

# Programming Languages

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## Contents

1	Semantics of Expressions	1
2	Untyped Lambda Calculus	5
3	Simply Typed Lambda Calculus	11
4	$\lambda$ -OCaml	14
5	Closure	17

# 1 Semantics of Expressions

In this section, we will define a simple programming language called **While**. The syntax of **While** has five categories: numerals **Num**, variables **Var**, arithmetic expressions **Aexp**, boolean expressions **Bexp**, and statements **Stm**. The structure for **Aexp**, **Bexp**, and **Stm** are given respectively as follows:

$$\begin{aligned} (\mathbf{Aexp}) \quad a &::= n \mid x \mid a_1 + a_2 \mid a_1 \star a_2 \mid a_1 - a_2 \\ (\mathbf{Bexp}) \quad b &::= \text{true} \mid \text{false} \mid a_1 = a_2 \mid a_1 \leq a_2 \mid \neg b \mid b_1 \wedge b_2 \\ (\mathbf{Stm}) \quad S &::= x := a \mid \text{skip} \mid S_1; S_2 \mid \text{if } b \text{ then } S_1 \text{ else } S_2 \mid \text{while } b \text{ do } S \end{aligned}$$

Explicitly, arithmetic expressions are defined recursively as so:

- (1) numerals and variables are arithmetic expressions,
- (2) if  $a_1, a_2 \in \mathbf{Aexp}$  then  $a_1 + a_2, a_1 \star a_2, a_1 - a_2 \in \mathbf{Aexp}$ .

Similarly boolean expressions are defined recursively

- (1) true and false are boolean expressions,
- (2) if  $a_1, a_2 \in \mathbf{Aexp}$  then  $a_1 = a_2, a_1 \leq a_2 \in \mathbf{Bexp}$ ,
- (3) if  $b_1, b_2 \in \mathbf{Bexp}$  then  $\neg b_1, b_1 \wedge b_2 \in \mathbf{Bexp}$ .

And finally statements:

- (1) if  $x$  is a variable and  $a$  is an arithmetic expression then  $x := a$  is a statement,
- (2) skip is a statement,
- (3) if  $S_1, S_2$  are statements, then  $S_1; S_2$  is a statement,
- (4) if  $b \in \mathbf{Bexp}$  and  $S_1, S_2$  are statements then **if**  $b$  **then**  $S_1$  **else**  $S_2$  and **while**  $b$  **do**  $S_1$  are statements.

So for example, if  $x, y$  are variables then

$$x := 5; y := 10; \text{while } x \leq 10 \text{ do if } 0 \leq y \text{ then } y := y - x \text{ else skip; } x := x + y$$

is a statement. What exactly it does is not important yet, but what is important is that it's a statement.

## 1.1 Definition

A **state** is a function  $\mathbf{Var} \rightarrow \mathbb{Z}$ , define **State** to be the set of all states (all functions  $\mathbf{Var} \rightarrow \mathbb{Z}$ ).

## 1.2 Definition

We define the function  $\mathcal{A}: \mathbf{Aexp} \rightarrow (\mathbf{State} \rightarrow \mathbb{Z})$ , which assigns to every **Aexp** its numerical value when evaluated at a specific state. We define  $\mathcal{A}$  recursively on the structure of **Aexp**:

- (1) for a numeral  $n$ ,  $\mathcal{A}[n]s = n$ ,
- (2) for a variable  $x$ ,  $\mathcal{A}[x]s = s x$ ,
- (3)  $\mathcal{A}[a_1 + a_2]s = \mathcal{A}[a_1]s + \mathcal{A}[a_2]s$ ,
- (4)  $\mathcal{A}[a_1 \star a_2]s = \mathcal{A}[a_1]s \cdot \mathcal{A}[a_2]s$ ,
- (5)  $\mathcal{A}[a_1 - a_2]s = \mathcal{A}[a_1]s - \mathcal{A}[a_2]s$ .

So for example, if  $s$  is a state which maps  $x \rightarrow 1$  and  $y \rightarrow 3$  then

$$\begin{aligned} \mathcal{A}[x + ((x \star y) + 1)]s &= \mathcal{A}[x]s + \mathcal{A}[(x \star y) + 1]s = \mathcal{A}[x]s + \mathcal{A}[x \star y]s + \mathcal{A}[1]s \\ &= \mathcal{A}[x]s + \mathcal{A}[x]s \cdot \mathcal{A}[y]s + \mathcal{A}[1]s = 1 + 1 \cdot 3 + 1 = 5 \end{aligned}$$

## 1.3 Definition

We define  $\mathcal{B} : \mathbf{Bexp} \rightarrow (\mathbf{State} \rightarrow \{tt, ff\})$  which assigns to every boolean expression a boolean value when evaluated at a specific state. Similar to  $\mathcal{A}$ , we define it recursively:

- (1)  $\mathcal{B}[\mathbf{true}]s = tt$ ,  $\mathcal{B}[\mathbf{false}]s = ff$ ,
- (2)  $\mathcal{B}[a_1 = a_2]s$  is  $tt$  if  $\mathcal{A}[a_1]s = \mathcal{A}[a_2]s$  and  $ff$  otherwise,
- (3)  $\mathcal{B}[a_1 \leq a_2]s$  is  $tt$  if  $\mathcal{A}[a_1]s \leq \mathcal{A}[a_2]s$  and  $ff$  otherwise,
- (4)  $\mathcal{B}[\neg b]s = \neg \mathcal{B}[b]s$ ,
- (5)  $\mathcal{B}[b_1 \wedge b_2]s = \mathcal{B}[b_1]s \wedge \mathcal{B}[b_2]s$ .

Where  $\neg$  and  $\wedge$  are defined as one would expect on  $\{tt, ff\}$ .

## 1.4 Definition

Let  $s$  be a state,  $x$  a variable, and  $v$  a number. Define  $s[x \mapsto v]$  to be the state defined by

$$s[x \mapsto v]y = \begin{cases} v & x = y \\ s y & \text{else} \end{cases}$$

So  $s[x \mapsto v]$  is the state obtained by overwriting the value of  $x$  in  $s$  to be  $v$ .

We now define the semantics of **While**. A program in **While** is a statement and a state, then the statement is run and a new state is produced. Formally we define a transition relation  $\langle \cdot, \cdot \rangle \rightarrow \cdot \subseteq (\mathbf{Stm} \times \mathbf{State} \times \mathbf{State})$ , here we read  $\langle S, s \rangle \rightarrow s'$  as “ $s'$  is derivable from  $S, s$ ”. We write

$$\frac{\langle S_1, s_1 \rangle \rightarrow s'_1, \dots, \langle S_n, s_n \rangle \rightarrow s'_n}{\langle S, s \rangle \rightarrow s'} \quad \text{if } \dots$$

To mean that if  $\langle S_i, s_i \rangle \rightarrow s'_i$  hold for  $1 \leq i \leq n$  and the condition in  $\dots$  holds, then  $\langle S, s \rangle \rightarrow s'$ . If there are no conditions, then we will forgo the horizontal line and just write  $\langle S, s \rangle \rightarrow s'$ .

We now list the transitions:

$$\begin{array}{ll} [\mathbf{ass}_{\text{ns}}] & \langle x := a, s \rangle \rightarrow s[x \mapsto \mathcal{A}[a]s] \\ [\mathbf{skip}_{\text{ns}}] & \langle \mathbf{skip}, s \rangle \rightarrow s \\ [\mathbf{comp}_{\text{ns}}] & \frac{\langle S_1, s \rangle \rightarrow s' \quad \langle S_2, s' \rangle \rightarrow s''}{\langle S_1; S_2, s \rangle \rightarrow s''} \\ [\mathbf{if}_{\text{ns}}^{\text{tt}}] & \frac{\langle S_1, s \rangle \rightarrow s'}{\langle \mathbf{if } b \text{ then } S_1 \text{ else } S_2 \rangle \rightarrow s'} \quad \text{if } \mathcal{B}[b]s = tt \\ [\mathbf{if}_{\text{ns}}^{\text{ff}}] & \frac{\langle S_2, s \rangle \rightarrow s'}{\langle \mathbf{if } b \text{ then } S_1 \text{ else } S_2 \rangle \rightarrow s'} \quad \text{if } \mathcal{B}[b]s = ff \\ [\mathbf{while}_{\text{ns}}^{\text{tt}}] & \frac{\langle S, s \rangle \rightarrow s' \quad \langle \mathbf{while } b \text{ do } S, s' \rangle \rightarrow s''}{\langle \mathbf{while } b \text{ do } S \rangle \rightarrow s''} \quad \text{if } \mathcal{B}[b]s = tt \\ [\mathbf{while}_{\text{ns}}^{\text{ff}}] & \langle \mathbf{while } b \text{ do } S, s \rangle \rightarrow s \quad \text{if } \mathcal{B}[b]s = ff \end{array}$$

We can compute transitions by successive applications of axioms (transitions without assumptions) and transitions.

## 1.5 Definition

The **deductive tree** of  $\langle S, s \rangle \rightarrow s'$  is a tree whose root is  $\langle S, s \rangle \rightarrow s'$  and the leaves are axioms. Every inner node is a transition which is a consequence of its children. We define  $\langle S, s \rangle \rightarrow s'$  if the sequent has a deductive tree.

The deductive tree will be written with the root on the bottom. For example, let  $s_0$  be the state such that  $x \mapsto 5$  and  $y \mapsto 7$ , define  $s_1 = s_0[z \mapsto 5]$ ,  $s_2 = s_1[x \mapsto 7]$ , and  $s_3 = s_2[y \mapsto 5]$ . We claim that  $\langle (z := x; x := y); y := z, s_0 \rangle \rightarrow s_3$ .

$$\frac{\frac{\langle z := x, s_0 \rangle \rightarrow s_1 \quad \text{ass} \quad \langle x := y, s_1 \rangle \rightarrow s_2 \quad \text{ass}}{\langle z := x; x := y, s_0 \rangle \rightarrow s_2} \text{comp} \quad \langle y := z, s_2 \rangle \rightarrow s_3 \quad \text{ass}}{\langle (z := x; x := y); y := z, s_0 \rangle \rightarrow s_3} \text{comp}$$

### 1.6 Definition

We say that two statements  $S_1, S_2$  are **semantically equivalent** if for every two states  $s, s'$ ,  $\langle S_1, s \rangle \rightarrow s'$  if and only if  $\langle S_2, s \rangle \rightarrow s'$ .

So for example,  $S$  is semantically equivalent to  $S; \text{skip}$  for every  $S \in \mathbf{Stm}$ . We will prove this: suppose  $\langle S, s \rangle \rightarrow s'$  then it has a deductive tree  $T$ , and so

$$\frac{\frac{T}{\langle s, s \rangle \rightarrow s'} \quad \langle \text{skip}, s' \rangle \rightarrow s' \quad \text{skip}}{\langle s; \text{skip}, s \rangle \rightarrow s'}$$

So we have that  $\langle S; \text{skip}, s \rangle \rightarrow s'$ . Now suppose the converse, but its deductive tree must end with

$$\frac{\frac{T}{\langle s, s \rangle \rightarrow s'} \quad \langle \text{skip}, s' \rangle \rightarrow s' \quad \text{skip}}{\langle s; \text{skip}, s \rangle \rightarrow s'}$$

and so  $\langle S, s \rangle \rightarrow s'$ . ■

In general if we want to prove something about the transition relation, we can induct on the shape of derivation trees: first we prove it for all simple derivation trees (which have a single axioms); then for each rule, assume the property holds for its premises and then show it holds for the conclusion of the rule.

### 1.7 Theorem

If  $\langle S, s \rangle \rightarrow s'$  and  $\langle S, s \rangle \rightarrow s''$  then  $s' = s''$ .

**Proof:** first we prove it for simple derivation trees, which are formed from  $[\text{ass}_{\text{ns}}]$  or  $[\text{skip}_{\text{ns}}]$ . Then we proceed to the other rules.

- (1)  $[\text{ass}_{\text{ns}}]$ : suppose  $S$  is  $x := a$  and then  $s'$  is  $s[x \mapsto \mathcal{A}[a]s]$ , which is unique ( $s''$  must also be this).
- (2)  $[\text{skip}_{\text{ns}}]$ :  $S$  is  $\text{skip}$  and so  $s' = s$ .
- (3)  $[\text{comp}_{\text{ns}}]$ : assume  $\langle S_1; S_2, s \rangle \rightarrow s'$  holds because  $\langle S_1, s \rangle \rightarrow s_0$  and  $\langle S_2, s_0 \rangle \rightarrow s'$  for some  $s_0$ . The only rule which can be applied to get  $\langle S_1; S_2, s \rangle \rightarrow s''$  is  $[\text{comp}_{\text{ns}}]$ , so there is a state  $s_1$  such that  $\langle S_1, s \rangle \rightarrow s_1$  and  $\langle S_2, s_1 \rangle \rightarrow s''$ . But by induction,  $s_1 = s_0$  and then applying induction again,  $s' = s''$ .
- (4)  $[\text{if}_{\text{ns}}^{\text{tt}}]$ : assume that  $\langle \text{if } b \text{ then } S_1 \text{ else } S_2, s \rangle \rightarrow s'$  holds because  $\mathcal{B}[b]s = tt$  and  $\langle S_1, s \rangle \rightarrow s'$ . Since  $\mathcal{B}[b]s = tt$ , the only rule which can be applied to get  $\langle \text{if } b \text{ then } S_1 \text{ else } S_2, s \rangle \rightarrow s''$  is  $[\text{if}_{\text{ns}}^{\text{tt}}]$ , so  $\langle S_1, s \rangle \rightarrow s''$ , and by induction  $s' = s''$ .
- (5)  $[\text{if}_{\text{ns}}^{\text{ff}}]$ : similar.
- (6)  $[\text{while}_{\text{ns}}^{\text{tt}}]$ : assume that  $\langle \text{while } b \text{ do } S, s \rangle \rightarrow s'$  because  $\mathcal{B}[b]s = tt$ ,  $\langle S, s \rangle \rightarrow s_0$ , and  $\langle \text{while } b \text{ do } S, s_0 \rangle \rightarrow s'$  for some  $s_0$ . The only rule which could be applied to get  $\langle \text{while } b \text{ do } S, s \rangle \rightarrow s''$  is  $[\text{while}_{\text{ns}}^{\text{tt}}]$  in lieu of

#### 4 *Semantics of Expressions*

$\mathcal{B}[[b]]s = tt$ . So there exists a  $s_1$  such that  $\langle S, s \rangle \rightarrow s_1$  and  $\langle \text{while } b \text{ do } S, s_1 \rangle \rightarrow s'$ . But then by induction  $s_0 = s_1$  and by induction again,  $s' = s''$ .

(7)  $[\text{while}_{\text{ns}}^{\text{ff}}]$ : straightforward. ■

Note that not every statement can derive a state: for example **while true do skip** has an infinite derivation tree and thus derives no state (for any initial state  $s$ ). Thus we could define  $\langle \cdot, \cdot \rangle$  to be a partial function

$$\langle \cdot, \cdot \rangle : \mathbf{Stm} \longrightarrow (\mathbf{State} \hookrightarrow \mathbf{State})$$

which accepts a statement and a state and returns the state which it derives, if it exists.

## 2 Untyped Lambda Calculus

Lambda calculus is a way of formalizing computations, it generalizes the concept of functions. A function in lambda calculus has the form  $\lambda x.t$  and should be thought of a function  $x \mapsto t(x)$ , in a language like OCaml, this corresponds to a function definition of the form `fun x → t`. It is built from syntax, and we then utilize semantics to give this syntax meaning.

### 2.1 Definition

Let  $V$  be an infinite set of variable symbols, then terms in lambda calculus are constructed recursively as follows:

- (1) every variable is an term,
- (2) if  $x \in V$  is a variable and  $t$  is an term, then  $\lambda x.t$  is an term,
- (3) if  $t_1$  and  $t_2$  are terms, then so is  $t_1 t_2$ .

Notice that lambda calculus terms have the *unique reconstruction property*: every term  $t$  has one of the above forms, and such a form is *unique*. We can then construct functions on lambda terms via term recursion, as given by the following examples.

### 2.2 Definition

Given an term of the form  $\lambda x.t$ , every instance of  $x$  in the term  $t$  is called **bound**, and all other instances are **free**. Formally we can define the set of free variables in an term recursively as follows:

- (1) for an term of the form  $x$  for a variable  $x$ ,  $\text{var}(x) = \{x\}$ ,  $\text{free}(x) = \{x\}$ ,  $\text{bnd}(x) = \emptyset$ ,
- (2) for an term of the form  $\lambda x.t$ ,  $\text{var}(\lambda x.t) = \text{var}(t) \cup \{x\}$ ,  $\text{free}(\lambda x.t) = \text{free}(t) \setminus \{x\}$ , and  $\text{bnd}(\lambda x.t) = \text{bnd}(t) \cup \{x\}$ ,
- (3) for an term of the form  $t_1 t_2$ ,  $\text{var}(t_1 t_2) = \text{var}(t_1) \cup \text{var}(t_2)$ ,  $\text{free}(t_1 t_2) = \text{free}(t_1) \cup \text{free}(t_2)$  and  $\text{bnd}(t_1 t_2) = \text{bnd}(t_1) \cup \text{bnd}(t_2)$ .

Alternatively, a **bound occurrence** of a variable  $x$  in  $t$  is an occurrence which occurs in  $t'$  where  $\lambda x.t'$  is a subterm of  $t$ . A **free occurrence** is an occurrence which is not bound. Then  $\text{free}(t)$  is the set of all variables which occur free in  $t$ ,  $\text{bnd}t$  is the set of all variables which occur bound in  $t$ .

So for example, let  $t = (\lambda x.\lambda y.x) x z$ , then  $\text{var}(t) = \{x, y, z\}$ ,  $\text{free}(t) = \{x, z\}$ ,  $\text{bnd}(t) = \{x, y\}$ . Here the  $x$  and  $y$  in  $\lambda x.\lambda y.x$  are bound occurrences, and the  $x$  and  $z$  following it (in  $x z$ ) are free. Notice that always  $\text{var}(t) = \text{free}(t) \cup \text{bnd}(t)$ , but as the above example shows, these two sets are not always disjoint. A proof of this union is done via term induction: prove it for  $t = x$ , then for  $t = \lambda x.t'$ , then finally for  $t = t_1 t_2$ .

- (1) for  $t = x$ ,  $\text{var}(t) = \{x\}$ ,  $\text{free}(t) = \{x\}$ , and  $\text{bnd}(t) = \emptyset$ , so the union holds.
- (2) for  $t = \lambda x.t'$ ,  $\text{var}(t) = \text{var}(t') \cup \{x\}$  which by induction is equal to  $\text{free}(t') \cup \text{bnd}(t') \cup \{x\}$ . Now  $\text{free}(t) = \text{free}(t') \setminus \{x\}$ ,  $\text{bnd}(t) = \text{bnd}(t') \cup \{x\}$  and so we see that  $\text{free}(t) \cup \text{bnd}(t) = \text{var}(t)$  as required.
- (3) for  $t = t_1 t_2$ ,  $\text{var}(t) = \text{var}(t_1) \cup \text{var}(t_2)$  which by induction is  $\text{free}(t_1) \cup \text{free}(t_2) \cup \text{bnd}(t_1) \cup \text{bnd}(t_2) = \text{free}(t) \cup \text{bnd}(t)$ .

### 2.3 Definition

An term without free variables is called a **combinator**. The **identity combinator** is the combinator  $\text{id} = \lambda x.x$ .

Suppose we'd like to take a term  $t$  and substitute  $x$  with another term  $t'$ . For example, suppose  $t'$  is the variable  $z$ , then  $\lambda y.x$  should become  $\lambda y.z$ . But then what should  $\lambda x.x$  become? Surely not  $\lambda x.z$ , as that alters the entire interpretation of the function. So variables should be substituted only at free occurrences. But what about if  $t'$  were  $x$  and  $t$  was  $\lambda x.y$ , then substituting at  $y$  gives  $\lambda x.x$ , which once again changes the meaning of

the function. So we should only substitute at free occurrences, if the  $\lambda$ -variable is not free in the term being substituted.

### 2.4 Definition

Let  $t, t'$  be terms and  $x$  a variable. Then  $t[x \mapsto t']$  is the term obtained by substituting  $x$  with  $t'$  according to the following rules:

- (1)  $x[x \mapsto t'] = t'$ ,
- (2)  $y[x \mapsto t'] = y$  if  $y$  is a variable distinct from  $x$ ,
- (3)  $(\lambda x.t)[x \mapsto t'] = \lambda x.t$ ,
- (4)  $(\lambda y.t)[x \mapsto t'] = \lambda y.(t[x \mapsto t'])$  if  $y \neq x$  and  $y \notin \text{free}(t')$ ,
- (5)  $(t_1 t_2)[x \mapsto t'] = t_1[x \mapsto t'] t_2[x \mapsto t']$ .

But then what would the substitution  $(\lambda y.x y)[x \mapsto y z]$  look like? Well  $y$  is free in the substituted term, so it doesn't match any of the above conditions. In such a case we take upon ourselves the following convention:

### Convention ( $\alpha$ -equivalence)

Terms that differ only in the named of bound variables are equivalent.

This means that we can view  $\lambda y.x y$  as  $\lambda w.x w$  and so the substitution becomes  $\lambda w.y z w$ . The rules for  $\alpha$ -equivalence is that if  $\lambda x.t$  is equivalent to  $\lambda y.t[x \mapsto y]$  if  $y \notin \text{var } t$ .

### 2.5 Definition

A term of the form  $(\lambda x.t)t'$  is called a **redex**. A term of the form  $\lambda x.t$  is called a **abstraction**. We define the  $\beta$  **reduction** on terms which maps redexes to terms by  $(\lambda x.t)t' \xrightarrow{\beta} t[x \mapsto t']$  where  $t[x \mapsto t']$  is the term obtained by substituting  $t'$  at all the free occurrences of  $x$ . A **value** is an abstraction or variable.

For example,  $(\lambda x.x)y \rightarrow y$ , and

$$(\lambda x.(\lambda x.x)x)(u r) \rightarrow (\lambda x.x)(u r) = u r$$

When performing a  $\beta$ -reduction, we need to consider the order with which we perform the reduction. There are 4 ways:

- (1) *Full  $\beta$ -reduction*, in which any redex can be reduced at any time. So at each step, we can arbitrarily choose a redex and reduce it. For example, take

$$(\lambda x.x) ((\lambda x.x) (\lambda z.(\lambda x.x) z))$$

which is just  $\text{id}(\text{id}(\lambda z.\text{id } z))$ . This term contains three redexes:

$$\text{id}(\text{id}(\lambda z.\text{id } z)), \quad \text{id}(\text{id}(\lambda z.\text{id } z)), \quad \text{id}(\text{id}(\lambda z.\text{id } z))$$

So we can choose for example to begin from the innermost redex and move outward:

$$\begin{aligned} & \text{id}(\text{id}(\lambda z.\text{id } z)) \\ \rightarrow & \text{id}(\text{id}(\lambda z.z)) \\ \rightarrow & \text{id}(\lambda z.z) \\ \rightarrow & \lambda z.z \end{aligned}$$

which cannot be reduced any more.

- (2) *Normal order*, in which the leftmost outermost redex is reduced first. So using the same example as above:

$$\begin{aligned} & \text{id}(\text{id}(\lambda z.\text{id } z)) \\ \rightarrow & \text{id}(\lambda z.\text{id } z) \\ \rightarrow & \lambda z.\text{id } z \\ \rightarrow & \lambda z.z \end{aligned}$$

The rules for normal order reduction are as follows:

$$\frac{}{(\lambda x.t)s \rightarrow t[x \mapsto s]} \quad , \quad \frac{t \rightarrow t'}{ts \rightarrow t's} \text{ if } t \text{ is not a value} \quad , \quad \frac{t \rightarrow t'}{\lambda x.t \rightarrow \lambda x.t'} \text{ if } t \text{ is not a value}$$

- (3) *Call-by-name*, which is similar to normal order but it performs no reductions inside abstractions. Using the same example:

$$\begin{aligned} & \text{id}(\text{id}(\lambda z.\text{id}z)) \\ \rightarrow & \text{id}(\lambda z.\text{id}z) \\ \rightarrow & \lambda z.\text{id}z \end{aligned}$$

The rules for call-by-name reduction are as follows:

$$\frac{}{(\lambda x.t)s \rightarrow t[x \mapsto s]} \quad , \quad \frac{t \rightarrow t'}{ts \rightarrow t's} \text{ if } t \text{ is not a value}$$

- (4) *Call-by-value*, which is the most commonly used in programming languages, like call-by-name, but a redex is reduced only when its right-hand side has already been reduced to a *value* (a term which cannot be reduced further, in this lambda calculus these are only abstractions).

$$\begin{aligned} & \text{id}(\text{id}(\lambda z.\text{id}z)) \\ \rightarrow & \text{id}(\lambda z.\text{id}z) \\ \rightarrow & \lambda z.\text{id}z \end{aligned}$$

The rules for call-by-value reduction are

$$\begin{aligned} & \frac{}{(\lambda x.t)v \rightarrow t[x \mapsto v]} \text{ if } v \text{ is a value} \quad , \quad \frac{s \rightarrow s'}{(\lambda x.t)s \rightarrow (\lambda x.t)s'} \text{ if } s \text{ is not a value} \quad , \\ & \frac{t \rightarrow t'}{ts \rightarrow t's} \text{ if } t \text{ is not a value} \end{aligned}$$

In this course we use call-by-value, since it is the most commonly used evaluation strategy.

Notice that in lambda calculus, all functions accept a single parameter as input. As in OCaml, to write a function which accepts multiple functions, we write one which accepts a single input and returns a function which also accepts a single input. So for example  $f = \lambda x.\lambda y.x$  can then be called like  $f\ u\ r$  and will return  $u$  after two  $\beta$ -reductions.

We now define booleans in lambda calculus (called Church booleans):

$$\text{tru} = \lambda t.\lambda f.t, \quad \text{fls} = \lambda t.\lambda f.f$$

So **tru** accepts two arguments and returns the first, **fls** accepts two and returns the second. We now define

$$\text{test} = \lambda b.\lambda m.\lambda n.b\ m\ n$$

So **test** accepts three arguments, the first  $b$  is a boolean (either **tru** or **fls**), and it applies it to the other two arguments. So for example

$$\text{test}\ \text{tru}\ v\ w = (\lambda b.\lambda m.\lambda n.b\ m\ n)\text{tru}\ v\ w \rightarrow (\lambda m.\lambda n.\text{tru}\ m\ n)v\ w \rightarrow (\lambda n.\text{tru}\ v\ n)w \rightarrow \text{tru}\ v\ w \rightarrow v$$

This doesn't do much, it just returns the first argument (after the boolean) if the boolean is true, and the second if it is false.

We can define a more interesting combinator

$$\text{and} = \lambda b.\lambda c.b\ c\ \text{fls}$$

Here  $b, c$  are booleans. Then if  $b$  is **tru**, **and**  $b\ c \rightarrow c$  after a  $\beta$ -reduction, and otherwise it will reduce to  $c$ . So if  $c$  is false, then **and**  $b\ c \rightarrow c = \text{fls}$  and if  $c$  is true then it reduces to  $c = \text{tru}$ , and if  $b$  is false then **and**  $b\ c \rightarrow b\ c\ \text{fls} \rightarrow \text{fls}$ . So **and** functions as one would expect it to.

Utilizing booleans, we can encode pairs of values as terms:

$$\begin{aligned} \text{pair} &= \lambda f.\lambda s.\lambda b.b\ f\ s \\ \text{fst} &= \lambda p.p\ \text{tru} \\ \text{snd} &= \lambda p.p\ \text{fls} \end{aligned}$$

Notice then that



$$\begin{aligned}
& \text{fst}(\text{pair } v \ w) \\
= & \text{fst}((\lambda f. \lambda s. \lambda b. b \ f \ s) \ v \ w) && \text{by definition} \\
\rightarrow & \text{fst}((\lambda s. \lambda b. b \ v \ s) \ w) && \beta\text{-reduction on underlined redex} \\
\rightarrow & \text{fst}(\lambda b. b \ v \ w) && \beta\text{-reduction on underlined redex} \\
= & (\lambda p. p \ \text{tru})(\lambda b. b \ v \ w) && \text{by definition} \\
\rightarrow & (\lambda b. b \ v \ w) \text{tru} && \beta\text{-reduction on underlined redex} \\
\rightarrow & \text{tru } v \ w && \beta\text{-reduction on underlined redex} \\
\rightarrow & v && \text{by definition of tru}
\end{aligned}$$

In a similar manner we can show that  $\text{snd}(\text{pair } v \ w) \rightarrow w$ .

We now demonstrate how we can represent numbers in lambda calculus, via Church numerals:

$$\begin{aligned}
c_0 &= \lambda s. \lambda z. z \\
c_1 &= \lambda s. \lambda z. s \ z \\
c_2 &= \lambda s. \lambda z. s(s \ z) \\
c_3 &= \lambda s. \lambda z. s(s(s \ z)) \\
&\text{etc.}
\end{aligned}$$

In general if we write  $s^n z$  for  $s(s(\dots s \ z \dots))$  ( $n$  times), then  $c_n = \lambda s. \lambda z. s^n \ z$ . So each number  $n$  is represented by the combinator  $c_n$  which accepts  $s, z$  and applies  $s$   $n$  times to  $z$ . Notice that  $c_0 = \text{fls}$ , which is reminiscent of the fact that false and zero mean the same thing in many compiled languages.

Let us define

$$\text{scc} = \lambda n. \lambda s. \lambda z. s(n \ s \ z)$$

We see then that

$$\text{scc } c_n \ s \ z = \lambda s. \lambda z. s(c_n \ s \ z) \ s \ z = s(s^n \ z) = s^{n+1} \ z = c_{n+1} \ z \ s$$

so  $\text{scc } c_n$  and  $c_{n+1}$  are equivalent in the sense that they operate the same on the same input. But bare in mind:  $\text{scc } c_n = \lambda s. \lambda z. s(c_n \ s \ z)$  which is not *equal* to  $c_{n+1}$ .

Similarly we can define

$$\text{plus} = \lambda n. \lambda m. \lambda s. \lambda z. m \ s \ (n \ s \ z)$$

so that  $\text{plusn } m \ s \ z$  will apply  $s$   $n$  times to  $z$ , resulting in  $s^m s^n z = s^{n+m} z$  as desired. Similarly we define

$$\text{times} = \lambda n. \lambda m. m \ (\text{plus } n) \ c_0$$

so that  $\text{times } n \ m$  will apply  $\text{plusn } m$  times to  $c_0$ , resulting in  $n + n + \dots + n + 0 = n \cdot m$ . In a similar vein, we can define  $\text{pow} = \lambda n. \lambda m. m \ (\text{times } n) \ c_1$ , so that  $\text{pow } c_n \ c_m$  is equal to  $c_{n^m}$ .

To test if a numeral is zero, we'd like to find a functions  $\text{ss}$  and  $\text{zz}$  such that applying  $\text{ss}$  one or more times to  $\text{zz}$  yields false, while not applying it at all yields true. That way when we do  $c_n \ \text{ss} \ \text{zz}$ , it will result in  $\text{tru}$  only if  $\text{ss}$  was never applied, meaning  $n = 0$ . Necessarily then  $\text{zz}$  must be  $\text{tru}$ , and have  $\text{ss}$  be the function which maps every input to  $\text{fls}$ . So we define

$$\text{iszro} = \lambda n. n \ (\lambda x. \text{fls}) \ \text{tru}$$

To define the predecessor combinator, we must be a bit more clever than with the successor. One implementation is

$$\begin{aligned}
\text{zz} &= \text{pair } c_0 \ c_0 \\
\text{ss} &= \lambda p. \text{pair}(\text{snd } p)(\text{plus } 1 \ (\text{snd } p)) \\
\text{prd} &= \lambda m. \text{fst}(m \ \text{ss} \ \text{zz})
\end{aligned}$$

The idea here is that applying  $\text{ss}$  to a  $(n, m)$  will result in  $(m, m + 1)$ . So starting from  $(0, 0)$ , you get  $(0, 1)$  then  $(1, 2)$  then  $(2, 3)$  and so on. In general  $\text{ss}^n z = (n - 1, n)$  for  $n \geq 1$  and so the predecessor is just the first value.

Using the predecessor combinator we can define a subtraction combinator similar to addition:

$$\text{sub} = \lambda m. \lambda n. m \ \text{prdn}$$

Notice though that  $\text{sub}$  cannot give negative numbers, after all we didn't define negative numbers, so if  $n \leq m$  then  $c_n - c_m$  is just  $c_0$ . Thus we can define

$$\begin{aligned}
\text{leq} &= \lambda m. \lambda n. \text{iszro}(\text{sub } m \ n) \\
\text{equal} &= \lambda m. \lambda n. \text{and}(\text{leq } n \ m) \ (\text{leq } m \ n)
\end{aligned}$$

## 2.6 Definition

A term without a redex is called a **normal form**. The normal form of a term  $t$  is the normal form obtained through  $\beta$  reduction. A term without a normal form is called **divergent**.

For example, the normal form of  $(\lambda x. \lambda y. x)y$  can be reduced to  $\lambda y. y$  which is its normal form. One example of a divergent combinator is

$$\text{omega} = (\lambda x. x \ x) (\lambda x. x \ x)$$

Since a single  $\beta$  reduction gives you back  $\omega$ , which gives what is essentially an infinite loop. We can also define the following combinator

$$\text{fix} = \lambda f. (\lambda x. f(\lambda y. x \ x \ y)) \ (\lambda x. f(\lambda y. x \ x \ y))$$

Suppose we'd like to write a function to compute factorials, which can be written as

```
if n=0 then 1
else n * factorial(n-1)
```

The idea is to unravel the function definition, to get something of the form

```

if n=0 then 1
else n * (if n-1=0 then 1
           else (n-1) * (if n-2=0 then 1
                           else (n-2) * ...))

```

Using Church numerals, we get

```
test (equal n c0)
  c1
  times n (test (equal (prd n) c0)
    c1
    times (prd n) (test (equal (prd (prd n)) c0)
      c1
      times (prd (prd n)) (...)))
```

Then we define

```
g = \fct.\lambda n. test (equal n c0) c1 (times n (fct (prd n)))
factorial = fix g
```

Let us give an example run of `factorial c3`:

```

factorial c3
= fix g c3
→ h h c3                                where h=λx.g(λy.x x y)
→ g fct c3                             where fct=λy. h h y
→ (λn. test(equal n c0) c1 (times n (fct (prd n))))c3
→ test(equal c3 c0) c1 (times c3 (fct (prd c3)))
→ times c3 (fct (prd c3))
→ times c3 (fct c2)
→ times c3 (h h c2)
→ times c3 (g fct c2)                   similar to how h h c3 can be reduced to g fct c3
→ times c3 (times c2 (g fct c1))       by the same process that we did for c3
→ times c3 (times c2 (times c1 (g fct c0)))
→ times c3 (times c2 (times c1 (test (equal c0 c0) c1 ...)))
→ times c3 (times c2 (times c1 c1))
→ c6

```

Let us prove that this works. Suppose we have a recurrence  $r = \lambda x. \langle \text{code with } r \rangle$ , let us use the notation  $\langle r \ c \rangle$  to mean that within the recurrence,  $r$  is called on the value  $c$ . Let us define  $g = \lambda r. \lambda x. \langle \text{code with } r \rangle$ , which is like  $r$  but it accepts the function it should run on. So if we were to define  $r$ , then  $r$  and  $g \ r$  would be functionally the same. We claim then that  $r = \text{fix } g$  is a term which is equivalent to  $r$  (does the same thing). Let us reduce it a bit on some term  $c$

$$\begin{array}{ll} & \text{r c} \\ = & \text{fix g c} \\ \rightarrow & \text{h h c} \quad \text{where h} = \lambda x. g(\lambda y. x \ x \ y) \\ \rightarrow & \text{g r' c} \quad \text{where r'} = \lambda v. \text{h h v} \end{array}$$

Now we claim that  $\mathbf{g} \ \mathbf{r}' \ \mathbf{c}$  gives the same result as  $\mathbf{r} \ \mathbf{c}$ , which we will prove on the number of recursive calls that  $\mathbf{r} \ \mathbf{c}$  makes. If we were to reduce this one more time, we'd get  $\langle \text{code with } \mathbf{r}' \rangle \ \mathbf{c}$ , but since  $\mathbf{r}$  makes no recursive calls on the input  $\mathbf{c}$ , this functions the same as  $\langle \text{code with } \mathbf{r} \rangle \ \mathbf{c}$ , which is  $\mathbf{r} \ \mathbf{c}$ . Now, suppose that on the first recursive call, the program calls  $\mathbf{r}' \ \mathbf{c}'$ , meaning for  $\mathbf{r}$  it would call  $\mathbf{r} \ \mathbf{c}'$ . Now  $\mathbf{r}' \ \mathbf{c}' = \mathbf{h} \ \mathbf{h} \ \mathbf{c}' = \mathbf{g} \ \mathbf{r}' \ \mathbf{c}'$ , and by our inductive hypothesis  $\mathbf{g} \ \mathbf{r}' \ \mathbf{c}' = \mathbf{r} \ \mathbf{c}'$ , so the code performs the same.

We can also define the *Y-combinator*:

$$Y = \lambda f. (\lambda x. f(x\ x)) (\lambda x. f(x\ x))$$

Which can similarly perform recursion. Like `fix`, it is a *fixed-point* combinator, which is a combinator `fix` such that  $f(\text{fix}f) = \text{fix}f$ . Indeed:

$$\begin{aligned} Y\ g &= (\lambda f. (\lambda x. f(x\ x)) (\lambda x. f(x\ x)))\ g && \text{by definition} \\ \rightarrow (\lambda x. g(x\ x)) (\lambda x. g(x\ x)) && \text{by } \beta\text{-reduction} \\ \rightarrow g((\lambda x. g(x\ x)) (\lambda x. g(x\ x))) && \text{by } \beta\text{-reduction} \\ = g(Y\ g) && \text{by the second equality} \end{aligned}$$

Though the final equality is only true up to  $\beta$ -reduction, meaning that  $Y\ g$  and  $g(Y\ g)$  both reduce to a similar term, not to one another. This is the trait which allows for recursion.

### 3 Simply Typed Lambda Calculus

#### 3.1 Definition

We define **types** in our simply typed lambda calculus recursively as follows:

- (1) `Bool` is a type,
- (2) if  $T_1, T_2$  are types, so is  $T_1 \rightarrow T_2$ .

Here  $\rightarrow$  is right-associative, meaning  $T_1 \rightarrow T_2 \rightarrow T_3$  is taken to mean  $T_1 \rightarrow (T_2 \rightarrow T_3)$ .

#### 3.2 Definition

We define terms once again recursively:

- (1) every variable is a term,
- (2) if  $x$  is a variable,  $t$  a term, and  $T$  a type, then  $\lambda x:T.t$  is a term (here the type refers to the variable, we will explain later),
- (3) if  $t_1, t_2$  are terms then so is  $t_1 t_2$ ,
- (4) `true`, `false` are terms,
- (5) if  $t_1, t_2, t_3$  are terms, then so is `if  $t_1$  then  $t_2$  else  $t_3$` .

Let us define `id` =  $\lambda x:\text{Bool}.x$ , then `id` is a term.

#### 3.3 Definition

We define  $\beta$ -reduction on simply typed redexes as follows:

- (1)  $(\lambda x:T.t)t' \xrightarrow{\beta} t[x \mapsto t']$ ,
- (2) `if true then  $t_1$  else  $t_2$`   $\xrightarrow{\text{hello there}}$   $t_1$ ,
- (3) `if false then  $t_1$  else  $t_2$`   $\xrightarrow{\beta}$   $t_2$ .

So for example, let `f` =  $\lambda x:\text{Bool} \rightarrow \text{Bool}.\lambda y:\text{Bool}.x y$ , then

<code>f id true</code>	
$= (\lambda x:\text{Bool} \rightarrow \text{Bool}.\lambda y:\text{Bool}.x y)\text{id true}$	definition
$\rightarrow (\lambda y:\text{Bool}.\text{id } y) \text{ true}$	$\beta$ -reduction on the underlined redex
$\rightarrow \text{id true}$	$\beta$ -reduction on the underlined redex
$\rightarrow \text{true}$	$\beta$ -reduction on the underlined redex

And

<code>f true id</code>	
$= (\lambda x:\text{Bool} \rightarrow \text{Bool}.\lambda y:\text{Bool}.x y)\text{true id}$	definition
$\rightarrow (\lambda y:\text{Bool}.\text{true } y) \text{ id}$	$\beta$ -reduction on the underlined redex
$\rightarrow \text{true id}$	$\beta$ -reduction on the underlined redex

We'd like to assign to terms a type. Suppose  $\Gamma$  is a set containing elements of the form  $x:T'$  where  $x$  ranges over all the variables (and each variable occurs only once), then we write  $\Gamma \vdash t:T$  to mean that if we assume  $\Gamma$  then  $t$  has the type  $T$ . If  $\Gamma$  is a such a set, we write  $\Gamma, t':T'$  to mean  $\Gamma \cup \{t':T'\}$ , and instead of  $\emptyset \vdash t:T$  we write  $\vdash t:T$ . We utilize Gentzen-style rules to form a deductive system for deducing the type of an abstraction. The first rule is for abstractions,

$$\frac{\Gamma, x:T \vdash t:T'}{\Gamma \vdash \lambda x:T.t : T \rightarrow T'} \quad (\text{T-ABS})$$

This just means that if we assume  $x$  has type  $T$  then  $t$  has type  $T'$ , then we can conclude that  $\lambda x:T.t$  has type  $T \rightarrow T'$ . Suppose for example we take the language C, and we set `t` = `x+x`, then if `x:float` we can conclude that `t:float` as well, so  `$\lambda x:\text{float}.x+x$`  has type `float  $\rightarrow$  float`. But if  $x$  is of type `int`, then `t` is of the same type

and  $\lambda x:\text{int}.x+x$  has type  $\text{int} \rightarrow \text{int}$ . Importantly, these examples are given to give some intuition for the rule, they are not valid  $\lambda$ -terms!

Obviously if  $x:T$  is already in  $\Gamma$  then  $\Gamma$  should deduce  $x:T$ :

$$\frac{x:T \in \Gamma}{\Gamma \vdash x:T} \quad (\text{T-VAR})$$

We also need a rule for applications:

$$\frac{\Gamma \vdash t:T' \rightarrow T \mid \Gamma \vdash t':T'}{\Gamma \vdash t \ t':T} \quad (\text{T-APP})$$

Which means that if  $t$  is a function  $T' \rightarrow T$  and  $t'$  has type  $T'$ , then the application  $t \ t'$  has type  $T$ . And for conditionals

$$\frac{\Gamma \vdash t_1:\text{Bool} \mid \Gamma \vdash t_2:T \mid \Gamma \vdash t_3:T}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T} \quad (\text{T-IF})$$

And of course **true** and **false** are Boolean types:

$$\frac{}{\Gamma \vdash \text{true} : \text{Bool}}, \quad \frac{}{\Gamma \vdash \text{false} : \text{Bool}} \quad (\text{T-TRUE}), (\text{T-FALSE})$$

Let us now show that  $\vdash \lambda x:\text{Bool}. \text{if } x \text{ then true else } x : \text{Bool} \rightarrow \text{Bool}$ . We form a deductive tree:

$$\frac{\frac{\frac{x:\text{Bool} \vdash x:\text{Bool} \quad \text{T-VAR} \quad x:\text{Bool} \vdash \text{true} : \text{Bool} \quad \text{T-TRUE} \quad x:\text{Bool} \vdash \text{false} : \text{Bool} \quad \text{T-FALSE}}{x:\text{Bool} \vdash \text{if } x \text{ then true else } x \quad \text{T-IF}}}{\vdash \lambda x:\text{Bool}. \text{if } x \text{ then true else } x : \text{Bool} \rightarrow \text{Bool}} \quad \text{T-ABS}$$

### 3.4 Definition

A term  $t$  is **well-typed** if its type can be deduced from the empty set, ie.  $\vdash t:T$  for some  $T$ .

### 3.5 Definition

A term of the form **true**, **false**, or  $\lambda x:T. t$  (an abstraction) is called a **value**.

### 3.6 Lemma (Progress Lemma)

If  $t$  is a closed (meaning it has no free variables) well-typed term. Then  $t$  is either a value or there is some  $t'$  with  $t \rightarrow t'$  through a step of  $\beta$ -reduction.

**Proof:** if  $t$  is a boolean or an abstraction, then it is a value. Otherwise  $t = \text{if } t_1 \text{ then } t_2 \text{ else } t_3$ , then  $t$  is closed if and only if all  $t_i$  are and by the derivation rule  $t_1:\text{Bool}$  which means that  $t_1$  must be a Boolean, and so  $t$  can be reduced. Finally if  $t = t_1 \ t_2$  then  $t$  is closed and well-typed, then  $t_1:T' \rightarrow T$  and  $t_2:T'$ , which means that  $t_1$  is either a value or can be reduced, likewise for  $t_2$ . If either can be reduced, then so too can  $t$  (since if  $t \rightarrow t_0$  then  $t \ t' \rightarrow t_0 \ t'$  and similar for  $t'$ ). If both are values, then  $t_1$  is of the form  $\lambda x.t_{11}$  and so it can be applied to a value and reduced. ■

### 3.7 Lemma (Substitution Lemma)

If  $\Gamma, x:T' \vdash t:T$  and  $\Gamma \vdash t':T'$ , then  $\Gamma \vdash t[x \mapsto t']:T$ .

**Proof:** by induction on the derivation of  $\Gamma, x:T' \vdash t:T$ .

- (1) T-VAR: so  $t = z$  and  $z:T \in \Gamma, x:T'$ . If  $z = x$  then  $t = z = x$ , so  $T = T'$  and  $t[x \mapsto t'] = t'$ . We must prove that  $\Gamma \vdash t':T$ , but we know that  $t':T' = T$  so this holds. If  $z \neq x$  then  $t[x \mapsto t'] = z$  and this is satisfied trivially.
- (2) T-ABS: then  $t = \lambda y:T_2. t_1$ ,  $T = T_2 \rightarrow T_1$ , and  $\Gamma, x:T' \vdash \lambda y:T_2. t_1:T$  so that  $\Gamma, x:T', y:T_2 \vdash t_1:T_1$ . We may assume by convention that  $x \neq y$  and that  $y$  is not free in  $t'$ . Since  $\Gamma \vdash t':T'$ , we get  $\Gamma, y:T_2 \vdash t':T'$ , and so by the induction hypothesis  $\Gamma, y:T_2 \vdash t[x \mapsto t']:T_1$ . By T-ABS, we get  $\Gamma \vdash \lambda y.T_2. t_1[x \mapsto t']:T$ , but  $\lambda y.T_2. t_1[x \mapsto t'] = (\lambda y.T_2. t_1)[x \mapsto t'] = t[x \mapsto t']$  as required.

- (3) T-TRUE and T-FALSE are immediate since  $t = \text{true}$  or  $\text{false}$  and  $T = \text{Bool}$  and so  $t[x \mapsto t'] = t$ .
- (4) T-IF is straightforward. ■

### 3.8 Theorem (Preservation Theorem)

If  $\Gamma \vdash t : T$  and  $t \rightarrow t'$  by  $\beta$ -reduction, then  $\Gamma \vdash t' : T$ .

**Proof:** suppose  $t = (\lambda x : T_1. t_1) t_2 : T_2$  then let us look at the derivation of  $t$ :

$$\frac{\frac{\Gamma, x : T_1 \vdash t_1 : T_2}{\Gamma \vdash \lambda x : T_1. t_1 : T_1 \rightarrow T_2} \text{T-ABS} \quad \Gamma \vdash t_2 : T_2}{\Gamma \vdash (\lambda x : T_1. t_1) t_2 : T_2} \text{T-APP}$$

Our goal is to show  $\Gamma \vdash t_1[x \mapsto t_2]$ . But we have that  $\Gamma, x : T_1 \vdash t_1 : T_2$  and  $\Gamma \vdash t_2 : T_2$  which gives us by the substitution lemma precisely this. ■

### 3.9 Definition

A term  $t$  can be **normalized** if there exists a value  $t'$  such that  $t$  can be reduced to  $t'$ .

Our goal is to prove that a closed well-typed term can be normalized. To do so we require some further mechanisms and proofs.

### 3.10 Definition

Let  $T$  be a type, then we define the predicate  $R_T$  on terms recursively as follows:

- (1)  $R_{\text{Bool}}$  is the set of all terms of type  $\text{Bool}$  which can be normalized.
- (2)  $R_{T_1 \rightarrow T_2}$  is the set of all terms  $t$  of type  $T_1 \rightarrow T_2$  that can be normalized and if  $R_{T_1}(s)$  then  $R_{T_2}(ts)$ .

### 3.11 Lemma

Suppose  $\vdash t : T$  and  $t$  can be reduced to  $t'$  then  $R_T(t)$  if and only if  $R_T(t')$ .

**Proof:** by induction on  $T$ . For  $T = \text{Bool}$  then if  $t : \text{Bool}$  and  $t$  can be normalized, so can  $t'$  and  $t' : \text{Bool}$  by the preservation theorem. And if  $t' : \text{Bool}$  then  $t : \text{Bool}$  again by the preservation theorem.

Now suppose  $T = T_1 \rightarrow T_2$ , if  $R_T(t)$  then it is obvious by the preservation theorem that  $t' : T$ . Now let  $R_{T_1}(s)$  then we must show that  $R_{T_2}(t's)$ , but since  $ts \rightarrow t's$  both of their types must be  $T_2$  as required. ■

### 3.12 Corollary

Suppose  $x_1 : T_1, \dots, x_n : T_n \vdash t : T$  and  $v_1, \dots, v_n$  are values of type  $T_i$  such that  $R_{T_i}(v_i)$ . Then for  $t' = t[x_1 \mapsto v_1, \dots, x_n \mapsto v_n]$ ,  $R_T(t')$ .

**Proof:** by induction on the derivation  $x_1 : T_1, \dots, x_n : T_n \vdash t : T$ . For T-VAR this is simply because  $t = x_i$  and  $T = T_i$  for some  $i$ , and the result is immediate. For T-ABS,  $t = \lambda x : S_1. s_2$ ,  $x_1 : T_1, \dots, x_n : T_n, x : S_1 \vdash s_2 : S_2$ , and  $T = S_1 \rightarrow S_2$ .

### 3.13 Theorem

Every closed well-typed term  $t$  can be normalized.

**Proof:** in the book. ■

## 4 $\lambda$ -OCaml

We define a language  $\lambda$ -OCaml similar to untyped  $\lambda$ -calculus as follows:

### 4.1 Definition

Terms in  $\lambda$ -OCaml are defined recursively as follows:

- (1) all variables are terms,
- (2) if  $x$  is a variable and  $t$  a term, then `fun  $x \rightarrow t$`  is a term,
- (3) if  $t_1$  is a term, then  $t_1 \ t_2$  is a term.

This is obviously equivalent to untyped  $\lambda$ -calculus where instead of  $\lambda x.t$  we write `fun  $x \rightarrow t$` . We also define types:

### 4.2 Definition

Suppose we have an infinite set of type variables, then a type is defined recursively as follows:

- (1) all type variables are types,
- (2) if  $T$  and  $S$  are types, so is  $T \rightarrow S$ .

Similar to typed  $\lambda$ -calculus we define the *type relation*  $\Gamma \vdash t : T$  where  $t$  is a term,  $T$  is a type, and  $\Gamma$  is a variable type set of which contains elements of the form  $x : S$  for variables  $x$  and types  $S$ , such that every variable is given a single type. It is a Gentzen calculus defined using the rules:

$$\frac{x : T \in \Gamma}{\Gamma \vdash x : T} \quad (\text{O-VAR})$$

$$\frac{\Gamma \vdash t_{12} : T_1 \rightarrow T_2 \mid \Gamma \vdash t_1 : T_1}{\Gamma \vdash t_{12} t_1 : T_2} \quad (\text{O-APP})$$

$$\frac{\Gamma \vdash x : T \mid \Gamma \vdash t : S}{\Gamma \vdash (\text{fun } x \rightarrow t) : T \rightarrow S} \quad (\text{O-ABS})$$

Notice that this is similar to simply typed  $\lambda$ -calculus except for O-ABS, where instead of viewing what type has  $t$  has under the assumption that  $x$  has type  $T$ , we give them both a type under the plain assumptions in  $\Gamma$ .

### 4.3 Definition

The problem of **type inference** is the problem of finding mapping between terms and types. Its input is a term  $t$ , and its output is a variable type set  $\Gamma$  and a map  $m$  between subterms of  $t$  (including  $t$ ) such that  $\Gamma \vdash t' : m(t')$  for all subterms  $t'$ .

We will solve this problem in three steps: (1) creating a system of equations between types, (2) solving the system, and (3) converting the solution to the appropriate  $\Gamma$  and  $m$ .

### 4.4 Definition

A term  $t$  is called **normalized** if for every two subterms  $t_1 = \text{fun } x \rightarrow t_{11}$  and  $t_2 = \text{fun } y \rightarrow t_{22}$ ,  $x$  and  $y$  are distinct variables.

By  $\alpha$ -equivalence, every term has an equivalent normalized term.

### 4.5 Definition

Let  $t$  be a term, let us define the set of equations  $A_t$  as follows: for every subterm  $t'$  correspond a unique type variable  $\alpha$ , then

- (1) if  $\alpha$  and  $\beta$  correspond to different occurrences of the same subterm, then  $\alpha = \beta \in A_t$ ,
- (2) suppose  $t_1 t_2$  is a subterm such that  $\alpha$  is the variable of  $t_1$ ,  $\beta$  of  $t_2$ , and  $\gamma$  of  $t_1 t_2$ , then  $\alpha = \beta \rightarrow \gamma \in A_t$ ,
- (3) for every subterm **fun**  $x \rightarrow t'$ , if  $\alpha$  is the variable of  $x$ ,  $\beta$  of  $t'$ , and  $\gamma$  of **fun**  $x \rightarrow t'$ , then  $\gamma = \alpha \rightarrow \beta \in A_t$ .

For example, let  $t$  be **(fun**  $x \rightarrow x$ ) $y$ , then let us map the subterms to type variables as follows:

$$y \mapsto \alpha_y, \quad x \mapsto \alpha_x^1, \quad x \mapsto \alpha_x^2, \quad \text{fun } x \rightarrow x \mapsto \alpha_f, \quad t \mapsto \alpha_t$$

Then

$$A_t = \{\alpha_x^1 = \alpha_x^2, \alpha_f = \alpha_x^1 \rightarrow \alpha_x^2, \alpha_f = \alpha_y \rightarrow \alpha_t\}$$

Now that we have finished step (1), we skip step (2) and progress to step (3). We will return to step (2) later.

#### 4.6 Definition

A **substitution** is a function  $\sigma$  which maps between type terms such that  $\sigma(T_1 \rightarrow T_2) = \sigma(T_1) \rightarrow \sigma(T_2)$ .  $\sigma$  **preserves** an equality  $T_1 = T_2$  if  $\sigma(T_1) = \sigma(T_2)$ , and it preserves a set of equations if it preserves every equality in the set.

So in the example above, one such substitution which preserves  $A_t$  is  $\sigma(\alpha_x^1) = \sigma(\alpha_x^2) = \sigma(\alpha_y) = \sigma(\alpha_t) = \alpha$ , and  $\sigma(\alpha_f) = \alpha \rightarrow \alpha$ .

#### 4.7 Definition

Let  $t$  be a term and  $\beta$  a function which maps subterms  $t'$  to their type variables. Suppose  $A_t$  is the resulting set of equations, and  $\sigma$  a substitution which preserves it. Then we define

$$\Gamma_\sigma^\beta = \{x: \sigma(\beta(x)) \mid x \in \text{var } t\}$$

So using the above example where  $\beta$  is the map

$$\beta: \quad y \mapsto \alpha_y, \quad x \mapsto \alpha_x^1, \quad x \mapsto \alpha_x^2, \quad \text{fun } x \rightarrow x \mapsto \alpha_f, \quad t \mapsto \alpha_t$$

Then using the above substitution  $\sigma$ , we have that

$$\Gamma_\sigma^\beta = \{x: \alpha, y: \alpha\}$$

#### 4.8 Theorem

Let  $t$  be a term,  $\beta$  a correspondence between subterms and type variables, and  $\sigma$  a substitution which preserves  $A_t$ . Then for every subterm  $t'$  of  $t$ ,

$$\Gamma_\sigma^\beta \vdash t': \sigma(\beta(t'))$$

Thus if we define  $m := \sigma \circ \beta$  and  $\Gamma := \Gamma_\sigma^\beta$ , we have a solution to the problem of type inference for  $t$ . And if there is no  $\sigma$  which preserves  $A_t$  then there is no solution to the problem of type inference for  $t$ .

**Proof:** by induction on  $t'$ .

- (1) If  $t'$  is a variable then  $t': \sigma(\beta(t'))$  is in  $\Gamma_\sigma^\beta$  and thus this follows from O-VAR.



- (2) If  $t'$  is of the form  $\text{fun } x \rightarrow t''$ , then let  $\alpha_1, \alpha_2, \alpha_3$  be the types of  $x, t'', t'$  respectively. Then  $\alpha_3 = \alpha_1 \rightarrow \alpha_2$  is an equation in  $A_t$  so  $\sigma(\alpha_3) = \sigma(\alpha_1) \rightarrow \sigma(\alpha_2)$ . In other words,  $\sigma(\beta(t')) = \sigma(\beta(x)) \rightarrow \sigma(\beta(t''))$ . Now, by induction we have that

$$\Gamma_\sigma^\beta \vdash x : \sigma(\beta(x)), \quad \Gamma_\sigma^\beta \vdash t'' : \sigma(\beta(t''))$$

So applying O-ABS yields

$$\Gamma_\sigma^\beta \vdash t' : \sigma(\beta(x)) \rightarrow \sigma(\beta(t'')) = \sigma(\beta(t'))$$

as required.

- (3) if  $t' = t_1 t_2$  then this follows similarly to the above case.

If  $m$  solves the problem of type inference, then define  $\sigma = m \circ \beta^{-1}$  and we claim that this is a substitution which preserves  $A_t$ . We split into cases by the type of equations in  $A_t$ :

- (1) Equations arising from different occurrences of the same subterm and so  $m$  will map this term to the same type, independent of the occurrence.
- (2) Equations arising from  $t' = \text{fun } x \rightarrow t''$ , then this follows from O-ABS.
- (3) Equations arising from  $t_1 t_2$  follows from O-APP. ■

So to solve step (2) all we must do is find a suitable substitution. This is called the problem of *unification*: given a set of equations of type variables, we must find a substitution which preserves it.

The unification algorithm, due to Hindley-Milner, functions as follows (its code written in OCaml):

```
1  type id = string
2
3  type term =
4    | Var of id
5    | Term of id * (term list)
6
7  type substitution = (id * term) list
```

Let us take a quick second to understand the types here. Firstly `id` is simply an alias for `string`. `terms` (denoted  $\tau$ ) are type terms, whose formal definition is:

$$\tau ::= \alpha \mid C\tau \dots \tau$$

$\alpha$  is the set of type variables, and  $C$  is a set of *type functions*. So for example  $C$  may contain the 0-ary `int` and `string` which represent types of integers and strings respectively. Another example is `Map` which is a 2-ary type function: `Map string int` is a hashmap from strings to ints. Yet another example is `Set`: `Set int` is a set of ints. In this  $C$ , we can chain type functions, so for example `Map (Set string) int` is a type term.

Hindley-Milner imposes only the restriction that  $C$  must include the type function  $\rightarrow$  which represents a function. Instead of  $\rightarrow \tau\tau'$  though, we write  $\tau \rightarrow \tau'$  (use infix instead of polish notation).

A *substitution* is simply a map from Vars to terms.

```
8  let rec occurs (x : id) (t : term) : bool =
9    match t with
10   | Var y -> x = y
11   | Term(_,s) -> List.exists (occurs x) s
```

`occurs` takes a variable  $x$  and a term  $t$  and checks if  $x$  occurs in  $t$ . It does so as follows: if  $t$  is a variable  $y$ , then return if  $x = y$ . Otherwise  $t = Ct_1 \dots t_n$ , so return if  $x$  occurs in any  $t_i$ .

```
12 let rec subst (s : term) (x : id) (t : term) : term =
13   match t with
14   | Var y -> if x = y then s else t
15   | Term(f,u) -> Term(f, List.map (subst s x) u)
```

`subst s x t`

corresponds to the substitution  $t[x \mapsto s]$ . So recursively, if  $t$  is the variable  $y$ , if  $x = y$  then  $t[x \mapsto s] = s$  otherwise  $t$  remains the same. And

$$(Ct_1 \dots t_n)[x \mapsto s] = C(t_1[x \mapsto s]) \dots (t_n[x \mapsto s])$$

```
16 let apply (s : substitution) (t : term) : term =
17   List.fold_right (fun (x,u) -> subst u x) s t
```

Here, if  $s = [(x_1, t_1), \dots, (x_n, t_n)]$  we want to apply  $s$  to a term  $t$ . Then what we want in the end is to get  $t[x_n \mapsto t_n] \dots [x_1 \mapsto t_1]$  which is what this does.

Now we get to the meat of the algorithm: the code which actually unifies a list of equations. First we have the function `unify_one` which unifies a single equation  $s = t$ . Then using this we define `unify`.

```
18 let rec unify_one (s : term) (t : term) : substitution =
19   match (s,t) with
20   | (Var x, Var y) -> if x = y then [] else [(x,t)]
21   | (Term(f,sc), Term(g,tc)) ->
22     if f = g && List.length sc = List.length tc
23     then unify (List.combine sc tc)
24     else failwith "not unifiable: head symbol conflict"
25   | (Var x, Term(_,_) as t) | (Term(_,_) as t, Var x) ->
26     if occurs x t
27     then failwith "not unifiable: circularity"
28     else [(x,t)]
29
30 and unify (e : (term * term) list) : substitution =
31   match e with
32   | [] -> []
33   | (x,y) :: t ->
34     let s2 = unify t in
35     let s1 = unify_one (apply s2 x) (apply s2 y) in
36     s1 @ s2
```

So the algorithm is as follows: given a list of equivalences  $e = (x, y) :: t$  first unify the equivalences in  $t$  recursively to get a substitution  $s2$ . Apply this substitution to  $x$  and  $y$  and unify them.

To unify a single equivalence  $s = t$ , we split into cases:

- (1) if both  $s = x$  and  $t = y$  are variables, then if they are the same variable no unification is needed. Otherwise we simply have  $x$  be substituted with  $t$ .
- (2) If  $s = Cs_1 \dots s_n$  and  $t = C't_1 \dots t_m$ , we must have that  $C = C'$  and  $n = m$  (we cannot unify `Set`  $\alpha$  with `Map int`  $\beta$  for example). If such is the case, we unify the list  $[(s_1, t_1), \dots, (s_n, t_n)]$  recursively, since we now have the equivalences  $s_i = t_i$ .
- (3) If  $s = x$  is a variable and  $t = Ct_1 \dots t_n$  is a compound term (or vice versa), then we cannot have that  $x$  occurs in  $t$  (we cannot unify `Set`  $\alpha$  with  $\alpha$  for example). If such is the case (that  $x$  does not occur in  $t$ ), then we simply have that  $x$  is substituted with  $t$ .

Notice that the same equivalence can have multiple unifiers. For example the equivalence between  $f x (g y)$  and  $f (g z) w$  has the unifiers: we can take  $S = [x \mapsto g z, w \mapsto g y]$ . Applying this to both yields  $f (g z) (g y)$ . But we can also have the unifier  $T = [x \mapsto g(f a b), y \mapsto f b a, z \mapsto f a b, w \mapsto g(f b a)]$ . Both terms then substitute out to  $f (g (f a b)) (g (f b a))$ .

#### 4.9 Definition

The **most general unifier** (mgu) for a set of equations  $A_t$  is a unifier  $\sigma$  such that for every other unifier  $\sigma'$  there exists a substitution  $\sigma''$  such that  $\sigma' = \sigma\sigma''$ . Meaning that all other unifiers can be obtained from  $\sigma$  using further substitutions.

In the above example,  $S$  is an mgu and  $T = S[z \mapsto f a b, y \mapsto f b a]$ . Hindlery-Milner's algorithm returns an mgu for the set of equivalences.

## 5 Closure

### 5.1 Definition

An **environment** is a list  $(x_1 : v_1) :: \dots :: (x_n : v_n)$  where  $x_i$  is a variable and  $v_i$  is a value (in whatever language, so a number, boolean, function, etc). Given an environment  $E$ , we define  $E(x)$  to be the value given to  $x$  by  $E$  (ie.  $E$  is of the form  $\dots :: (x : E(x)) :: \dots$ ).

We define a ternary relation between environments, expressions, and values:

$$E \vdash e \Rightarrow v$$

which is to be read as “the expression  $e$  has value  $v$  in environment  $E$ ”. We define this using the following Gentzen-style rules:

$$\begin{array}{c} \frac{}{E \vdash v \Rightarrow v} \text{ (VAL)} \qquad \frac{E(x) = v}{E \vdash x \Rightarrow v} \text{ (VAR)} \\[10pt] \frac{E \vdash e_1 \Rightarrow v_1 \mid \dots \mid E \vdash e_n \Rightarrow v_n}{E \vdash (e_1, \dots, e_n) \Rightarrow (v_1, \dots, v_n)} \text{ (N-TUPLE)} \\[10pt] \frac{E \vdash e_1 \Rightarrow \text{true} \mid E \vdash e_2 \Rightarrow v}{E \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \Rightarrow v} \text{ (COND1)} \qquad \frac{E \vdash e_1 \Rightarrow \text{false} \mid E \vdash e_3 \Rightarrow v}{E \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 \Rightarrow v} \text{ (COND2)} \end{array}$$

These should all be pretty self-explanatory rules.

Now, for a function we must somehow give it a value which captures all the values in the environment, thus we create new values of the form  $\langle E, f \rangle$  where  $E$  is an environment and  $f$  is a function. This is called the *closure* of  $f$  in  $E$ . We continue developing rules for  $\vdash$ :

$$\begin{array}{c} \frac{}{E \vdash (\text{fun } x \rightarrow e) \Rightarrow \langle E, (\text{fun } x \rightarrow e) \rangle} \text{ (FUN1)} \\[10pt] \frac{}{E \vdash (\text{fun } (x_1, \dots, x_n) \rightarrow e) \Rightarrow \langle E, (\text{fun } (x_1, \dots, x_n) \rightarrow e) \rangle} \text{ (FUN2)} \end{array}$$

So we give to a function  $f$  the value of its closure  $\langle E, f \rangle$  in the environment  $E$ .

$$\begin{array}{c} \frac{E \vdash e_1 \Rightarrow \langle E', (\text{fun } x \rightarrow e) \rangle \mid E \vdash e_2 \Rightarrow v' \mid (x : v') :: E' \vdash e \Rightarrow v}{E \vdash (e_1 \ e_2) \Rightarrow v} \text{ (APP1)} \\[10pt] \frac{E \vdash e_1 \Rightarrow \langle E', (\text{fun } (x_1, \dots, x_n) \rightarrow e) \rangle \mid E \vdash e_2 \Rightarrow (v_1, \dots, v_n) \mid (x : v_1) :: \dots :: (x : v_n) :: E' \vdash e \Rightarrow v}{E \vdash (e_1 \ e_2) \Rightarrow v} \text{ (APP1)} \end{array}$$

Now recall that the syntax for setting a variable is **let**  $x = e_1$  **in**  $e_2$ . So the rule for **let** is that we just add  $(x : e_1)$  to the environment:

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid (x : v_1) :: E \vdash e_2 \Rightarrow v}{E \vdash \text{let } x = e_1 \text{ in } e_2 \Rightarrow v} \text{ (LET)}$$

We also have **let rec** whose syntax is **let rec**  $f \ x = e_1$  **in**  $e_2$ . Now the idea is that **let rec**  $f \ x = e$  will be given the closure  $\langle E, (\text{fun } x \rightarrow e) \rangle$  where  $E$  contains an infinite pair  $f : \langle E, (\text{fun } x \rightarrow e) \rangle$ . Such an object can be represented in memory as an object with a pointer which points to itself. So given an environment  $E$ , a function name  $f$ , and an expression  $(\text{fun } x \rightarrow e)$  (where importantly  $e$  may contain occurrences of  $f$ ), we assumed we can construct an environment  $E'$  such that  $E' = (f : \langle E', (\text{fun } x \rightarrow e) \rangle) :: E$ , and then the rule is:

$$\frac{E' = (f : \langle E', (\text{fun } x \rightarrow e) \rangle) :: E \vdash e_2 \Rightarrow v}{E \vdash \text{let rec } f \ x = e_1 \text{ in } e_2 \Rightarrow v} \text{ (LETREC)}$$

Before giving an example, let us define some boolean and arithmetic rules:

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2 \mid v_1 \leq v_2}{E \vdash e_1 \leq e_2 \Rightarrow \mathbf{true}} \text{ (LEQ1)}$$

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2 \mid v_1 = v_2}{E \vdash e_1 = e_2 \Rightarrow \mathbf{true}} \text{ (EQ1)}$$

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2}{E \vdash e_1 + e_2 \Rightarrow v_1 + v_2} \text{ (ADD)}$$

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2}{E \vdash e_1 \cdot e_2 \Rightarrow v_1 \cdot v_2} \text{ (MUL)}$$

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2 \mid v_1 > v_2}{E \vdash e_1 \leq e_2 \Rightarrow \mathbf{false}} \text{ (LEQ2)}$$

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2 \mid v_1 \neq v_2}{E \vdash e_1 = e_2 \Rightarrow \mathbf{false}} \text{ (EQ2)}$$

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2}{E \vdash e_1 - e_2 \Rightarrow v_1 - v_2} \text{ (SUB)}$$

$$\frac{E \vdash e_1 \Rightarrow v_1 \mid E \vdash e_2 \Rightarrow v_2}{E \vdash e_1 / e_2 \Rightarrow v_1 / v_2} \text{ (DIV)}$$

So for example, suppose our initial environment is the empty list, and we'd like to compute the value of

`let rec f x = (if x = 1 then 1 else x · f(x - 1)) in (f 2)`

Which should give  $2! = 2$ . Let us write `fact` in place of `fun x → (if x = 0 then 1 else x · f(x - 1))`, so

$$\begin{array}{c}
\frac{E' \vdash x \Rightarrow 2 \quad \text{VAR} \quad E' \vdash 1 \Rightarrow 1 \quad \text{VAL}}{E' \vdash x = 1 \Rightarrow \mathbf{false}} \text{EQ2} \quad \frac{E' \vdash x \Rightarrow 2 \quad \text{VAR} \quad \frac{E' \vdash f \Rightarrow \mathbf{fact} \quad \text{VAR} \quad \frac{E' \vdash x - 1 \Rightarrow 1}{\frac{E' \vdash x \Rightarrow 2 \quad \text{VAR} \quad E' \vdash 1 \Rightarrow 1 \quad \text{VAL}}{E' \vdash x = 1 \Rightarrow \mathbf{true}} \text{EQ} \quad \frac{E'' \vdash 1 \Rightarrow 1 \quad \text{VAL}}{E'' \vdash x = 1 \Rightarrow \mathbf{true}} \text{COND1}}{E' \vdash f(x-1) \Rightarrow 1} \text{APP1} \\
\frac{E' \vdash x = 1 \Rightarrow \mathbf{false} \quad \frac{E' \vdash f(x-1) \Rightarrow 1}{E' \vdash x \cdot f(x-1) \Rightarrow 2} \text{MUL}}{E' = (x : 2) :: E' \vdash (\mathbf{if } x = 0 \mathbf{ then } 1 \mathbf{ else } x \cdot f(x-1))} \text{COND2} \\
\frac{E \vdash f \Rightarrow \langle E, \mathbf{fact} \rangle \quad \text{VAR} \quad E \vdash 2 \Rightarrow 2 \quad \text{VAL} \quad E = (f : \langle E, \mathbf{fact} \rangle) \vdash (f \ 2) \Rightarrow 2}{\boxed{\vdash} \vdash \mathbf{let \ rec } f \ x = (\mathbf{if } x = 1 \mathbf{ then } 1 \mathbf{ else } x \cdot f(x-1)) \mathbf{ in } (f \ 2) \Rightarrow 2} \text{APP1} \\
\boxed{\vdash} \vdash \mathbf{let \ rec } f \ x = (\mathbf{if } x = 1 \mathbf{ then } 1 \mathbf{ else } x \cdot f(x-1)) \mathbf{ in } (f \ 2) \Rightarrow 2 \quad \text{LETREC}
\end{array}$$