TECHNICAL UNIVERSITY BERLIN

GEODESY AND GEOINFORMATION SCIENCE



ADJUSTMENT CALCULATION HOMEWORK V

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TASK I

Functional Model:

$$s_{61} = \sqrt{(x_1 - x_6)^2 + (y_1 - y_6)^2}$$

$$s_{91} = \sqrt{(x_1 - x_9)^2 + (y_1 - y_9)^2}$$

$$s_{96} = \sqrt{(x_6 - x_9)^2 + (y_6 - y_9)^2}$$

$$s_{151} = \sqrt{(x_1 - x_{15})^2 + (y_1 - y_{15})^2}$$

$$s_{159} = \sqrt{(x_9 - x_{15})^2 + (y_9 - y_{15})^2}$$

$$r_{16} = \tan^{-1} \left(\frac{y_6 - y_1}{x_6 - x_1}\right) - \omega_1$$

$$r_{115} = \tan^{-1} \left(\frac{y_{15} - y_1}{x_{15} - x_1}\right) - \omega_1$$

$$r_{61} = \tan^{-1} \left(\frac{y_9 - y_6}{x_9 - x_6}\right) - \omega_6$$

$$r_{915} = \tan^{-1} \left(\frac{y_9 - y_6}{x_1 - x_9}\right) - \omega_9$$

$$r_{91} = \tan^{-1} \left(\frac{y_1 - y_9}{x_1 - x_9}\right) - \omega_9$$

$$r_{96} = \tan^{-1} \left(\frac{y_6 - y_9}{x_6 - x_9}\right) - \omega_9$$

$$r_{151} = \tan^{-1} \left(\frac{y_1 - y_{15}}{x_1 - x_{15}}\right) - \omega_{15}$$

$$r_{159} = \tan^{-1} \left(\frac{y_9 - y_{15}}{x_9 - x_{15}}\right) - \omega_{15}$$

Observation Equation

$$s_{61} + v_1 = \sqrt{(x_1 - x_6)^2 + (y_1 - y_6)^2}$$

$$s_{91} + v_2 = \sqrt{(x_1 - x_9)^2 + (y_1 - y_9)^2}$$

$$s_{96} + v_3 = \sqrt{(x_6 - x_9)^2 + (y_6 - y_9)^2}$$

$$s_{151} + v_4 = \sqrt{(x_1 - x_{15})^2 + (y_1 - y_{15})^2}$$

$$s_{159} + v_5 = \sqrt{(x_9 - x_{15})^2 + (y_9 - y_{15})^2}$$

$$r_{16} + v_6 = \tan^{-1}\left(\frac{y_6 - y_1}{x_6 - x_1}\right) - \omega_1$$

$$r_{115} + v_7 = \tan^{-1}\left(\frac{y_{15} - y_1}{x_{15} - x_1}\right) - \omega_1$$

$$r_{61} + v_8 = \tan^{-1} \left(\frac{y_1 - y_6}{x_1 - x_6} \right) - \omega_6$$

$$r_{69} + v_9 = \tan^{-1} \left(\frac{y_9 - y_6}{x_9 - x_6} \right) - \omega_6$$

$$r_{915} + v_{10} = \tan^{-1} \left(\frac{y_{15} - y_9}{x_{15} - x_9} \right) - \omega_9$$

$$r_{91} + v_{11} = \tan^{-1} \left(\frac{y_1 - y_9}{x_1 - x_9} \right) - \omega_9$$

$$r_{96} + v_{12} = \tan^{-1} \left(\frac{y_6 - y_9}{x_6 - x_9} \right) - \omega_9$$

$$r_{151} + v_{13} = \tan^{-1} \left(\frac{y_1 - y_{15}}{x_1 - x_{15}} \right) - \omega_{15}$$

$$r_{159} + v_{14} = \tan^{-1} \left(\frac{y_9 - y_{15}}{x_9 - x_{15}} \right) - \omega_{15}$$

Stochastic Model:

$$\sum_{ll} = \begin{bmatrix} \sigma_s^2 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \sigma_r^2 \end{bmatrix}$$

Result:

Vector of adjusted Unknown:

Adjusted_Unknown =

1.0e+06 *

4.965804165317863

5.314698152754688

4.962997537828491

5.320448851544192

-0.000001570785137

-0.00000000005203

0.000000314142015

-0.000000471248385

Standard Deviation of Adjusted Unknown:

Std_Dev_Adj_unkwn =

0.030228896653077

0.022371333095265

0.027133358447850

0.039873020648717

0.000006904982993

0.000005267637138

0.000003978874041

0.000006005847364



Vector of Residuals:

Residuals =

0.006158735206438 0.000243409139557 -0.001472910277698 -0.030444739934955 0.011014231215076 -0.000001396280299 0.000001396280299 0.000002430187053 -0.000002430187053 -0.000009597273603 0.000006263348281 0.000003333925322 -0.000003059701964 0.000003059701964

Standard Deviation of Residuals:

Std_Dev_Residuals =

0.027593254407889 0.029495880503038 0.037097391685102 0.021241972171481 0.021897861881229 0.000003082325872 0.000003082325872 0.000002491742222 0.000002491742222 0.000004075193097 0.000004495930296 0.000004257386720 0.000003178117753 0.000003178117753

Vector of Adjusted Observation:

Adjusted_Observation =

1.0e+04 *

0.430785715873521 1.075985224340914 0.680633052708972 0.639903855526007 0.875176801423121 0.000232615161416 0.000359562330335 0.000389696433379 0.000127535381108 0.000326571837763 0.000390253663993 0.000410279924660 0.000563767920494 0.00090951612406



Standard deviation of Adjusted Observations:

Std_Dev_Adj_Obs =

- 0.024795741187135
- 0.022499100052855

0

- 0.030413731900309
- 0.029944951408685
- 0.000004945305606
- 0.000004945305606
- 0.000005267637138
- 0.000005267637138
- 0.000004165282888
- 0.000003707207992
- 0.000003978874041
- 0.000004884296046
- 0.000004884296046