CAN Packet

* data: Motor_Controller_K1 → MOTOR_CONTROLLER_K1
  _K2

  ✓ handler: hkcan3

  ✓ id: CAN_ID_EXT

  ✓ data length: Start_frame.data_length = 0;
  Start_frame.rtr = 1;

need 2 frames

Voltage, currents

MOTOR_CONTROLLER_K1
10F8109A

K2
10F8108D

request frame sent empty

put mock data in recieve

Kelly

Frame 1:
DRIVING_DIRECTION_K
MOTOR_SPEED_K
MOTOR_ERROR_CODE_K

Frame 2:
BATTERY_VOLTAGE_K
BATTERY_CURRENT_K
MOTOR_TEMP_K
MOTOR_CONTROLLER_TEMP_K

2 seperate CAN Frames

All have their own id, start, end