

9.32 For each function x given below, find a single expression for x (i.e., an expression that does not involve multiple cases). Group similar unit-step function terms together in the expression for x .

$$(a) x(t) = \begin{cases} -t-3 & -3 \leq t < -2 \\ -1 & -2 \leq t < -1 \\ t^3 & -1 \leq t < 1 \\ 1 & 1 \leq t < 2 \\ -t+3 & 2 \leq t < 3 \\ 0 & \text{otherwise;} \end{cases}$$

$$(b) x(t) = \begin{cases} -1 & t < -1 \\ t & -1 \leq t < 1 \\ 1 & t \geq 1; \text{ and} \end{cases}$$

$$(c) x(t) = \begin{cases} 4t+4 & -1 \leq t < -\frac{1}{2} \\ 4t^2 & -\frac{1}{2} \leq t < \frac{1}{2} \\ -4t+4 & \frac{1}{2} \leq t < 1 \\ 0 & \text{otherwise.} \end{cases}$$

$$x(t) = (4t+4) \left[u(t+1) - u\left(t+\frac{1}{2}\right) \right] + 4t^2 \left[u\left(t+\frac{1}{2}\right) - u\left(t-\frac{1}{2}\right) \right] + (4-4t) \left[u\left(t-\frac{1}{2}\right) - u(t-1) \right]$$

$$= (4t+4) u(t+1) + (-4t-4+4t^2) u\left(t+\frac{1}{2}\right) + (-4t^2+4-4t) u\left(t-\frac{1}{2}\right) + (4t-4) u(t-1)$$

$$= (4t+4) u(t+1) + (4t^2-4t-4) u\left(t+\frac{1}{2}\right) + (-4t^2-4t+4) u\left(t-\frac{1}{2}\right) + (4t-4) u(t-1)$$

$$= 4 \left[(t+1) u(t+1) + (t^2-t-1) u\left(t+\frac{1}{2}\right) + (-t^2-t+1) u\left(t-\frac{1}{2}\right) + u(t-1)^2 \right]$$

3.24 Determine whether each system \mathcal{H} given below is memoryless.

(a) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) d\tau$;

(b) $\mathcal{H}(x(t)) = \text{Even}(x)(t)$;

(c) $\mathcal{H}(x(t)) = x(t-1) + 1$;

(d) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) d\tau$;

(e) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) \delta(\tau) d\tau$;

(f) $\mathcal{H}(x(t)) = tx(t)$; and

(g) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$.

(d) $\mathcal{H}_m(t) = \int_{-\infty}^{\infty} x(\tau) d\tau$

$\therefore \mathcal{H}_m(t_0) = \int_{-\infty}^{\infty} x(\tau) d\tau$

$\mathcal{H}_m(t_0)$ depends ~~it depends~~ on $x(t)$ for $t_0 \leq t \leq \infty$. Therefore the system is not memoryless

(g) $\mathcal{H}_m(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$
 $= \int_{-\infty}^{\infty} x(\tau) \delta(\tau-t) d\tau$
 $= x(t)$

$\mathcal{H}_m(t_0)$ depends on $x(t)$ for $t = t_0$

\therefore memoryless

3.25 Determine whether each system \mathcal{H} given below is causal.

(a) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) d\tau$;

(b) $\mathcal{H}(x(t)) = \text{Even}(x)(t)$;

(c) $\mathcal{H}(x(t)) = x(t-1) + 1$;

(d) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) d\tau$;

(e) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) \delta(\tau) d\tau$; and

(f) $\mathcal{H}(x(t)) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$.

(b) $\mathcal{H}_m(t) = \text{Even}\{x\}(t) = \frac{1}{2} [x(t) + x(-t)]$

$\mathcal{H}_m(t_0)$ depends on $x(t)$ for $t = \pm t_0$

\therefore system not causal

(f) $\mathcal{H}_m(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$
 $= \int_{-\infty}^t x(\tau) d\tau$

$\mathcal{H}_m(t_0)$ depends on $x(t)$ for $t \leq t_0$

\therefore causal

3.26 For each system \mathcal{H} given below, determine if \mathcal{H} is invertible, and if it is, specify its inverse.

(a) $\mathcal{H}(x(t)) = x(at - b)$ where a and b are real constants and $a \neq 0$;

(b) $\mathcal{H}(x(t)) = x^{n(t)}$, where x is a real function;

(c) $\mathcal{H}(x(t)) = \text{Even}(x)(t) - \text{Odd}(x)(t)$;

(d) $\mathcal{H}(x(t)) = \mathcal{D}x(t)$, where \mathcal{D} denotes the derivative operator; and

(e) $\mathcal{H}(x(t)) = x^2(t)$.

let $y = \mathcal{H}x$

$$\therefore y(t) = e^{n(t)}$$

$$\therefore y(t) > 0$$

Taking natural logarithm on both sides we get

$$\ln y(t) = n(t)$$

$$\text{or, } n(t) = \ln y(t)$$

\therefore The system is invertible

$\boxed{\frac{e}{x}}$

$\boxed{x_1(t) = -A}$

$\boxed{x_2(t) = A}$

where A is a positive real constant.

$$\therefore \mathcal{H}x_1(t) = A^2$$

$$\therefore \mathcal{H}x_2(t) = (-A)^2 = A^2$$

both inputs have same outputs

\therefore not invertible

3.27 Determine whether each system \mathcal{H} given below is BIBO stable.

(a) $\mathcal{H}x(t) = \int_{t-1}^{t+1} x(\tau) d\tau$ [Hint: For any function f , $|\int_a^b f(x) dx| \leq \int_a^b |f(x)| dx$];

(b) $\mathcal{H}x(t) = \frac{1}{2}x^2(t) + x(t)$;

(c) $\mathcal{H}x(t) = \frac{1}{t}x(t)$;

(d) $\mathcal{H}x(t) = e^{-|t|}x(t)$; and

(e) $\mathcal{H}x(t) = \left(\frac{1}{t}\right)x(t)$.

(d) $\mathcal{H}x(t) = e^{-|t|}x(t)$

let $y = \mathcal{H}x$, having x bounded by $|x(t)| \leq A < \infty$

$$\begin{aligned} \text{we have, } |y(t)| &= |e^{-|t|}x(t)| = (e^{-|t|})|x(t)| \\ &= e^{-|t|}|x(t)| \end{aligned}$$

replacing $e^{-|t|}$ and $|x(t)|$: $|y(t)| \leq A = A < \infty$

$$\therefore |y(t)| < \infty$$

\therefore bounded input \Rightarrow bounded output

\therefore BIBO Stable

e considering: $n(t)=1$ we have: $y_{in}(t) = \frac{1}{t-1} [1]$
 $= \frac{1}{t-1}$

As $t \rightarrow 1$
 $|y(t)| \rightarrow \infty$] n is bounded but
 y is not bounded
 \therefore system not BIBO stable

1.38 Determine whether each system \mathcal{H} given below is time invariant.

(a) $\mathcal{H}x(t) = \mathcal{D}x(t)$; where \mathcal{D} denotes the derivative operator;

(b) $\mathcal{H}x(t) = \text{Even}(x)(t)$;

(c) $\mathcal{H}x(t) = \int_{-\infty}^{\infty} x(\tau - \alpha) d\tau$, where α is a constant;

(d) $\mathcal{H}x(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$, where h is an arbitrary (but fixed) function;

(e) $\mathcal{H}x(t) = x(-t)$; and

(f) $\mathcal{H}x(t) = \int_{-\infty}^{\infty} x(\tau) d\tau$.

b $y_{in}(t-t_0) = y_{in}'(t)$ where $n'(t) = n(t-t_0)$

We have $y_{in}(t) = \text{Even}\{n\}(t) = \frac{1}{2} [n(t) + n(-t)]$

$$y_{in}(t_0) = \frac{1}{2} [n(t) + n(-t)]$$

$$\therefore y_{in}(t-t_0) = \frac{1}{2} [n(t-t_0) + n(-[t-t_0])]$$

$$= \frac{1}{2} [n(t-t_0) + n(-t+t_0)]$$

$$y_{in}'(t) = \frac{1}{2} [n'(t) + n'(-t)] = \frac{1}{2} [n(t-t_0) + n(-t-t_0)]$$

Since $y_{in}(t-t_0) \neq y_{in}'(t)$ for all n and t_0

\therefore System is not time invariant

d $y_{in}(t-t_0) = y_{in}'(t) \dots n'(t) = n(t-t_0)$

$$y_{in}(t) = \int_{-\infty}^{\infty} n(\tau) h(t-\tau) d\tau$$

$$y_{in}(t-t_0) = \int_{-\infty}^{\infty} n(\tau) h(t-t_0-\tau) d\tau$$

From the definition of \mathcal{H} ,

$$\begin{aligned}\mathcal{H}n'(t) &= \int_{-\infty}^{\infty} n'(\tau) h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} n'(\tau - t_0) h(t - \tau) d\tau\end{aligned}$$

Letting $\lambda = \tau - t_0$ or, $\tau = \lambda + t_0$
or, $d\tau = d\lambda$

$$\mathcal{H}n'(t) = \int_{-\infty}^{\infty} n(\lambda) h(t - [\lambda + t_0]) d\lambda$$

$$= \int_{-\infty}^{\infty} n(\lambda) h(t - \lambda - t_0) d\lambda$$

$$= \int_{-\infty}^{\infty} n(\lambda) h(t - t_0 - \lambda) d\lambda$$

$$= \mathcal{H}n(t - t_0)$$

Since

$$\mathcal{H}n(t - t_0) = \mathcal{H}n'(t)$$

for all x and t_0 .

System is time invariant.

3.29 Determine whether each system \mathcal{H} given below is linear.

(a) $\mathcal{H}x(t) = \int_{t-1}^{t+1} x(\tau) d\tau$;

(b) $\mathcal{H}x(t) = e^{x(t)}$;

(c) $\mathcal{H}x(t) = \text{Even}(x)(t)$;

(d) $\mathcal{H}x(t) = x^2(t)$; and

(e) $\mathcal{H}x(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$, where h is an arbitrary (but fixed) function.

(b) $a_1 \mathcal{H}x_1(t) + a_2 \mathcal{H}x_2(t) = a_1 e^{x_1(t)} + a_2 e^{x_2(t)}$

$$\begin{aligned}\Rightarrow \mathcal{H}[a_1 x_1 + a_2 x_2](t) &= e^{a_1 x_1(t) + a_2 x_2(t)} \\ &= e^{a_1 x_1(t)} e^{a_2 x_2(t)}\end{aligned}$$

$$\mathcal{H}(a_1 x_1 + a_2 x_2) = a_1 \mathcal{H}x_1 + a_2 \mathcal{H}x_2$$

doesn't hold for all x_1, x_2, a_1 and a_2

\therefore System not linear.

$$\underline{\text{e}} \quad \boxed{a_1 \mathcal{H}x_1(t) + a_2 \mathcal{H}x_2(t)} = a_1 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau + a_2 \int_{-\infty}^{\infty} x_2(\tau) h(t-\tau) d\tau \quad \text{--- ①}$$

and,

$$\begin{aligned} \mathcal{H}[a_1 x_1 + a_2 x_2](t) &= \int_{-\infty}^{\infty} [a_1 x_1(\tau) + a_2 x_2(\tau)] h(t-\tau) d\tau \\ &= a_1 \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau + a_2 \int_{-\infty}^{\infty} x_2(\tau) h(t-\tau) d\tau \quad \text{--- ②} \end{aligned}$$

Since ① = ②, system is linear.

$$\mathcal{H}(a_1 x_1 + a_2 x_2) = a_1 \mathcal{H}x_1 + a_2 \mathcal{H}x_2$$

3.33 For each system \mathcal{H} and the functions $\{x_k\}$ given below, determine if each of the x_k is an eigenfunction of \mathcal{H} , and if it is, also state the corresponding eigenvalue.

(a) $\mathcal{H}x(t) = x^2(t)$, $x_1(t) = a$, $x_2(t) = e^{-at}$, and $x_3(t) = \cos t$, where a is a complex constant;

(b) $\mathcal{H}x(t) = \mathcal{D}x(t)$, $x_1(t) = e^{at}$, $x_2(t) = e^{at^2}$, and $x_3(t) = 42$, where \mathcal{D} denotes the derivative operator and a is a real constant;

(c) $\mathcal{H}x(t) = \int_{t-1}^t x(\tau) d\tau$, $x_1(t) = e^{at}$, $x_2(t) = t$, and $x_3(t) = \sin t$, where a is a nonzero complex constant; and

(d) $\mathcal{H}x(t) = |x(t)|$, $x_1(t) = a$, $x_2(t) = t$, $x_3(t) = t^2$, where a is a strictly positive real constant.

x_1 eigenfunction of eigenvalue a

$$\begin{aligned} \mathcal{H}x_1(t) &= \mathcal{D}x_1(t) \\ &= \mathcal{D}e^{at} \\ &= ae^{at} \Rightarrow ax_1(t) \\ &= ax_1(t) \end{aligned}$$

$$\begin{aligned} \mathcal{H}x_2(t) &= \mathcal{D}x_2(t) \\ &= \mathcal{D}e^{at^2} \\ &= \mathcal{D}e^{at^2} \\ &= 2ate^{at^2} \end{aligned}$$

x_2 not an eigenfunction

$$\mathcal{H}x_3(t) = \mathcal{D}x_3(t) = \mathcal{D} \cdot 42 = 0 = 0 \cdot x_3(t)$$

x_3 eigenfunction w/ eigenvalue 0

D3A

```
test.m x +
/Users/arfaz/Desktop/test.m
1 fprintf('%-8s %-8s %-8s\n', 'Celsius', 'Fahrenheit', 'Kelvin');
2 for celsius = -50 : 10 : 50
3     fahrenheit = 9 / 5 * celsius + 32;
4     kelvin = celsius + 273.15;
5     fprintf('%8.2f %8.2f %8.2f\n', celsius, fahrenheit, kelvin);
6 end
```

```
Command Window
>> unitStepFunction1
Not enough input arguments.

Error in unitStepFunction1 (line 3)
    if t >= 0

>> D3
Celsius Fahrenheit Kelvin
-50.00 -58.00 223.15
-40.00 -40.00 233.15
-30.00 -22.00 243.15
-20.00 -4.00 253.15
-10.00 14.00 263.15
0.00 32.00 273.15
10.00 50.00 283.15
20.00 68.00 293.15
30.00 86.00 303.15
40.00 104.00 313.15
50.00 122.00 323.15
>>
```

D4A

```
unitStepFunction1.m x +
/Users/arfaz/Library/CloudStorage/OneDrive-UniversityofVictoria/0 UVIC/2 ENGR Y3/4 ECE 260 A01 T03/1 Assignments/0 Solutions/unitStepFunction1.m
1 function x = unitStepFunction1(t)
2     % unitstep - Compute the unit-step function.
3     if t >= 0
4         x = 1;
5     else
6         x = 0;
7     end
8 end
9
10
```

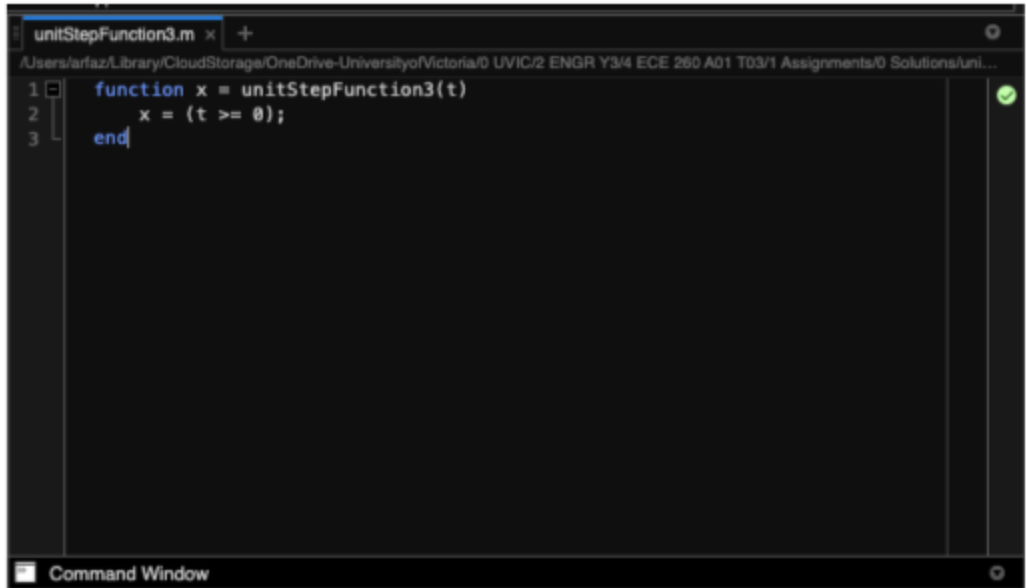
Command Window

D4B

```
unitStepFunction2.m x +
/Users/arfaz/Library/CloudStorage/OneDrive-UniversityofVictoria/0 UVIC/2 ENGR Y3/4 ECE 260 A01 T03/1 Assignments/0 Solutions/unit...
1 function x = unitStepFunction2(t)
2     x = zeros(size(t));
3     m = length(x);
4     for i = 1 : m
5         if t(i) >= 0
6             x(i) = 1;
7         end
8     end
9 end
```

Command Window

D4C



A screenshot of a MATLAB editor window. The title bar shows the file name 'unitStepFunction3.m' and a plus sign for additional tabs. The path bar indicates the file is located at '/Users/arfaz/Library/CloudStorage/OneDrive-UniversityofVictoria/0 UVIC/2 ENGR Y3/4 ECE 260 A01 T03/1 Assignments/0 Solutions/uni...'. The main editor area contains the following MATLAB code:

```
1 function x = unitStepFunction3(t)
2     x = (t >= 0);
3 end
```

Line numbers 1, 2, and 3 are visible on the left margin. A green checkmark icon is present on the right side of the editor, indicating successful execution. At the bottom of the window, there is a 'Command Window' tab.