

Lecture 31 – Processor design 6

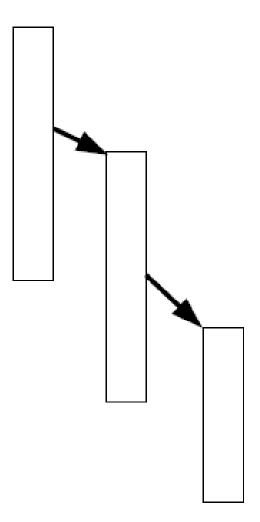
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Jump instructions

- We will now look at the remaining few instructions to make our processor more complete
- We had no branching instructions so far; all programs have to be a strictly linear sequence of instructions
- That is obviously not a very desirable situation
- We need the capability to branch or to break the sequential flow of instructions to implement any sort of loops
- Additionally, we need the capability to branch based on some condition based on the values of registers
- We use two forms of branching: one based on an immediate address and the other based on a register value (flag register)

Jump instructions

- Branching involves the shifting of the program execution from one point in the program to another
- This is a change in the control flow of the program and may be used to perform different actions on the basis of the results achieved so far
- Jump is a type of branching where the control is transferred absolutely, without any memory of the branching point
- Branching is natural in our every day activities



- The branching may be conditional, based on a current state of the processor
- We include a flag register in the processor to indicate particular conditions
- The condition of one of the flag register bits can be used for branching
- If the jump is conditioned on a flag bit being set, the branching happens only if that flag has a value of 1 and the program proceeds with the instruction at the branch address
- If the flag is at state 0, execution proceeds normally with the next instruction as if the conditional branch instruction is a *nop* instruction
- The flag register stores limited history of the results of the computations performed by the processor
- This may include aspects like: Did the last arithmetic operation result in an overflow? Did it result in a carry from the most significant bit? Was the result of the previous operation a zero?
- These, in conjunction with branching, are essential to control the program based on the results of operations

- For example, if we want to run a loop ten times, we can repeat the code 10 times, which makes the code long
- It also allows no flexibility to run the code 12 times, if we desire it
- An alternative is to use a count (typically stored in a register) that is initialized to 10
- After one set of computations is over, the count can be reduced by 1
- The program can branch to the start of the computations if the count is still not zero
- It is clear that the second option results in shorter code
- Even better, if the count is initialized to 12 or 25, the code remains exactly the same

- Our simple processor has the following 4 flag bits: zero, carry, sign, and parity, with respective flags Z, C, S, and P
- The zero flag is set if the previous ALU operation produced an exact 0 as the result (i.e., if AR is zero)
- Similarly, the carry flag is set if the previous operation resulted in a carry-out or borrow-in from the most significant bit
- The S bit copies the sign bit of the last arithmetic operation and becomes 1 if the result was negative
- The parity bit counts the number of 1 bits in the result of the last operation
- If that number is odd, the parity bit is 1

 Instructions that do not use the ALU – such as the data movement instructions, branching instructions, and the like – do not change the flag values

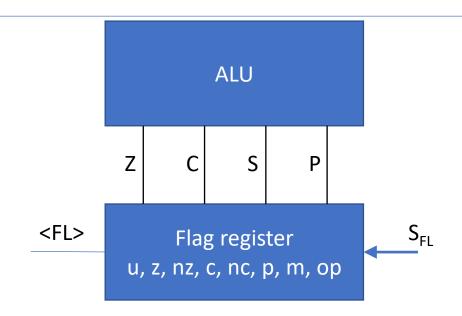
 Some processors group all flags into a special register word known as the Program Status Word (PSW)

 Special instructions may move the PSW to or from internal registers or memory

This allows their manipulation as data

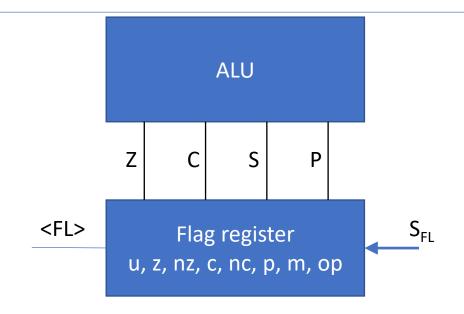
Jump instruction

- For the simple flag register defined, the <FL> flag for conditional instructions can take one of the following values: u, z, nz, c, nc, p, m, op
- These respectively stand for unconditional, zero, non-zero, carry, no-carry, positive, minus, and oddparity
- Unconditional case is always true, irrespective of the state of the flag bits
- Zero condition is true when the Z bit is set and the non-zero condition is true otherwise
- Similarly, the carry and no-carry conditions are true when the C bit of the flags is 1 and 0 respectively
- The plus condition is true when the sign bit S is 0 and the minus condition is true otherwise
- The odd-parity condition is true if the flag bit P is 1



Implementing the jump instruction

- To implement the jump function, we need to change the PC to the contents of the AR if the flag condition is satisfied
- If not, it should have no effect
- The conditional jump instructions use a modified control signal, labelled "End if <FL>'"
- This means that the End control signal is activated only if the selected flag is at a 0 level
- This is the case where the condition is not satisfied and hence the instruction has no impact

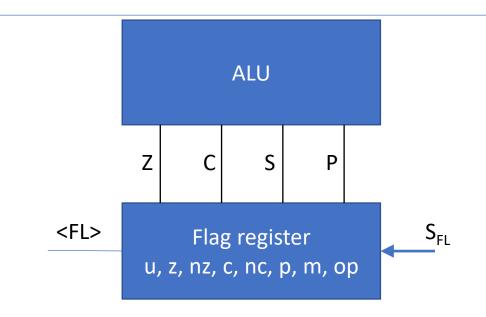


| Assembly Instruction | Machine Code | Action |
|-------------------------|-----------------|-----------------------------------------------------------|
| jmpd <fl> xx</fl> | EO-E7 | [PC] ← xx if <fl> = 1</fl> |
| jmpr <fl></fl> | E8-EF | $[PC] \leftarrow [AR] \text{ if } \langle FL \rangle = 1$ |

| Instruction | Control Signals | Select Signals |
|--------------------|-----------------------------------------------------------------------------------------------------------------------------------|----------------------------------------|
| jumpd <fl> xx</fl> | Ck 3: E _{PC} , L _{MR} , I _{PC} , E _{FL} , End if <fl>' Ck 4: RD, L_{PC}, End</fl> | $S_{FL} \leftarrow \langle FL \rangle$ |
| jmpr <fl></fl> | Ck 3: E _{FL} , End if <fl>' Ck 4: E_{AR}, L_{PC}, End</fl> | $S_{FL} \leftarrow \langle FL \rangle$ |

Implementing the jump instruction

- However, for instructions with immediate operands (such as jumpd), the next word has to be jumped over so that the PC points to the next real instruction
- At the same time, the value of PC should be incremented whether the value of flag is true or not
- Hence, the PC value is saved in MR and PC is incremented
- Then if the flag condition is satisfied, the value at the address is loaded into PC



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