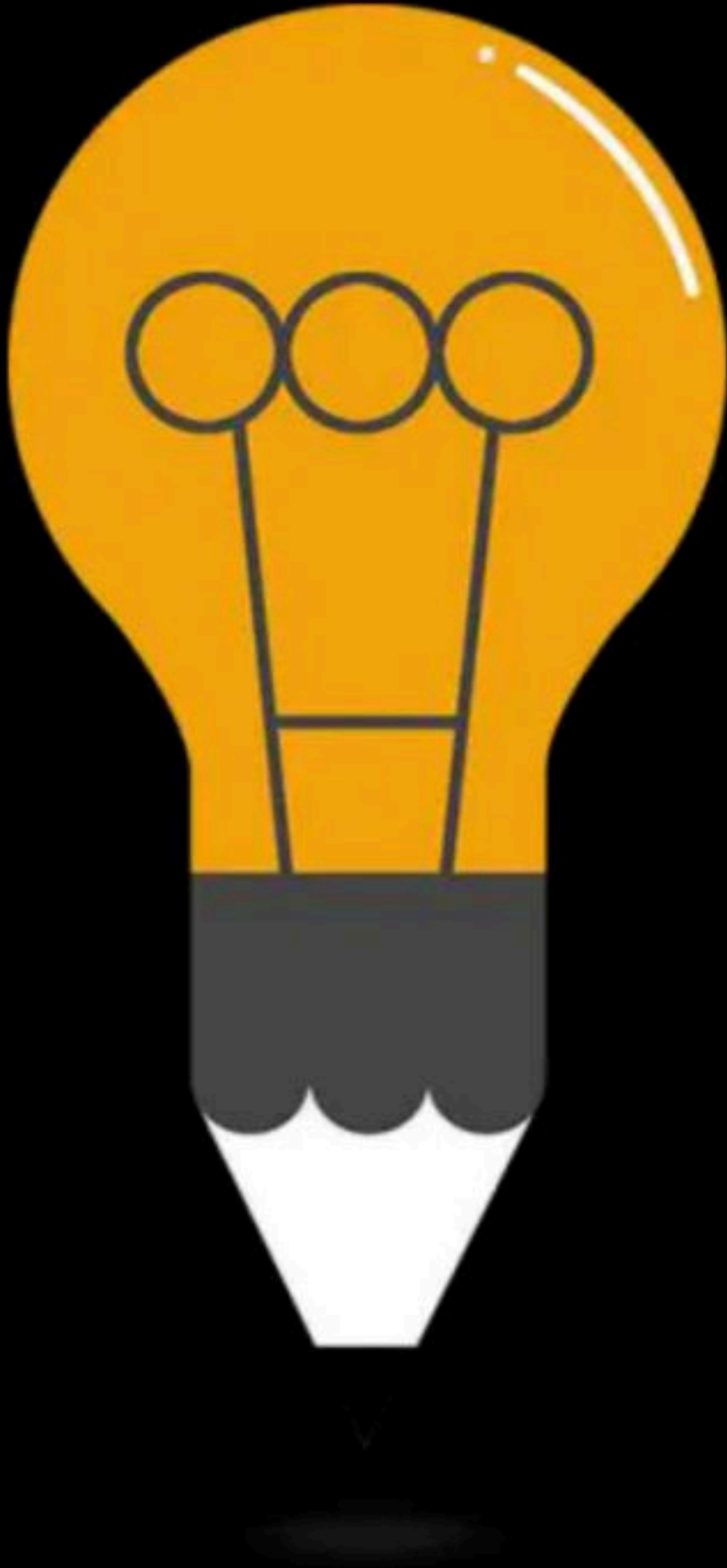




# Multithreading, System Call & Fork Call

Comprehensive Course on Operating System for GATE - 2024/25



# Operating System

## Process Synchronization

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# Solution 1

*Boolean lock=false;*

```
while(true)  
{  
    while(lock);  
    lock=true;  
    CS  
    lock=false;  
    RS;  
}
```

```
while(true)  
{  
    while(lock);  
    lock=true;  
    CS  
    lock=false;  
    RS;  
}
```

# Solution 2

```
int turn=0;
```

```
while(true)  
{  
    while(turn!=0);  
    CS  
    turn=1;  
    RS;  
}
```

```
while(true)  
{  
    while(turn!=1);  
    CS  
    turn=0;  
    RS;  
}
```



# Solution 3: Peterson's Solution

*Boolean Flag[2];*  
*int turn;*

```
while(true) {  
    Flag[0]=true;  
    turn=1;  
    while(Flag[1] && turn==1);  
        CS  
    Flag[0]=False;  
        RS;  
}
```

```
while(true){  
    Flag[1]=true;  
    turn=0;  
    while(Flag[0] && turn==0);  
        CS  
    Flag[1]=False;  
        RS;  
}
```

# Synchronization Hardware

↳ inst<sup>ns</sup> provided in cpu arch.,  
so that inst<sup>ns</sup> can be used for synch..

- ✓ 1. TestAndSet()
- ✓ 2. Swap()

Flag is boolean

# TestAndSet()

Returns the current value flag and sets it to true.

TestAndSet (Flag)

if Flag == false

---

↳ flag = true

Return false

if flag == true

---

↳ flag = true

Return true



# TestAndSet()

Shared

~~Boolean Lock=False;~~ True

```
boolean TestAndSet(Boolean *trg){
    boolean rv = *trg;
    *trg = True;
    Return rv;
}
```

M.E. ✓

Progress ✓

Bounded waiting ✗

P1, P2

```
while(true)
{
    while(TestAndSet(&Lock));
        CS
    Lock=False;
}
```

Confusion → clear ✗

lock  $\Rightarrow$  false  
True

c.s. is free  
c.s. is occupied

# Swap()

Boolean Key;

Boolean Lock=False;

//Local for each process  
//Shared

```
void Swap(Boolean *a, Boolean *b)
{
    boolean temp = *a;
    *a=*b;
    *b=temp;
}
```

single inst<sup>n</sup>

M.E. ✓

Progress ✓

D.W. ✗

P1  
key = ~~T~~F

while(true){

Key = True;

while (key==True)

{ Swap(&Lock, &Key); }

CS

Lock=False;

RS

}

P2  
key = ~~T~~T

lock = ~~False~~  
~~T~~T

# Synchronization Tools

- ✓✓ 1. Semaphore
- ✗ 2. Monitor

↳ provided by OS,  
↳ to be used to provide synch.



# Semaphore

unsigned

◎ Integer value which can be accessed using following functions only

- wait() / P() / Degradate() → decreases semaphore value by 1
  - signal() / V() / Upgrade() → increases
- atomic

# wait() & signal()

*S is semaphore here*



```
wait(S)
{
    while(S <= 0);
    S--;
}
```

```
signal(S)
{
    S++;
}
```



# Types of Semaphore

## Binary Semaphore

value can be either 0 or 1

0, 1

## Counting Semaphore

value can be any +ve integer

0, 1, 2, 3, 4, 5, 6, 7, ... ..

# Types of Semaphore

## Binary Semaphore

It is used to implement the solution of critical section problems with multiple processes

↓  
mutual Exclusion

## Counting Semaphore

It is used to control access to a resource that has multiple instances

# Critical Section Solution

Binary semaphore

$S = 1$  ~~0~~ ~~1~~ 0

$P_1$

$P_2$

```
while(True)
{
    wait(S)
    C.S.
    signal(s)
}
```

```
while(True)
{
    wait(s)
    C.S.
    signal(s)
}
```



# Characteristics of Semaphores

- ◎ Used to provide mutual exclusion ✓
- ◎ Used to control access to resources ✓
- ◎ Solution using semaphore can lead to have deadlock
- ◎ Solution using semaphore can lead to have starvation
- ◎ Solution using semaphore can be busy waiting solutions
- ◎ Semaphores may lead to a priority inversion
- ◎ Semaphores are machine-independent ✓

# Happy Learning.!



wed 8:30 PM

sat

2-3 hours

