

Medical Image Analysis and Processing

Medical Image Segmentation Pixel Classification - Clustering

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Distance/online Course: Session 20 Episode#1

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Contents

- › Adaptive Fuzzy C-Means (AFCM)
- › Bias Corrected FCM (BCFCM)

Pixel Classification — Image Segmentation in Presence of Intensity Inhomogeneity

- › *Intensity Inhomogeneity Aware* segmentation:
- › Two core article:
 - Adaptive Fuzzy C-Means (AFCM)
 - Bias Corrected FCM (BCFCM)

Adaptive Fuzzy C-Means (AFCM):

› Notation:

- $y(i, j)$: Acquired image intensity at location (i, j) ,
- C : # of segments,
- q : fuzziness parameter of algorithm (we assume $q = 2$),
- $u_k(i, j)$: Membership value at pixel location (i, j) for segment # k ,
- v_k : Centroid of segment # k

› Conventional Fuzzy C-Means (FCM) cost function:

$$J_{FCM} = \sum_{(i,j)} \sum_{k=1}^C u_k^2(i, j) \|y(i, j) - v_k\|_2^2, \quad s. t. \sum_{k=1}^C u_k(i, j) = 1$$

Adaptive Fuzzy C-Means (AFCM):

› AFCM cost function:

$$J_{AFCM} = \sum_{(i,j)} \sum_{k=1}^C u_k^2(i,j) \|y(i,j) - m(i,j)v_k\|_2^2 + \dots$$

$$\lambda_1 \sum_{(i,j)} \left((m(i,j) * D_i)^2 + (m(i,j) * D_j)^2 \right) + \dots$$

$$\lambda_2 \sum_{(i,j)} \left((m(i,j) ** D_{ii})^2 + 2(m(i,j) ** D_{ij})^2 + (m(i,j) ** D_{jj})^2 \right)$$

- › $m(i,j)$: unknown multiplier field (model the brightness variation), **slow variation!**
- › D_i and D_j are 1st order finite Difference operator for partial derivatives $(\frac{\partial m}{\partial x}, \frac{\partial m}{\partial y})$
- › D_{ii} , D_{jj} and D_{ij} are 2nd order finite Difference operator for partial derivatives $(\frac{\partial^2 m}{\partial x^2}, \frac{\partial^2 m}{\partial y^2}, \frac{\partial^2 m}{\partial x \partial y})$

Adaptive Fuzzy C-Means (AFCM):

- › The second and third terms are measure of smoothness:
- › For 2D continuous function f :

$$S_1 = \iint_{-\infty}^{+\infty} \left(\left(\frac{\partial f}{\partial x} \right)^2 + \left(\frac{\partial f}{\partial y} \right)^2 \right) dx dy = \iint_{-\infty}^{+\infty} |\nabla f|^2 dx dy$$

$$S_2 = \iint_{-\infty}^{+\infty} \left(\left(\frac{\partial^2 f}{\partial x^2} \right)^2 + 2 \left(\frac{\partial^2 f}{\partial x \partial y} \right)^2 + \left(\frac{\partial^2 f}{\partial y^2} \right)^2 \right) dx dy = \iint_{-\infty}^{+\infty} \|H(f)\|_F^2 dx dy$$

Adaptive Fuzzy C-Means (AFCM):

› Algorithm steps:

1. Initial guess for $\{v_k\}_{k=1}^C$ using k-means, FCM, ... and set $m(i, j) = 1$

2. Compute membership functions:

$$u_k(i, j) = \frac{\|y(i, j) - m(i, j)v_k\|^{-2}}{\sum_{l=1}^C \|y(i, j) - m(i, j)v_l\|^{-2}}$$

3. Compute centroids:

$$v_k = \frac{\sum_{(i,j)} u_k^2(i, j)m(i, j)y(i, j)}{\sum_{(i,j)} u_k^2(i, j)m^2(i, j)}$$

4. Compute multiplier field:

$$y(i, j) \sum_{k=1}^C u_k^2(i, j)v_k = m(i, j) \sum_{k=1}^C u_k^2(i, j)v_k^2 + \lambda_1(m(i, j) ** H_1(i, j)) + \lambda_2(m(i, j) ** H_2(i, j))$$

where $H_1(i, j) = D_i * \check{D}_i + D_j * \check{D}_j$ and $H_2(i, j) = D_{ii} * \check{D}_{ii} + 2(D_{ij} * \check{D}_{ij}) + D_{jj} * \check{D}_{jj}$, $\check{f}(i) = f(-i)$

5. Step over 2-3-4 until convergence

Adaptive Fuzzy C-Means (AFCM):

› Step (4):

$$y(i,j) \sum_{k=1}^c u_k^2(i,j) v_k = m(i,j) \sum_{k=1}^c u_k^2(i,j) v_k^2 + \lambda_1(m(i,j) ** H_1(i,j)) + \lambda_2(m(i,j) ** H_2(i,j))$$

› may be rewrite as: $\mathbf{f} = \mathbf{A}\mathbf{m}$

› For $y \in \mathbb{R}^{M \times N}$ then $\mathbf{f} \in \mathbb{R}^{MN}$, $\mathbf{m} \in \mathbb{R}^{MN}$ and $\mathbf{A} \in \mathbb{R}^{MN \times MN}$

› Huge! systems of linear equations

› It is possible to solve via weighted Jacobi iteration:

$$\mathbf{m}^{(i+1)} = [(1 - \omega)\mathbf{I} - \omega\mathbf{D}^{-1}(\mathbf{L} + \mathbf{U})]\mathbf{m}^{(i)} + \omega\mathbf{D}^{-1}\mathbf{f}, \quad \mathbf{A} = \mathbf{D} + \mathbf{L} + \mathbf{U}, \omega^* = \frac{2}{3}$$

and multiresolution (multigrid) scheme.

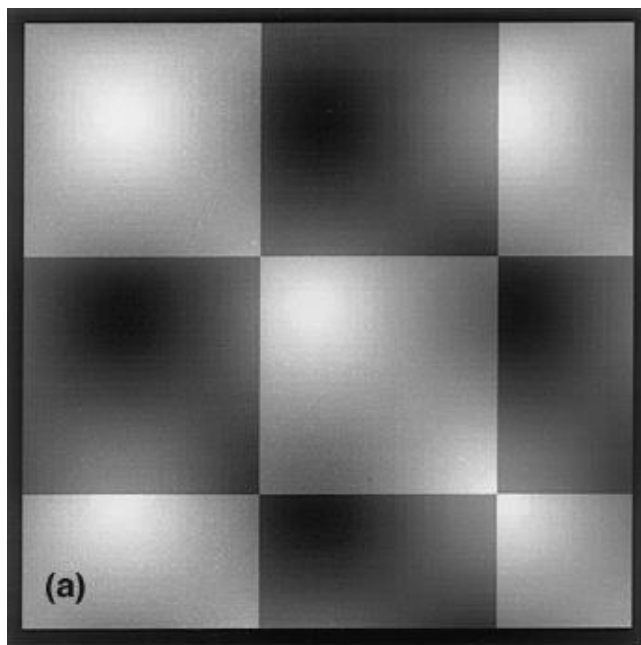
Adaptive Fuzzy C-Means (AFCM):

› Example for A decomposition:

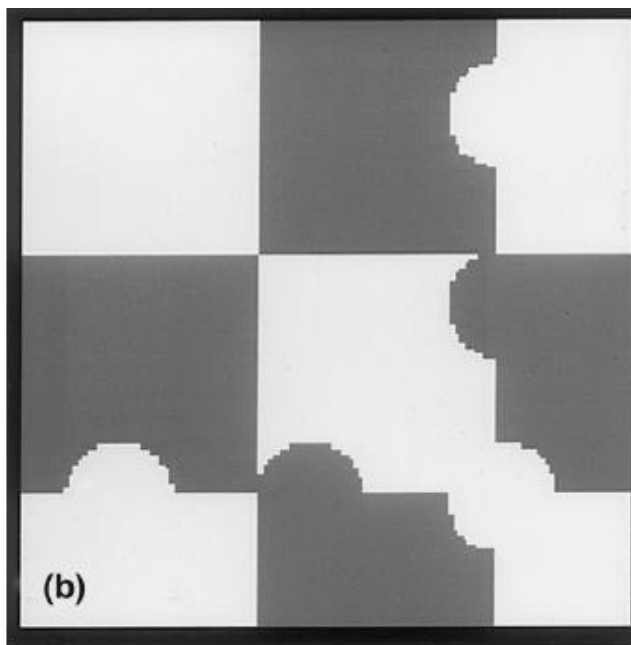
$$\underbrace{\begin{bmatrix} a & b \\ c & d \end{bmatrix}}_A = \underbrace{\begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix}}_D + \underbrace{\begin{bmatrix} 0 & 0 \\ c & 0 \end{bmatrix}}_L + \underbrace{\begin{bmatrix} 0 & b \\ 0 & 0 \end{bmatrix}}_U$$

Adaptive Fuzzy C-Means (AFCM):

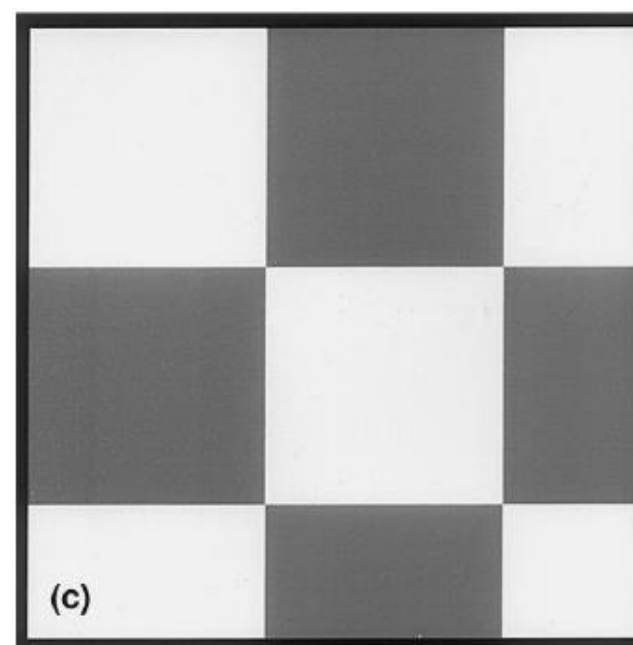
› Results:



(a) original



(b) FCM



(c) AFCM

Bias Corrected FCM (BCFCM)

› Notation:

- $y(i, j)$: Log-transferred *acquired* image intensity at location (i, j) ,
- $x(i, j)$: Log-transferred *true* image intensity at location (i, j) ,
- $\beta(i, j)$: Log-transferred *bias field* at location (i, j) ,

$$y(i, j) = x(i, j) + \beta(i, j)$$

- C : # of segments,
- q : fuzziness parameter of algorithm (we assume $q = 2$),
- $u_k(i, j)$: Membership value at pixel location (i, j) for segment # k ,
- v_k : Centroid of segment # k

Bias Corrected FCM (BCFCM)

- › Bias Corrected Fuzzy C-Means (AFCM) cost function:

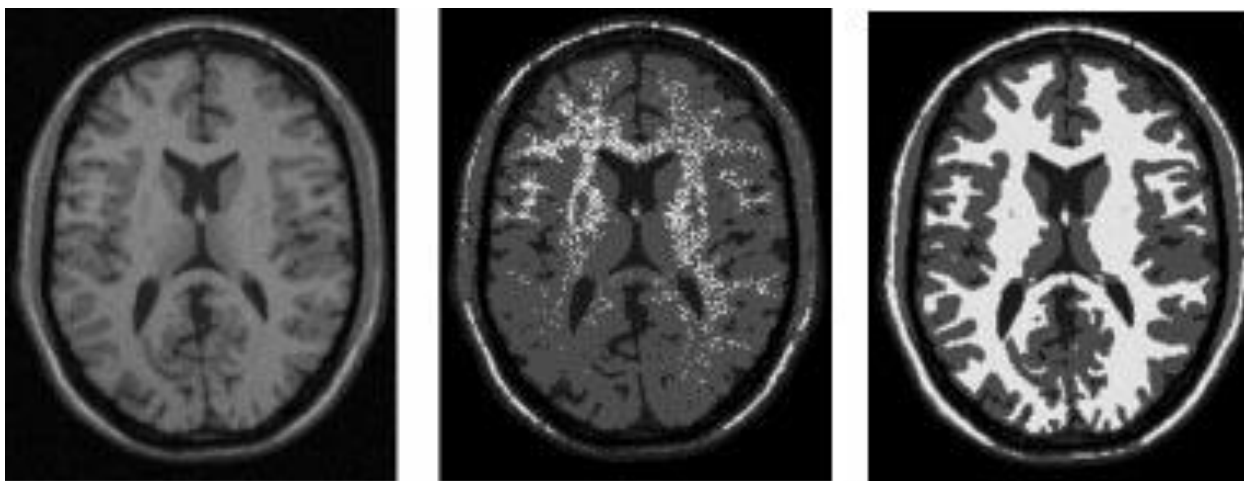
$$J_{BCFCM} = \sum_{(i,j)} \sum_{k=1}^c u_k^2(i,j) \|y(i,j) - \beta(i,j) - v_k\|_2^2 +$$

$$\frac{\alpha}{N_R} \sum_{(i,j)} \sum_{k=1}^c \left(u_k^2(i,j) \sum_{y(p,q) \in N(i,j)} \|y(p,q) - \beta(p,q) - v_k\|_2^2 \right)$$

- › where $N_{(i,j)}$ stands for the set of neighbors that exist in a window around location (i,j) and N_R is its cardinality.
- › The new term the labeling of a pixel (voxel) to be influenced by the labels in its immediate neighborhood, the neighborhood effect acts as a regularizer and biases the solution toward piecewise-homogeneous labeling.

Bias Corrected FCM (BCFCM)

- › Results (5% Gaussian noise and 20% intensity inhomogeneity):
- › Left (simulated data), Center (FCM), Right (BCFCM)



The End

› AnY QuEsTiOn?

