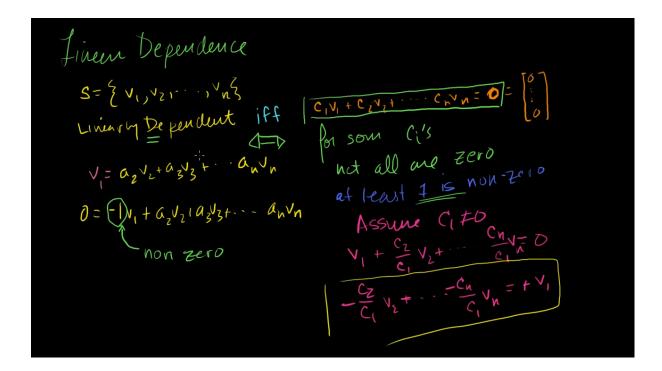


## More on Linear Independence

Understanding when vectors are team players (dependent) or solo stars (independent)

Source: More on linear independence (video) | Khan Academy

# What Does "Linearly Dependent" Mean? — Formal Definition



Let's define a set of vectors:

$$S = \{ ec{v}_1, ec{v}_2, \ldots, ec{v}_n \}$$

This set is linearly dependent if and only if:

More on Linear Independence

$$c_1ec{v}_1+c_2ec{v}_2+\cdots+c_nec{v}_n=ec{0}$$

...for some scalars  $c_1, c_2, \ldots, c_n \in \mathbb{R}$  where **not all**  $c_i = 0$ 

- The condition  $\vec{0}$  represents the **zero vector**, which is a vector where every component is 0, like (0,0), (0,0,0), etc.
- If even one scalar is non-zero, of the set is linearly dependent.

Think of this like cooking: If you can mix some ingredients (vectors) in just the right non-zero proportions to end up with something bland and flavorless (the zero vector), then the ingredients weren't unique — one or more could be made from the rest!

# **Equivalent Definition: Redundant Vector View**

An alternate, equivalent definition:

A set of vectors is linearly dependent if at least one vector in the set can be written as a **linear combination** of the others.

Mathematically:

$$ec{v}_1=a_2ec{v}_2+a_3ec{v}_3+\cdots+a_nec{v}_n$$

### Proof of Equivalence

Subtract  $\vec{v}_1$  from both sides:

$$\vec{0} = -\vec{v}_1 + a_2\vec{v}_2 + \cdots + a_n\vec{v}_n$$

We now have a linear combination that

- $\checkmark$  equals  $\vec{0}$ , and
- $\checkmark$  not all scalars are zero (-1)
- → matches the original definition

Conversely (another way to prove this equivalent definition):

Suppose we have a linear dependence, then it is:

$$c_1\vec{v}_1+\cdots+c_n\vec{v}_n=\vec{0}$$

 $\bigcirc$  In a linearly dependent set, there must exist **at least one non-zero scalar** in the linear combination that yields the zero vector. For the purpose of analysis or proof, **it is not essential to identify exactly which scalar is non-zero**. Therefore, any one may be chosen arbitrarily (e.g.,  $c_1 \neq 0$ ) to **demonstrate that a particular vector can be expressed as a linear combination** of the others.

Because it's a linear dependent, it has at least one non-zero constant ightarrow assume  $c_1 
eq 0$ .

Divide through by  $c_1$ , rearrange, and boom  $\aleph$ :

$$\vec{v}_1 = -\frac{c_2}{c_1}\vec{v}_2 - \dots - \frac{c_n}{c_1}\vec{v}_n$$

Again,  $ec{v}_1$  is a combo of the others ightarrow equivalent definition confirmed lacksquare



$$\begin{cases}
 \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \\
 \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} 
\end{cases} = \text{span}(x) = R^{2} \\
 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + C_{2} \begin{bmatrix} 3 \\ 2 \end{bmatrix} = D \\
 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + C_{2} \begin{bmatrix} 3 \\ 2 \end{bmatrix} = D \\
 \begin{bmatrix} 4 \\ 2 \end{bmatrix} = D \\$$

Are 
$$ec{v}_1 = egin{bmatrix} 2 \\ 1 \end{bmatrix}$$
 and  $ec{v}_2 = egin{bmatrix} 3 \\ 2 \end{bmatrix}$  linearly dependent?  $\ref{eq:v}$ 

Let's solve:

$$c_1 egin{bmatrix} 2 \ 1 \end{bmatrix} + c_2 egin{bmatrix} 3 \ 2 \end{bmatrix} = egin{bmatrix} 0 \ 0 \end{bmatrix}$$

This leads to the system:

$$egin{cases} 2c_1+3c_2=0 \ 1c_1+2c_2=0 \end{cases}$$

Multiply second equation by 2:

$$2c_1 + 4c_2 = 0$$

Subtract from first:

$$(2c_1+3c_2)-(2c_1+4c_2)=-c_2=0\Rightarrow c_2=0\Rightarrow c_1=0$$

- Both coefficients must be 0 ⇒ Vectors are linearly independent!
- Neither vector can be made from the other.
- lacksquare These vectors span  $\mathbb{R}^2$  (the full 2D plane).

## 🚔 Example 2

$$\begin{cases}
\begin{bmatrix} 2 & 1 & 1 \\ 2 & 1 \\ 2 & 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} + C_{3} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 2 \end{bmatrix} - 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 3 \\ 2 \end{bmatrix} - 1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \end{bmatrix} \\
2C_{1} + 3C_{2} + C_{3} = 0
\end{cases}$$

$$\begin{array}{c} C_{3} = -1 & C_{1} = -4 \\ C_{2} = 3 \end{array}$$

$$\begin{array}{c} C_{1} + 2C_{2} + 2C_{3} = 0 \\ C_{1} + 4C_{2} - 2 = 0 \\ C_{1} + 4C_{2} - 2 = 0 \end{array}$$

$$\begin{array}{c} C_{1} + 4C_{2} - 2 = 0 \\ C_{1} = -4 \\ C_{2} = 3 \\ C_{2} = 3 \end{cases}$$

$$\begin{array}{c} C_{1} = -4 \\ C_{2} = -3 \\ C_{2} = 3 \\ \end{array}$$

Are 
$$ec{v}_1=igg[egin{a}2\\1\end{bmatrix}$$
 ,  $ec{v}_2=igg[egin{a}3\\2\end{bmatrix}$  ,  $ec{v}_3=igg[egin{a}1\\2\end{bmatrix}$  linearly dependent?  $@$ 

### Now test:

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = \vec{0}$$

Leads to the system:

$$\left\{ egin{aligned} 2c_1+3c_2+1c_3&=0\ 1c_1+2c_2+2c_3&=0 \end{aligned} 
ight.$$

💡 This system has **more unknowns than equations** (3 variables, 2 equations), making it underdetermined. Hence, it admits infinitely many solutions. Infinite solutions mean we

can assign an arbitrary value to any one variable (e.g.,  $c_3=-1$ ) to **explore whether at least one non-trivial solution exists** among them.

 $\mathbb{Q}$  Observation: 3 vectors in  $\mathbb{R}^2$ ? Always dependent! It's overkill.

Why? Because in a 2D space,

only 2 vectors max can be linearly independent. Third one's always a combo 💥

Still, let's verify:

Pick 
$$c_3=-1$$

Substitute into the equations:

$$2c_1 + 3c_2 - 1 = 0 \Rightarrow 2c_1 + 3c_2 = 1$$

$$c_1 + 2c_2 - 2 = 0 \Rightarrow c_1 + 2c_2 = 2$$

Now solve:

Multiply second equation by 2:

$$2c_1 + 4c_2 = 4$$

Subtract first:

$$(2c_1+4c_2)-(2c_1+3c_2)=c_2=3\Rightarrow c_1=-4$$

So:

$$c_1 = -4, \quad c_2 = 3, \quad c_3 = -1$$

 $\bigvee$  Not all zero  $\rightarrow$  **Linearly dependent**.

$$\Rightarrow \text{Extra proof:} -4\begin{bmatrix}2\\1\end{bmatrix} + 3\begin{bmatrix}3\\2\end{bmatrix} + (-1)\begin{bmatrix}1\\2\end{bmatrix} = \begin{bmatrix}-8\\-4\end{bmatrix} + \begin{bmatrix}9\\6\end{bmatrix} + \begin{bmatrix}-1\\-2\end{bmatrix} = \begin{bmatrix}0\\0\end{bmatrix} = \vec{0} \checkmark$$

We found a linear combo that makes zero! In fact, all 3 coefficients are non-zero

## Key Takeaways

- A set of vectors  $\{ ec{v}_1, \ldots, ec{v}_n \}$  is **linearly dependent** if:  $c_1 ec{v}_1 + \cdots + c_n ec{v}_n = ec{0} \quad ext{for some } c_i 
  eq 0$
- Equivalent view: One vector is a linear combo of others III
- The zero vector can always be made by the zero-scalar combo (trivial solution) — not enough to claim dependence.
- If only solution is all-zero → linearly independent √
- More vectors than dimensions (e.g. 3 vectors in  $\mathbb{R}^2$ )  $\rightarrow$   $\blacksquare$  Guaranteed dependence
- Independent vectors = no redundancy. Each one adds new direction
- Dependent vectors = redundancy. Some directions are recycled 🛟