

# Implementation of a robot behaviour learning simulator

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## Last Week 23/04

In our last meeting, we talked about the working of the simulator and the way it should log the data format from the simulation when it is running. I talked about the tools I might use to make the GUI and came to know the format for the log file.

# Today's Agenda

I was not able to work upon the data-log part of the simulation, but worked on

- Deciding the tool for Robot's GUI
- Making the GUI with a small turtlesim robot simulation
- Making the model for Gazebo's board, with boxes in Gazebo simulator

# Future Works

- I did not use JavaFX for making the GUI, after I read about ROS's RQT development kit.
- The way I made the GUI for a turtlesim simulation, I will have to make a plugin for logging the data in our preferred format.
- To make a box in 3D modelling, that entirely covers the box in our gazebo simulation.
- Placing the box in Gazebo, and trying to SLAM (*Simultaneous Localization and Mapping*) the robot around various boxes by giving a final goal point.

# Demonstrations

Let's move forward to see the demonstration.

## A humble suggestion

Due to working at home conditions right now, I find it a bit hard to focus. I chose not to go to Laboratory, due to the risks. I would appreciate if we could have more than one meeting in a week, with either one of you (if there are schedule clashes). It will help me focus more on the work than thinking 'friday is too far' and working loosely.



# Last Slide

Thank you for your time. I hope you have a great day.