

11:00
1.5 hours

2:00 PM
2 hours

Tom.
Same time
= classes

Sat.
?

Operating System Revision: Part 1

Special class

Operating System: Basics & Process Management

By: Vishvadeep Gothi

OS

- Software abstracting hardware
- Interface between user and hardware
- Set of utilities to simplify application development/execution
- Control program
- Acts like a government

Chapter Number	Chapter Name
1	Introduction
2	Process Management
3	CPU Scheduling
4	Process Synchronization
5	Deadlock
6	Memory Management & Virtual Memory
7	File System
8	Disk Scheduling

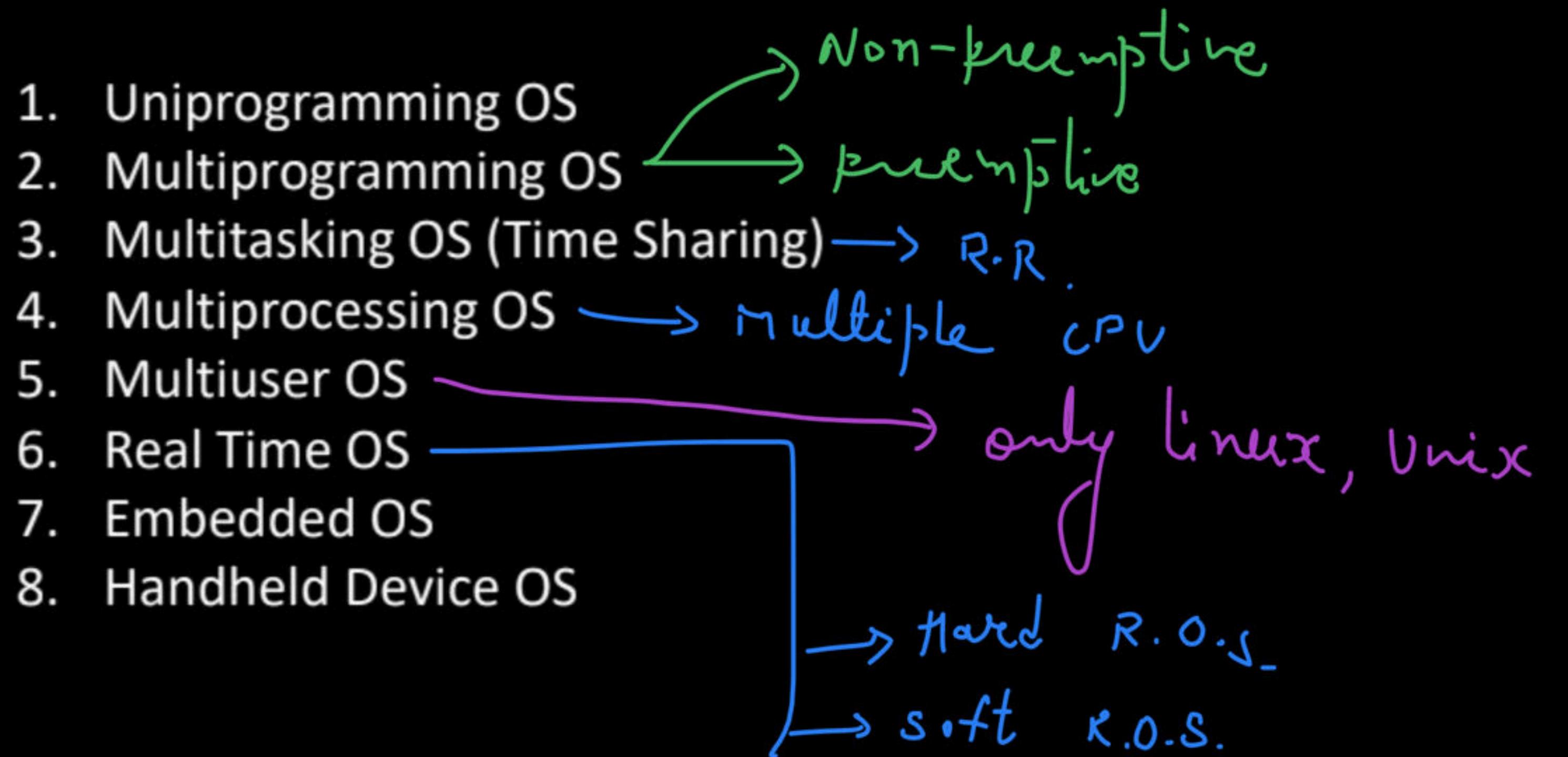
Services of OS

- User Interface
- Program Execution
- I/O Operation
- File-System Manipulation
- Communication (Inter-process Communication)
- Error Detection
- Resource Allocation
- Accounting
- Protection & Security

Goals of OS

- Convenience (User-friendly)
- Efficiency
- Portability
- Reliability
- Scalability
- Robustness

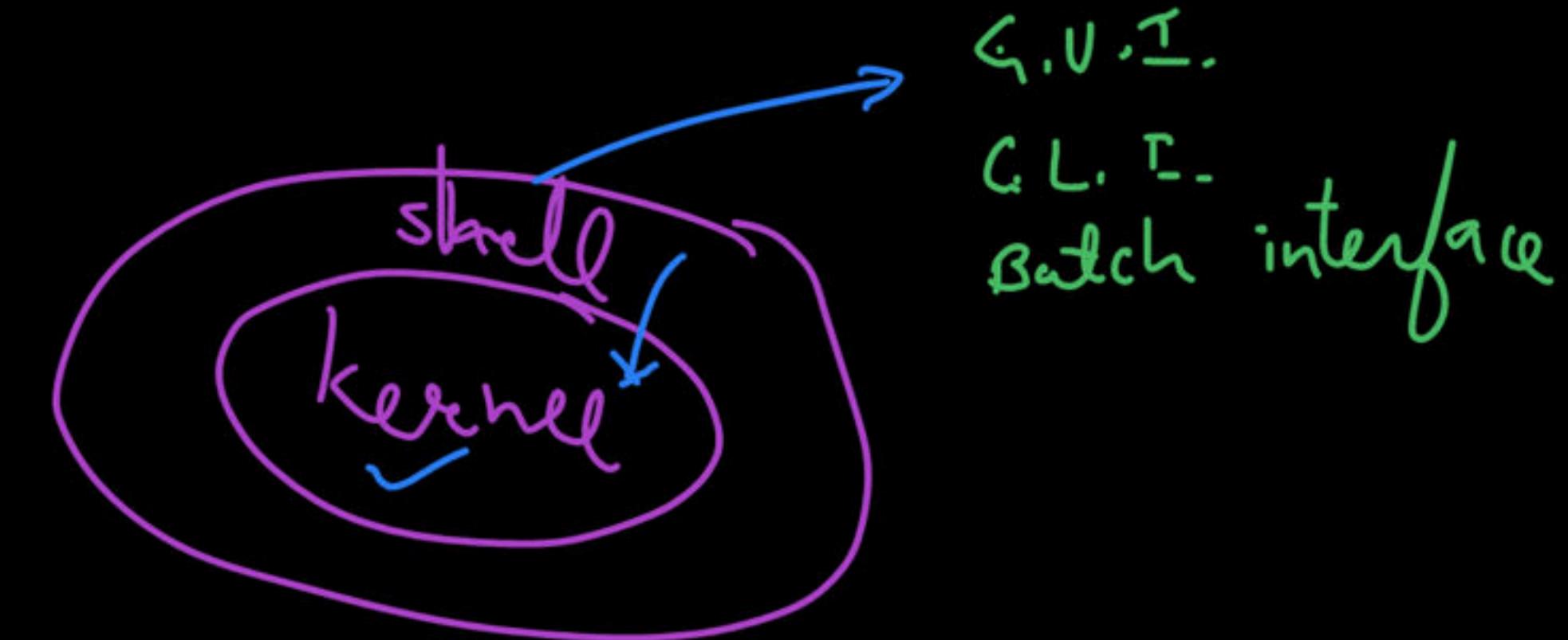
Types of OS



System Call

A system call is a way for programs to interact with the operating system

Parts of OS



Dual Mode of Operation

2 modes:

User Mode (mode bit = 1)

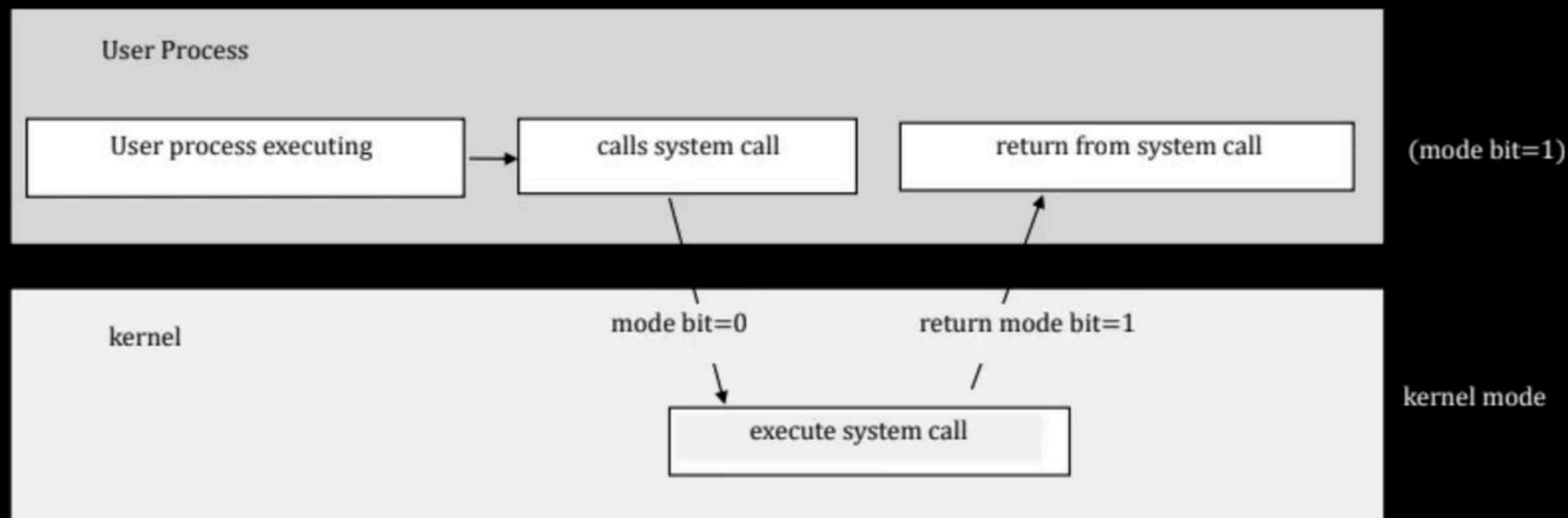
Kernel/System/Supervisor/Privileged Mode (mode bit = 0)

Dual Mode of Operation

2 modes:

User Mode (mode bit = 1)

Kernel/System/Supervisor/Privileged Mode (mode bit = 0)



Process

Process:

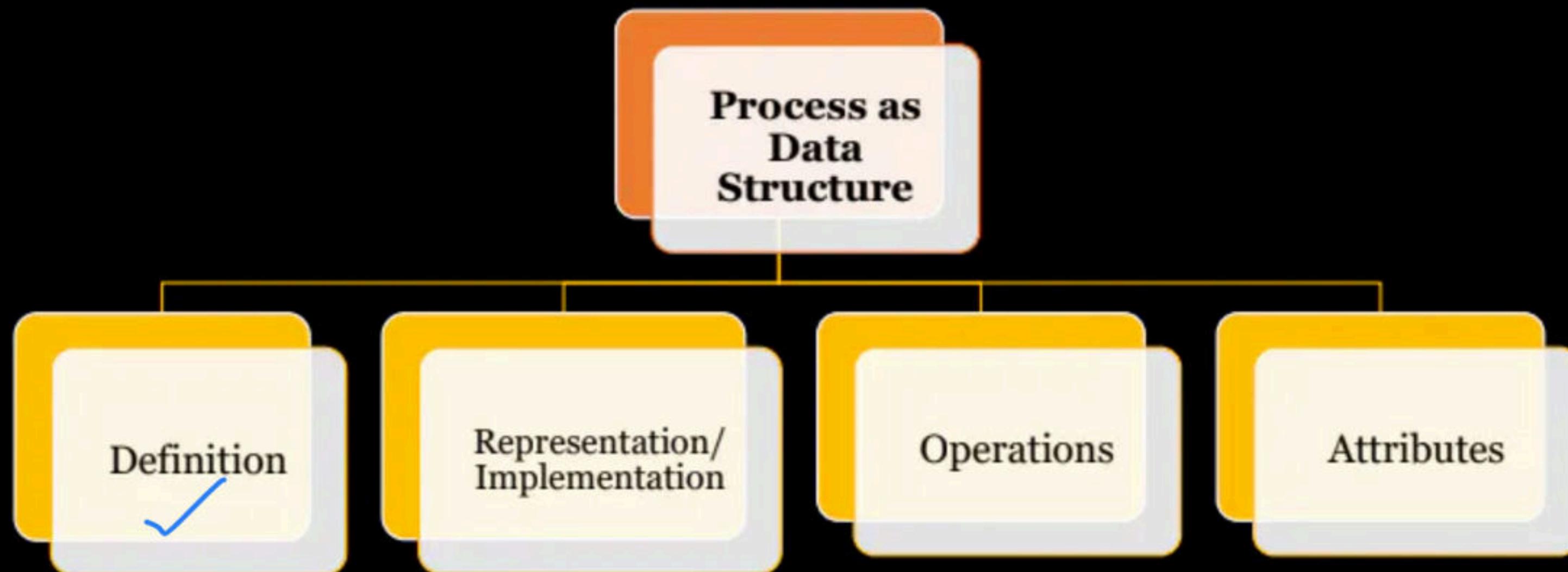
- Program under execution
- An instance of a program
- Schedulable/Dispatchable unit (CPU)
- Unit of execution (CPU)
- Locus of control (OS)

↳ Prog. + Run-time activities

◎ **Process:**

- Program under execution
- An instance of a program
- Schedulable/Dispatchable unit (CPU)
- Unit of execution (CPU)
- Locus of control (OS)

Process as Data Structure



Representation of a Process



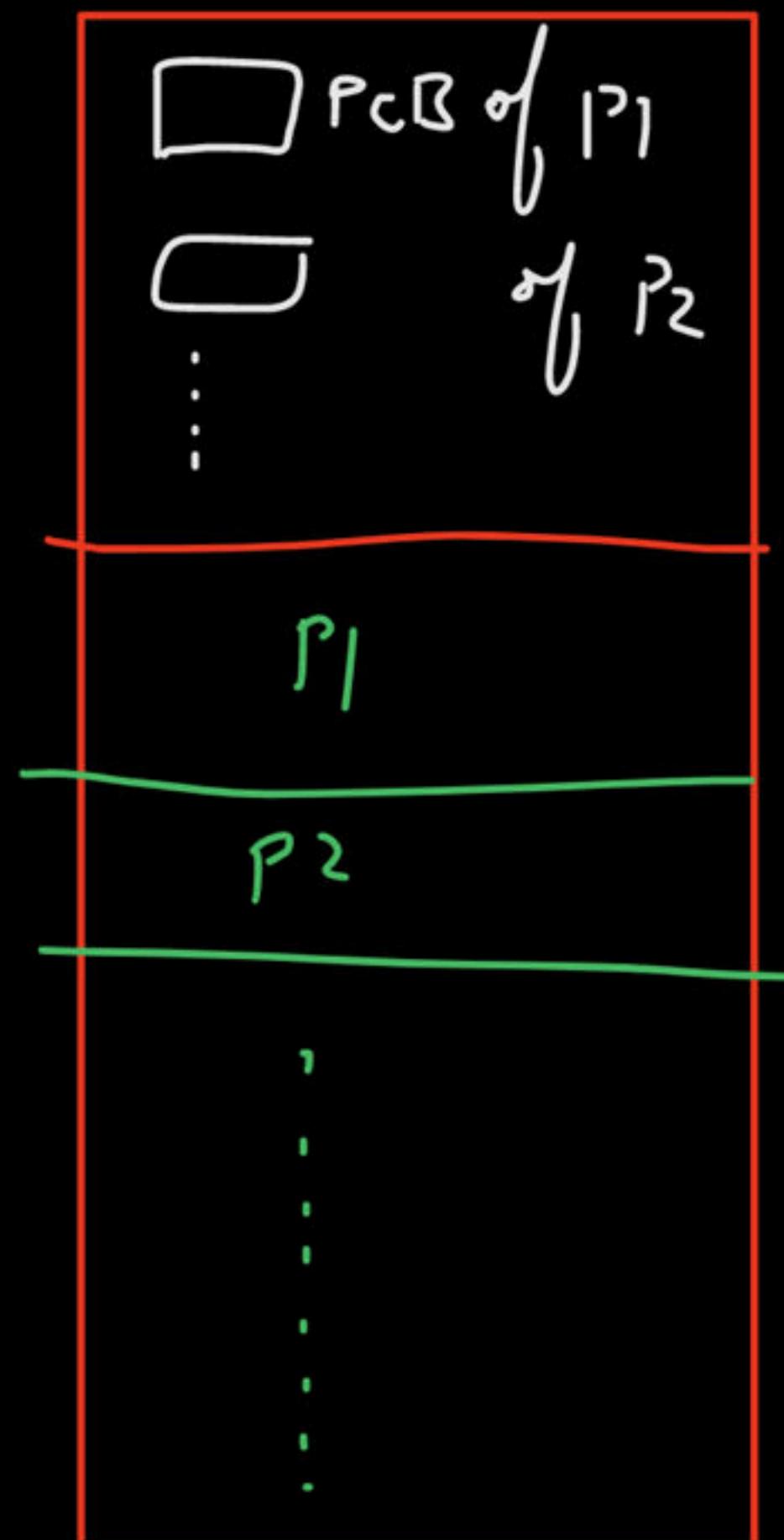
Operations on a Process

- Create (Resource Allocation)
- Schedule, Run
- Wait/Block
- Suspend, Resume
- Terminate (Resource Deallocation)

Attributes of a Process

- ◎ PID = P1
- ◎ PC → 66135A4
- ◎ GPR
- ◎ List of Devices
- ◎ Type
- ◎ Size
- ◎ Memory Limits
- ◎ Priority
- ◎ State
- ◎ List of Files

content



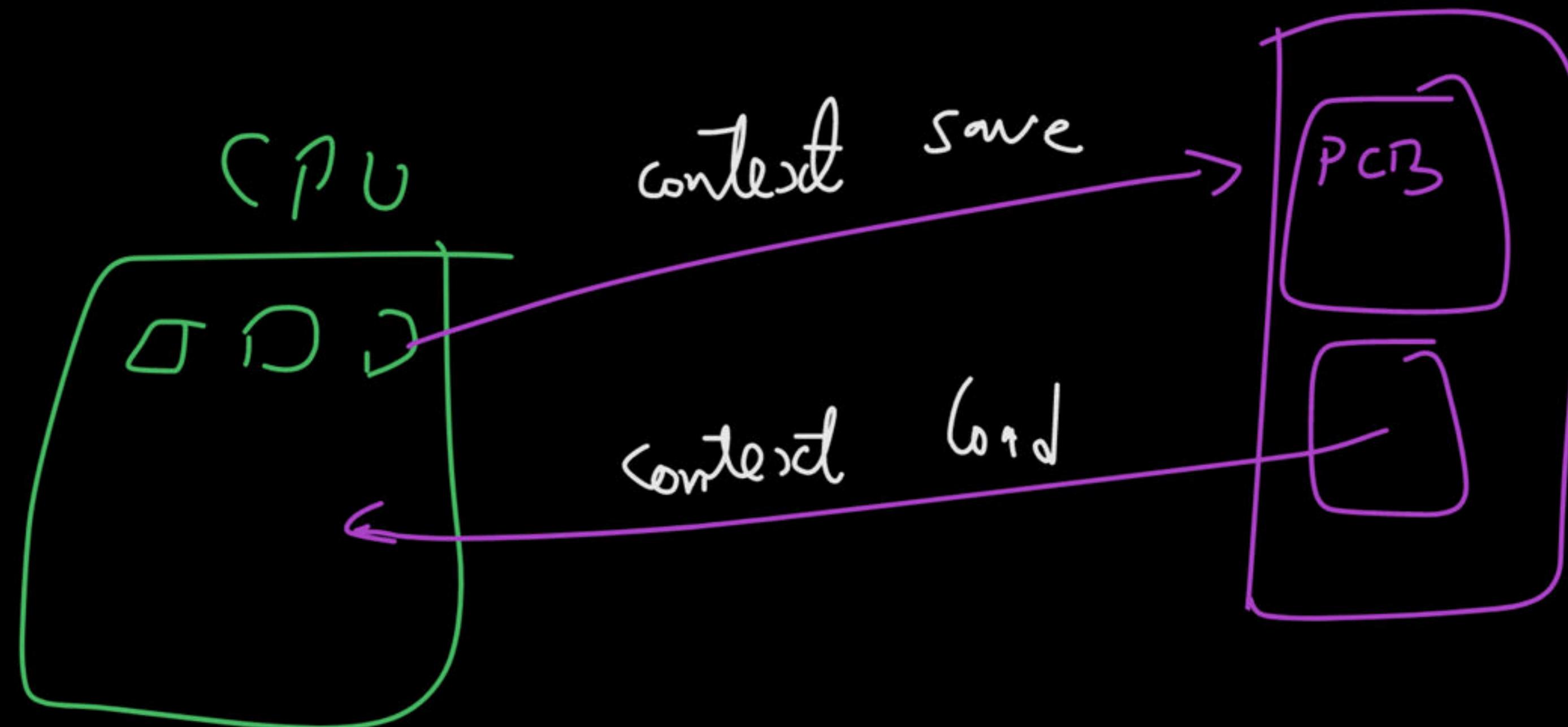
PCB (Process Control Block)

- ◎ Also known as processor descriptor

Context

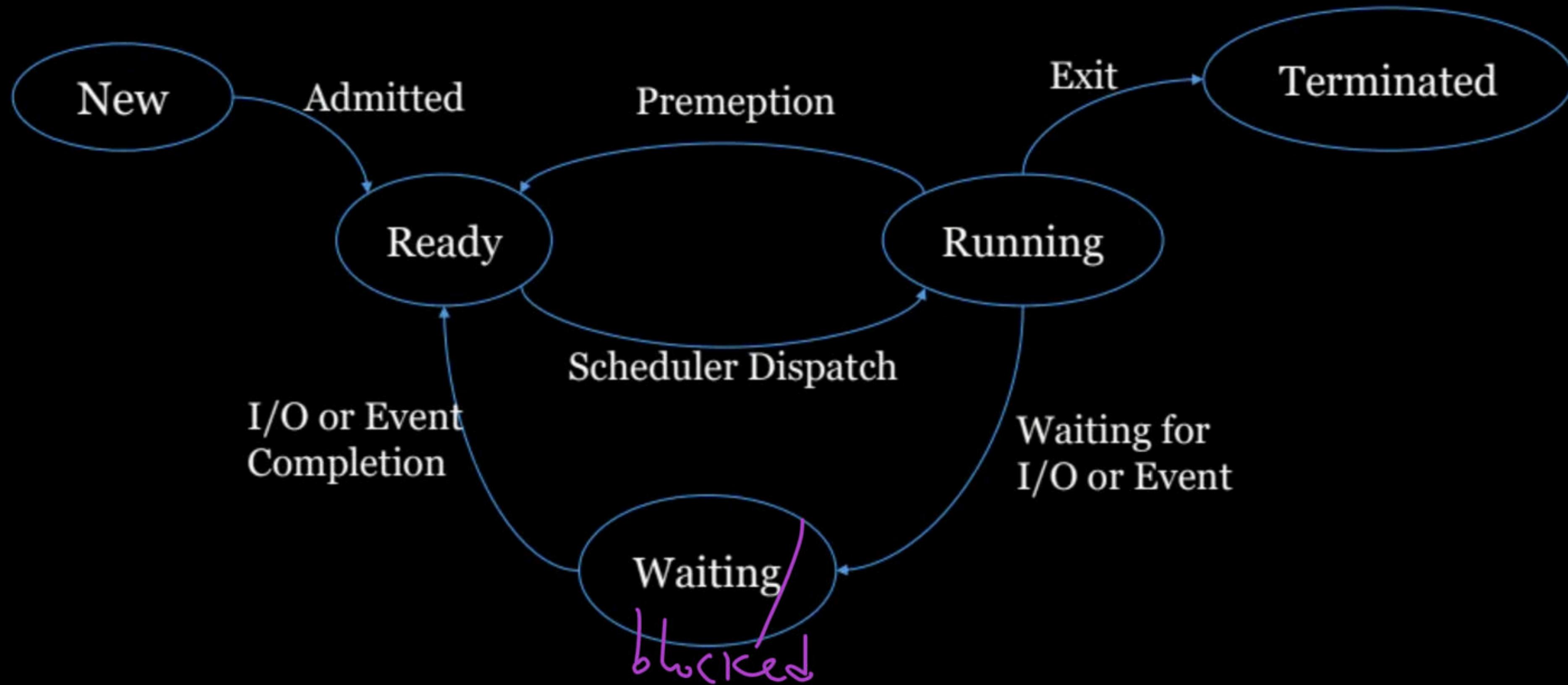
The content of PCB of a process are collectively known as 'Context' of that process

Context Switch



Process States

Process States



Process States

New:

All installed processes are known to be in new state

Ready:

All processes which are waiting to run on CPU are known to be in ready state

Process States

Running:

A process which is running on CPU has its state as running

Terminated:

A completed process has its state as terminated

Blocked:

All processes which are waiting for any IO or event

Process States Transitions

New To Ready: When process is admitted by OS

Ready to Running: When a process is dispatched to CPU

Running to Terminated: When a process is completed

Running to Blocked: When a process goes for IO or event

Running to Ready: When a process is preempted

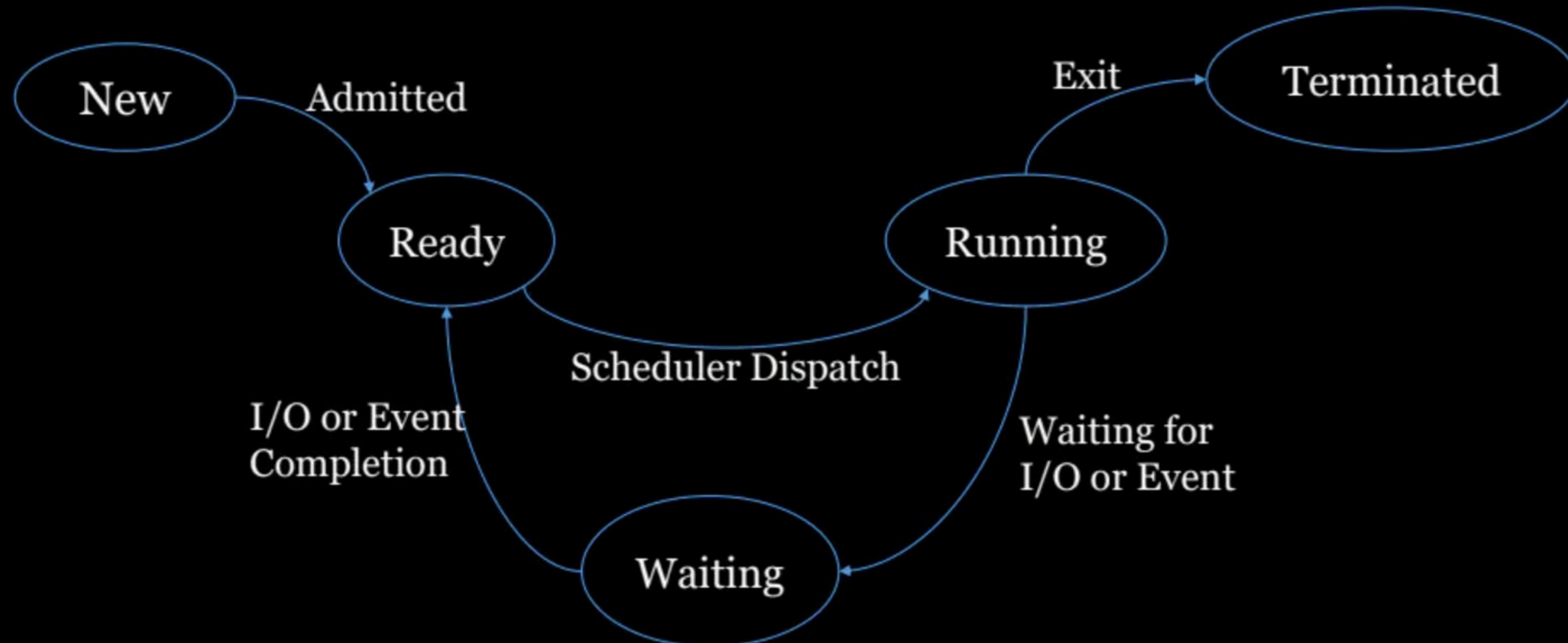
Blocked to Ready: When a process completes IO or event

Process States Transitions

2 Transitions are voluntary:

- o Running to Terminated
- o Running to Blocked

Process States: Non-preemptive



CPU vs IO Bound Process

→ CPU extensive

CPU Bound: If the process is intensive in terms of CPU operations

→ I/O extensive

Scheduling Queues

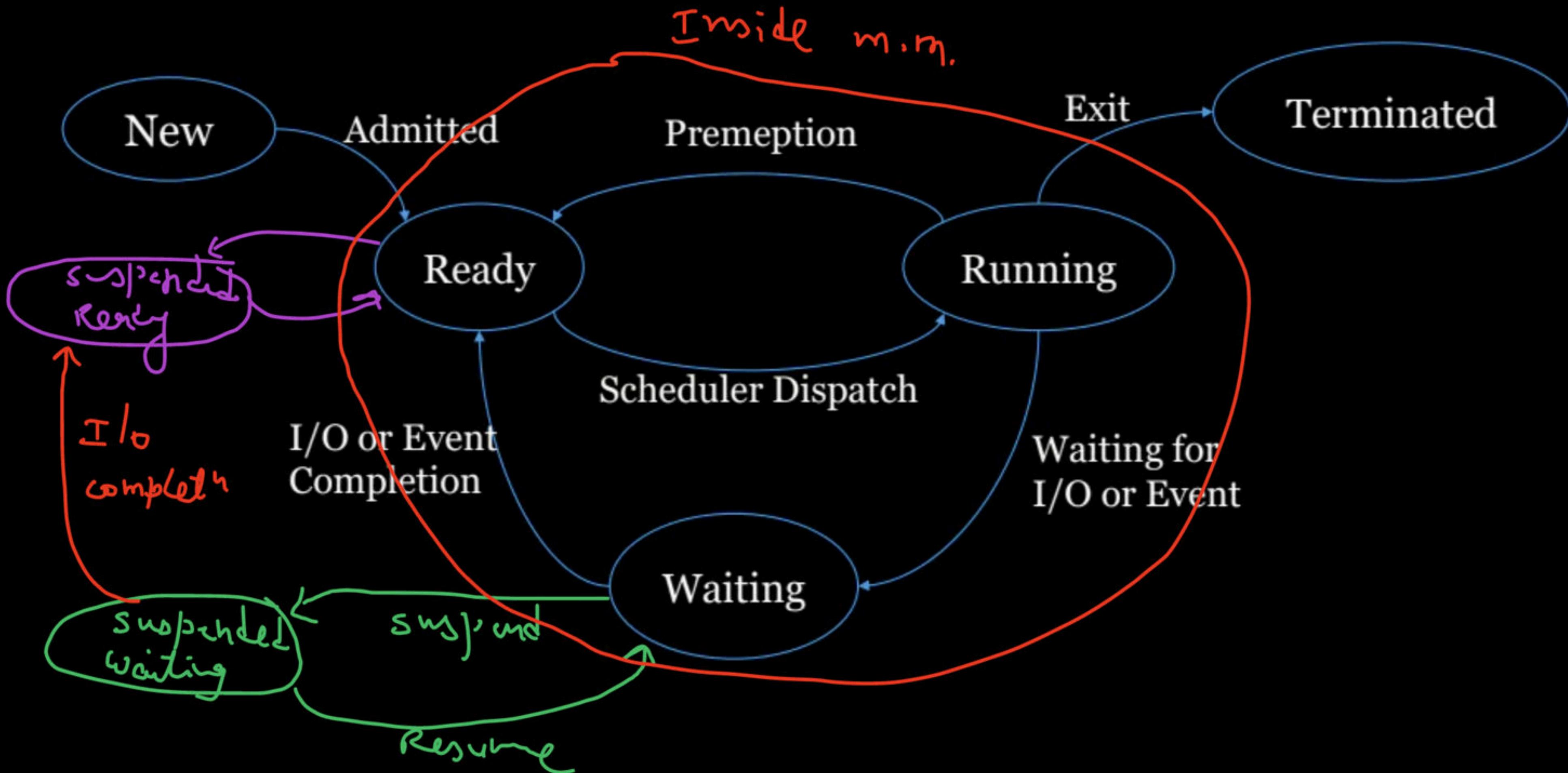
- ◎ Job Queue → new state → single
- ◎ Ready Queue → Ready state → single
- ◎ Device Queue
 - ↳ blocked state → ^{one} for each device

Scheduling Queues

Types of Schedulers

1. Long-Term Scheduler (Job)
2. Short-Term Scheduler (CPU)
3. Mid-Term Scheduler (Medium-term) → swapping

Updated Process States



CPU Scheduling

Function:

Make a selection of a process to run next on CPU.
among all ready processes.

CPU Scheduling

Function:

Make a selection

Goal

- Minimize Wait time and Turn-around time
- Maximize CPU utilization (Throughput)
- Fairness

↳ no starvation

(FCFS, RR, HRRN)

- minimize avg. response time }
- maximize interactivity } → RR

SJF, SJRTF

Scheduling Times

1. Arrival Time (AT)
2. Burst Time (BT)
3. Completion Time(CT)
4. Turnaround Time (TAT) = CT - AT
5. Waiting Time (WT) = TAT - BT

Scheduling Times

- 6. Response Time (RT):
- 7. Deadline (D):
- 8. Scheduling Length (L):
- 9. Throughput:

CPU Scheduling: Types

CPU Scheduling:

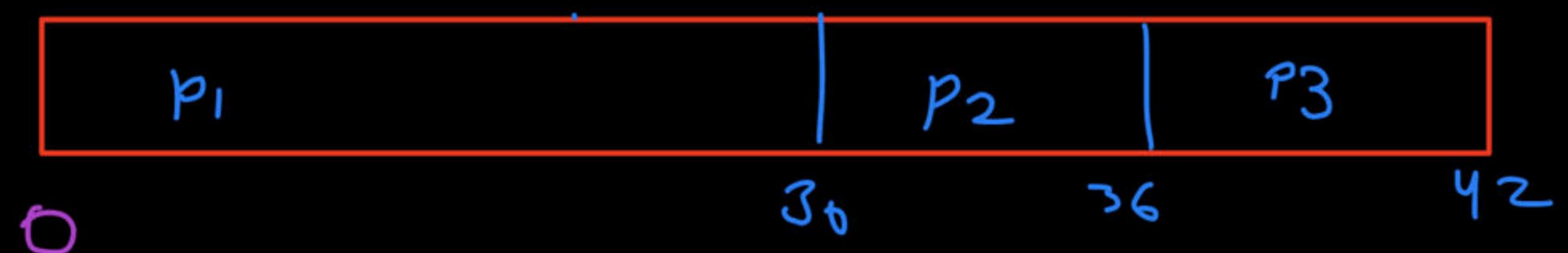
1. Preemptive
2. Non-preemptive

FCFS (First Come First Serve)

- ◎ Criteria: min AT first
 - Tie-breaker: min process ID first
- ◎ Type: Non-preemptive

FCFS (First Come First Serve)

Process	A _T	Burst Time
P1	0	30
P2	6	6
P3	0	6

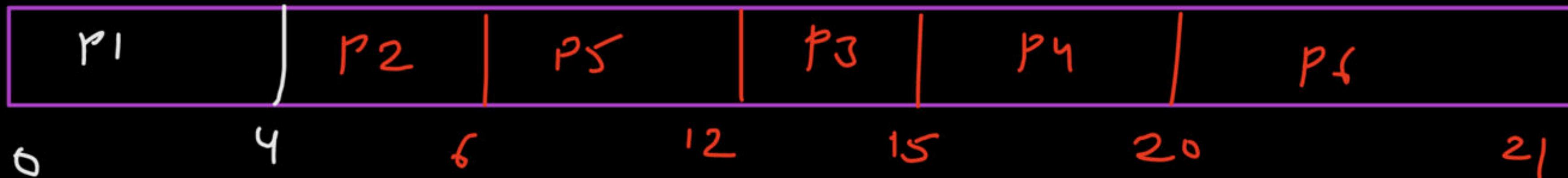


FCFS (First Come First Serve)

Process	Arrival Time	Burst Time	Completion Time	Turnaround Time	Waiting Time
P1	0	30	30	30	0
P2	0	6	36	36	30
P3	0	6	42	42	36

FCFS (First Come First Serve)

Process	Arrival Time	Burst Time	C_T	TAT	WT
P1	0	4	4	4	0
P2	1	2	6	5	3
P3	4	3	15	11	8
P4	5	5	20	15	10
P5	2	6	12	10	4
P6	9	1	21	12	11

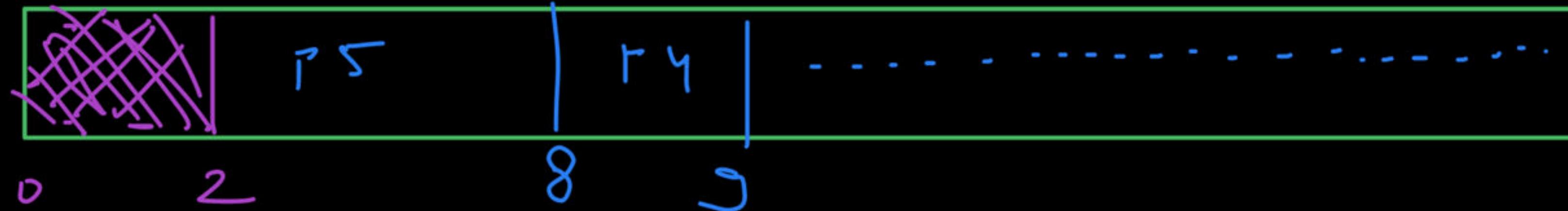


FCFS (First Come First Serve)

Process	Arrival Time	Burst Time	Completion Time	Turnaround Time	Waiting Time
P1	0	4			
P2	1	2			
P3	2	3			
P4	3	5			
P5	4	6			
P6	5	1			

FCFS (First Come First Serve)

Process	Arrival Time	Burst Time
P1	4	4
P2	8	2
P3	6	3
P4	3	1
P5	2	6
P6	7	7



FCFS (First Come First Serve)

Process	Arrival Time	Burst Time	Completion Time	Turnaround Time	Waiting Time
P1	4	4			
P2	8	2			
P3	6	3			
P4	5	3			
P5	2	1			
P6	7	7			

Convoy Effect

FCFS (First Come First Serve)

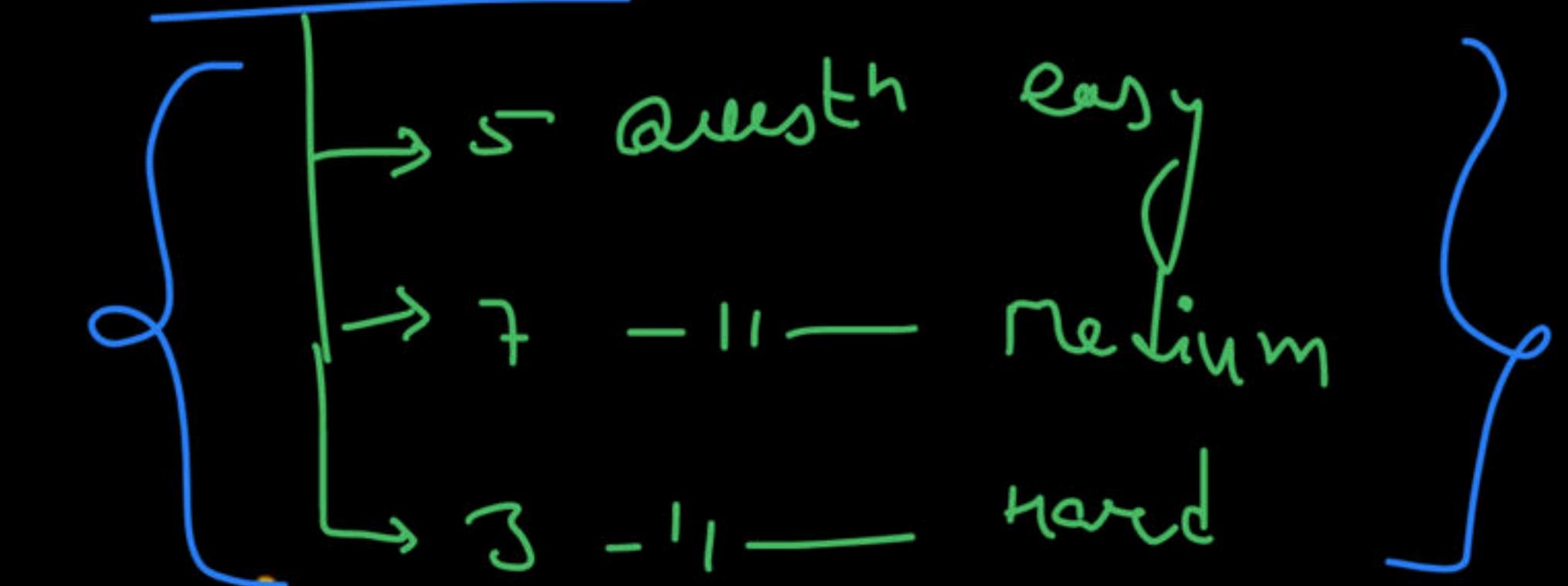
Advantages:

1. Easy to implement
2. No complex logic
3. No starvation / fairness

Disadvantages:

1. No option of Preemption
2. Convoy effect makes the system slow

min 15 quest's



Happy Learning.!