## NUMERICAL LINEAR ALGEBRA: Solutions for Sheet 3

1. Suppose Ax = b and  $(A + \delta A)(x + \delta x) = b$ , which together imply  $(A + \delta A)(x + \delta x) = Ax$ . Multiplying this out gives  $Ax + A\delta x + \delta A(x + \delta x) = Ax$  and consequently  $A\delta x = -\delta A(x + \delta x)$ . Assuming A is invertible,  $\delta x = -A^{-1}(\delta A)(x + \delta x)$ . We now apply norm inequalities to obtain

$$\|\delta x\| = \|A^{-1}(\delta A)(x + \delta x)\| \le \|A^{-1}\| \|\delta A\| \|x + \delta x\| = \frac{\|A\|}{\|A\|} \|A^{-1}\| \|\delta A\| \|x + \delta x\|.$$

Dividing by  $||x + \delta x||$  gives the desired result,

$$\frac{\left\|\delta x\right\|}{\left\|x+\delta x\right\|} \leq \left\|A\right\| \left\|A^{-1}\right\| \frac{\left\|\delta A\right\|}{\left\|A\right\|}.$$

This bounds the relative perturbation of the solution by the relative perturbation in the matrix, magnified by the condition number  $\kappa(A) = ||A|| \, ||A^{-1}||$ . Small errors in A might lead to large errors in the computed solution.

2. We have

$$\kappa(Q) = \|Q\| \|Q^{-1}\| = \|Q\| \|Q^T\|$$

and since ||Z|| = 1 for an orthogonal matrix Z we get  $\kappa(Q) = 1$ . The Cholesky factorisation of  $A^TA$  is given by  $A^TA = LL^T$  where L is a lower triangular matrix. Now consider the QR factorisation of A, i.e. A = QR. Then we get

$$A^T A = (QR)^T QR = R^T Q^T QR = R^T R.$$

If

$$R = \left[ \begin{array}{c} \hat{R} \\ 0 \end{array} \right]$$

with  $\hat{R} \in \mathbb{R}^{n \times n}$  and  $\hat{R}^T \hat{R} = R^T R$ . So  $\hat{R}^T$  could be  $L^T$ . In fact this precisely depends on the choices of sign of the diagonal entries in the Cholesky and QR algorithm.

3. Hilbert matrix

size	condition number
4	1.5514e + 04
8	1.5258e + 10
12	1.8032e + 16

Result for  $x = A \setminus b$  where b = sum(A, 2) with solution  $x = [1, ..., 1]^T$  gives

$$x = \begin{bmatrix} 0.999999976736699 \\ 1.000002910963504 \\ 0.999909292281920 \\ 1.001227445722276 \\ 0.991048902442979 \\ 1.039167445001900 \\ 0.891228720678228 \\ 1.196361444783960 \\ 0.770302875862095 \\ 1.167911583742747 \\ 0.930297943531136 \\ 1.012541473056602 \end{bmatrix}$$

4. One Gauss–Seidel iteration applied to the system Ax = b is

**for** 
$$i = 1, ..., n$$

$$x_i^{(k+1)} = \left(b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k+1)} - \sum_{j=i+1}^{n} a_{ij} x_j^{(k)}\right) / a_{ii}.$$

Since A is lower triangular,  $a_{ij} = 0$  if j > i. Thus, the Gauss-Seidel iteration reduces to

for 
$$i = 1, ..., n$$

$$x_i^{(k+1)} = \left(b_i - \sum_{i=1}^{i-1} a_{ij} x_j^{(k+1)}\right) / a_{ii}.$$

Notice that this is identical to forward substitution:

$$x_1 = b_1/a_{11}, \quad x_2 = (b_2 - x_1 a_{21})/a_{22}, \quad \dots, \quad x_n = \left(b_n - \sum_{j=1}^{n-1} a_{nj} x_j\right)/a_{nn}$$

Thus, Gauss-Seidel will solve a lower triangular matrix exactly in only one iteration.

Suppose A is nearly upper triangular. Then we would want an iterative method for which one step is similar to backwards substitution. Such a method executes the Gauss-Seidel iteration in reverse order:

**for** 
$$i = n, ..., 1$$

$$x_i^{(k+1)} = \left(b_i - \sum_{j=i+1}^n a_{ij} x_j^{(k+1)} - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)}\right) / a_{ii}.$$

5. The spectral radius is defined as  $\rho(A) := \max_{\lambda \in \Lambda(A)} |\lambda|$ , where  $\Lambda(A)$  is the spectrum of A. Let  $\lambda_{\max}$  be an eigenvalue of A such that  $\rho(A) = |\lambda_{\max}|$ . Then there must be a non-trivial eigenvector v associated with  $\lambda_{\max}$ . As eigenvectors are not scale-dependent, we can pick v such that ||v|| = 1, where  $||\cdot||$  is the vector norm which induces the operator norm. Then

$$\rho(A) = |\lambda_{\max}| = |\lambda_{\max}| \, ||v|| = ||\lambda_{\max}v|| = ||Av|| \le \max_{||x|| = 1} ||Ax|| = ||A||.$$

Thus  $\rho(A) \leq ||A||$  for any operator norm A.

Does this hold if  $\|\cdot\|$  is not an operator norm (e.g., the Frobenius norm)? Can you prove this?

6. Let  $\lambda$  be an eigenvalue of  $A \in \mathbb{R}^{n \times n}$  such that  $(A - \lambda I)x = 0$  for some  $x \neq 0$ . Take k such that  $|x_k| = \max_i |x_i|$ . Then the kth row of the equation  $(A - \lambda I)x = 0$  gives

$$(a_{kk} - \lambda)x_k = -\sum_{j=1, j \neq k}^n a_{kj}x_j.$$

Thus,

$$|a_{kk} - \lambda| |x_k| = \Big| \sum_{j=1, j \neq k}^n a_{kj} x_j \Big| \le \sum_{j=1, j \neq k}^n |a_{kj}| |x_j|.$$

Dividing through by  $|x_k|$  (which must be greater than zero since  $x \neq 0$ ), we have

$$|a_{kk} - \lambda| \le \sum_{j=1, j \ne k}^{n} |a_{kj}| \frac{|x_j|}{|x_k|} \le \sum_{j=1, j \ne k}^{n} |a_{kj}|.$$

Having proved Gerschgorin's Theorem, we will apply it to bound the spectral radius of the Jacobi iteration matrix. Recall that the Jacobi splitting of A = L + D + U (L strictly lower triangular, D diagonal, U strictly upper triangular) yields the iteration matrix  $M^{-1}N = D^{-1}(-L - U)$ . Thus,

$$A = \begin{pmatrix} 9 & 1 & 1 \\ 1 & 5 & 0 \\ 1 & 1 & 3 \end{pmatrix}, \quad M = \begin{pmatrix} 9 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 3 \end{pmatrix}, \quad N = \begin{pmatrix} 0 & -1 & -1 \\ -1 & 0 & 0 \\ -1 & -1 & 0 \end{pmatrix}.$$

The Jacobi iteration matrix is thus

$$M^{-1}N = \begin{pmatrix} 0 & -\frac{1}{9} & -\frac{1}{9} \\ -\frac{1}{5} & 0 & 0 \\ -\frac{1}{3} & -\frac{1}{3} & 0 \end{pmatrix}$$

Applying Gerschgorin's Theorem to each row yields three bounds:

$$|\lambda| \le 2/9$$
,  $|\lambda| \le 1/5$ ,  $|\lambda| \le 2/3$ .

From this we deduce that  $\rho(M^{-1}N) \leq 2/3$ .

But we can get a tighter bound by using the result from Question 2. Calculate that  $||M^{-1}N||_1 = 8/15 < 2/3$ . Thus,  $\rho(M^{-1}N) \le 8/15$ . In fact, we find  $\rho(M^{-1}N) \approx 0.2910$ .

7. Define A to be the upper triangular matrix with 1/2 on the main diagonal ones in all superdiagonal entries. This is an example of a non-normal matrix. All the eigenvalues are 1/2, so  $\rho(A) = 1/2$ . Thus, we must have  $||A^k||_{\infty} \to 0$  as  $k \to \infty$ . But there is growth of  $A^k$  for transient values of k, and this can have wide-ranging implications. For example, it warns us that iterative methods may not converge very nicely, since  $||x^{(k)} - x|| \le ||(M^{-1}N)^k|| ||x^{(0)} - x||$ .

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A = triu(ones(10)) - 1/2*eye(10);
Ak = A;
for k=1:50,
    normAk(k) = norm(Ak,'inf');
    Ak=Ak*A;
end

semilogy([1:50], normAk);
xlabel('power, k', 'fontsize', 14)
ylabel('||A||_\infty','fontsize', 14)
title('infinity norms of matrix powers', 'fontsize', 14)
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8. Let Ax = b, and let A = D + L + U. Define the SOR method by:

$$(D + \omega L) \ x^{(k + \frac{1}{2})} = \omega b + ((1 - \omega) D - \omega U) \ x^{(k)}, \tag{1}$$

$$(D + \omega U) \ x^{(k+1)} = \omega b + ((1 - \omega) D - \omega L) \ x^{(k+\frac{1}{2})}$$
 (2)

¿From the 1st equation, we obtain that:

$$x^{(k+\frac{1}{2})} = \omega (D + \omega L)^{-1} b + (D + \omega L)^{-1} ((1 - \omega) D - \omega U) x^{(k)},$$
(3)

Substituting the value of  $x^{(k+\frac{1}{2})}$  into the 2nd equation we have

$$x^{(k+1)} = (D + \omega U)^{-1} ((1 - \omega) D - \omega L) ((D + \omega L)^{-1} ((1 - \omega) D - \omega U)) x^{(k)}$$
(4)

$$+ \omega (D + \omega U)^{-1} ((1 - \omega) D - \omega L) (D + \omega L)^{-1} b + \omega (D + \omega U)^{-1} b$$
 (5)

It is clear that

$$G = (D + \omega U)^{-1} ((1 - \omega) D - \omega L) (D + \omega L)^{-1} ((1 - \omega) D - \omega U)$$

is the iteration matrix. One can show that if

$$A = M - N \iff N = M - A \iff M^{-1}N = I - M^{-1}A \tag{6}$$

Hence, it is enough to show that  $G = M^{-1} N$  as given above can be expressed as  $G = I - M^{-1} A$  where M is the symmetric matrix to be determined. It follows that

$$(1 - \omega)D - \omega L = -(D + \omega L) + (2 - \omega)D$$

and similarly

$$(1 - \omega)D - \omega U = -(D + \omega U) + (2 - \omega)D$$

Then G can be transformed to:

$$G = (D + \omega U)^{-1} ((1 - \omega) D - \omega L) (D + \omega L)^{-1} ((1 - \omega) D - \omega U)$$
(7)

$$= -(D + \omega U)^{-1} \left( (D + \omega L) ((D + \omega L)^{-1}) \right) ((1 - \omega) D - \omega U)$$
(8)

$$+ (2 - \omega) (D + \omega U)^{-1} D (D + \omega L)^{-1} ((1 - \omega) D - \omega U)$$
(9)

$$= (D + \omega U)^{-1} (D + \omega U) - (2 - \omega) (D + \omega U)^{-1} D$$
(10)

$$+ (2 - \omega) (D + \omega U)^{-1} D (D + \omega L)^{-1} ((1 - \omega) D - \omega U)$$
(11)

$$= I - (2 - \omega) (D + \omega U)^{-1} D (I - (D + \omega L)^{-1} ((1 - \omega) D - \omega U))$$
(12)

$$= I - (2 - \omega) (D + \omega U)^{-1} D (D + \omega L)^{-1} (D + \omega L - (1 - \omega) D + \omega U)$$
(13)

$$= I - \omega (2 - \omega) (D + \omega U)^{-1} D (D + \omega L)^{-1} A$$
(14)

So M for this splitting is given by

$$M = \frac{1}{\omega (2 - \omega)} (D + \omega L) D^{-1} (D + \omega U).$$

9. (or see solution for question 10) Writing  $J = M^{-1}N$  the Jacobi iteration matrix, we have M = diag(A) and N = M - A so

$$M = \begin{pmatrix} a_{11} & & & \\ & a_{22} & & \\ & & \ddots & \\ & & & a_{nn} \end{pmatrix}, M^{-1} = \begin{pmatrix} \frac{1}{a_{11}} & & & \\ & \frac{1}{a_{22}} & & \\ & & \ddots & \\ & & & \frac{1}{a_{nn}} \end{pmatrix}, N = \begin{pmatrix} 0 & a_{12} & \cdots & a_{1n} \\ a_{21} & 0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & a_{nn-1} \\ a_{n1} & \cdots & a_{n-1n} & 0 \end{pmatrix}$$

and therefore

$$J = \begin{pmatrix} 0 & \frac{a_{12}}{a_{11}} & \cdots & \frac{a_{1n}}{a_{11}} \\ \frac{a_{21}}{a_{22}} & 0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \frac{a_{nn-1}}{a_{n-1n-1}} \\ \frac{a_{n1}}{a_{nn}} & \cdots & \frac{a_{n-1n}}{a_{nn}} & 0 \end{pmatrix}$$

We now apply Gershgorin's theorem as in question 6, and we have that for all eigenvalues  $\lambda$  there exists some i, such that

$$|\lambda| = |\lambda - 0| \le \sum_{i=1, i \neq i}^{n} \left| \frac{a_{ij}}{a_{ii}} \right| < 1 \tag{15}$$

by SRDD of A. Therefore all eigenvalues of J have modulus strictly less than one, and hence the Jacobi iteration converges.

10. We want to prove that if A is SRDD then both the Jacobi and Gauss-Seidel iterations converge. It is clear that if a matrix is SRDD then it is non-singular. By Gershgorin Circle Theorem its spectral radius does not contain the origin hence it is non-singular (see Question 6).

Let  $\lambda$  be the eigenvalue for both the Jacobi and Gauss-Seidal iteration method. For the Jacobi iteration method it means that:

$$-D^{-1} (L+U) \underline{x} = \lambda \underline{x}$$
$$(L+U) \underline{x} = \lambda D \underline{x}$$
$$(L+U+\lambda D) \underline{x} = 0$$

Similarly for the G-S iteration method:

$$(U + \lambda L + \lambda D) \underline{x} = 0.$$

Now let us assume in both cases that there exists  $\lambda$  such that  $|\lambda| \geq 1$ . As  $\lambda$  is greater than equal to 1 then A becomes even more diagonally dominant as the term  $\lambda D$  increases. Hence  $(L + U + \lambda D)$  or  $(U + \lambda L + \lambda D)$  are singular. But this contradicts the fact that A is non-singular. Therefore  $|\lambda| < 1$ . Therefore all eigenvalues of the Jacobi and Gauss-Seidal lie within the unit disc, hence the spectral radius is strictly less than 1, and both methods converge independent of b and a and a and a and a and a both methods converge independent of a and a an