CSC3150 Assignment5 Report

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1 Introduction

In this Assignment, my objective is to make a prime device in Linux, and implement file operations in kernel module to control this device. Meanwhile, I will implement ioctl function to change the device configuration. The figure below demonstrates the general idea of my solution to this project.

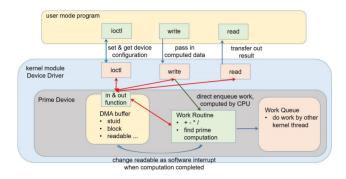


Figure 1: Genral Idea of my implementation

2 Design of my program

In this assignment, there are five functions in total that are needed to be implemented. They are drv_ioctl function, drv_read, drv_write, init_modules, and exit_modules function.

As we have user mode and kernel mode, the user's read, write and ioctl functions will conrresponds to the kernel's drv_read, drv_write, and init_modules functions.

In the following section, I will explain my design of them one by one logically.

2.1 init_module()

2.1.1 Register chrdev

In this function, some initialization jobs will be done.

First, I use $dev = alloc_chrdev_region()$ to allocate a range of char device numbers. Then I will get an available number by MAJOR() and MINOR() macro.

After that, I allocate a cdev structure by dev_cdevp = cdev_alloc(). After which, I use cdev_init(dev_cdevp, &fops) to initialise it. "fops" is a kind of function map, which maps the function in the user mode to the function in the kernel mode.

I use cdev_add() function to make the cdev structure alive.

2.1.2 Allocate DMA buffer

Direct Memory Access buffer aka DMA buffer, is a register or memory on my device that I simulated. This buffer is as IO port mapping in the main memory. I use kzalloc() function to alloc a memory space.

2.1.3 Allocate work routine

I use kmalloc() function to allocate the work routine.

2.2 exit_module

In this function, the main purpose is to finish the process. So first, I free the DMA buffer by using kfree() function. Next, I delete character device by cdev_del() function. Furthermore, I also free the work.

2.3 drv_ioctl

In this function, it will change the IO configuration by changing the information stored in DMA buffer. Each mode corresponds to each position in DMA buffer. For example, the HW5_IOCSETSTUID changes the number store in the DMASTUIDADDR.

Figure 2: DMA buffer structure

```
#ifndef IOC HW5 H
 #define IOC HW5 H
                                    121
 #define HW5 IOC MAGIC
 #define HW5_IOCSETSTUID
#define HW5_IOCSETRWOK
                                     IOW (HW5 IOC MAGIC, 1, int)
                                     IOW (HW5 IOC MAGIC, 2, int)
                                    _IOW(HW5_IOC_MAGIC, 3, int)
 #define HW5_IOCSETIOCOK
                                     IOW(HW5_IOC_MAGIC, 4, int)
IOW(HW5_IOC_MAGIC, 5, int)
 #define HW5 IOCSETIRQOK
 #define HW5 IOCSETBLOCK
 #define HW5_IOCWAITREADABLE
                                     _IOR(HW5_IOC_MAGIC, 6, int)
 #define HW5 IOC MAXNR
 #endif
```

Figure 3: IO control modes

2.3.1 IOWAITREADABLE

This mode, the ioctl function implements kind of different things from other modes. It is used to check whether a non-blocking write has finished or not, in order to check whether the answer is readable or not.

My design is that, first I will set a readflag, which check the information in DMA buffer to see whether the mode is readable. If it is still not readable, I use a while loop to check it again. I use msleep(50) to decrease the time for while looping. If you set the msleep time much larger, the effect will be seen more clearly. For example, if you set the msleep function to 5000, the difference between block write and non-blocking write will be seen more clearly.

2.4 drv_write

This function is called when user use write function in user mode. The main contribution of this function is to put the information of the user to the DMA buffer, and let the drv_arithmetic function to figure out the answer using DMA buffer.

To begin with, I first change the readable to 0, which means the answer is not readable.

After that, the first thing to do is to put the operator and operands to the DMA buffer. Next, initialise the work. Then, check the IO mode: whether this is a blocking write or a non-blocking write. If it is a blocking write, after scheduling work, I use flush_scheduled_work function. If this is a non-blocking write, I will not use flush_scheduled_work function. Then, I set the readable mode in the DMA buffer to be 1.

After that, use drv_arithmetic function to calculate the answer of the problem.

2.5 drv_arithmetic

In this section, it do the calculation using the operator and operands stored in the DMA buffer. And also store the data to the DMA buffer. The operators include:+-*/. The operator is stored in the DMAOPCODEADDR, operand 1 is in the DMAOPERANDBADDR, operand 2 is in the DMAOPERANDCADDR. The result will be stored in the DMAANSADDR.

2.6 drv_read

This function is simply read the answer in the DMA buffer and also change the readable mode to be 0;

3 Execute my program

First, type "make" in the directory of main.c folder. Then, you will see many files are created.

If it is the first time to run this program, you should type "dmesg" to displays the available major and minor number, then type "sudo ./mkdev.sh major minor". This can also be removed by typing "sydo ./rmnod.sh".

Type "./test" to run the test program.

Type "make clean". You can see the information of the kernel will be shown on the screen.

4 What I learned and problem I met

In this project, I learned how to make a prime device in Linux, and implement file operations in kernel module to control this device. I learned how to link user and kernel functions. During this project, I met a trouble about how to transfer user variable to kernel, and how to transfer kernel variables to user. Get_user function, however, does not even work when I want to transfer a structure defined by myself. I finally solve it by using copy_from_user function and copy_to_user function.

5 Screen Shots

Figure 4: operator + in user mode

```
[49030.655154]
[49030.655160]
                         OS_ASS:drv_ioctl(): Placking TO
[49030.655164]
[49035.702330]
[49035.702333]
[49035.702334]
[49035.702334]
                           OS_AS5:drv_ioctl(): Blocking IO
[49035.702343]
[49035.702344]
[49035.702345]
                          OS_AS5:drv_write(): queue work
OS_AS5:drv_write(): block
[49035.702349]
[49035.702533]
[49035.702605]
                          OS_AS5,drv_arithmetic_routine(): 100 + 10 = 110
                         OS_ASS:drv_arithmetic_routine(). 100 + 10 - 110
OS_ASS:drv_read(): ans = 110
OS_ASS:drv_write(): queue work
OS_ASS:drv_arithmetic_routine(): 100 + 10 = 110
OS_ASS:drv_ioctl(): wait readable 1
OS_ASS:drv_read(): ans = 110
[49035.702631]
 49035.702633]
[49035.702000] US_AS5:drv_ioctl(): wait readable 1

[49035.702686] OS_AS5:drv_read(): ans = 110

[49035.702841] OS_AS5:drv_release(): device close

[49045.064719] OS_AS5:exit_modules():free dma buffer

[49045.064720] OS_AS5:exit_modules():unregister chrdev

[49045.064721] OS_AS5:exit_modules():
                          OS_AS5:exit_modules():.....End.....
```

Figure 5: operator + in kernel mode

Figure 6: operator - in user mode

Figure 7: operator - in kernel mode

Figure 8: operator * in user mode

Figure 9: operator * in kernel mode

Figure 10: operator / in user mode

Figure 11: operator / in kernel mode

Figure 12: operator p in user mode

Figure 13: operator p in kernel mode

Figure 14: operator p in user mode

Figure 15: operator p in kernel mode