Now Spectral Products

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Digikröm CM110/CM112 Monochromator / Spectrograph

User Manual

(CVI Document # 8-2063-C) / 1049517 Revised 2/2000 Copyright 1998, CVI Laser Corporation 1200g/mm BLAZZ @ 200 n~

CVI Laser Corporation 200 Dorado Pl, SE

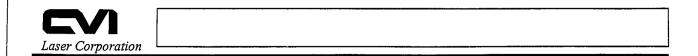
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Chapter 1: Introduction

Introduction

1.1 Mission Statement

Our mission is to provide our customers with reliable products, on time, and at a fair price. We are continually striving to maintain the highest standards, by assuring defect-free products and by providing prompt and courteous customer service.

The staff at CVI Laser Corporation will be happy to answer any questions about our products and our services. For immediate assistance, please contact the Spectral Products Group directly at (505) 296-9541, by fax (505) 298-9908, or by e-mail at instruments@cvilaser.com

1.2 Warranty

This product is warranted to be free of defects in materials and workmanship for one year from date of purchase.

This manual and the software it describes are provided free of charge as a service to the customer. The software is intended to be used as a tool for development and as an example of one possible method of code implementation. It is not intended to be a "user application."

Any software associated with this product is provided "as is" with no warranty, expressed or implied. While it is CVI Laser Corporation's intent to provide error-free development tools, no guarantee is made regarding either the accuracy or usefulness of this material

Failures or damages resulting from lack of operator attention to proper procedures, failure to follow operating instructions, unauthorized modifications, and natural disasters are not covered under this warranty.

The Digikröm CM110/112 does not contain any user serviceable parts. Removing its cover, without explicit written permission from CVI Laser Corporation, will void any written or implicit warranty.

CVI reserves the right, without prior or further notice, to make changes to any of its products described or referred to herein to improve reliability, function, or design.

CVI accepts no liability for incidental or consequential damages arising from the use of this software.

CVI Laser Corporation does not recommend the use of its components or software products in life support applications wherein a malfunction or failure of the product may directly threaten life or result in injury.

CVI does not recommend that this product be used on the same power line as other equipment with high current draw requirements.

1.3 Copyrights

CVI Laser Corporation maintains the copyright on this material, but grants the customer rights to use or to modify the software described herein without obtaining CVI Laser Corporation's permission and without the requirement to reference CVI Laser Corporation as the source of the material.

LabVIEW® is a registered trademark of National Instruments.

WindowsTM, Microsoft[®] Visual BasicTM and Microsoft[®] Quick BasicTM are registered trademarks of Microsoft Corporation.

1.4 Product Overview

The Digikröm CM110/112 is a one-eighth meter, Czerny-Turner type monochromator/spectrograph. Unlike other small devices that provide only one optical orientation, the Digikröm CM110/112 can accommodate both a straight through and a right-angle orientation from the source. Optical path conversion is outlined in Appendix G: Product Conversions.

Getting Started

2.1 Verify Shipping Contents

The following items are shipped with your order of a CM110/112 1/8m monochromator:

	210 (
Qty	Item
1	CM110/112
1	DKFS100 Slit Set (2 each,125mm, .15mm, .3mm, .6mm, 1.2mm and 2.4mm slits)
1	DK12V power supply
1	Power cord
1	Dual power cable
1	User's manual
1	Demonstration software. If not included, this can be downloaded from our website at www.cvilaser.com

2.2 Hardware Connections

Power is supplied to the CM110/112 by the power supply, which has an output patch cord with two connectors. The connector with the threaded sleeve connects to the CM110/112, page 30, while the un-sleeved connector is for the optional DK1200 hand-held controller.

a. Attach the power cord to the three-prong outlet on the back of the power pack.

b. Attach the connector from the power supply to the single output end of the dual output patch cord.

c. Attach the locking power plug located at the other end of the dual power cable, labeled CM110/112, to the power jack on the back of the Digikröm CM110/112, labeled POWER. Lock it in place.

d. Plug the power cord into your wall or power strip outlet. The CM110/112 will reset and find home position.

The RS232 connection requires a cable with a DB9-M subminiature connector at the monochromator, and a computer communications port connector as appropriate for the user. CVI Laser offers a DK12AT, DK12PS and DK12MA cable for connecting to AT, PS2 and MAC style computers, respectively.

Pin Assignments for the Female DB-9 Connector at Rear of CM110/112 (See Appendix I)

Pin	NAME	FUNCTION
1	DCD	Not used with the CM110/112
2	RxD	Data out (from CM110/112 to computer)
3	TxD	Data in (from computer to CM110/112)
4	DTR	Not used with the CM110/112
5	GND	Signal ground
6	DSR	Not used in CM110/112
7	RTS	Request to send (from computer)
8	CTS	Clear to send (from CM110/112)
9	RNG	Not used in CM110/112

The pin assignments above are mapped one-to-one between the cable connection of a Digikröm CM110/112 and an IBM-AT style serial communications port.

2.3 Baud Rate

The computer must be set to the Digikröm CM110/112 data type and baud rate

Character length: 8 bits

Baud rate:

9600 bits/sec

Stop bits:

1

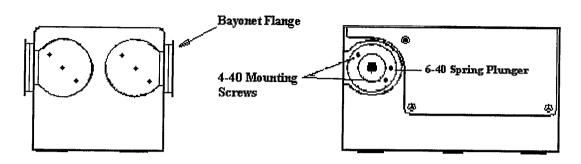
Parity:

None

The Digikröm CM110/112 is factory configured and the character length, number of stop bits and parity cannot be changed. Its signal levels and format are the same as those that are specified for the RS-232. The CM110/112 emulates data communications equipment (DCE).

2.3 Attaching a Detector

Attach a detector to the monochromator using the bayonet mounting flange. In order to maintain a tight optical seal between the monochromator and the detector, it may be useful to allow the detector's mounting flange to protrude slightly into the hole in the slit plate. A rubber or foam gasket between flat surfaces is also frequently used.



2.4 Product Specifications

- Wavelength Drive: Anti-backlash worm and wheel with microprocessor control. Bi-directional. Usable in positive or negative grating orders.
- Beam Path: Either right angle or straight through(standard configuration) from source
- Design: Czerny-Turner, dual-grating turret
- Focal Length: 110 mm
- F/#: 3.3 /NA = 0.15
- Gratings: 30 x 30 mm. See the Standard Grating Table in Appendix B.
- Wavelength Precision:
- >0.2 nm with 1200 g/mm grating
- Wavelength Accuracy:
- \pm 0.2 nm with 1200 g/mm grating
- Slewing Speed:
- >100 nm/second with 1200 g/mm grating
- Maximum Resolution:
- 0.2 nm with 1200 g/mm grating
- **Bandpass:**
- 1 nm with .150mm slit and 1200 g/mm grating
- Standard Slits (mm): 0.125, 0.15, 0.3, 0.6, 1.2, and 2.4. For other values, consult CVI Laser Corporation.
- Software: Demo control program with source is included. A LabVIEW Driver is available upon request.
- Power: UL listed 110/220 V power pack, meets or exceeds UL1950, CSA 1402C, and IEC 950.
- Interface: RS-232 standard
- Warranty: One year from delivery date
- CE marked
- Options: Hand-held control module for local control, IEEE-488 interface, Interface cables, GPIB to RS232 converter, Gold optics for IR range.

$$f = \frac{f}{D} = 3.3$$

NA = SMO = 0.15

Arctin
$$\left(\frac{2}{4}\right)$$
 =
Arctin $\left(\frac{1}{244}\right)$ =
Arctin $\left(\frac{1}{244}\right)$ = 8.6°



Software

3.1 CM110/112 Demo Software-WindowsTM

3.1.1 Hardware Connections

Refer to section 2.2, page 5 for the proper power and communication line connections, as well as any other pertinent installation information. The serial port and baud rate setting for the CM110/112 is saved in the "CM11X.INI" file in the WindowsTM directory.

3.1.2 Getting Started

Software Installation

The software is written in Visual BasicTM for WindowsTM.

To install the CM110/112 demo software, run the program SETUP.EXE found on disk number one. It must be run from within Microsoft® WindowsTM. Once the demo software has been installed, you are ready to get started.

The demo software does not allow the user to plot. We offer software packages with plotting capability and also AD110, AD130, AD140, and Kestrel Spec data acquisition software for CCD cameras.

Configure Serial Port

The first time you run the CM110/112 demo software, you may need to configure the software for the correct serial port. When you run the program, it will search for the "CM11X.INI" file in the WindowsTM directory. If this file exists, the CM110/112 demo software will initialize the serial port with the information that is saved in the "CM11X.INI" file. If the computer is unable to locate the "CM11X.INI" file, the "Initializing Communication Port" form will appear on the screen. If you want to re-initialize the serial port, do it now. You can skip the initialization procedure by clicking "Cancel" in the "Initializing Communication Port" form. However, if you choose not to reinitialize, some commands may not perform. If the computer is able to communicate with the monochromator, the computer will prompt you with the "saving configuration dialog box". Clicking "Yes" will save the configuration to "CM11X.INI" in the Windows directory.

Menus and Commands

This section contains descriptions about both menus and the commands. For each menu, a brief description of commands are given. For more information on these commands, please refer to either Section 3.2.2, page 9 or the online help menu.

Commands Menu

Control Use the "Control" sub-menu to display control commands. The commands are: Goto, Scan, Speed, Step, Size, Select, Inc and Dec, Query, and Echo.

Setup Use the sub-menu to drop-down setup commands that are used to specify the operation of the monochromator. They are: Calibrate, Zero, Order, Units, Type (CM112 only).

Exit Use the "Exit" command on the file menu to quit the CM110/112 Demo Software.

Novram Menu

Novram Read Use this command to read a byte from the monochromator's non-volatile memory.

Novram Write Use this command to write a byte to the monochromator's non-volatile memory.

WARNING!!! Improper use of this command may corrupt the configuration and the calibration information of the monochromator. Consult CVI before using!

Novram Utility Use this command to read, or write 128 (0-127) bytes from or to either the monochromator's non-volatile memory or the file. The print feature is also included in this command.



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COM Port Menu

Baud Finding Use this command to determine the current baud rate of the CM110/112.

Loopback COM Test Use this command to test the serial cable and the communication port. To run this command make

an adapter to plug into your serial port which will loopback the PC's serial data output into its serial

data input. Placing a jumper between pins 2 and 3, and leaving all other pins unconnected does this.

line is true if the PC enables the line, and the CTS line is true if this line is high.

Initialize COM Port Use the command to initialize a serial port and the baud rate of your host computer.

Option Menu

Save Configuration Use "Save Configuration" to save the current values of the serial port, and the baud rate. These

values will be saved to the file "CM11X.INI" in the Windows directory.

Help Menu

Contents Use the "Contents" command to access the table of contents page of the CM110/112 Help file.

Using Help Use the "Using Help" command to display the contents page about How to Use Help.

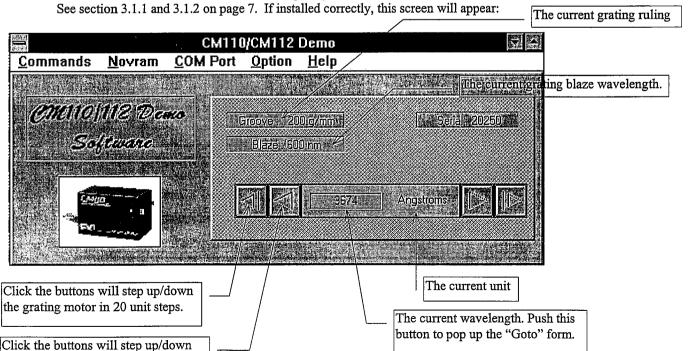
About CM110/112 Use this command to display the program version information.

3.1.3 CM110/112 Visual BasicTM

the grating motor in a single unit step.

CVI Spectral Products offers software that was designed in Microsoft[®] Visual BasicTM 16 bit, Ver. 4.0 for WindowsTM and will run on Windows 3.11, 95 and NT 4.0. If you are interested in writing software that supports the CM110/112, we will be pleased to send this software to you upon request. If you have any questions about the operation of your monochromator or if you have suggestions, please contact us. We appreciate your comments and suggestions.

Hardware Connections / Software Installation / Configuring Serial Port



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3.2 CM110/112 Demo Software-DOS

3.2.1 Installation

Ensure that monochromator is powered up and RS232 is connected.

Place the installation disc into the A drive on your computer.

At the A:\> type

DKDEMO (Enter)

Caution: turn numlock off if using any arrow keys. Disregard if using the arrow keys on numerical keypad.

The following screen should appear:

Use the present Setup (Y), or (N) to re-configure the Test $$\operatorname{\textbf{Press}}$ Y or N

Digikröm Model: CM110
Interface Used: RS-232
RS232 COM port used: COM 1
Time Test Setup was last saved: x/x/xx
Date Test Setup was last saved: x/x/xx

Selecting "Y" without power to the monochromator or no RS232 connected, may cause the computer to "hang up". Selecting "N" will allow the user to change the parameters listed on the setup screen.



3.2.2 Menus and Commands

Goto This command allows the user to enter a new wavelength. Press the "Enter" key to complete this

command.

Query Pressing the enter key will bring up the following sub-menu:

Position Type

Units-Describes the current units

Step Size-Describes the current step size

Number of Gratings-Describes the number of gratings in your Digikröm Current Grating #-This command identifies which grating is currently set

Scan Speed-This command describes the current scan speed

Blaze Wavelength-This command describes the Blaze Wavelength of the current grating

Grating

Units This command allows the user to change the units.

0 = centi-microns 1 = nanometers 2 = Angstroms

Zero This command allows the user to change the location of zero order from the home position in

NOVRAM. Changes made using this command will erase the values preset at the factory.

Calibrate This command prompts the user to "Enter the Calibration value" in the current units. Changes made

using this command will erase the values preset at the factory.

Order This command prompts the user to "Enter the order Byte (1 or 254). 1 = + order and 254 = - order.

Grating Select This command allows the user to select a new grating.

Size This command allows the user to enter a new step size.

Scan Speed This command allows the user to enter a new scan speed.

Dec This command allows the user to rotate the grating by one motor step in the counter-clockwise

direction.

Inc This command allows the user to rotate the grating by one motor step in the clockwise direction.

Echo This command allows the user to see if the monochromator is communicating with their computer.

Echo=27 means "yes".

Scan This command allows the user to enter the wavelength for the "Beginning Scan Position, and the

wavelength for the "Ending Scan Position."

Reset This command returns the grating to the home position.

Type* This command is for CM112 only and allows the user to change between additive or subtractive

mode. Consult CVI before using this command!!

Pressing the "Esc" key with Num lock off, and to "Save the Test Setup" your keyboard will allow you to escape from the Menu

*Note: The CM112 has separate digital drives in each cascaded monochromator and can be used in additive or subtractive mode. Additive dispersion provides better resolution. Subtractive dispersion provides better imaging and low temperal dispersion.

In additive dispersion, the two gratings rotate in the same direction. The grating of the first monochromator spreads the spectrum over an angular range. The grating of the second monochromator doubles this dispersion. In subtractive dispersion, the two gratings rotate in opposite directions. The first monochromator is used to select a bandpass. The second monochromator removes temporal and angular aberrations introduced by the first monochromator.

Operation

4.1 Writing Your Own Control Program

The subscript D indicates the decimal value of the byte is listed.

This command allows recalibration of the monochromator positioning scale factor and should ALWAYS be used immediately after using the ZERO command (see page 13). The monochromator should be set to the peak of a known spectral line, then the position of that line is input using the CALIBRATE command.

CAUTION: Use of this command will erase factory settings.

To CM110/112:

<18>D <High Byte> <Low Byte>

CM110/112 Action: If (256 * <High Byte>) + <Low Byte> is a valid position, then the scale factor used in determining position will be recalibrated to make the current position agree with the input position. The gratings

return to zero after completion.

From CM110/112:

<Status Byte>

From CM110/112:

 $<24>_{\rm D}$

DEC

This command decrements the zero offset value and changes the grating angle by 0.0075 degrees in the clockwise direction. This is generally always followed by the ZERO command. The CM110/112 does not track the change in wavelength incurred by this command. The new offset is not in effect unless the ZERO command is issued.

To CM110/112:

 $<1>_{D}$

From CM110/112:

<Status Byte>

CM110/112 Action: Moves one motor step clockwise

From CM110/112:

 $<24>_{D}$

DEC Machine #2 (CM112 only)

This command decrements the zero offset value for machine #2 and changes the grating angle by 0.0075 degrees in the clockwise direction. This is generally always followed by the ZERO command. The CM110/112 does not track the change in wavelength incurred by this command. The new offset is not in effect unless the ZERO command is issued.

To CM110/112:

 $<2>_{D}$

From CM110/112:

<Status Byte>

CM110/112 Action: Moves one motor step clockwise

From CM110/112:

 $<24>_{\rm D}$

The ECHO command is used to verify communications with the CM110/112.

To CM110/112:

 $<27>_{D}$

From CM110/112:

 $<27>_{D}$

CM110/112 Action: No action.

GOTO

This command moves the monochromator to a selected position. Valid values of position are grating dependent and are described in Appendix C.

To CM110/112:

<16>D <High Byte> <Low Byte>

From CM110/112:

<Status Byte>

CM110/112 Action:

If valid, move to position (256 * <High Byte>) + <Low Byte> [units].

From CM110/112:

 $<24>_{D}$

For example, the command to instruct the monochromator to GOTO the wavelength 250 nm could be sent as the three bytes <16> p <0> p <250> p (if the current units are in nm). Here, <16> p specifies the GOT O command while <0> p <250> p specifies the destination of 250 nm.



INC

This command increments the zero offset value and changes the grating angle by 0.0075 degrees in the counter-clockwise direction. This is generally always followed by the ZERO command. The CM110/112 does not track the change in wavelength incurred by this command. The new offset is not in effect unless the ZERO command is issued.

To CM110/112: <7> D From CM110/112: <5tatus Byte>

CM110/112 Action: Moves one motor step counter-clockwise

From CM110/112: <24> D

INC Machine #2 (CM112 only)

This command increments the zero offset value for Machine #2 and changes the grating angle by 0.0075 degrees in the counter-clockwise direction. This is generally always followed by the ZERO command. The CM110/112 does not track the change in wavelength incurred by this command. The new offset is not in effect unless the ZERO command is issued.

To CM110/112: <8>_D From CM110/112: <8>_D

CM110/112 Action: Moves one motor step counter-clockwise

From CM110/112: <24>_D

ORDER

This command determines if the grating rotates clockwise or counter-clockwise.

To CM110/112: <51>p <Order Byte>
From CM110/112: <Status Byte>

CM110/112 Action: If valid, moves to the zero order position of the selected grating. Rotation of the grating thereafter

will be clockwise if the order byte was 01, and counter-clockwise if the order byte was 254.

From CM110/112: <24>D

OUERY

This command displays the monochromator's status.

To CM110/112: <56>D < Query Byte> From CM110/112: <Status Message>

<Query Byte> Status Message

<00>p <Position High Byte> <Low Byte>

<01>_D <0><Type Byte>

0 = Single

1 = Additive dbl(CM112 only) 254 = Subtractive dbl(CM112 only)

<02>D <Grooves/mm High Byte> <Low Byte>

<03>_D <Blaze High Byte> <Low Byte> <04>_D <0> <Current Grating No.>

<05>D <Speed High Byte> <Low Byte>

 $<06>_D$ <0><Size Byte>

<13>_D <0> <Number of gratings> <14>_D <0> <Current Units>

<19>D <Serial Number High Byte> <Serial Number Low Byte>

CM110/112 Action: No action. From CM110/112: <Status Byte> From CM110/112: <24>_D



RESET

This command returns the grating to home position.

To CM110/112:

<255> p <255><255>

CM110/112 Action: Grating will return to home position

SCAN

This command scans the monochromator between a START position and an END position at a rate determined by the SPEED command. The START may be greater or smaller than the END. Valid values of position are grating and units dependent and are described in Appendix B, page 21.

To CM110/112:

 $<12>_{\rm D}$

<Start High Byte> <Start Low Byte> <End High Byte> <End Low.Byte>

<Status Byte>

From CM110/112: CM110/112 Action:

Sets CTS low, and moves below (above) the starting value. Sets CTS high and accelerates to

scanning speed. Sets CTS low when the Start is reached. Sets CTS high again as END is passed.

From CM110/112:

 $<24>_{\rm D}$

SELECT

Selects the grating that will be used.

To CM110/112:

<26>D <Grating Byte>

From CM110/112:

<Status Byte>

CM110/112 Action:

If valid, moves to the zero order position of the selected grating. Valid grating bytes are 1 and 2.

From CM110/112:

 $<24>_{\rm D}$

SIZE

This command determines the change in magnitude and the direction of the monochromator's position after a STEP command.

To CM110/112:

<55> D <Size Byte>

From CM110/112:

<Status Byte>

CM110/112 Action:

No immediate action. If the Size Byte is less than or equal to 127 (i.e., the most significant bit = 0), a subsequent STEP command will increase the position by that number of units. If the Size Byte is

greater than 127 (most significant bit = 1), then a subsequent STEP command will decrease the

position by that number of units.

From CM110/112:

 $<24>_{D}$

SPEED

Selects the speed at which the monochromator may scan. Valid values of speed are grating dependent and are given in Appendix B, page 20.

To CM110/112:

<13> D < High Byte > < Low Byte >

From CM110/112:

<Status byte>

CM110/112 Action: No immediate action. If a valid value is selected, the SCAN command will thereafter cause the

monochromator to move at approximately a speed value of (256 * <High Byte> + <Low Byte>)

[Å/sec].

From CM110/112:

 $<24>_{\rm D}$



STEP

Moves the monochromator by a preset amount defined by the SIZE command.

To CM110/112:

 $<54>_{\rm D}$

From CM110/112:

<Status byte>

CM110/112 Action: If valid, moves the monochromator so that the position is changed by the value determined by SIZE.

From CM110/112:

TYPE*

Induces the CM112 only, to change between additive and subtractive mode. Consult CVI before using this command!!

To CM112:

 $<57>_{\rm D}$

From CM112:

<Status byte>

CM112 Action:

If <Type> is <01>, then the monochromator will subsequently operate in the additive mode. If

<Type> is <254>, then the monochromator will subsequently operate in the subtractive mode. The monochromator will return to the zero order position in both cases.

From CM112:

 $<24>_{D}$

UNITS

This command allows the selection of units used in the GOTO, SCAN, SIZE, and CALIBRATE commands.

To CM110/112:

<50>_D <Units Byte>

From CM110/112:

<Status byte>

CM110/112 Action: If units byte is valid, the CM110/112 will move to the zero order position. The specified units will

be used in subsequent commands. Note: Each grating may have a different type of unit specified.

Ex; Grating 1 = A, grating 2 = nm. The valid units bytes are listed below.

<Units Byte> <Spectral Units> 00 Microns

> 01 Nanometers 02 Angstroms

From CM110/112: $<24>_{D}$

This command allows the recalibration of the position of the zero order transmission of the monochromator. Note: on a CM112, this will Zero both gratings at the same time. The monochromator should be set to the peak of the zero order transmission for each grating while wavelength = 0 using INC, then the zero command is entered.

CAUTION: Use of this command will erase factory settings.

To CM110/112:

 $<52>_{D}<1>_{D}$

CM110/112 Action: The current zero offset values of the gratings are saved as the zero order position.

From CM110/112:

<Status Byte>

From CM110/112:

 $<24>_{\rm D}$

*Note: The CM112 has separate digital drives in each cascaded monochromator and can be used in additive or subtractive mode. Additive dispersion provides better resolution. Subtractive dispersion provides better imaging and low temperal dispersion.

In additive dispersion, the two gratings rotate in the same direction. The grating of the first monochromator spreads the spectrum over an angular range. The grating of the second monochromator doubles this dispersion. In subtractive dispersion, the two gratings rotate in opposite directions. The first monochromator is used to select a bandpass. The second monochromator removes temporal and angular aberrations introduced by the first monochromator.



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4.2 Hand Held Controller DK1200

The DK1200 Handheld Controller instructs the CM110/112 to control a selected spectral region or the CM110/112 can be remotely controlled via a computer.

4.2.1 Operation

The DK1200 receives power from the CM110/112 power pack. Attach the free end of the dual power cable to the DK1200 extension cable. Attach other end of cable to power jack on back of controller. Once the DK1200 receives power, the control display will read:

Connect the controller RS232 cable to the rear of the CM110/112. Connect the other end of the dual power cable to the power jack on the CM110/112. The CM110/112 will find home position and the control unit display will read:

The keyboard consists of 21 keys, 11 control keys, and 10 number keys, including a decimal point. The STOP option, SLIT ADJ and FILTER/SOURCE keys are disabled with the DK1200.

KEY	
NAME	PURPOSE
GOTO	The user can change the λ wavelength by entering a value for a new wavelength and then pressing enter. This command changes the grating angle, which in turn changes the wavelength at the exit slit.
SCAN λ_2 - λ_1	The user can scan the intensity of light leaving the exit slit over a wavelength range defined as λ_2 - λ_1 . The user can scan different ranges of wavelength by entering the values of λ_1 and λ_2 with this command, then pressing enter. The value of λ_2 - λ_1 may be either positive or negative. Valid values of wavelength are both grating and unit dependent. See Appendix A, page 20.
FILTER SOURCE	Not applicable
ENTER STOP	Press the ENTER/STOP key after every command to carry out that action.
OPTIONS	This command offers 7 menu commands to adjust grating angle number, current units, current order, current type, baud rate, calibration, and to go to next. See section 4.2.4, page 19.
SCAN SPEED	This command selects the speed at which the CM110/112 will scan the intensity of light at the exit slit for a given wavelength range. The user should refer to Appendix B, page 21 for a list of scan speeds that are appropriate for various gratings.
SLIT ADJ	Not applicable
MANUAL •	This command allows the user to change the rotation of the grating by one motor step. It also allows the user to set a new zero position for either λ equal to zero or a nonzero value.
RESET	Resets the grating turret to the home position when pressed simultaneously with the arrow key .

Page 15



Use the GOTO command to instruct the CM110/112 to find a discrete wavelength. The values of wavelength are grating dependent. Once the key is pressed, the display reads:

```
GOTO \lambda
ENTER \lambda = _
```

In response to this prompt, the user may enter the desired wavelength value and press ENTER. During this part of the operation, the display reads:

```
GOTO \lambda = xxxxx
RUNNING......
```

Once the CM110/112 finds the specified wavelength, the GOTO operation stops and the READY screen appears.

The SCAN key allows the user to scan between a start and an end position specified by the user. The START position(λ_1) may be greater or smaller than the END position(λ_2). Valid values of position are grating and units dependent. The scanning speed for the SCAN command is a constant and is determined by the user. Once the SCAN key is pressed, the display reads:

```
SCAN \lambda_1 - \lambda_2
ENTER \lambda_1 =
```

Enter the starting wavelength and press ENTER. The display will then read:

```
SCAN xxxxx - \lambda_2
ENTER \lambda_2 =
```

Now, enter the ending wavelength and press ENTER. Note: once the scan is started it cannot be stopped unless power is disconnected. After the ending wavelength value is entered, the CM110/112 will go to the START position at maximum speed. The CM110/112 will begin scanning, while the display reads:

```
SCAN xxxxx - xxxxxx
SCANNING . . . . .
```

When the scan is complete, the DK1200 will display the READY screen.

The SCAN SPEED key allows the user to control the rate at which the wavelength changes. Values of speed are grating and units dependent and are given in Appendix B, page 21. Once the key is pressed, the display reads:

```
SCAN SPD = xxxxx yy/s
NEW SPD?= zzzzz yy/s
```

xxxxx= indicates the present scan speed.
yy = indicates the present unit.
zzzzz = indicates the new scan speed
s = second

Pressing the SCAN SPEED key allows the user to cycle to the next value. Pressing ENTER will select the new scan speed. If the user does not wish to change the scan speed, pressing the \leftarrow key will return to the READY screen.

The QUERY command offers 19 categories to inquire about. These categories are described in section 4.2.3, page 18.

ENTER=.....ccccccccc QUERY=Next ←=Cancel

Note: cccccccc = the query subject. Pressing QUERY again will cycle through the query options.

Pressing ENTER will select the coccccc query

Pressing the \leftarrow key will return to the **READY** screen.

The **OPTIONS** command offers seven functions described in section 4.2.4, page 19. Cycle through these options by pressing the **OPTIONS** key. Each option is selected by pressing **ENTER**. Once selected, each option has submenus that will prompt the user for information. Press **ENTER** to accept the changes. Pressing the ← will exit the **OPTIONS** mode and return to the **READY** screen.

OPTION.....xxxxxx yyyyyyyyy

The MANUAL key can be used as a decimal point or MANUAL mode key. Section 4.2.5, page 19 describes the functions available under MANUAL. Note: once the MANUAL key is pressed, and you want to exit the program without entering a change, you must use reset and ← or power off the controller. The power off method will not move the mono and retain previous settings. The reset method will cause the mono to physically move.

Pressing the MANUAL key will display the following screen:

CHANGING STEP SIZE

To change the step size, press "6" and ENTER. The DK1200 will display the following message:

MANUAL: 5 = Size 3 = Step - 6 = Step +

Press "5" to specify the step size. The DK1200 will display the following message:

CUR. SIZE = ppppppppppp NEW SIZE = (see right)

Value of 1-127 increments from size 1 to 127 Value of 127-256 decrements from 1 to 127

After entering the step size and pressing ENTER, the following message is displayed:

$$5 = \text{Size} \quad \lambda = \frac{1}{9} = \text{Step} + \frac{1}{9} = \frac{1}{9$$

Current λ is displayed.

Pressing "3" decreases λ by one established step size.

Pressing "9" increases λ by one established step size.

Pressing the MANUAL key will exit the MANUAL mode and return the program to the READY screen.



CHANGING THE OFFSET

Note: this command will erase the values previously programmed into your NOVRAM's memory.

To change the offset value, press MANUAL, enter "4". The DK1200 will display the following message:

CM110

$$\begin{aligned}
\mathbf{MANUAL} &= \dots & \mathbf{CANCEL} \\
\mathbf{1} &= \mathbf{Dec.} & 7 &= \mathbf{Inc.}
\end{aligned}$$

- 7 moves the grating one step below zero (ccw)
- 1 moves the grating one step above zero (cw)

MANUAL =..... CANCEL
4 = Inc&Dec 6 = Step

CM112

Press 4 (Inc&Dec). Note: avoid pressing 6. If you do, press Manual to exit and start over. The display will read:

- 7 & 1 moves grating 1, one step above/below zero
- 8 & 2 moves grating 2, one step above/below zero

Pressing MANUAL displays:

CM110

 CM112

Motor 1 is entrance side, Motor 2 is exit side Press 1 or 2 and display will read:

Pressing Enter establishes a new zero, ← keeps old zero

Any change in zero offset will be reflected here. Pressing any key will return the program to the READY screen.

4.2.2 Error Screens

VALUE INVALID

Whenever a value is entered that is out of range of the machine or the grating or the units are incorrect, the following screen appears:

VALUE INVALID HIT ANY KEY TO CONT

Pressing any key will return the program to the READY screen.

COMPLETION ERROR

When there is a failure to complete a task, a value of 24 occurs, the following message appears:

<24> WAS NOT RECEIVED TURN OFF & ON

The CM110/112 must be turned off and then back on to recover from this error



4.2.3 Query Commands

ENTER = Wavelength $OUERY = Next \leftarrow Cancel$ ENTER = Type $OUERY = Next \leftarrow Cancel$ ENTER = Cur. Grve OUERY = Next ← Cancel ENTER = Cur. Blaze QUERY = Next ← Cancel $ENTER = \dots Num. Grts.$ QUERY = Next ← Cancel ENTER = Scan Spd OUERY = Next ← Cancel $ENTER = \dots Size$ $OUERY = Next \Leftarrow Cancel$ $\overline{\text{ENTER}} = \dots \cdot \overline{\text{Offs. m1g1}}$ $QUERY = Next \leftarrow Cancel$ $ENTER = \dots Offs. m1g2$ $OUERY = Next \leftarrow Cancel$ $ENTER = \dots Offs. m2g1$ $QUERY = Next \Leftarrow Cancel$ $ENTER = \dots Offs. m2g2$ $QUERY = Next \Leftarrow Cancel$ $ENTER = \dots Cal. m1g1$ $QUERY = Next \Leftarrow Cancel$ $ENTER = \dots Cal. m1g2$ $QUERY = Next \Leftarrow Cancel$ $ENTER = \dots Grtngs m1$ $QUERY = Next \leftarrow Cancel$ ENTER = Cur. Unit QUERY = Next ← Cancel $ENTER = \dots Grve m1g1$ $QUERY = Next \Leftarrow Cancel$ $ENTER = \dots Blze m1g1$ QUERY = Next ←Cancel $ENTER = \dots Grve m1g2$ $QUERY = Next \iff Cancel$ $ENTER = \dots Blze m1g2$ $QUERY = Next \iff Cancel$

PURPOSE

This command describes the current wavelength.

This command is used with the CM112 only. It describes if the monochromator is in subtractive or additive mode.

This command describes the groove of the current

This command describes the blaze of the current

This command describes which grating is currently in the optical path.

This command describes the current scan speed.

This command describes the size of each motor step.

This command describes the number of motor steps, using motor 1, required for grating 1 to move from the "home" position to the zero order position.

This command describes the number of motor steps, using motor 1, required for grating 2 to move from the "home" position to the zero order position.

This command describes the number of motor steps, using motor 2, required for grating 1 to move from the "home" position to the zero order position.(CM112 only)

This command describes the number of motor steps, using motor 2, required for grating 2 to move from the "home" position to the zero order position.(CM112 only)

This command describes the number of motor steps required to move the grating #1 from zero order to a specified "calibration" wavelength.

This command describes the number of motor steps required to move the grating #2 from zero order to a specified "calibration" wavelength.

This command describes the number of gratings configured in NOVRAM.

This command describes the current unit setting: microns, nanometers, or angstroms.

This command describes the groove spacing of grating 1 that is configured in NOVRAM.

This command describes the blaze of grating 1 that is configured in NOVRAM.

This command describes the groove spacing of grating 2 that is configured in NOVRAM.

This command describes the blaze of grating 2 that is configured in NOVRAM.



4.2.4 Option Commands

OPTION COMMAND

OI HOILCOIMIMI				
OPTION: Select Grt				
Number of Grtngs $= 2$				
OPTION: Unit				
CUR. UNIT = angs				
OPTION: Order				
CUR. ORDER =+				
OPTION: Type				
CUR. TYPE = Single				
OPTION: Baudrate				
BAUDRATE = 9600				
OPTION: Calibration				
Ready $\lambda = 00000$				
OPTION: Remote				
OPTIONS = Nxt ←Cancel				

PURPOSE

The CM 110 has two gratings. This command alternates the use of gratings 1 and 2.

This command changes the current units to microns, nanometers, angstroms, and inverse centimeters of electron volts.

This command changes the grating order by changing the direction that the grating rotates (clockwise, +, or counter clockwise, -).

Not applicable. This option is installed for the CM112 only.

Not applicable. This option is not installed for changes.

This command calibrates the instrument at a wavelength specified by the user.

This command sets the control module so that the monochromator can be operated remotely through an RS-232 serial port.

4.2.5 Manual Commands

MANUAL COMMAND

	MANUAL =	Cancel
i	MANUAL = 4 = Inc & Dec	6 = Step
	MANUAL =	Cancel
	1 = Dec	7 = Inc
	MANUAL:	.5 = Size
	3 = Step -	9 = Step +

Press MANUAL -----

PURPOSE

This command allows the user to recalibrate to a zero wavelength or a nonzero wavelength.

This command moves the motor one step CCW, when pressing INC, and one step CW when pressing DEC.

This command allows the user to calibrate to a nonzero wavelength. This command moves the motor one step CCW, when pressing STEP+, and one step CW when pressing STEP-.

To exit MANUAL mode.

Appendices

A. Wavelength Ranges

The CM110/112 is restricted to angles between 0 and 70 degrees. The upper restriction is imposed because the grating is almost edge-on to the incident beam beyond this angle.

From these restrictions, one may use the grating equations to calculate the valid ranges and step sizes for any particular grating. The table below lists the maximum wavelength for each grating set in the CM110/112's software.

UPPER WAVELENGTH SCAN LIMIT AND MAXIMUM WAVELENGTH INCREMENTS PER ANGULAR STEP FOR DIFFERENT GRATINGS (Lower wavelength scan limit is zero)

Grating	Upper limit
Grv/mm	nm
3600	500
2400	750
1800	1000
1200	1500
600	3000
300	6000
150	12000
75	24000

Diffraction Limit to Resolution

The grating used in a CM110/112 is a reflective surface with a series of vertical parallel grooves. Collimated light is directed toward the grating, which in turn diffracts the light into component wavelengths. A slight rotation of the grating causes a change in wavelength transmission. For a fully illuminated grating, the resolution of a grating, or ability to distinguish between two wavelengths, is given by the following equation:

$$\Delta \lambda = \frac{\lambda}{N} \text{ or } \Delta \lambda = \frac{\lambda}{Wd}$$

Example: with 1200 gr/mm, 30mm wide @ 600nm

 $\Delta \lambda = 600/(1200 * 30) = .017$ nm if grating is full

m = order

N = total number of grooves illuminated

 λ = wavelength at slit

d =is groove density in gr/mm

W = grating width(mm)

Grating Equation

$$\lambda = \frac{\left(2\cos\frac{\phi}{2}\right)\sin\theta}{mG}$$

Where

G is groove density in gr/mm

is the full Ebert angle. This is a fixed angle determined by the position of the grating, the collimating mirror, and the focusing mirror. It is approximately 25.4° for the CM110/112.

 θ — is the angle that the grating rotates measured from the point at which white light is specularly reflected through the instrument. 70° is the maximum grating angle for the CM110/112. The CM110/112 grating drive provides a minimum $\Delta\theta$ of .0075°

m- is the order of diffraction. For light incident normal to the grating, some of the light will be reflected, diffracted to the right (+1 order), and diffracted to the left (-1 order). Diffraction at greater angles also occurs, but it is not significant (orders $\pm 2, \pm 3, \ldots$)..

Appendix B: Wavelength Scan/Slew Speeds

B. Wavelength Scan/Slew Speeds

Valid scan speeds required by the SPEED command are listed below:

TABLE E-1 Allowed Scan Speed Specifiers [Å/sec]

Grating [grv/mm]

(8"										
n =	0	1	2	3	4	5	6	7	8	9
3600	333	166	83	41	20	10	5	2	1	0
2400	500	250	125	62	31	15	7	3	1	0
1800	666	332	166	82	40	20	10	4	2	0
1200	1000	500	250	125	62	31	15	7	3	1
600	2000	1000	500	250	124	62	30	14	6	2
300	4000	2000	1000	500	248	124	60	28	12	4
150	8000	4000	2000	1000	496	248	120	56	24	8
75	16000	8000	4000	2000	992	496	240	112	48	16

The actual scan speed of the monochromator is determined by the formula:

Actual Speed = Maximum Speed / 2^n Where n = the order of diffraction

Examples:

User defines scan speed as 1000 Å/sec w/1220 g/mm grating

Actual speed = $1000 / 2^0 = 1000 \text{ Å/sec}$

User defines scan speed as 62 Å/sec w/600 g/mm grating

Actual speed = $2000 / 2^5 = 62.5 \text{ Å/sec}$

C. Encoding/Decoding Data Bytes

Many computer-based commands (RS-232) both send and receive information in the form of multi-byte specifiers. For a number given in decimal form, such as base 10, to be sent to the monochromator, the number must first be broken down into hexadecimal bytes (8 bits). Then, each byte is converted into a decimal value. This decimal value is transmitted as a ASCII character to the communication device. Then, the monochromator translates the characters into the form necessary to perform the operation. Conversely, the monochromator sends the data back in decimal characters. Each is a byte long, and the computer application must convert these separate bytes back to a useful decimal value.

ENCODING DATA BYTES

The desired command is GOTO 100 nm. The GOTO command in RS-232 is specified as:

<16><HIBYTE><LOWBYTE>

(onmard (16> < A/B> < A%B)

Int div (a/13)

A % B

where the units for the two byte specifier are determined by the current UNITS selected. For this example, the units are in Angstroms.

Convert the desired specifier to proper units. Step 1: 100 nm = 1000 Angstroms

NOTE: The following steps will be shown two ways: (A) with conversions performed by a unspecified algorithm, for example, using a calculator with decimal-hex conversion capability, and (B) using a numeric algorithm that is more suitable for computers.

Method A:

Convert to Hexadecimal Step 2: 1000(base 10) = 3E8(base 16)

Break the hex value into two bytes Step 3: $3E8(base 16) => 03 \mid E8$

Hi Lo

Convert each byte to its decimal equivalent Step 4:

Hibyte: 03(base 16) => 03(base 10)Lowbyte: E8(base 16) => 232(base 10)

Step 5: Send the command. The specifiers are 3 and 232.

Method B:

Step 3:

Note: All the following numbers are given in decimals.

Divide by 256 and round down to the nearest whole number. Step 2:

1000 / 256 = 3.90625 rounds to 3 = Hibyte

Adjust the remainder. The remainder is the Lowbyte. 1000 - (256 x Hibyte) = 1000 - (256 x 3) = 232Remainder = 232 = Lowbyte

Send the command. The specifiers are 3 and 232. Step 4:



Appendix C: Encoding / Decoding Data Bytes

DECODING DATA BYTES

The desired command is QUERY POSITION.

The QUERY POSITION command returns two bytes indicating the current wavelength, in the form

<HIBYTE><LOWBYTE>

To be useful to the user, the two bytes must be converted back to a single decimal number. As before, we can do this by either method A or method B, by essentially reversing the above procedures.

For this example, the QUERY POSITION command returns the ordered pair (5, 106), Hibyte, Lowbyte respectively, as the current wavelength. For this example, the units are in Angstroms.

Method A:

Step 1: Convert each byte to its hex equivalent

Hibyte: 05(base 10) = 5(base 16)Lowbyte: 106(base 10) = 6A(base 16)

Step 2: Concatenate the 2 bytes to form one hex number

 $05 \mid 6A = 056A(base 16)$

Step 3: Convert the hex number to a decimal

056A(base 16) = 1386(base 10) Å = 138.6 nm.

Method B:

Note: All of the following numbers are in decimals.

Step 1: Use the formula:

Wavelength (λ) = (Hibyte x 256) + Lowbyte

 $(05 \times 256) + 106 = 1386$ Angstroms



Appendix D: Status Bytes

D. Status Bytes

Whenever the CM110/112 is given a command, it will respond with a status byte that indicates whether or not the command was accepted. Each bit in the status byte has a meaning, which is given below. When a command is not accepted, some of the bits of the status byte will indicate the reason. In general, if <Status Byte>D is smaller than 128, then the command was accepted.

Bit 7: 0 if the command is accepted.

1 if the command is not accepted.

Bit 6: 0 if the command requires action

1 if the command requires no action (specifier value equals present value)

Bit 5: 0 if the specifier was too large

1 if the specifier was too small (Irrelevant if Bit 7 is 0.)

Bit 4: 0 if scan is positive going

1 if scan is negative going (Irrelevant if Bit 7 is 0.)

Bit 3: 0 if positive orders

1 if negative orders

Bit 2,1,0: Binary value is:

000 if units are microns

001 if units are nanometers

010 if units are angstroms

For the SCAN command, which uses two specifiers, bits 6 and 5 take slightly different meanings.

Bit 6: 1 if Lambda 1 is not acceptable

0 if Lambda 1 is acceptable

Bit 5: 1 if Lambda 2 is not acceptable

0 if Lambda 2 is acceptable



Appendix E: Novram Program

E. Novram Program/Calibration Procedures

These commands are Read from Novram and Write to Novram. There are 128 memory locations in the Novram, and their addresses are from 0 to 127. Table on page 27 gives the address and the meaning in the Novram memory.

READ FROM NOVRAM

These commands read a byte from the monochromator's non-volatile memory.

To CM110/112:

<156>D<Address Byte>

From CM110/112:

<Data Byte>

From CM110/112:

<Status byte>

CM110/112 Action: No action.

From CM110/112:

 $<24>_{D}$

Data Byte contains a returned value, and Address Byte is 0 through 127.

WRITE TO NOVRAM

These commands write a byte to the monochromator's non-volatile memory.

WARNING !!!

Improper use of this command may corrupt the configuration and calibration information of the monochromator. Consult CVI if you need to restore factory settings.

To CM110/112:

 $<159>_D$ < Address Byte >

<Data Byte><Checksum Byte>

From CM110/112:

<Status byte>

CM110/112 Action:

If valid, Data Byte is saved into non-volatile memory at Address Byte.

From CM110/112:

 $<24>_{D}$

Valid choices for Address Byte are integer values between 0 and 127, and valid values for DataByte are integer values between 0 and 255. The CheckSum Byte = Address Byte + Data Byte. The checksum will be truncated to 1 byte long if its value is bigger than 255.

CALIBRATION: Proper calibration should always be a two step procedure where ZERO is set first, followed by calibrating at a specific wavelength as follows:

CALIBRATING ZERO WITH A HANDHELD CONTROLLER

Calibrating CM110 zero will erase the value previously programmed into your NOVRAM's memory. Consult CVI before proceeding with CM112. CM112 Zero is factory set.

- Using a white light source, illuminate the entrance slit. Make sure the light source is aligned perpendicular to the entrance slit.
- Install your smallest slits, preferably .125 mm, at both the entrance and exit.
- Look through the exit slit. You should see the illuminated white light source.
- If necessary, you may have to reset the Zero location using the MANUAL command.
- Using GOTO, Set $\lambda=0$
- Press Enter.
- Press MANUAL. Press 4 for Inc/Dec.
- To move the motor one step counterclockwise press "1", one step clockwise press "7". Press either "1" or "7" until you see the white light source at its brightest intensity.
- You will be asked if you want to accept the new value for zero. You can accept or reject the changes. 9.
- 10. Press MANUAL to exit.



Appendix E: Novram Program

CALIBRATING AT A WAVELENGTH WITH A HANDHELD CONTROLLER

Recalibration will erase the values previously programmed in your NOVRAM's memory.

- 1. Using a discrete light source, such as a HeNe laser or a Hg pen lamp, illuminate the entrance slit. Make sure the light source is aligned perpendicular to the entrance slit.
- 2. Install your smallest slits, preferably .125 mm, at both the entrance and exit.
- 3. Use a appropriate detector for determining maximum intensity.
- 4. Using GOTO, set λ = (to the new wavelength). Press Enter.
- 5. If the new wavelength is not correct, enter into MANUAL mode, press 6 (step).
- 6. At this point, you have three options: 3=STEP-, 5=SIZE, and 9=STEP+. "3" and "9" move the motor one unit wavelength in each direction. Toggle between 3 and 9, until the light source is at its maximum intensity.
- 7. Press MANUAL to exit.
- 8. Press OPTIONS until CALIBRATION appears. Press ENTER.
- 9. Enter the spectral wavelength, in the appropriate units, press ENTER to calibrate the machine.



Appendix E: Novram Program

NOVRAM ADDRESS

Address	The meaning of the content			
0	The baudrate index: 0 is 9600 b/s			
1	Current selected grating: 1 or 2.			
2	Zero offset high byte of machine 1, grating 1.			
3	Low byte of the above number.			
4	Zero offset high byte of machine 1, grating 2.			
5	Low byte of the above number.			
6	Calibration high byte of machine 1, grating 1			
7	Low byte of the above number			
8	Calibration high byte of machine 1, grating 2			
9	Low byte of the above number			
10	Groove index of grating 1; 0: = 3600 g/mm; 1: = 2400; 2: = 1800;			
	3:= 1200; 4: = 600; 5: = 300; 6: = 150; 7: = 75.			
11	Groove index of grating 2. The meaning is the same as grating 1.			
12	Blazed high byte of grating 1 in nm.			
13	Low byte of the above number.			
14	Blazed high byte of grating 2 in nm.			
15	Low byte of the above number.			
16	Total gratings of machine 1.			
17	Total gratings of machine 2. (CM112 only)			
18	Zero offset high byte of machine 2, grating 1. (CM112 only)			
19	Low byte of the above number. (CM112 only)			
20	Zero offset high byte of machine 2, grating 2. (CM112 only)			
21	Low byte of the above number. (CM112 only)			
Order and Type. Bit 0 (for m1g1): 1 is - order, 0 is + order; Bit 1 (for m1g2): 1 is -				
	is + order; Bit 4 (for grating 1): 1 is subtractive dispersion, 0 is additive dispersion; Bit 5			
	(for grating 2): 1 is subtractive dispersion, 0 is additive dispersion. (Bits 4,5 CM112 only)			
23	Not used			
24	Current machine 1 unit – 0=centimicrons, 1=nm, 2=angstroms			
25	Current machine 2 unit – 0=centimicrons, 1=nm, 2=angstroms (CM112 only)			
26	Serial number high byte			
27	Serial number low byte			
Not used				
29	Not used			
30	Not used			
31	Not used			
32	AA in hex if programmed			
33	AA in hex if programmed			
34 - 127	Not used			

Appendix F: Accessories

F. Accessories

CM110/112.

Complete listing of additional accessories and pricing is available from CVI Instruments Group.

Light Sources and Calibration Lamps available through CVI Laser Corporation

Part #	Description					
AS201-S	Xenon fiber optic "extended" light source, with type S liquid lightguide, 175 W in a combination power supply/lamp housing assembly. Range: 200-1100 nm.					
AS202-V	Xenon fiber optic "ozone blocking" light source with type V liquid lightguide, 175 W in a combination power supply and lamp housing assembly. Range: 320-700 nm.					
AS220	Visible source assembly. A 30 W tungsten-halogen lamp in housing with focusing optics. A separate constant current power supply is provided for filament temperature control. Fiber coupling is available. Range: 300-2500 nm.					
AS240	UV-Deuterium source assembly. A 30 W deuterium lamp in its own housing for c monochromators. Fiber coupling is available. Range 180-400 nm.	oupling with Digikröm				
AS260	Spectral calibration assembly, lamp housing and power supply for the following spectral c	alibration lamps.				
	AS361 Hg spectral calibration lamp. Range: 180-1020 nm					
	AS362 Ne spectral calibration lamp. Range: 800-3500 nm	is in the second of the second				
	AS363 Xe spectral calibration lamp. Range: 800-3500 nm	Table 1				
	AS364 Ar spectral calibration lamp. Range: 700-1000 nm	1000 ·				
	AS365 Kr spectral calibration lamp. Range: 400-2200 nm	sab Wa V				
AD110	Photobyte-P Photomultiplier Amplifier System The AD110 is a computer controlled photomultiplier amplifier, which allows currer interfaced with a side-on PMT. Signals from the detector are sent to an A/D converte which communicates with LabVIEW®, QuickBASIC®, and VisualBasic® software pack is provided and connections are explained in the AD110 user's manual.	r data acquisition card,				
AD130	Photodetector Module The AD130 is a Photobyte S detector module. It was designed to operate with any of C monochromators. The AD130 module does not have the sensitivity of a photomula appropriate for some applications. CVI Laser Corporation offers an uncooled germanium photodiode to extend the useab module. However, due to high dark currents, this option is considerably less sensitive the systems. Interface cabling is provided and connections are explained in the AD130 user's	tiplier tube, and is not le range of the AD130 an alternative detection				
AD140	CCD Detection System The AD140 system consists of either a Digikröm CM110/112 monochromator, an EDC camera and a plug-in interface card and connecting cables. The software is written Windows TM and runs on Windows TM 3.1. Interface cabling is provided and connection AD140 user's manual.	in Visual Basic™ for				
AE G	A C 11 1' C C'1					

AF Series - A full line of fiber optic couplers, adapters, and cable assemblies that allow even greater portability of the



Appendix G: Product Conversions

G. Product Conversions

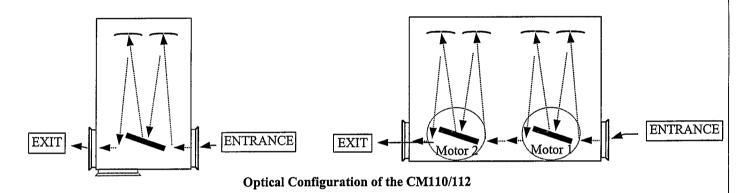
Changing Slits

To change the entrance slit, pull the slit out from the slit mount. The slit mount flange has a spring ball plunger that is factory set for holding the slits firmly in place. When sliding the slit in and out, you should feel the force of the ball plunger.

Converting to a Spectrograph

The CM110/112 can be used in spectrograph mode when using the AD140 CCD camera with the exit folding mirror in place. Simply remove the exit slit and the bayonet flange. Then, attach the AD140 using its own mount.

If you are considering coupling the CM110/112 in spectrograph mode with other CCD array detection devices, use the CMSP110 instead. This unit has significant design differences, such as a different focusing mirror and exit port adapter (see below). Call CVI for a quote on converting your CM110/112 to a CMSP110/112 or vice versa.



Changing the Optical Path

Optical configuration may be changed to allow for either a right angle or a straight-through optical path. The Digikröm CM110/112 is factory assembled with a removable folding mirror in place, unless otherwise requested by the customer. Therefore, the instrument is usually configured for a straight-through optical path.

NOTE: only one of the two folding mirrors in the CM110/112 is removable. Before you attempt to remove the mirror, refer to page 28, and follow directions below:

The conversion of the monochromator from the straight-through optical configuration to the right angle optical configuration is a six-step process.

- 1. The folding mirror assembly is held in place by two 4-40 screws (items #1) located at the exit flange side. Remove the two screws, and gently pull the folding mirror mount assembly out of the CM110/112 housing.
- 2. To remove the folding mirror from its mount, remove the center 4-40 screw (item #2) that holds the mirror in place. Gently pull the mirror off of the mount. Be careful not to touch the mirror's surface because it can be easily scratched or damaged.
- 3. Reinsert the middle screw into the mirror mount assembly and attach with a 4-40 nut. This is necessary in order to keep stray light to a minimum.
- 4. Move the exit flange from the side position to the position where you removed the folding mirror.
- 5. Install the mirror mount (which you disassembled in step 2) into the opening where you removed the exit flange.
- 6. The monochromator should be re-zeroed. NOTE: do not proceed with this step until you understand Calibrating Zero with a Handheld Controller and Calibrating at a Wavelength on pages 24 and 25.

Changing Gratings

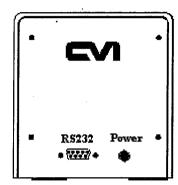
To change gratings, please contact the Spectral Products Group at CVI Laser Corporation at (505) 296-9541.



Appendix H: Reference drawings

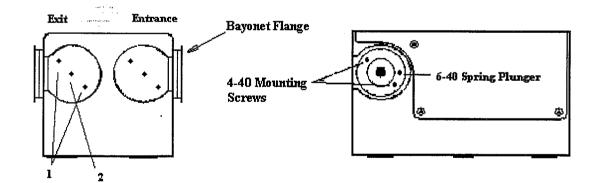
H. Reference Drawings

Connections - Power / RS232



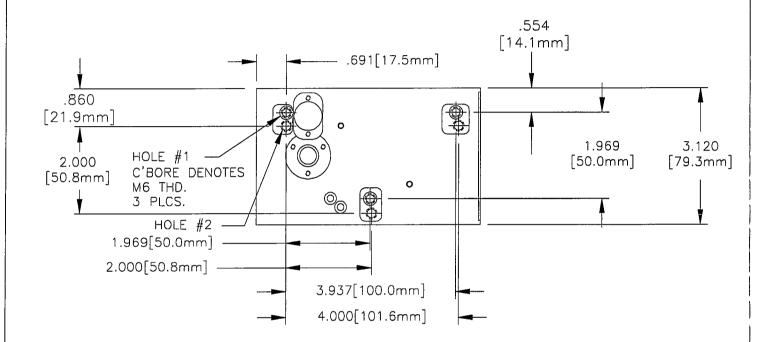
Digikröm CM110- End View

Changing the Optical Path



Appendix H: Reference drawings

Optical Bench Mounting

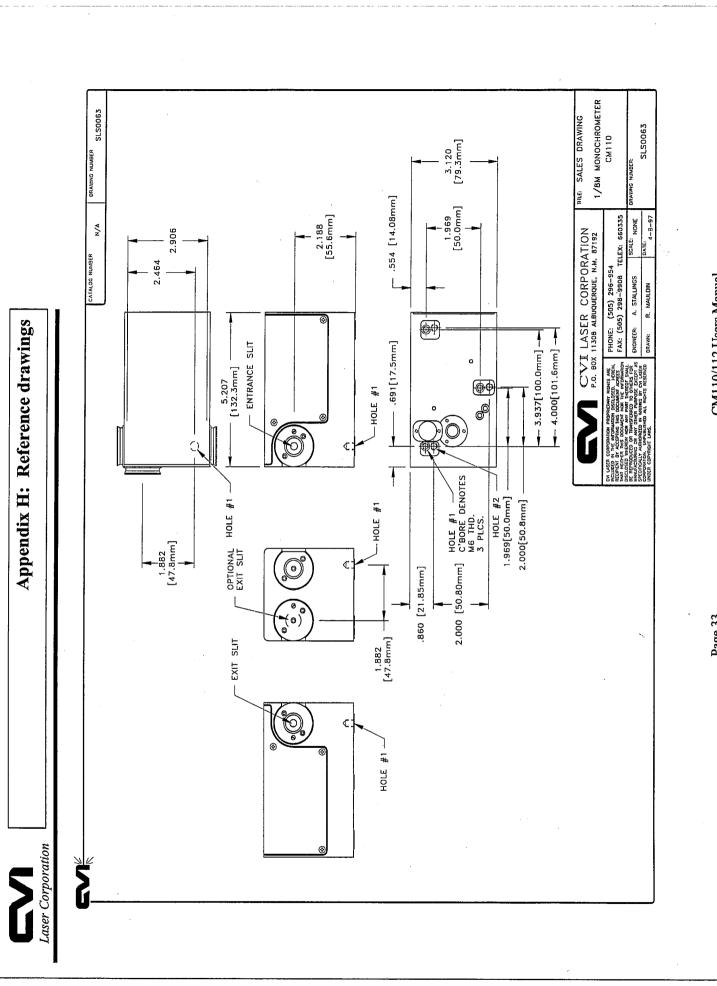


Digikröm CM110-Bottom View

Description

- 1 M6 threads (3) used for attaching the instrument to a optical bench.
- 2 ½ 20 threads (3) used for attaching the instrument to a optical bench.

Threaded holes are occupied with set screws to prevent light leaks. If set screws are removed for mounting, retain for future use.



Optical Path Design

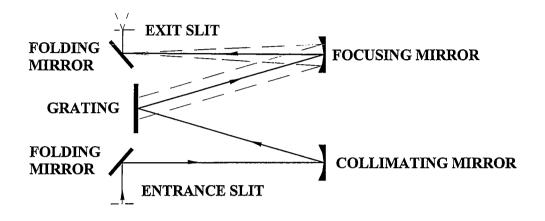


Figure 1
Schematic of the "Straight-through" Optical Configuration for the Digikröm CM110

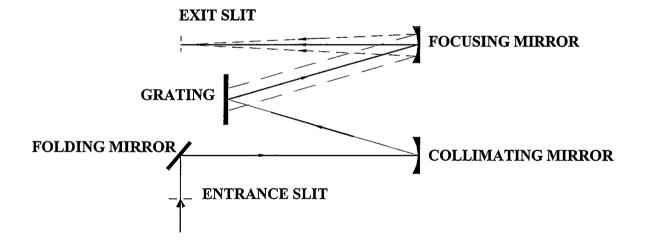


Figure 2
Schematic of the "Right Angle" Optical Configuration for the Digikröm CM110



APPENDIX I: CM TO COMPUTER PIN OUT

I. Reference CM110/CM112 Interface Pin Layout

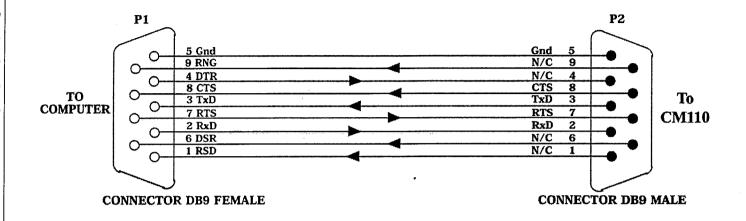


Fig. I-1 CM110 to AT 9 Pin Serial Port

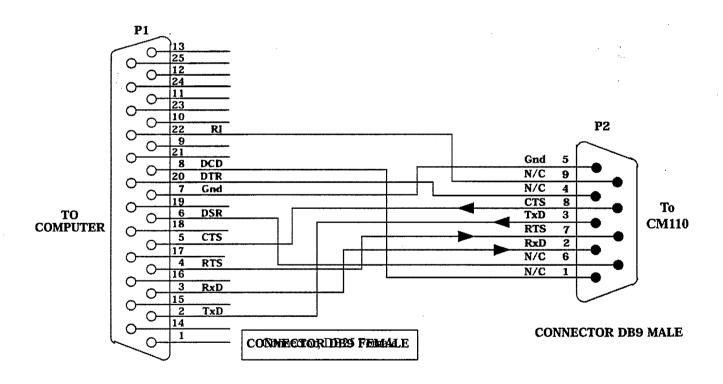


Fig. I-2 CM110 To PC 25-Pin Serial Port



APPENDIX J: SERIAL RELAY COMMANDS

J. Reference Serial Relay Command

SERIAL RELAY OPERATION

All CVI Instruments with an RS232 interfaces now support a serial relay mode. The serial mode allows multiple instruments to be controlled from one serial port.

In the serial relay mode, a daisy-chain cable allows serial messages to be relayed from instrument to instrument. Only one selected instrument will respond to the message.

A computer sends a serial message over its RxD line to instrument #1. If instrument #1 is in the SELECT state, that message is interpreted as a command. If the instrument is in the DELSELCT state, the message received on the RxD line is retransmitted on the TxD line. The handshaking signals (CTS,.RTS) are similarly relayed. The deselected instrument acts as a repeater.

DELSELECT COMMAND

The **DESELECT** command places the instrument in a serial relay mode. In the mode the instrument will echo all inputs. The monochromator will only recognize the **SELECT** command while in this mode;

To Instrument <255> <254> From Instrument <255> <254>

Instrument action: Relays all commands (Only recognizes select command).

SELECT COMMAND

The SELECT command places the instrument in normal operation. Because the SELECT command is serial number specific, a SELECT command will enable only a single instrument.

To Instrument <255><253> <HighByte><LowByte>
From Instrument <255><253> <HighByte><LowByte>

From Instrument <24>

Instrument action: Recognizes all commands (Normal operation).

* Where 256 * <HighByte> + <LowByte> = Serial Number of Instrument

Caution:

Only a single instrument should be selected at one time.

Therefore, a DESELECT command should precede each SELECT command.

Data Rate.

All instruments must be set for the same baud rate, number of stop bits, and number of parity bits.

