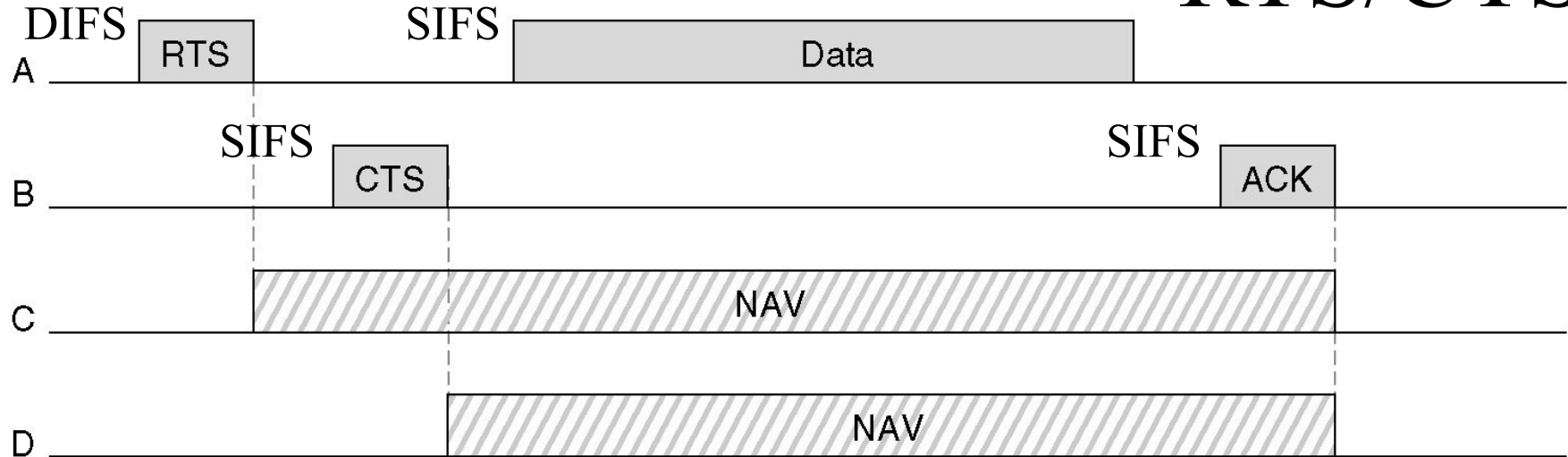
B wants to send to C  
but mistakenly thinks  
the transmission will fail



(b)

Hidden vs  
exposed  
terminal

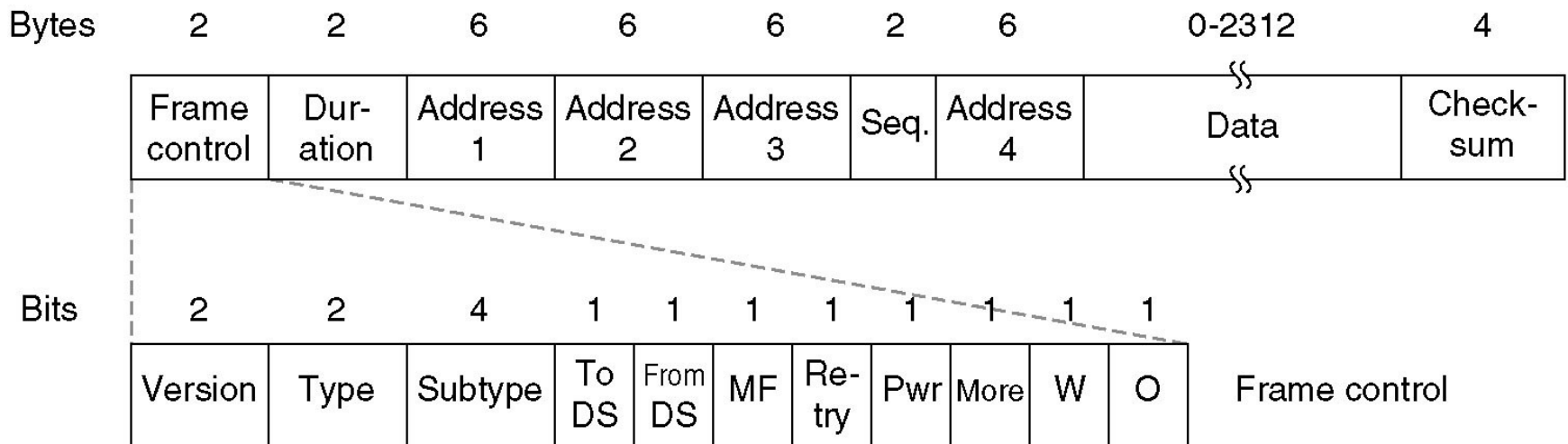
# RTS/CTS



Time →

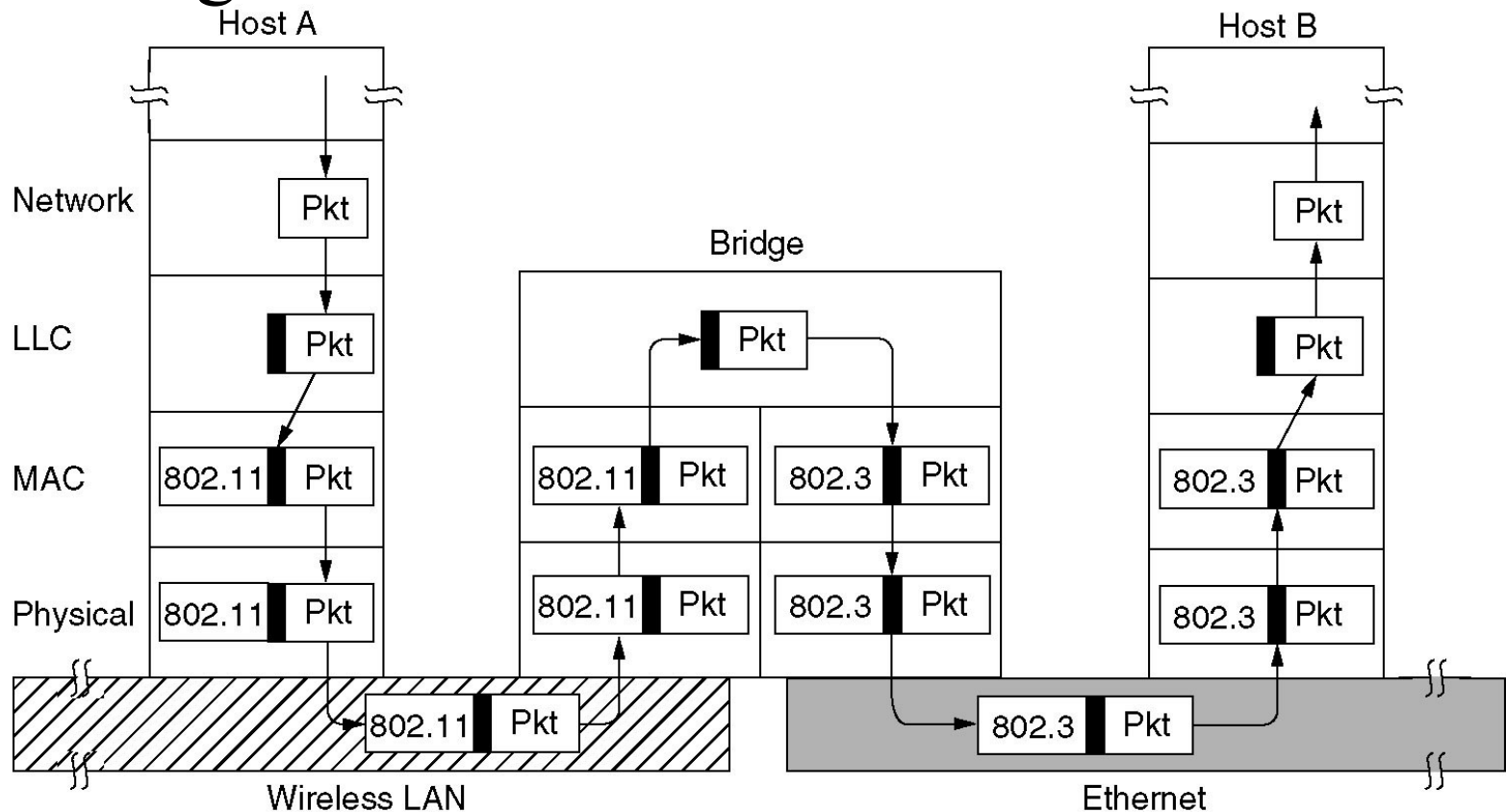
# 802.11 frame

- Frame control
- Duration: NAV (network allocation vector)
- Addresses: dst, src, receiving, transmitting



# Layer 2 internetworking

- Bridge



# How bridge works

- Objectives: plug-and-play

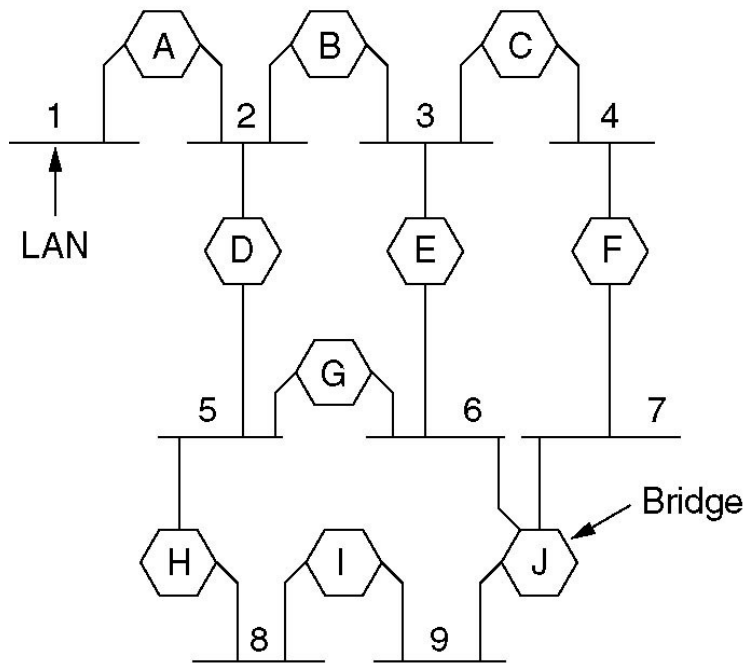
No hardware change, no software update, no setting of address, no downloading of routing tables or parameters.

- How

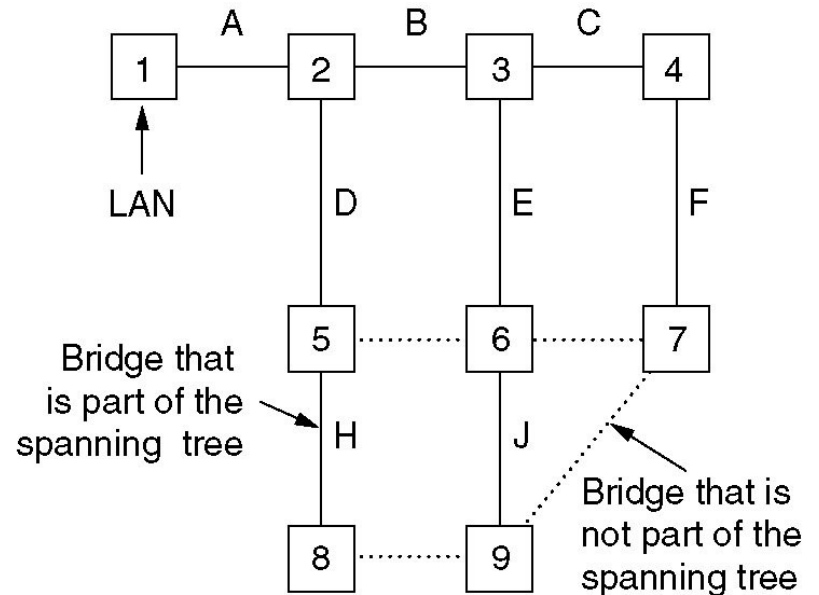
1. Each bridge connects with a number of LANs with a port connecting to a single LAN
2. Assume a packet is broadcasting in LAN1, bridge A needs to decide whether to forward it to its other ports, depending on the destination address. If the destination address in a hash table is in LAN1, no need; otherwise, forwards it.
3. Initially, the hash table is empty, then using flooding algorithm .
4. Anytime it hears a frame from a LAN, it adds the destination LAN for the source node, associated with the time. (backward learning).

# Spanning tree

- A tree of shortest paths



(a)



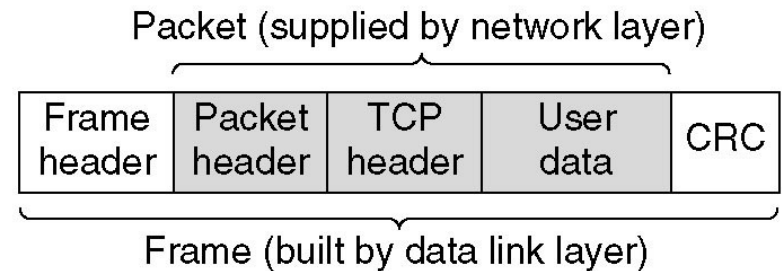
(b)

# Architecture, again!

- Network architecture
  - services
  - protocols

Application layer	Application gateway
Transport layer	Transport gateway
Network layer	Router
Data link layer	Bridge, switch
Physical layer	Repeater, hub

(a)



(b)



# Summary

- MAC
  - Ethernet
    - Aloha, slotted Aloha
    - CSMA, CSMA/CD
  - 802.11
    - CSMA/CA
    - RTS/CTS
  - internetworking
    - spanning tree

# Some other algorithms

- Tree protocols
  - Collisions are resolved using divide-and-conquer, collision resolution algorithm (CRA)
  - Assume:
    - Synchronous channel
    - Users are able to detect {idle, collision, success}
    - A user corresponds to a leaf of a binary tree.

# Tree protocols (cont'd)

- Static tree algorithm
  - Admission rule: newly arriving packets are admitted only after all the packets arrived during the previous collision resolution interval (CRI) are successfully transmitted
  - Retransmission rule: When a collision occurs, try to divide the users involved in the collision into two groups and resolve the collision among one group of users at a time
- Dynamic tree algorithm
  - At each CRI, the level of initial node is adjusted based on the throughput and the length of the previous cycle