RadRoad Project

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https://github.com/argo-marketplace/RadRoads/tree/master/notebooks

Hypothesis

This project serves the hypothesis of finding the most applicable street for autonomous cars.

- **<u>Longest</u>**
- **<u>Straightest</u>**
- Shortest
- Curviness

Introduction

Nominatim:

https://wiki.openstreetmap.org/wiki/Nominatim

https://nominatim.openstreetmap.org/search.php?q=manhattan%2C+new+york&polygon_geojson=1&viewbox=

OSMnx

https://github.com/gboeing/osmnx