## Computer Vision II - Homework Assignment 4

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This homework is due on July 12, 2017 at 9:00. Please note that a late handin is not possible for this assignment!

## Problem 1 - Horn-Schunck optical flow - 32 points

In this problem, you will implement a global optical flow algorithm. The test data for this assignment is from the Middlebury optical flow database, and you can evaluate your implementations with the corresponding ground truth data and the provided functions read\_flow\_file and flow\_to\_color.

In a first step, you implement several basic functions that will be needed for the optical flow estimation. For a quantitative evaluation of optical flow, we use the average endpoint (EP) error metric. The endpoint error for a pixel is defined as follows:

EP error = 
$$\sqrt{(u - u_{gt})^2 + (v - v_{gt})^2}$$
, (1)

where u, v are the horizontal and vertical components of the flow vector at a certain pixel and  $u_{gt}$ ,  $v_{gt}$  represents the corresponding ground truth.

• Write a function evaluate\_flow(uv,uv\_gt) that computes the average endpoint error (AEPE) by averaging the EP error of all pixels.

1 point

• The ground truth data uses the value 2e9 for invalid pixels. Make sure to not include these pixels in your AEPE calculation.

1 point

To evaluate the brightness constancy given an initial flow estimate  $uv_0$ , it is necessary to warp the second image  $I_2$ . Here, a so-called backward warping is performed, i.e. for each pixel (i,j) the corresponding brightness value is obtained at the position  $I_2(i+u_0,j+v_0)$ .

• Write a function warp\_image(im2,uv0) that returns the second image warped by the initial estimate  $uv_0$ . Use bilinear interpolation.

2 points

• Load images frame10.png, frame11.png and convert the data to grayscale. Load the ground truth data flow10.flo using the provided function read\_flow\_file. Apply the ground truth flow to obtain the warped second image  $I_2^w$ . Display  $I_1$ ,  $I_2^w$  and the difference between both images. What do you observe?

To obtain an efficient optimization scheme for the optical flow estimation, it is necessary to linearize the brightness constancy assumption around an initial flow estimate  $uv_0$  such that

$$I_2(i+u(i,j),j+v(i,j)) - I_1(i,j) \approx I_x \cdot (u(i,j)-u_0(i,j)) + I_y \cdot (v(i,j)-v_0(i,j)) + I_t.$$
 (2)

Here,  $I_x$  and  $I_y$  denote the spatial derivatives of the warped second image  $I_2^w$  and  $I_t = I_2^w - I_1$ .

• Calculate  $I_x$ ,  $I_y$  and  $I_t$  in the function compute\_grad\_images(im1,im2,uv0). Use central differences to approximate the derivatives  $I_x$  and  $I_y$  and apply an appropriate boundary handling.

2 points

Now, you implement a simplified form of dense Horn-Schunck optical flow without the coarse-to-fine estimation.

• Implement the logarithm of an optical flow posterior assuming a pairwise MRF prior as well as a Gaussian distribution with parameter  $\sigma$  for likelihood and prior. In particular, write the function

```
logposterior_HS(uv, uv0, Ix, Iy, It, lambda, sigma)
```

to compute the log-posterior itself and

to calculate its gradient. The parameter  $\lambda$  scales the smoothness or prior term and allows for a trade-off between the two components of the posterior.

6 points

• Implement a flow estimation algorithm

performing an iterative minimization of the negative log posterior. Use Julia's Optim package to perform the optimization with method = LBFGS() and iterations = 200.

3 points

• Use the grayscale images frame10.png, frame11.png and estimate Horn-Schunck optical flow with parameter  $\sigma = 1$ . Write a function

```
find_lambda(im1,im2,uv0,uv_gt,sigma)
```

to determine an appropriate trade-off parameter  $\lambda$ , e.g. with grid search. Here, an evaluation of the AEPE w.r.t. the ground truth flow10.flo might be beneficial.

3 points

• Display your flow result using the provided function flow\_to\_color and calculate its AEPE.

1 point

• Estimate Horn-Schunck flow for a significantly smaller trade-off parameter  $\lambda_2$  and for a significantly larger parameter  $\lambda_3$ . Display the results. What do you observe?

2 points

• Compare the AEPE of your results for  $\lambda_1, \ldots, \lambda_3$ . Do the visual results match the quantitative evaluation?

1 points

• Perform 5 iterations of the optical flow estimation using the previously obtained flow field  $uv_{k-1}, k = 1, ..., 5$  as the initial flow estimate for the next iteration k. Find an appropriate parameter  $\lambda$ , evaluate the AEPE and visualize the results for each iteration. What do you observe?

6 points