# Infintesimal Calculus 3

Assignment 7 Ari Feiglin

### Exercise 7.1:

- (1) Let  $b \in \mathbb{R}^m$  and  $A \in \mathbb{R}^{m \times n}$  and we define  $g : \mathbb{R}^n \longrightarrow \mathbb{R}^m$  by g(x) = Ax + b. Let  $a \in \ker(f)$ , show that  $\ker(g) = a + \{R_1^T(A), \dots, R_m^T(A)\}^{\perp}$ .
- (2) Suppose  $E \subseteq \mathbb{R}^n$  and  $f: E \longrightarrow \mathbb{R}^m$  is continuously differentiable in E. Let  $a \in \ker(f)$  and V be the affine space tangent to  $\ker(f)$  at a. Prove that  $V = a + \{\nabla f_1(a), \dots, \nabla f_m(a)\}^{\perp}$ .
- (1) First we will show that  $\ker(A) = \{R_1^T(A), \dots, R_m^T(A)\}^{\perp}$ . We know that  $v \in \ker(A)$  if and only if Av = 0, that is if and only if for every  $1 \le i \le m$ :  $R_i(A)v = 0$ . Since  $u^Tv = u \cdot v$ , this is equivalent to  $R_i^T(A) \cdot v = 0$  for all  $1 \le i \le m$ , which is equivalent to  $v \in \{R_1^T(A), \dots, R_m^T(A)\}$ , as required.

We now claim that  $\ker(g) = \ker(A) + a$ . Suppose  $v \in \ker(g)$  then g(v) = Av + a = 0, so Av = -a. Notice then that A(v - a) = Av - Aa, since  $v, a \in \ker(g)$ , Av = Aa = -a so A(v - a) = 0 and so  $v - a \in \ker(A)$  so  $v \in \ker(A) + a$ . And if  $v \in \ker(A) + a$  then A(v - a) = 0 so Av - Aa = Av + a = 0 so  $v \in \ker(g)$ . So  $\ker(g) = \ker(A) + a$  as required.

And since we showed that  $\ker(A) = \{R_1^T(A), \dots, R_m^T(A)\}^{\perp}$  we have that

$$\ker(g) = \{R_1^T(A), \dots, R_m^T(A)\}^{\perp} + a$$

as required.

(2) Let  $g(x) = df|_a(x-a) = J_f(a) \cdot (x-a)$  so  $V = \ker(g)$ . Notice that g(x) is of the form  $J_f(a) \cdot x + v$ , so by the above subquestion  $\ker(g) = v + \left\{ R_1^T(J_f(a)), \dots, R_m^T(J_f(a)) \right\}^{\perp}$  for any  $v \in \ker(g)$ . Since  $g(a) = J_f(a) \cdot 0 = 0$ ,  $a \in \ker(g)$  and since  $R_i^T(J_f(a)) = \nabla f_i(a)$ , we have that

$$\ker(g) = {\nabla f_1(a), \dots, \nabla f_m(a)}^{\perp} + a$$

## Exercise 7.2:

At the point a = (1, 1, 1) what is the direction where the function

$$f(x, y, z) = x \cdot \tan^{-1}(yz)$$

increases the most (as a unit vector)? Also compute the directional derivative of f at a in this point.

The largest rate of change is in the direction of  $\nabla f(a)$  which is

$$\nabla f(a) = \begin{pmatrix} \tan^{-1}(yz) \\ \frac{xz}{1+z^2y^2} \\ \frac{xy}{1+z^2v^2} \end{pmatrix} (a) = \begin{pmatrix} \frac{\pi}{4} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$

normalizing gives us the vector

$$u \approx \begin{pmatrix} 0.74317 \\ 0.47312 \\ 0.47312 \end{pmatrix}$$

which is the vector we were looking for.

We know that  $D_u f(a) = u \cdot \nabla f(a)$  which in this case since u is the normalized vector of  $\nabla f(a)$  is simply equal to  $\|\nabla f(a)\| = \sqrt{\frac{\pi^2}{16} + \frac{1}{2}}$ .

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#### Exercise 7.3:

We define a surface in  $\mathbb{R}^3$  by  $z = x^2 + y^2$ . Find a point on the surface such that the tangent plane at this point is perpendicular to  $(1,1,-2)^T$ .

If we define  $f(x, y, z) = x^2 + y^2 - z$  then the surface is defined by  $\ker(f)$ . Let v be a point on this surface then  $v \in \ker(f)$ , and we know that the tangent to the plane at v is given by  $v + \{\nabla f(v)\}^{\top}$ . And so the space of vectors perpendicular to this plane is  $\operatorname{span}(\nabla f(v))$ . So we need a v such that  $(1, 1, -2) \in \operatorname{span}(\nabla f(v))$ . We know that

$$\nabla f = \begin{pmatrix} 2x \\ 2y \\ -1 \end{pmatrix}$$

So we need to find x, y, and  $\alpha$  such that  $(1,1,-2)=(2\alpha x,2\alpha y,-\alpha)$ . So we have that  $\alpha=2$  and  $x=y=\frac{1}{4}$ , and so  $z=x^2+y^2=\frac{1}{8}$ , thus the point is

$$\begin{pmatrix} \frac{1}{4} \\ \frac{1}{4} \\ \frac{1}{8} \end{pmatrix}$$

## Exercise 7.4:

Find the directional derivative of f at a in the direction h:

- (1)  $f(x,y) = x\sin(x+y), a = (\frac{\pi}{4}, \frac{\pi}{4}), h = (-1,0).$
- (2)  $f(x, y, z) = xy^2z^3$ , a = (3, 2, 1), h = (4, 3, 0).

We first notice that all these functions are differentiable as the composition of standard functions. Thus  $D_h f(a) = h \cdot \nabla f(a)$  for h unit vector.

(1) We have

$$\nabla f = \begin{pmatrix} \sin(x+y) + x\cos(x+y) \\ x\cos(x+y) \end{pmatrix}$$

Thus

$$D_h(a) = \begin{pmatrix} -1\\0 \end{pmatrix} \cdot \begin{pmatrix} 1\\0 \end{pmatrix} = -1$$

(2) We have

$$\nabla f = \begin{pmatrix} y^2 z^3 \\ 2xyz^3 \\ 3xy^2 z^2 \end{pmatrix}$$

We must normalize h to get  $\frac{1}{5}h$  and we have

$$D_h(a) = \frac{1}{5} \begin{pmatrix} 4\\3\\0 \end{pmatrix} \cdot \begin{pmatrix} 4\\12\\36 \end{pmatrix} = 10.4$$

### Exercise 7.5:

Find  $dg\big|_a(h)$  where  $g=\varphi\circ f$  where  $f(x,y)=(x^2+xy+1,y^2+2)$  and  $\varphi(x,y)=(x+y,2x,y^2)$ .

We know that  $\left.dg\right|_a=\left.d\varphi\right|_{f(a)}\circ\left.df\right|_a$ , and the representation of the differentials is their Jacobian:

$$J_f = \begin{pmatrix} 2x + y & x \\ 0 & 2y \end{pmatrix} \qquad J_\varphi = \begin{pmatrix} 1 & 1 \\ 2 & 0 \\ 0 & 2y \end{pmatrix}$$

And since f(a) = (3,3):

$$dg\big|_{a} = J_{g}(a) = J_{\varphi}(f(a)) \cdot J_{f}(a) = \begin{pmatrix} 1 & 1 \\ 2 & 0 \\ 0 & 6 \end{pmatrix} \cdot \begin{pmatrix} 3 & 1 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 3 \\ 6 & 2 \\ 0 & 12 \end{pmatrix}$$

And so:

$$dg\big|_{a}(h) = J_{g}(a) \cdot h = \begin{pmatrix} 10.5\\19\\6 \end{pmatrix}$$

Exercise 7.6:

Suppose  $f: \mathbb{R}^n \longrightarrow \mathbb{R}$  is a function such that there is a constant M > 0 such that for every  $x, y \in \mathbb{R}^n$ :

$$|f(x) - f(y)| < M||x - y||$$

Such a function is called Lipschitz. Prove or disprove:

- (1) f is continuous on  $\mathbb{R}^n$ .
- (2) f is differentiable on all of  $\mathbb{R}^n$ .
- (3) If  $f: \mathbb{R}^n \longrightarrow \mathbb{R}$  is continuously differentiable on the closed unit ball around 0 then it is Lipschitz-continuous.
- (1) This is true, suppose  $x \in \mathbb{R}^n$  and  $x_n \longrightarrow x$  then

$$|f(x_n) - f(x)| \le M||x_n - x|| \longrightarrow 0$$

So  $f(x_n) \longrightarrow f(x)$  and therefore f is continuous at x for all  $x \in \mathbb{R}^n$  as required.

(2) This is false, take f(x) = |x| in  $\mathbb{R}$ . This function is Lipschitz-continuous:

$$|f(x) - f(y)| = ||x| - |y|| \le |x - y|$$

but it is not differentiable at x = 0.

(3) We know that since  $f \in C^1$ , for every x and y in the closed unit ball:

$$f(y) - f(x) = \nabla f(x + t(y - x)) \cdot (y - x)$$

where  $0 \le t \le 1$  by f's 0th order Taylor series expansion. Let us define

$$g(x) = \|\nabla f(x)\|$$

for every x in the closed unit ball. Since  $f \in C^1$ ,  $\nabla f$  is continuous in the closed unit ball, and therefore so is g as its norm (if a function is continuous, so is its norm). And since the closed unit ball is compact, g must be bounded, so  $g(x) \leq M$ , that is  $\|\nabla f\| \leq M$  for some N. So then by the Cauchy-Schwarz inequality:

$$|f(y)-f(x)| = \left|\nabla f\left(x+t(y-x)\right)\cdot(y-x)\right| \leq \left\|\nabla f\left(x+t(y-x)bigr\right)\right\|\cdot\|y-x\| \leq M\|y-x\|$$

since x + t(y - x) is in the closed unit ball. So f is Lipschitz continuous as required.