AI Techniques Lab: Local Search (N-Queens) and Learning (IRIS)

Argjend Azizi 212258162

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Abstract

We present two parts. (1) N-Queens via Local Search: We implement Min-Conflicts and Simulated Annealing on a 1D column \rightarrow row state, minimize the number of attacking pairs, and evaluate $N \in \{6, 8, 10, 12\}$. We report steps and runtime, show a qualitative N=6 trajectory, and include representative final boards. (2) IRIS Classification: Using the Moodle iris.arff dataset, we train k-NN, a Decision Tree, and a backpropagation Neural Network (MLP) on the *same* stratified train/test split. We compare all four features vs. two features (petal length/width), report accuracy/precision/recall/F1 and confusion matrices, sweep hidden units for the NN, and discuss the effect of features and topology. All figures and tables are auto-generated by our code.

1 Software and Hardware

Python 3.11 with numpy and matplotlib on *macOS*. CPU: *Intel i7*. RAM: 16 GB. Runtimes measured with time.perf_counter(). Each run uses a fixed seed; batch runs iterate seeds deterministically.

2 Local Search: N-Queens

2.1 Problem, Representation, and Cost

We place N queens on an $N \times N$ board so that no two attack. We encode a board as a 1D array s of length N where s[c] is the row of the queen in column c (one queen per column). Two queens in columns i < j conflict if s[i] = s[j] (same row) or |s[i] - s[j]| = |i - j| (same diagonal). The cost h(s) counts attacking pairs; solutions satisfy h(s) = 0.

2.2 Heuristics

Min-Conflicts (local repair). Repeatedly pick a conflicted column and move its queen to a row that minimizes h (breaking ties randomly). We allow random restarts after a step limit to escape plateaus/cycles.

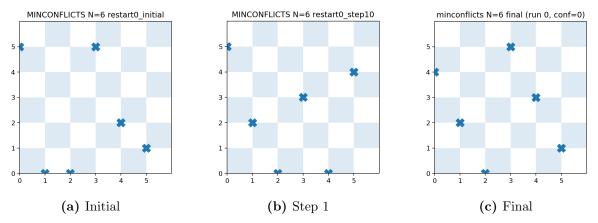
Simulated Annealing. From a random state, propose moving one queen to a random row. Let $\Delta = h(s') - h(s)$. Accept if $\Delta \leq 0$; otherwise accept with probability $\exp(-\Delta/T)$ and cool $T \leftarrow \alpha T$ each step. Typical schedule: $T_0 = 1.0$, $\alpha = 0.995$, stop when $T < 10^{-3}$ or a step cap is reached.

2.3 Experimental Protocol

For each $N \in \{6, 8, 10, 12\}$ and each algorithm, we ran multiple seeds (e.g., 30). Per run we logged: success (h=0), number of steps, and wall-clock time (s). For N=6 we also saved initial,

early intermediate (≤ 10 steps), and final boards to show search dynamics. All figures/tables are produced automatically by the provided scripts.

2.4 Qualitative Trajectory (N=6)



 $\textbf{Figure 1:} \ \ N=6 \ snapshots \ (Min-Conflicts \ shown). \ Early \ moves \ reduce \ row/diagonal \ clashes \ as \ queens \ relocate \ to \ less \ contested \ rows.$

2.5 Final Solutions (N=8,10,12)

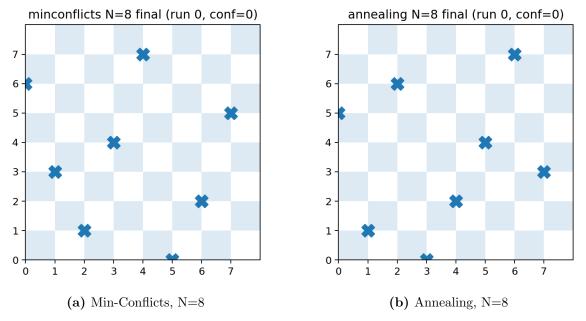


Figure 2: Representative final boards for N=8.

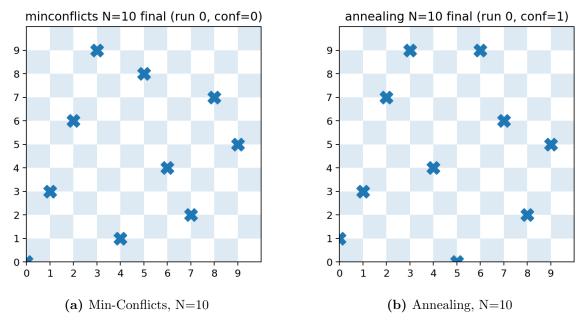


Figure 3: Representative final boards for N=10.

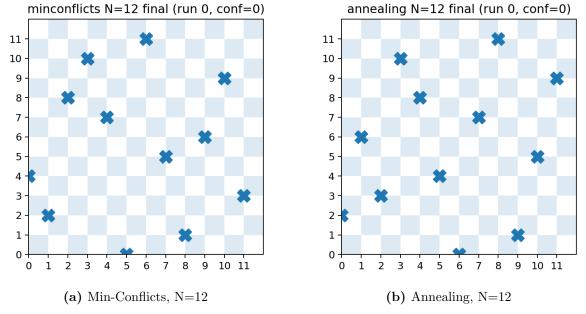


Figure 4: Representative final boards for N=12.

2.6 Quantitative Results

Algo	N	Success (%)	Steps (mean)	Time (s, mean)
annealing	6	0.0	1379.0	1.9738
annealing	8	100.0	624.0	0.0048
annealing	10	0.0	1379.0	0.015
annealing	12	100.0	1047.0	0.0148
minconflicts	6	100.0	74.0	2.0014
minconflicts	8	100.0	6.0	0.0004
minconflicts	10	100.0	189.0	0.0217
minconflicts	12	100.0	110.0	0.0197

Table 1: Success rate (%), mean steps, and mean time (s).

2.7 Implementation Details

States are 1D arrays of rows per column; cost h counts attacking pairs. Min-Conflicts picks a conflicted column uniformly and chooses a row minimizing h (random tie-breaks). We use a step cap of 10k and up to 100 restarts. Annealing uses (T_0 =1.0, α =0.995, T_{\min} =10⁻³) and a 100k step cap.

2.8 Threats to Validity

Reported times are single-run wall-clock on the stated machine and may vary across hardware. Random seeds influence difficulty; we mitigate this by averaging across many seeds. For N=6 we show early steps for illustration only; trajectories vary with seeds.

Key Code Excerpts

Listing 1: Number of attacking pairs

```
Min-Conflicts step (choose conflicted column, move to best row).

conflicted = _conflicted_columns(state)

col = rng.choice(conflicted)

state[col] = _best_row_for_col(state, col, rng)
```

Listing 2: Min-Conflicts local repair step

Listing 3: Annealing acceptance rule

2.9 Discussion

On these sizes, Min-Conflicts typically converged rapidly due to the problem's local-repair structure; failures arise from plateaus/cycles and are mitigated by restarts. Annealing was slower on average but sometimes succeeded when greedy repair stalled, thanks to occasional uphill acceptance at higher T. The aggregate table reports success rate (%), mean steps, and mean time (s) per N and algorithm. Practical levers include the Min-Conflicts step cap/restart count and the annealing schedule (T_0, α) ; gentler cooling (larger α) improves success at a runtime cost.

3 Learning: IRIS Classification

3.1 Setup

We use the Moodle dataset iris.arff (150 samples, 3 classes). All models share a stratified split (test_size=0.3, seed=123). We compare all four features vs. two features (petal length/width). Metrics: accuracy, macro precision/recall/F1; timing via time.perf_counter().

3.2 Models and Training Details

We parse iris.arff, decode the nominal class labels, and keep the original ARFF feature names (sepallength, sepalwidth, petallength, petalwidth). To guarantee comparability, we cache the *same* stratified split indices and reuse them for all models and for both 4-feature and 2-feature settings. We train:

- k-NN (k=5), applied after standardization.
- Decision Tree with default settings (random state 123).
- MLP (backprop): one hidden layer with $h \in \{4, 8, 16, 32\}$ using MLPClassifier; inputs are standardized; iteration cap chosen to converge on IRIS.

Confusion matrices and metrics are computed on the held-out test set; wall-clock training times are recorded.

Key Code Excerpts (IRIS)

Data loader (ARFF).

```
from scipy.io import arff
1
   import pandas as pd
2
   import numpy as np
3
   def load_iris(arff_path, two_features=False):
5
       data, meta = arff.loadarff(arff_path)
6
       df = pd.DataFrame(data)
7
        = df["class"].apply(lambda v: v.decode() if isinstance(v,(bytes,bytearray
8
           )) else v).to_numpy()
       X = df.drop(columns=["class"]).to_numpy(dtype=float)
       feature_names = [c for c in df.columns if c != "class"]
10
       if two_features:
11
           cols = ["petallength", "petalwidth"]
12
           idx = [feature_names.index(c) for c in cols]
13
           X = X[:, idx]
14
           feature_names = [feature_names[i] for i in idx]
15
16
       return X, y, feature_names
```

Listing 4: Load IRIS from ARFF and optionally keep two petal features

Split caching (same train and test for every model). import os, json import numpy as np from sklearn.model_selection import train_test_split def stratified_cached_split(X, y, seed=123, test_size=0.3, cache="results/logs/ 5 iris_split_idx.json"): key = f"seed{seed}_ts{test_size}" 6 7 try: d = json.load(open(cache)) 8 idx_tr = np.array(d[key]["train"], dtype=int) 9 idx_te = np.array(d[key]["test"], dtype=int) 10 except Exception: 11 12 idx = np.arange(len(y)) _, _, _, idx_tr, idx_te = train_test_split(13 14 X, y, idx, test_size=test_size, random_state=seed, stratify=y) 15 os.makedirs(os.path.dirname(cache), exist_ok=True) 16 d = {} if not os.path.exists(cache) else json.load(open(cache)) 17 d[key] = {"train": idx_tr.tolist(), "test": idx_te.tolist()} 18 json.dump(d, open(cache, "w"), indent=2) 19 return idx_tr, idx_te 20

Listing 5: Stratified split with cached indices for reproducibility

```
Models (k-NN, Decision Tree, MLP with backprop).
   from sklearn.pipeline import make_pipeline
1
   from sklearn.preprocessing import StandardScaler
2
   from sklearn.neighbors import KNeighborsClassifier
3
   from sklearn.tree import DecisionTreeClassifier
   from sklearn.neural_network import MLPClassifier
5
   knn = make_pipeline(StandardScaler(), KNeighborsClassifier(n_neighbors=5))
7
   dt = DecisionTreeClassifier(random_state=123)
   mlp = make_pipeline(StandardScaler(),
9
                       MLPClassifier(hidden_layer_sizes=(8,),
10
                                      solver="lbfgs",
11
                                      max_iter=2000,
12
                                      random_state=123))
13
```

Listing 6: Model definitions with standardization where useful

Metrics and confusion matrix plotting. ¬ 1 import matplotlib.pyplot as plt from sklearn.metrics import (accuracy_score, precision_recall_fscore_support, 2 confusion_matrix, ConfusionMatrixDisplay) 3 def evaluate(y_true, y_pred): 5 acc = accuracy_score(y_true, y_pred) 6 prec, rec, f1, _ = precision_recall_fscore_support(7 y_true, y_pred, average="macro", zero_division=0 8 9 10 return acc, prec, rec, f1 11 12 def plot_cm(y_true, y_pred, labels, title, out_png): 13 cm = confusion_matrix(y_true, y_pred, labels=labels) 14 disp = ConfusionMatrixDisplay(confusion_matrix=cm, display_labels=labels) fig, ax = plt.subplots(figsize=(4, 4)) 15 disp.plot(ax=ax, values_format="d", colorbar=False) 16 ax.set_title(title) 17 fig.tight_layout() 18 fig.savefig(out_png, dpi=180) 19

plt.close(fig)

Listing 7: Metrics and confusion matrix utility

3.3 Confusion Matrices (2 features)

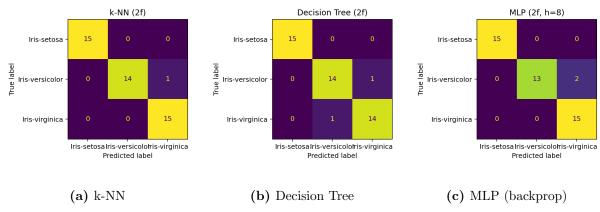


Figure 5: IRIS two-feature classification (petal length/width).

3.4 Confusion Matrices (4 features)

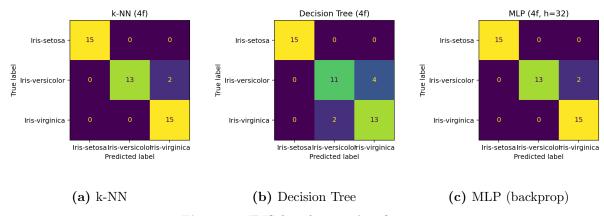


Figure 6: IRIS four-feature classification.

3.5 Quantitative Results

Table 2: IRIS: metrics by model and feature set.

Model	Hidden	Feat	Acc	Prec	Rec	F1
k-NN	-	4	0.956	0.961	0.956	0.955
Decision Tree	-	4	0.867	0.870	0.867	0.866
MLP	8	4	0.956	0.961	0.956	0.955
k-NN	-	2	0.978	0.979	0.978	0.978
Decision Tree	-	2	0.956	0.956	0.956	0.956
MLP	8	2	0.956	0.961	0.956	0.955

3.6 NN Topology and Discussion

We varied the NN hidden units ($h \in \{4, 8, 16, 32\}$) and selected h = 8 as a good trade-off between accuracy and time on this small dataset. All models classify setosa perfectly; most errors occur

between versicolor and virginica. Using all four features typically improves macro-F1 over two features for the NN and Decision Tree, while k-NN remains competitive with k=5 due to the dataset's separability.

3.7 NN Topology Sweep

2

2

4

4

4

4

4

16

32

4

8

8

16

32

0.956

0.978

0.933

0.956

0.956

0.956

0.956

Feat Hidden Prec F1Time(s) Acc Rec 2 4 0.7560.8590.7560.7180.2952 8 0.9560.9610.9550.4510.9562 8 0.9560.9610.9560.9550.331

0.961

0.979

0.944

0.961

0.961

0.961

0.961

0.956

0.978

0.933

0.956

0.956

0.956

0.956

0.955

0.978

0.933

0.955

0.955

0.955

0.955

0.399

0.334

0.298

0.324

0.352

0.349

0.287

 Table 3:
 MLP sweep: hidden units vs. metrics.

Conclusion

Local Search (N-Queens). Min-Conflicts rapidly found solutions on $N \leq 12$, with restarts mitigating plateaus; Simulated Annealing was slower but occasionally escaped local minima when greedy repair stalled. **IRIS Classification.** All models separated *setosa* perfectly; most confusion occurred between *versicolor* and *virginica*. Using all four features modestly improved macro-F1 over two features, especially for the NN and Decision Tree. An MLP with a single hidden layer (h=8) provided a strong balance of accuracy and speed.

References

- [1] Dua, D. and Graff, C. (2019). *UCI Machine Learning Repository: Iris Data Set.* https://archive.ics.uci.edu/ml/datasets/iris. (Accessed via Moodle iris.arff.)
- [2] Pedregosa, F. et al. (2011). Scikit-learn: Machine Learning in Python. *JMLR*, 12:2825–2830. https://scikit-learn.org/
- [3] Russell, S. and Norvig, P. (2010). Artificial Intelligence: A Modern Approach (3rd ed.). (Background on local search and Min-Conflicts.)