

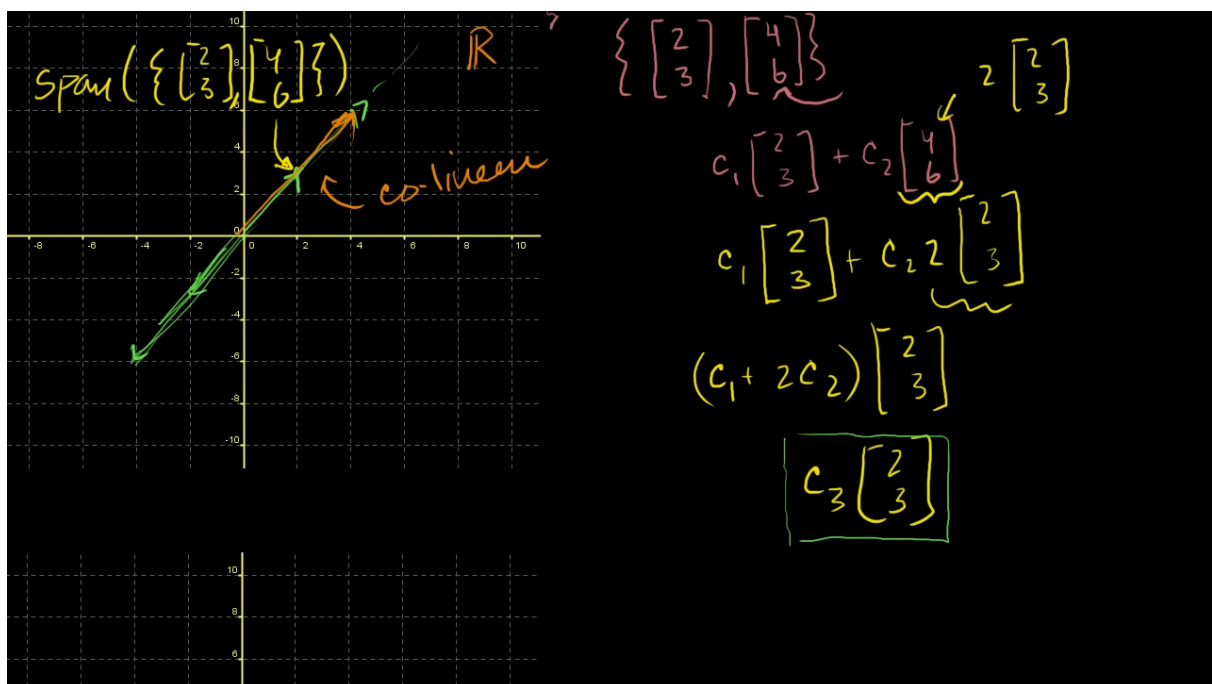


Introduction to Linear Independence

Source: [Introduction to linear independence \(video\)](#) | Khan Academy



Span of Vectors: What Directions Can We Reach?



Example: Vectors $\vec{v}_1 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ and $\vec{v}_2 = \begin{bmatrix} 4 \\ 6 \end{bmatrix}$

- The **span** of a set of vectors is the set of **all vectors you can reach** by forming **linear combinations**:


$$c_1\vec{v}_1 + c_2\vec{v}_2$$


- Since $\vec{v}_2 = 2\vec{v}_1$, we can write:

$$c_1\vec{v}_1 + c_2\vec{v}_2 = (c_1 + 2c_2)\vec{v}_1$$

Let's call $c_3 = c_1 + 2c_2$. So:

$$\text{All combinations} \Rightarrow \vec{v} = c_3\vec{v}_1$$

- **Visual Analogy** : Every linear combination of \vec{v}_1 and \vec{v}_2 lies on a **straight line** through the origin—the line defined by \vec{v}_1 in both directions (positive and negative).

Think of \vec{v}_1 as a rail, and \vec{v}_2 just another train car riding that same track .

Linear Dependence: The “No New Info” Scenario

Definition

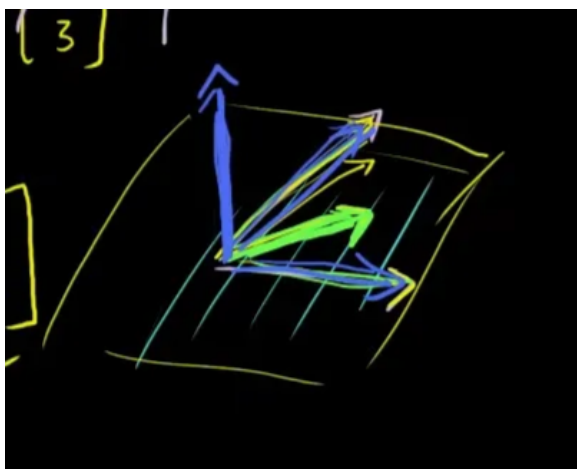
A set of vectors is **linearly dependent** if **one vector can be expressed as a combination of the others**.

Our Earlier Example

- $\vec{v}_2 = 2\vec{v}_1$, so \vec{v}_2 contributes **no new direction**.
- Span is still just a **1D line**, even with two vectors.
- **Conclusion:** The set $\{\vec{v}_1, \vec{v}_2\}$ is **linearly dependent**.

🔄 Imagine having two compasses, but both only ever point north. One isn't helping!

\mathbb{R}^3 Example: The Plane vs 3D Space



Visualize

- Two non-parallel vectors in \mathbb{R}^3 define a **plane** 🪂.
- To span the full 3D space (\mathbb{R}^3), we need a third vector that **isn't** stuck in that plane.

Scenario

- If vector 3 lies **in** the plane formed by vectors 1 and 2 → it's **redundant** (still just define a plane).
- If vector 3 shoots **out of** the plane → it adds a **new dimension** and the set becomes linearly **independent**.



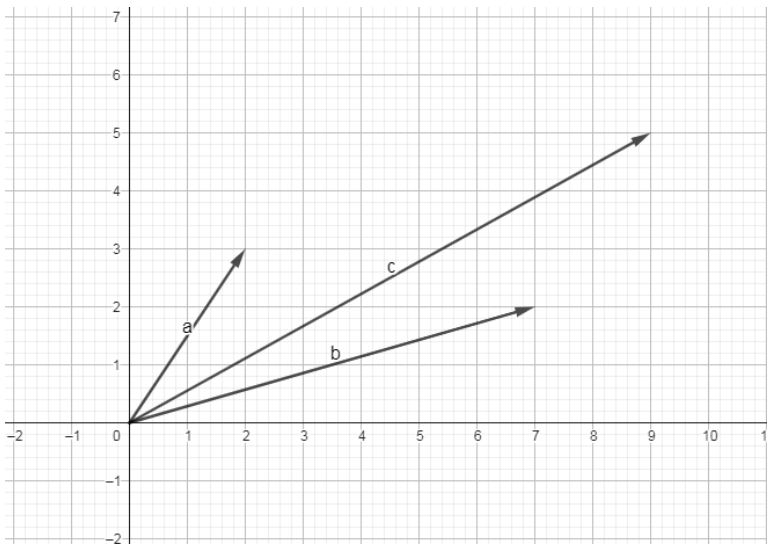
Picture a paper plane lying on a desk (2 vectors); adding a pencil standing upright is the 3rd vector breaking out into full 3D.



2D Trick Question: Three Vectors in \mathbb{R}^2

Vectors:

$$\vec{a} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 7 \\ 2 \end{bmatrix}, \quad \vec{c} = \begin{bmatrix} 9 \\ 5 \end{bmatrix}$$



- At first glance, none are scalar multiples... so maybe they're independent?
- But 🧐: $\vec{c} = \vec{a} + \vec{b}$
- So \vec{c} is **dependent** on the first two!
- Hence, the set is **linearly dependent** despite appearing unique at first glance.

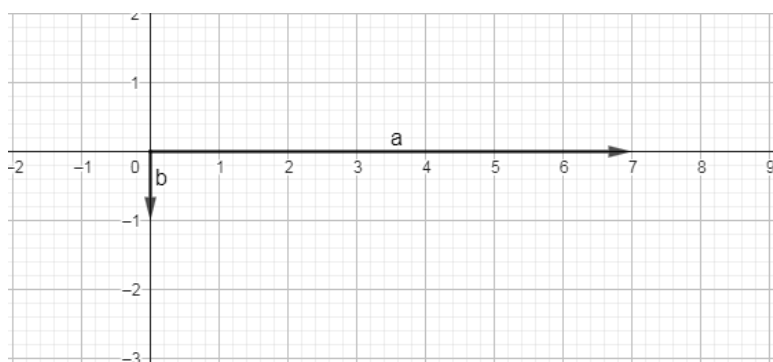


It's like solving a puzzle only to realize one piece was made by taping two others together.


Pure Independence: Vectors That Go Their Own Way

Example:

$$\vec{v}_1 = \begin{bmatrix} 7 \\ 0 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$




- Can we get one from the other? Nope.
- No scalar of \vec{v}_1 gives \vec{v}_2 , and vice versa.
- 🌟 They point in **perpendicular directions**.
- Together, their span = \mathbb{R}^2 , the entire 2D space.

 Like mixing red and blue—suddenly you can make purple and everything else. Perfect independence!

Redundant Sets Still Span the Same Space

Even with dependent sets, the **span** can be the same:

- In the example above, the span of $\{\vec{a}, \vec{b}, \vec{c}\}$ is still \mathbb{R}^2 .
- \vec{c} is just **extra baggage**.
- The **most efficient** set that spans the space is called a **basis** (formal definition to come).


 Why carry three pens when two are enough to draw the whole map?

Independence in 3D: The Axes Squad








Vectors:

$$\vec{v}_1 = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 7 \end{bmatrix}$$

- None of these can be written as a combo of the others.
- Each adds a **completely new direction**.
- They're just scaled versions of the standard unit vectors $\hat{i}, \hat{j}, \hat{k}$.
- This is the **perfect linearly independent set** in \mathbb{R}^3 .

 Like x, y, and z axes—each pointing into its own dimension without overlap.

Key Takeaways

-  **Span:** All vectors that can be built from linear combinations of a given set.
-  **Linear dependence:** At least one vector is **redundant**—can be formed from the others.
-  **Linear independence:** No vector in the set can be built from others—each adds **new directionality**.
-  In \mathbb{R}^2 , any more than 2 vectors will be linearly dependent.
-  In \mathbb{R}^3 , 3 **non-coplanar** vectors can span the entire space.
-  A **basis** is a **minimal set of linearly independent vectors** that span the entire space.
-  More vectors \neq better span. Efficiency matters!