A Summary of Bleichenbacher's Padding Oracle Attack

In this document we summarize the implementation details of Bleichenbacher's PKCS1 v1.5 padding oracle attack. We assume that the reader is acquainted with the attack and only aim to summarize its implementation and provide some basic details; of course, for details about the attack, refer to the original article.

We denote the public modulus by N, the public exponent by e, the private exponent by d, and the given ciphertext to be decrypted by $c = m^e \mod N$. We denote by O the Bleichenbacher oracle which determines whether an encrypted message is PKCS-conforming or not.

Step 1: The "blinding" phase

This part of the attack is used to find an initial ciphertext c_0 that conforms to the PKCS standard. If a conforming ciphertext c is given, this stage can be skipped, and the output of it can be set to $c_0 = c$ and $s_0 = 1$. If c is not necessarily PKCS-conforming, in this step we search for it thus:

Algorithm 1 The "blinding" phase

```
1: \mathbf{procedure} \ \mathrm{BLINDING}(c, N, e, O)
2: \mathbf{repeat}
3: s_0 \leftarrow \mathrm{RANDOM\_INT}() \ \mathrm{mod} \ N
4: c_0 \leftarrow s_0^e \cdot c \ \mathrm{mod} \ N
5: \mathbf{until} \ O(c_0)
6: \mathbf{return} \ s_0, c_0
7: \mathbf{end} \ \mathbf{procedure}
```

Step 2: Searching for PKCS-conforming messages

In this stage, the algorithm maintains a set of possible intervals (ranges) of the plaintext m, we call it M. The algorithm iteratively reduces the number of possibilities for m; in each iteration, the algorithm searches for a value s such that $O(c \cdot (s^e) \mod N) = 1$ — notice that this is similar to the blinding phase; in the blinding phase, random values of s are generated, while here different methods of searching for s are used — and then uses this value to reduce the set of possible values of m. The method of searching for such a value s varies according to the iteration number — the first iteration behaves differently to the others — and to the number of intervals in M. Notice that this step relies on the values of s_0 and c_0 returned from the previous step. We denote by k the byte-length of N.

The algorithm relies on a few procedures which we also describe here:

FIND_MIN_CONFORMING (c_0, s_{min}) finds the minimal value s that is greater than s_{min} such that $O(c_0 \cdot (s^e) \mod N) = 1$. In other words, in this case s is searched for sequentially beginning with an initial value s_{min} . This is the searching method used for the first iteration and for iterations where M contains more than one interval (with appropriate values for s_{min} as shown below).

SEARCH_SINGLE_INTERVAL searches for a value s as described above in a more complex method; it is used when M consists of more than a single interval.

NARROW_M (M, s) is run in each iteration of the algorithm after finding its value of s as described above, and uses this value to find a new set of intervals M' for the next iteration. Notice that in the code below,

when constructing a new set of intervals M' (which becomes the set of intervals M for the next iteration of the algorithm), we treat the union operator \cup as though it merges existing intervals in M'.

Algorithm 2 Procedures for step 2

```
1: B \leftarrow 2^{8(k-2)}
 2: procedure FIND_MIN_CONFORMING(c_0, s_{min}, N, e, O)
             s \leftarrow s_{min}
             while O(c_0 \cdot (s^e) \bmod N) = 0 \operatorname{do}
 5:
                   s \leftarrow s+1
             end while
 6:
             \mathbf{return}\ s
 7:
 8: end procedure
 9: procedure SEARCH_SINGLE_INTERVAL(s_{prev}, M, c_0, N, e, O)
            a, b \leftarrow M[0]
r \leftarrow \left[2 \cdot \frac{b \cdot s_{prev} - 2B}{N}\right]
10:
11:
             while true do
12:
                   for s from \left\{ \left\lceil \frac{2B+rN}{b} \right\rceil \right\} to \left\lfloor \frac{3B+rN}{s} \right\rfloor do if O\left(c_0 \cdot (s^e) \bmod N\right) = 1 then
13:
14:
15:
                               return s
                         end if
16:
                   end for
17:
             end while
18:
19: end procedure
20: procedure NARROW_M(M, s, N)
             M' \leftarrow \{\}
21:
22:
             for a, b in M do
                   for r from \left\lceil \frac{as-3B+1}{N} \right\rceil to \left\lfloor \frac{bs-2B}{N} \right\rfloor do M' \leftarrow M' \cup \left\{ \left[ \max\left(a, \left\lceil \frac{2B+rN}{s} \right\rceil \right), \min\left(b, \left\lfloor \frac{3B-1+rn}{s} \right\rfloor \right) \right] \right\}
23:
24:
25:
                   end for
             end for
26:
27: end procedure
```

The algorithm for step 2 follows:

Algorithm 3 Step 2

```
1: procedure STEP2(c_0, s_0, N, e, O)
         M \leftarrow \{[2B, 3B-1]\}
         i \leftarrow 1
 3:
         repeat
 4:
              if i = 1 then
 5:
                   s \leftarrow \text{FIND\_MIN\_CONFORMING}\left(c_0, \left\lceil \frac{N}{3B} \right\rceil, N, e, O\right)
 6:
              else if |M| > 1 then
 7:
                   s \leftarrow \text{find\_min\_conforming}\left(c_0, s+1, N, e, O\right)
 8:
9:
              else
                   s \leftarrow \texttt{SEARCH\_SINGLE\_INTERVAL}\left(s, M, c_0, N, e, O\right)
10:
              end if
11:
              M \leftarrow \text{NARROW\_M}\left(M, s, N\right)
12:
13:
              i \leftarrow i+1
14:
         until |M| = 1 and |M[0]| = 1
         return M[0][0] \cdot s^{-1} \mod N
15:
16: end procedure
```