

**Final - Computer Science 2 (2020-21)**

**Time: 3 hours.**

*Attempt all questions, giving proper explanations.*

*You may quote any result proved in class without proof.*

1. How is the number 22.5 stored as a floating point number in the computer ? Give the sign, mantissa and exponent. [4 marks]
2. (a) How many floating point numbers are there in  $[0, 1]$ ? [2 marks]  
 (b) How many floating point numbers are there in  $[1, \text{Machine\$double.xmax}]$ ? [2 marks]  
 (c) Are the number of floating point numbers in  $[0, 1]$  equal to the number of floating point numbers in  $2 + [0, 1] = [2, 3]$ ? Explain. [2 marks]
3. Consider the solution to  $x = g(x)$  in  $[0, 1]$  where  $g(x) = \frac{1}{4}(1 - x)^4$ . Consider the iterations  $x_{k+1} = g(x_k)$ . Starting from  $x_0 = \frac{1}{2}$  roughly how many iterations are necessary before we are within  $10^{-6}$  of the solution? [4 marks]
4. Consider the equation  $x^2 - 3 = 0$ .
  - (a) Show, starting from  $x_0 = 1$ , that Newton's method converges to  $\sqrt{3}$ . [4 marks]
  - (b) For what values of  $x_0$  does Newton's method converge to  $\sqrt{3}$ ? It is enough to give a non-rigorous explanation. [2 marks]
5. Consider the matrix  $\mathbf{A}$  and the vector  $\mathbf{b}$  given below.
 
$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 2 \\ 1 & 3 & 1 \\ 1 & 1 & 3 \end{bmatrix}, \quad \mathbf{b} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 3 \end{pmatrix}$$
  - (a) Find the QR decomposition of  $\mathbf{A}$ . [4 marks]
  - (b) Find the least squares solution of the system  $\mathbf{Ax} = \mathbf{b}$ . [2 marks]
6. Consider an infinitely differentiable function  $f : [0, 1] \rightarrow \mathbf{R}$ .
  - (a) Write down the Newton-Cotes formula for  $\int_0^1 f(x)dx$  with 4 equally spaced points  $0 = x_0 < x_1 < x_2 < x_3 = 1$ . [4 marks]
  - (b) What is the error in approximating the integral by the approximation? [2 marks]
7. For this problem you may use R for some of the computations.
  - (a) Find a set of points  $x_0, x_1, x_2 \in [0, 1]$  such that for any  $f \in \mathcal{P}_5$ , the set of polynomials of degree at most 5, we have
 
$$\int_0^1 f(x)dx = \int_0^1 p_2(x)dx$$
 where  $p_2(x)$  is the Lagrange polynomial passing through the points  $(x_i, f(x_i))$ ,  $i = 0, 1, 2$ . [5 marks]
 **Note:** If you require to find the roots of a polynomial  $a_0 + a_1x + a_2x^2 + \dots + a_nx^n$ , type `polyroot(z=c(a0, a1, a2, ..., an))` in R.
  - (b) For any  $f \in \mathcal{P}_5$  write down  $\int_0^1 f(x)dx$  as a linear combination of  $f(x_i)$ ,  $i = 0, 1, 2$ , where  $x_i$  are computed above. [3 marks]
  - (c) Explain why this quadrature rule is better than the Simpson quadrature rule. [1 mark]

8. Consider the solution  $(x(t), y(t))$ ,  $0 \leq t \leq \frac{3}{4}$ , to the *system* of differential equations:

$$\begin{aligned}\frac{dx}{dt} &= (x+2)^2, & x(0) &= -1, \\ \frac{dy}{dt} &= x, & y(0) &= 0.\end{aligned}$$

For  $h > 0$ , we use the Euler approximation :

$$\begin{aligned}x_{i+1} &= x_i + h(x_i + 2)^2, \\ y_{i+1} &= y_i + hx_i.\end{aligned}$$

with  $x_0 = -1$ ,  $y_0 = 0$  and  $(x_i, y_i)$  the approximation at the point  $t_i = ih$ . Show that

$$y_{[\frac{1}{2h}]+1} - y_{[\frac{1}{2h}]} = O(h^2).$$

(Above  $[a]$  denotes the integer part of  $a$ .) [4 marks]