

Infinitesimal Calculus 3

Assignment 8
Ari Feiglin

Exercise 8.1:

Find the critical points of the following functions and determine their types:

- (1) $f(x, y) = (x - 1)^2 - 2y^2$
- (2) $f(x, y) = x^4 + y^4 - 2x^2 + 4xy - 2y^2$

- (1) The gradient here is

$$\nabla f = \begin{pmatrix} 2(x-1) \\ -4y \end{pmatrix}$$

which is equal to 0 only at $(1, 0)$, so this is the only critical point. If we hold y constant at 0, then $x = 1$ is a minimum, ie $x = 1$ is the minimum of $f(x, 0) = (x - 1)^2$ as it is a positive parabola. But if we hold x constant at 1 then $y = 0$ is the maximum of $f(1, y) = -2y^2$ so $(1, 0)$ is an inflection point (neither a maximum nor a minimum).

- (2) The gradient here is

$$\nabla f = \begin{pmatrix} 4x^3 - 4x + 4y \\ 4y^3 + 4x - 4y \end{pmatrix}$$

which, if when 0, means that $4x^3 + 4y^3 = 0$ and so $y = -x$ and therefore $4x^3 - 8x = 0$ and so $x = 0$ or $x = \pm\sqrt{2}$. So the critical points are

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} \sqrt{2} \\ -\sqrt{2} \end{pmatrix} \quad \begin{pmatrix} -\sqrt{2} \\ \sqrt{2} \end{pmatrix}$$

We will now compute the hessian:

$$H_f(x, y) = \begin{pmatrix} 12x^2 - 4 & 4 \\ 4 & 12y^2 - 4 \end{pmatrix}$$

So for $\pm\sqrt{2}(1, -1)$, the hessian is the same:

$$\begin{pmatrix} 20 & 4 \\ 4 & 20 \end{pmatrix}$$

And therefore they are minima. For $(0, 0)$, $x = 0$ is a maximum of $f(x, 0) = x^4 - 2x^2$ but $x = 0$ is a minimum of $f(x, x) = 2x^4$, and so $(0, 0)$ is an inflection point.

Exercise 8.2:

We define the following function:

$$f(x, y) = (y - 3x^2)(y - x^2)$$

- (1) Show that $(0, 0)$ is a critical point.
- (2) Show that for every $a, b \in \mathbb{R}$, $f(at, bt)$ has a local minimum at $(0, 0)$.
- (3) Show that $(0, 0)$ is not a minimum of f .

- (1) The gradient is

$$\nabla f = \begin{pmatrix} -6x(y - x^2) - 2x(y - 3x^2) \\ y - x^2 + y - 3x^2 \end{pmatrix} = \begin{pmatrix} 12x^3 - 8xy \\ -4x^2 + 2y \end{pmatrix}$$

And since $\nabla f(0, 0) = 0$, $(0, 0)$ is indeed a critical point.

- (2) We know that $d_t(f(at, bt)) = d_{x,y}f(at, bt) \cdot \begin{pmatrix} a \\ b \end{pmatrix} = \nabla f(at, bt) \cdot \begin{pmatrix} a \\ b \end{pmatrix}$ by the chain rule. This is equal to $12a^4t^3 - 12a^2bt^2 + 2b^2t$. This is equal to 0 at $t = 0$ (as it should since $(0, 0)$ is a critical point of f 's), so $t = 0$ is a critical point. And its second derivative relative to t at $t = 0$ is $2b^2$ which is positive if $b \neq 0$, so if $b \neq 0$ then $t = 0$ is a minimum, as required. If $b = 0$ then

$$f(at, 0) = (-3a^2t^2)(-a^2t^2) = a^4t^4$$

which obviously has a minimum at $t = 0$ as required.

- (3) Take $y = 2x^2$ then

$$f(x, 2x^2) = -x^2 \cdot x^2 = -x^4$$

and so $x = 0$ is a maximum here, so $(0, 0)$ cannot be a minimum.

Exercise 8.3:

Find the critical points of the following function and categorize them:

$$f(x, y) = x^3y^2(1 - x - y)$$

We first find f 's gradient:

$$\nabla f = \begin{pmatrix} x^2y^2(-4x - 3y + 3) \\ x^3y(-2x - 3y + 2) \end{pmatrix}$$

And so $\nabla f = 0$ if and only if $x = 0$ or $y = 0$ or at the point $(\frac{1}{2}, \frac{1}{3})$. We will first deal with the case that $x = 0$ and $y \neq 0$.

Here, notice that if we consider y to be constant then $f(x, y)$ has an extrema (relative to x) whenever $x^3(1 - x - y)$ does, and it is of the same type since $y^2 > 0$. So we now ask a more general question: when does a function $g(x) = -x^4 + \alpha x^3$ have an extrema at $x = 0$? Notice that $g'(x) = -4x^3 + 3\alpha x^2$ and so $g(x)$ has critical points at $x = 0$ and $x = \frac{3\alpha}{4}$. Computing $g'(\frac{\alpha}{2})$ gives $\frac{\alpha^3}{4}$. So if $\alpha < 0$ then $g'(x) < 0$ for $x > 0$ and it is also negative at $\frac{\alpha}{2}$. So around $x = 0$, the derivative of g is negative and therefore $x = 0$ is an inflection point. If $\alpha > 0$ then $g'(x) > 0$ for $x < 0$ and it is also positive at $\frac{\alpha}{2}$ and therefore $x = 0$ is an inflection point. If $\alpha = 0$ then $g(x) = -x^4$ and therefore $x = 0$ is a maximum. In our case $\alpha = 1 - y$ so unless $y = 1$, $(0, y)$ is an inflection point.

We now deal with the case that $x \neq 0$ and $y = 0$. We split it up into cases:

- If $x > 1$ then $(x, 0)$ is above the line $y = 1 - x$ and therefore there exists a ball around $(x, 0)$ such that for every $(a, b) \in B$, $b > 1 - a$ and $a > 0$ so $1 - a - b < 0$ and therefore $f(a, b) < 0 = f(x, 0)$. So $(x, 0)$ is a local maximum for $x > 1$.
- If $x < 0$ then $(x, 0)$ is below the line $y = 1 - x$ so there exists a ball around $(x, 0)$ which is also underneath $y = 1 - x$ and its x values are negative. So for every $(a, b) \in B$, $f(a, b) < 0 = f(x, 0)$ and so $(x, 0)$ is a local maximum for $0 < x < 1$.
- If $0 < x < 1$ then $(x, 0)$ is below the line $y = 1 - x$, so there exists a ball around $(x, 0)$ which is underneath the line and has positive x values, and so for every $(a, b) \in B$, $f(a, b) > 0$, so $(x, 0)$ is a local minimum for $0 < x < 1$.
- If $x = 1$, then it lies on the line $y = 1 - x$, so every ball around $(x, 0)$ has values above and below this line, and for radii small enough, the x values are positive, so there are elements in the ball whose image is positive and some whose image is negative, so $(1, 0)$ is an inflection point.
- For reasons nearly identical to the ones given above, $(0, 1)$ and $(0, 0)$ are also an inflection points.

Lastly, for the point $(\frac{1}{2}, \frac{1}{3})$ we find the Hessian of the function:

$$H_f = \begin{pmatrix} y^2(2x(-4x - 3y + 3) - 4x^2) & x^2(2y(-4x - 3y + 3) - 3y^2) \\ x^2(2y(-4x - 3y + 3) - 3y^2) & x^3(-2x - 3y + 2 - 3y) \end{pmatrix}$$

Specifically at this point

$$H_f\left(\frac{1}{2}, \frac{1}{3}\right) = -\begin{pmatrix} \frac{1}{9} & \frac{1}{12} \\ \frac{1}{12} & \frac{1}{8} \end{pmatrix}$$

which is a negative-definite matrix (the negative of a positive-definite matrix), and therefore $(\frac{1}{2}, \frac{1}{3})$ is a maximum. I summarize the findings below:

- Maxima: $(x, 0)$ for $x > 1$ or $x < 0$, and $(\frac{1}{2}, \frac{1}{3})$.
- Minima: $(x, 0)$ for $0 < x < 1$.
- Inflection points: $(0, y)$ for $y \in \mathbb{R}$ and $(1, 0)$.

Exercise 8.4:

Show that the following equations define z as a function of x and y in a neighborhood of the given point, and further find z_x and z_y in this neighborhood.

- (1) $F(x, y, z) = y^2 + xy + z^2 - e^z - 4 = 0$ around $(0, e, 2)$, further compute z_{yy} .
- (2) $F(x, y, z) = xz + y \ln z + x^2 = 0$ around $(-2, 0, 2)$, further compute z_{xy} .

Both functions here are functions $F: \mathbb{R}^{2 \times 1} \longrightarrow \mathbb{R}^1$, so by using the implicit function theorem at the given point, if the restricted Jacobian is invertible, then z is indeed a function of x and y . Note that the reduced Jacobian is simply $J_{f,z} = (f_z)$, so all we need to show is that at this point, $f_z \neq 0$. Further, it satisfies

$$\begin{pmatrix} z_x & z_y \end{pmatrix} = J_z = -J_{f,z}^{-1} \cdot J_{f,(x,y)} = -f_z^{-1} \cdot J_{f,(x,y)}$$

- (1) Here

$$f_z = 2z - e^z$$

so at this point $f_z = 4 - e^2 \neq 0$, as required. And so

$$\begin{pmatrix} z_x & z_y \end{pmatrix} = -\frac{1}{2z - e^z} \cdot \begin{pmatrix} y & 2y + x \end{pmatrix} = \begin{pmatrix} \frac{y}{e^z - 2z} & \frac{2y + x}{e^z - 2z} \end{pmatrix}$$

and by further differentiating z_y by y , we find that:

$$z_{yy} = \frac{2(e^z - 2z) - (2y + x) \cdot z_y(e^z - 2)}{(e^z - 2z)^2}$$

And so

$$\begin{aligned} z_x(0, e) &= \frac{e}{e^2 - 4} \\ z_y(0, e) &= \frac{2e}{e^2 - 4} \\ z_{yy}(0, e) &= \frac{2(e^2 - 4) - 2e \cdot \frac{2e}{e^2 - 4}(e^2 - 2)}{(e^2 - 4)^2} \end{aligned}$$

- (2) Here

$$f_z = x + \frac{y}{z}$$

and at this point $f_z = -2 \neq 0$, as required. And so

$$\begin{pmatrix} z_x & z_y \end{pmatrix} = -\frac{1}{x + \frac{y}{z}} \cdot \begin{pmatrix} z + 2x & \ln(z) \end{pmatrix} = \begin{pmatrix} -\frac{z^2 + 2xz}{xz + y} & \frac{-z \ln(z)}{xz + y} \end{pmatrix}$$

and by further differentiating z_x by y :

$$z_{xy} = -z_y \frac{2(z + x)(xz + y)^2 - xz(z + 2x)}{(xz + y)^2}$$

And so

$$\begin{aligned} z_x(-2, 0) &= -1 \\ z_y(-2, 0) &= \frac{\ln(2)}{2} \\ z_{xy}(-2, 0) &= \frac{\ln(2)}{4} \end{aligned}$$

Exercise 8.5:

Does the following equation define z as a function of x and y around $(-1, 0, 0)$? Does it define a y as a function of x and z ? x as a function of y and z ?

- It does not. Since z^4 and $\cos(z)$ are even, if z is a solution to this equation then so is $-z$, and so there can be no function which maps from values of x and y to values of z unless it is the constant zero function. But $z = 0$ is a solution if and only if $x^2 + y^5 = 1$, but this does not define an open set.
- It does, and we can find the function explicitly:

$$y = \sqrt[5]{(z^4 + 1)^2 - \cos(z) - x^2 + 1}$$

Since this is defined on all of \mathbb{R}^2 , it is defined over every neighborhood of $(-1, 0, 0)$.

- Using the implicit function theorem, since

$$\frac{\partial f}{\partial x}(-1, 0, 0) = \frac{x}{\sqrt{x^2 + y^5 + \cos(z) - 1}}(-1, 0, 0) = -1$$

and therefore the differential of x is invertible, so by the implicit function theorem, x can be written as a function of y and z in some environment of the point, as required.

Exercise 8.6:

Prove that there exists a ball $B \subseteq \mathbb{R}^4$ whose center is at $(2, 1, -1, -2)$ and functions $f, g: B \rightarrow \mathbb{R}$ continuously differentiable such that

$$f(2, 1, -1, -2) = 4 \quad g(2, 1, -1, 2) = 3$$

and for every $(x, y, z, a) \in B$:

$$f^2 + g^2 + a^2 = 29 \quad \frac{f^2}{x^2} + \frac{g^2}{y^2} + \frac{a^2}{z^2} = 17$$

We can use the implicit function theorem to prove this. We first define the function $h: \mathbb{R}^{4 \times 2} \rightarrow \mathbb{R}^2$ by

$$h(x, y, z, a, f, g) = \left(f^2 + g^2 + a^2 - 29, \frac{f^2}{x^2} + \frac{g^2}{y^2} + \frac{a^2}{z^2} - 17 \right)$$

Notice then that

$$J_{h, \begin{pmatrix} f \\ g \end{pmatrix}}(x, y, z, a, f, g) = \begin{pmatrix} 2f & 2g \\ \frac{2f}{x^2} & \frac{2g}{y^2} \end{pmatrix}$$

so at $(2, 1, -1, 2, 4, 3)$:

$$J_{h, \begin{pmatrix} f \\ g \end{pmatrix}} = \begin{pmatrix} 8 & 6 \\ \frac{1}{2} & 6 \end{pmatrix}$$

which is invertible as it has a non-zero determinant. Thus by the implicit function theorem, in a neighborhood of $(2, 1, -1, 2)$ (which contains a ball centered at this point B , so we'll just take the ball B) such that f and g are indeed

continuously differentiable functions of x, y, z, a where $h(x, y, z, a, f(x, y, z, a), g(x, y, z, a)) = 0$ (which exactly defines the equations given in the question) and $f(2, 1, -1, 2) = 4$ and $g(2, 1, -1, 2) = 3$ (which are the initial conditions given in the question), as required.

Exercise 8.7:

Show that the function $f(x, y) = (e^x \cos(y), e^x \sin(y))$ is not invertible but is locally invertible in a neighborhood of every point in \mathbb{R}^n .

Firstly we know that f is continuously differentiable. And

$$J_f = \begin{pmatrix} e^x \cos(y) & -e^x \sin(y) \\ e^x \sin(y) & e^x \cos(y) \end{pmatrix} = e^x \begin{pmatrix} \cos(y) & -\sin(y) \\ \sin(y) & \cos(y) \end{pmatrix}$$

which has a determinant of

$$e^{2x} (\cos^2(y) + \sin^2(y)) + e^{2x} \neq 0$$

so J_f is always invertible, and since f is continuously differentiable, for every point there is a neighborhood of it in which f is locally invertible.

f itself is not globally invertible since $f(0, 0) = f(0, 2\pi) = (1, 0)$ so it is not injective.