Linear Reduction

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In this paper we will define the concept of linear reduction in the context of syntax parsing. We will progress through more and more complicated examples, beginning from the programming of a simple calculator until we ultimately have created an extensible programming language.

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0 Notation

 $\mathbb N$ denotes the set of natural numbers, including 0.

 $\overline{\mathbb{N}}$ is defined to be $\mathbb{N} \cup \{\infty\}$.

 $f:A \longrightarrow B$ means that f is a partial function from A to B.

If X is a set and x is some symbol, then $X_x = X^x = X \cup \{x\}.$

1 Theoretical Background

1.1 Stateless Reduction

The idea of linear reduction is simple: given a string ξ the first character looks if it can bind with the second character to produce a new character, and the process repeats itself. There is of course, nuance. This nuance hides in the statement "if it can bind": we must define the rules for binding.

Let us define an reducer to be a tuple (Σ, β, π) where Σ is an alphabet; $\beta: \overline{\Sigma} \times \overline{\Sigma} \longrightarrow \overline{\Sigma}$ is a partial function called the reduction function where $\overline{\Sigma} = \Sigma \times \overline{\mathbb{N}}$; and π is the initial priority function. A program over an reducer is a string over $\overline{\Sigma}$. We write a program like $\sigma_{i_1}^1 \cdots \sigma_{i_n}^n$ instead of as pairs $(\sigma^1, i_1) \dots (\sigma^n, i_n)$. In the character σ_i , we call i the priority of σ .

Then the rules of reduction are as follows, meaning we define $\beta(\xi)$ for a program: We do so in cases:

- (1) If $\xi = \sigma_i$ then $\beta(\xi) = \sigma_0$.
- (2) If $\xi = \sigma_i^1 \sigma_i^2 \xi'$ where $i \ge j$ and $\beta(\sigma_i^1, \sigma_i^2) = \sigma_k^3$ is defined then $\beta(\xi) = \sigma_k^3 \xi'$.
- (3) Otherwise, for $\xi = \sigma_i^1 \sigma_i^2 \xi'$, $\beta(\xi) = \sigma_i^1 \beta(\sigma_i^2 \xi')$.

A string ξ such that $\beta(\xi) = \xi$ is called *irreducible*. Notice that it is possible for a string of length more than 1 to be irreducible: for example if $\beta(\sigma^1, \sigma^2)$ is not defined then $\sigma_i^1 \sigma_i^2$ is irreducible.

$$\beta(\sigma_1\tau_2) \xrightarrow{(3)} \sigma_1\beta(\tau_2) \xrightarrow{(1)} \sigma_1\tau_2$$

But such strings are not desired, since in the end we'd like a string to give us a value. So an irreducible string which is not a single character is called *ill-written*, and a string which is not ill-written is *well-written*.

Now the initial priority function is $\pi: \Sigma \longrightarrow \overline{\mathbb{N}}$ which gives characters their initial priority. We can then canonically extend this to a function $\pi: \Sigma^* \longrightarrow (\Sigma \times \overline{\mathbb{N}})^*$ defined by $\pi(\sigma^1 \cdots \sigma^n) = \sigma^1_{\pi(\sigma^1)} \cdots \sigma^n_{\pi(\sigma^n)}$. Then a β -reduction of a string $\xi \in \Sigma^*$ is taken to mean a β -reduction of $\pi(\xi)$.

Notice that once again we require that π only be a partial function. This is since that we don't always need every character in Σ to have an initial priority; some symbols are only given their priority through the β -reduction of another pair of symbols. So we now provide a new definition of a *program*, which is a string $\xi = \sigma^1 \cdots \sigma^n \in \Sigma^*$ such that $\pi(\sigma^i)$ exists for all $1 \le i \le n$. We can only of course discuss the reductions of programs, as $\pi(\xi)$ is only defined if ξ is a program.

Example: let $\Sigma = \mathbb{N} \cup \{+,\cdot\} \cup \{(n+),(n\cdot) \mid n \in \mathbb{N}\}$. β as follows:

$$\begin{array}{cccc} \frac{\sigma_i^1,\sigma_j^2}{n,+} & \beta(\sigma_i^1,\sigma_j^2) \\ \hline n,+ & (n+) \\ n,\cdot & (n\cdot) \\ (n+),m & n+m \\ (n\cdot),m & n\cdot m \\ (n\cdot),(m+) & (n\cdot m,+) \\ (n+),(m+) & (n+m,+) \\ (n\cdot),(m\cdot) & (n\cdot m,\cdot) \\ \end{array}$$

Where n, m range over all values in \mathbb{N} . Here $\beta(\sigma_i, \sigma_j)$'s priority is j. We define the initial priorities

$$\pi(n) = \infty$$
, $\pi(+) = 1$, $\pi(\cdot) = 2$

Now let us look at the string $1 + 2 \cdot 3 + 4$;. Here,

$$\begin{array}{c} 1_{\infty} +_{1} 2_{\infty} \cdot_{2} 3_{\infty} +_{1} 4_{\infty} & \longrightarrow (1+)_{1} 2_{\infty} \cdot_{2} 3_{\infty} +_{1} 4_{\infty} \\ & \longrightarrow (1+)_{1} (2 \cdot)_{2} 3_{\infty} +_{1} 4_{\infty} \\ & \longrightarrow (1+)_{1} (2 \cdot)_{2} (3+)_{1} 4_{\infty} \\ & \longrightarrow (1+)_{1} (6+)_{1} 4_{\infty} \\ & \longrightarrow (7+)_{1} 4_{\infty} \\ & \longrightarrow (7+)_{1} 4_{0} \\ & \longrightarrow (11)_{0} \end{array}$$

So the rules for β we supplied seem to be sufficient for computing arithmetic expressions following the order of operations. \Diamond

Example: We can also expand our language to include parentheses. So our alphabet becomes $\Sigma = \mathbb{N} \cup \{+,\cdot,(,)\} \cup \{\underline{n+,\underline{n\cdot},\underline{n}} \mid n \in \mathbb{N}\}$. We distinguish between parentheses and bold parentheses for readability. We extend β as follows:

$$\begin{array}{ccc} \sigma_i^1,\sigma_j^2 & \beta(\sigma_i^1,\sigma_j^2) \\ \hline n,+ & \underline{n+_j} \\ n,\cdot & \underline{n\cdot_j} \\ \underline{n+,m} & (n+m)_j \\ \underline{n\cdot,m} & (n\cdot m)_j \\ \underline{n\cdot,m+} & \underline{n\cdot m,+_j} \\ \underline{n+,m+} & \underline{n+m,+_j} \\ \underline{n+,m+} & \underline{n+m,+_j} \\ \underline{n\cdot,m\cdot} & \underline{n\cdot m,\cdot_j} \\ \underline{n+,m} & \underline{n+m} \\ \underline{n\cdot m,j} \\ \underline{n\cdot m,j} \\ \underline{n\cdot m} \\$$

 $(n+m)_j$ means n+m with a priority of j, not $n+m_j$. And we define the initial priorities

$$\pi(n) = \infty, \quad \pi(+) = 1, \quad \pi(\cdot) = 2, \quad \pi(() = \infty, \quad \pi()) = 0$$

So for example reducing $2 \cdot ((1+2) \cdot 2) + 1$,

$$\begin{array}{c} 2_{\infty} *_{2} \left(_{\infty}(\infty 1_{\infty} +_{1} 2_{\infty})_{0} *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty} \longrightarrow \underbrace{2 *_{2} \left(_{\infty}(\infty 1_{\infty} +_{1} 2_{\infty})_{0} *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty}}_{2 *_{2} \left(_{\infty}(\infty 1 +_{1} 2_{\infty})_{0} *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty}} \\ \longrightarrow \underbrace{2 *_{2} \left(_{\infty}(\infty 1 +_{1} 2_{0})_{0} *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty}}_{2 *_{2} \left(_{\infty}(\infty 3 -_{0})_{0} *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty}} \\ \longrightarrow \underbrace{2 *_{2} \left(_{\infty} 3_{\infty} *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty}}_{2 *_{2} \left(_{\infty} 3 *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty}} \\ \longrightarrow \underbrace{2 *_{2} \left(_{\infty} 3 *_{2} 2_{\infty}\right)_{0} +_{1} 1_{\infty}}_{2 *_{2} \left(_{\infty} 6 -_{0}\right)_{0} +_{1} 1_{\infty}} \\ \longrightarrow \underbrace{2 *_{2} \left(_{\infty} 6 -_{0}\right)_{0} +_{1} 1_{\infty}}_{2 *_{2} 6 -_{0} +_{1} 1_{\infty}} \\ \longrightarrow \underbrace{2 *_{2} 6 +_{1} 1_{\infty}}_{2 *_{2} 1 +_{1} 1_{\infty}} \\ \longrightarrow \underbrace{12 +_{1} 1_{0}}_{1 3_{0}} \\ \longrightarrow \underbrace{13 -_{0}}_{1 3_{0}} \end{array}$$

1.2 Stateful Reduction

Suppose we'd like to reduce a program with variables in it. Then we cannot just use the previous definitions, as the actions of σ (which is to be understood as the function $\beta(\sigma, \bullet)$) are determined before any reduction occurs. We need a way to store the value of variables, a state.

This leads us to the following definition: let Σ_P and Σ_A be two disjoint sets of symbols: Σ_P the set of *printable symbols* and Σ_A the set of *abstract symbols*. Σ_P will generally be a set consisting of the string representations of abstract symbols, be it operators like + and \cdot or variable names. Σ_A are the actual objects which can "execute something". Let us further define $\Sigma = \Sigma_P \cup \Sigma_A$.

Now a state is a mapping from printable symbols to strings. So for example, if x is a printable symbol a line like let x = 1 should change the state so that x maps to the abstract symbol representing 1.

A point state is a partial function $s: \Sigma_P \longrightarrow \Sigma_A$. If s_1, s_2 are point states, define their composition to be a point state $s_1 s_2$ such that

$$s_1 s_2(\sigma) = \begin{cases} s_2(\sigma) & \sigma \in \text{dom}(s_2) \\ s_1(\sigma) & \sigma \in \text{dom}(s_1) \end{cases}$$

A state is a sequence of point states: $\bar{s} = (s_1, \dots, s_n)$. Let us define

State =
$$\{\Sigma_P \longrightarrow \Sigma_A\}^+$$

 \Diamond

the set of all states.

Let $\overline{s} = (s_1 \cdots s_n) \in \mathsf{State}$ be a state, then define

- for $\sigma \in \Sigma_P$ we define $s(\sigma) = s_1 \cdots s_n(\sigma)$ (the composition of states),
- define $pop \ \overline{s} = (s_1, \dots, s_{n-1}),$
- define push $\overline{s} = (s_1, \dots, s_n, \emptyset)$ (\Ø is the empty state),
- if s is a point state, $\overline{s}s = (s_1, \dots, s_{n-1}, s_n s)$,
- if s is a point state, $\overline{s} + s = (s_1, \dots, s_n, s)$ (so push $\overline{s} = \overline{s} + \emptyset$).

So if we'd like to revert to a previous state, we simply pop from the current state. And substituting the current state only alters the current (topmost) point state.

Now we begin with an initial β function which is a partial function

$$\beta: \overline{\Sigma}_A \times (\overline{\Sigma} \cup \{\varepsilon\}) \times \mathsf{State} \longrightarrow \overline{\Sigma}^* \times \mathsf{State}$$

Recall that $\overline{\Sigma}$ is $\Sigma \times \mathbb{N}$. We will denote tuples in $X \times \mathsf{State}$ by $\langle x, | s \rangle$ for $x \in X$ and $s \in \mathsf{State}$ for the sake of readability. So we now wish to extend to a β function

$$\beta: \overline{\Sigma}^* \times \mathsf{State} \longrightarrow \overline{\Sigma}^* \times \mathsf{State}$$

We do this as follows: given $\xi \in (\Sigma \times \overline{\mathbb{N}})^*$ and $s \in \mathsf{State}$ we define $\beta \langle \xi \mid s \rangle$ as follows:

- (1) if $\xi = \sigma_i \xi'$ for $\sigma \in \Sigma_P$ then $\beta \langle \xi \mid s \rangle = \langle s(\sigma)_i \xi' \mid s \rangle$,
- (2) if $\xi = \sigma_i \xi'$ such that $\beta \langle \sigma_i \varepsilon \mid s \rangle = \langle \xi'' \mid s' \rangle$ is defined then $\beta \langle \xi \mid s \rangle = \langle \xi'' \xi' \mid s' \rangle$,
- (3) if $\xi = \sigma_i^1 \sigma_i^2 \xi'$ for $\sigma^1 \in \Sigma_A$, $i \ge j$, such that $\beta \langle \sigma_i^1 \sigma_i^2 \mid s \rangle = \langle \xi'' \mid s' \rangle$ is defined, then $\beta \langle \xi \mid s \rangle = \langle \xi'' \xi' \mid s' \rangle$,
- (4) otherwise for $\xi = \sigma_i^1 \sigma_i^2 \xi'$, if $\beta \langle \sigma_i^2 \xi' \mid s \rangle = \langle \xi'' \mid s' \rangle$ then $\beta \langle \xi \mid s \rangle = \langle \sigma_i^1 \xi'' \mid s' \rangle$.

Notice that (2) cares not about the priority of σ , and neither if $\beta(\sigma_i, \tau_i)$ is defined for some $\tau \neq \varepsilon$.

We also define the *initial priority function* to be a map $\pi: \Sigma_P \longrightarrow \overline{\mathbb{N}}$ (this is not a partial function: every printable symbol must be given a priority). This is once again canonically extended to a function $\pi: \Sigma_P^* \longrightarrow (\Sigma_P \times \overline{\mathbb{N}})^*$. And an *initial state* s_0 which is a point state. The quintuple $(\Sigma_P, \Sigma_A, \beta, \pi, s_0)$ is called an *reducer*. The reduction of a string $\xi \in S$ is the process of iteratively applying β to $\langle \pi(\xi) \mid s_0 \rangle$.

Example: let

$$\begin{split} &\Sigma_P = \mathbb{N} \cup \{+,\cdot,=,;\} \cup \{\texttt{let}\} \cup \left\{x^i \mid i \in \mathbb{N}\right\}, \\ &\Sigma_A = \mathbb{N} \cup \{(n+),(n\cdot) \mid n \in \mathbb{N}\} \cup \{\texttt{let}\} \cup \left\{(\texttt{let}x^i),(\texttt{let}x^i =) \mid i \in \mathbb{N}\right\} \end{split}$$

where the natural numbers in Σ_A are not the same as the natural numbers in Σ_P since they must be disjoint, same for let. But they both essentially represent the same thing: s_0 maps $n \mapsto n$ for $n \in \mathbb{N}$ (the left-hand n is in Σ_p , the right-hand n is in Σ_A) and let \mapsto let. All other printable symbols are mapped to ε .

And similar to the previous example we define $\pi(n) = \infty$, $\pi(+) = 1$, and $\pi(\cdot) = 2$. We extend this to $\pi(\cdot) = 0$, $\pi(=) = 0$, $\pi(=) = \infty$, and $\pi(x^i) = \infty$.

Let us take the same transitions as the example in the previous section for $n, (n+), (n\cdot)$ (we have to add the condition that the state doesnt change). We further add the transitions

$$\begin{array}{c|c} \left\langle \sigma_i^1 \sigma_j^2 \mid s \right\rangle & \beta \left\langle \sigma^1 \sigma^2 \mid s \right\rangle \\ \hline \left\langle \sigma; \mid s \right\rangle & \left\langle \sigma_j \mid s \right\rangle \\ \left\langle \mathsf{let} x^i \mid s \right\rangle & \left\langle (\mathsf{let} x^i)_j \mid s \right\rangle \\ \left\langle (\mathsf{let} x^i) = \mid s \right\rangle & \left\langle (\mathsf{let} x^i =)_j \mid s \right\rangle \\ \left\langle (\mathsf{let} x^i =)\sigma \mid s \right\rangle & \left\langle \varepsilon \mid s[x^i \mapsto \sigma] \right\rangle \end{array}$$

In the final transition, $n \in \Sigma_A$. Then for example (we will be skipping trivial reductions):

$$\begin{split} \det x^1 &= 1 + 2; \ \det x^2 = 2; \ x^1 \cdot x^2; \longrightarrow \det_{\infty} x_{\infty}^1 =_0 \ 1_{\infty} +_1 \ 2_{\infty};_0 \ \det_{\infty} x_{\infty}^2 =_0 \ 2_{\infty};_0 \ x_{\infty}^1 \cdot_2 \ x_{\infty}^2;_0 \\ & s_0 \longrightarrow (\det x^1 =)_0 1_{\infty} +_1 \ 2_{\infty};_0 \ \det_{\infty} x_{\infty}^2 =_0 \ 2_{\infty};_0 \ x_{\infty}^1 \cdot_2 \ x_{\infty}^2;_0 \\ & s_0 \longrightarrow (\det x^1 =)_0 3_0 \ \det_{\infty} x_{\infty}^2 =_0 \ 2_{\infty};_0 \ x_{\infty}^1 \cdot_2 \ x_{\infty}^2;_0 \\ & s_0[x^1 \mapsto 3] \longrightarrow \det_{\infty} x_{\infty}^2 =_0 \ 2_{\infty};_0 \ x_{\infty}^1 \cdot_2 \ x_{\infty}^2;_0 \\ & s_0[x^1 \mapsto 3, \ x^2 \mapsto 2] \longrightarrow x_{\infty}^1 \cdot_2 \ x_{\infty}^2;_0 \\ & s_0[x^1 \mapsto 3, \ x^2 \mapsto 2] \longrightarrow (3 \cdot)_2 x_{\infty}^2;_0 \\ & s_0[x^1 \mapsto 3, \ x^2 \mapsto 2] \longrightarrow (3 \cdot)_2 2_{\infty};_0 \\ & s_0[x^1 \mapsto 3, \ x^2 \mapsto 2] \longrightarrow (3 \cdot)_2 2_{\infty};_0 \\ & s_0[x^1 \mapsto 3, \ x^2 \mapsto 2] \longrightarrow 6_0 \end{split}$$

1.3 Valued Reduction

We define the following four base sets:

- (1) U the universe of values, these are all the internal values an object may have.
- (2) $\mathcal{T}_{\mathcal{P}}$ the set of *printable terms*, these are the tokens which a programmer may pass to the reducer.
- (3) \mathcal{T}_{Σ} the set of type terms.
- (4) $\mathcal{T}_{\mathcal{A}}$ the set of abstract terms.

The sets $\mathcal{T}_{\mathcal{P}}$, \mathcal{T}_{Σ} , $\mathcal{T}_{\mathcal{A}}$ are all disjoint, we place no such restriction on \mathcal{U} as the purpose it serves is different. Let \mathcal{A} be a set of *atomic abstract terms*, then the construction of abstract terms is

$$\mathcal{T}_{\mathcal{A}} ::= \mathcal{A} \mid \mathcal{A}\mathcal{T}_{\Sigma}$$

And let Σ be a set of *atomic types*, each with an associated arity, which may be ∞ . Let Σ^n be the set of atomic types of arity n, then the construction of type terms is

$$\mathcal{T}_{\Sigma} ::= \Sigma^0 \mid \Sigma^n \mathcal{T}_{\Sigma}^1 \cdots \mathcal{T}_{\Sigma}^n \mid \Sigma^{\infty} \mathcal{T}_{\Sigma}^1 \cdots \mathcal{T}_{\Sigma}^n$$

as n ranges over all $\mathbb{N}_{>0}$.

Define

- (1) $\mathcal{T} := \mathcal{T}_{\mathcal{P}} \cup \mathcal{T}_{\Sigma} \cup \mathcal{T}_{\mathcal{A}}$ the set of basic terms.
- (2) $\mathcal{T}_{\mathcal{I}} := \mathcal{T}_{\Sigma} \cup \mathcal{T}_{\mathcal{A}}$ the set of internal terms.
- (3) $\Pi_{\mathcal{I}} := \mathcal{T}_{\mathcal{I}} \times \mathcal{U}$ the set of termed values.
- (4) $\Pi := \Pi_{\mathcal{I}} \cup \mathcal{T}_{\mathcal{P}}$ the set of atomic expressions.

Elements of $\overline{\Pi}$ will be written like $\sigma_n(v)$ where σ is the term, n the priority, and v the value (nothing for printable terms).

In valued reduction, we abstract away some inputs to the initial beta-reducer in order to allow for easier implementation. An initial beta-reducer is a partial function

$$\widehat{\beta}: \mathcal{T}_{\mathcal{I}} \times \mathcal{T}^{\varepsilon} \longrightarrow \mathcal{T}_{\mathcal{I}}^{\varepsilon} \times (\overline{\mathbb{Z}} \times \overline{\mathbb{Z}} \to \overline{\mathbb{Z}}) \times (\mathcal{U} \times \mathcal{U} \times \operatorname{State} \to \mathcal{U} \times \mathcal{T}_{\mathcal{P}}^* \times \operatorname{State})$$

We extend this to a derived β -reducer,

$$\beta: \overline{\Pi}^* \times \text{State} \longrightarrow \overline{\Pi}^* \times \text{State}$$

with the following rules: given an input $\langle \xi \mid s \rangle$ its image is

(1) If $\xi = \sigma_n \xi'$ for $\sigma \in \mathcal{T}_{\mathcal{P}}$ then

$$\beta \langle \xi \mid s \rangle = \langle s(\sigma)_n \xi' \mid s \rangle.$$

(2) If $\xi = \sigma_i(v)\xi'$ and $\widehat{\beta}(\sigma, \varepsilon) = (\alpha, \rho, f)$ is defined, then if $f(v, -, s) = (w, \zeta, s')$ and $\rho(i) = k$ then

$$\beta \langle \xi \mid s \rangle = \langle \alpha_k(w) \pi(\zeta) \xi' \mid s' \rangle.$$

(3) If $\xi = \sigma_i(v)\tau_j(u)\xi'$ and $i \ge j$ and $\widehat{\beta}(\sigma,\tau) = (\alpha,\rho,f)$ is defined, then if $f(v,u,s) = (w,\zeta,s')$ and $\rho(i,j) = k$ then

$$\beta \langle \xi \mid s \rangle = \langle \alpha_k(w) \pi(\zeta) \xi' \mid s \rangle.$$

(4) Otherwise, if $\xi = \sigma_i(v)\xi'$ and $\beta\langle \xi' \mid s \rangle = \langle \xi'' \mid s' \rangle$,

$$\beta \langle \xi \mid s \rangle = \langle \sigma_i(v) \xi'' \mid s' \rangle.$$

1.3.1 States

Similar to before, we define point-states as partial maps $\mathcal{T}_{\mathcal{P}} \longrightarrow \Pi_{\mathcal{I}}$. And if s_1, s_2 are two point-states and $\sigma \in \mathcal{T}_{\mathcal{P}}$ then

$$s_1 s_2(\sigma) = \begin{cases} s_2(\sigma) & \sigma \in \text{dom} s_2 \\ s_1(\sigma) & \sigma \in \text{dom} s_1 \end{cases}$$

We will denote finite point states as $[\sigma_1 \mapsto \varkappa_1, \dots, \sigma_n \mapsto \varkappa_n]$, and this denotes the point-state which maps σ_i to \varkappa_i .

A state will now have two fields: a sequence of point-states, as well as a sequence of indexes. For a state $\bar{s} = [(s_1, \ldots, s_n), I = (i_1, \ldots, i_k)]$, let us define

- (1) $\bar{s} + s = [(s_1, \dots, s_n, s), I]$
- (2) $\bar{s} +_c s = [(s_1, \dots, s_n, s), (i_1, \dots, i_k, n+1)]$
- (3) $pop \ \bar{s} = [(s_1, \dots, s_{n-1}), I] \ \text{if} \ i_k < n \ \text{otherwise}, \ [(s_1, \dots, s_{n-1}), (i_1, \dots, i_{k-1})]$
- $(4) \quad \bar{s}s = [(s_1, \dots, s_n s), I]$
- (5) $\bar{s}(\sigma) = s_1 \cdots s_n(\sigma)$ for $\sigma \in \Sigma_P$

Furthermore, if $\sigma \in \mathcal{T}_{\mathcal{P}}$ and $\varkappa \in \Pi_{\mathcal{I}}$ let us define $\bar{s}\{\sigma \mapsto \varkappa\}$ as $(s_1, \ldots, s_i[\sigma \mapsto \varkappa], \ldots, s_n)$ where i is the maximum index such that $\sigma \in \text{dom} s_i$.

1.3.2 The Initial Beta Reducer

We now describe the initial beta reducer. By convention, atomic abstract terms will be red, type terms will be green, internal terms will be blue.

End:

• $\sigma \text{ end} \longrightarrow \sigma \text{ minfty } (u, _, s \rightarrow u, \varepsilon, s)$

Arithmetic:

- $\sigma \text{ op} \longrightarrow \text{op}\sigma \text{ snd } (u, f, s \rightarrow (u, f), \varepsilon, s)$
- op σ op $\sigma \longrightarrow$ op σ snd $((u, f), (v, g), s \longrightarrow (f(u, v), g), \varepsilon, s)$
- op $\sigma \sigma \longrightarrow \sigma$ snd $((u, f), v, s \to f(u, v), \varepsilon, s)$
- σ rparen \longrightarrow rparen σ snd $(u, _, s \to u, \varepsilon, s)$
- op σ rparen $\sigma \longrightarrow$ rparen σ snd $((f,u),v,s \rightarrow f(u,v),\varepsilon,s)$
- Iparen rparen $\sigma \longrightarrow \sigma$ fst $(-, u, s \rightarrow u, \varepsilon, s)$

Lists:

- Ibrack $\sigma \longrightarrow \mathsf{Ibrack}\sigma$ fst $(-, u, s \rightarrow (u), \varepsilon, s)$
- Ibrack $\sigma \rightarrow$ Ibrack σ fst $(\ell, u, s \rightarrow (\ell, u), \varepsilon, s)$
- Ibrack σ rbrack \longrightarrow list σ infty $(\ell, _, s \to \ell, \varepsilon, s)$
- period num \longrightarrow index zero $(-, n, s \rightarrow n, \varepsilon, s)$
- list σ index $\longrightarrow \sigma$ fst $(\ell, i, s \to \ell_i, \varepsilon, s)$

Variables:

- let $x \longrightarrow$ letvar snd $(-, -, s \rightarrow (x, \emptyset), \varepsilon, s)$
- letvar index \longrightarrow letvar fst $((x, \ell), n, s \rightarrow (x, (\ell, n)), \varepsilon, s)$
- letvar equal \longrightarrow leteq minfty $((x,\ell), _, s \to (x,\ell), \varepsilon, s)$
- leteq $\sigma \longrightarrow \varepsilon \varnothing ((x,\ell), v, s \to \varepsilon, \varepsilon, s')$ where s' is $s[x \mapsto \sigma(v)]$ if $\ell = \varnothing$ and otherwise let t be the result of setting $s(x).\ell_1....\ell_n$ to v, then $s' = s[x \mapsto t]$.

Scoping:

- Ibrace $\varepsilon \longrightarrow \varepsilon \varnothing (_,_,s \to \varepsilon,\varepsilon,s+\varnothing)$
- rbrace $\varepsilon \longrightarrow \varepsilon \varnothing (_, _, s \to \varepsilon, \varepsilon, pop s)$