

# Implementation of a Robot Behaviour Learning Simulator

Kushagra Singh Bisen

Ecole des Mines de Saint Etienne

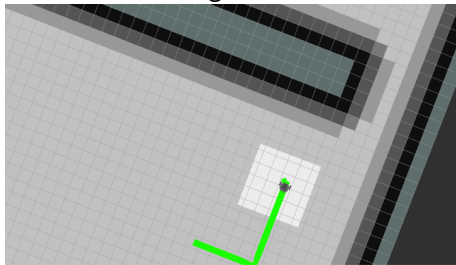
*kushagrasingh.bisen@etu.emse.fr*

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# Regarding the log file

- Manhattan Distance Implementation is done.
- Obstacle Grid around the robot is done.
- Robot is able to move producing clean odometry values.

You can see the grid around the robot.



# Regarding the Unified Log File

- Different data from topics — > Different Formats, I tried to get them into one file, but difference in frequency of publication and updation gave me an error.
- I will try the method in following 2 days, and I think I will get an output.

Thank you for your time.