Participatory Budgeting with Multiple Resources

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What's so good about PB?



Vergroenen openbare ruimte Geuzenveld, Slotermeer, Sloterdijken

> Lees meer



€ 65.000

1462 stemmen



Bijeenkomsten voor eenzame ouderen

Geuzenveld, Slotermeer, Sloterdijken

> Lees meer

€ 18.780 1000 stemmen



Opknappen Natuurspeeltuin Nature...

Geuzenveld, Slotermeer, Sloterdijken

> Lees meer

€ 50.000 1216 stemmen



Bewoners Restaurant Armoedebestr...

Geuzenveld, Slotermeer, Sloterdijken

> Lees meer € 10.000

981 stemmen



Bloementuin in het Sloterpark

Geuzenveld, Slotermeer, Sloterdijken

> Lees meer

€ 5.000 1207 stemmen



Voedselbos in het Sloterpark

Geuzenveld, Slotermeer, Sloterdijken

> Lees meer € 20.000

948 stemmen

Introducing Multiple Resources









Introducing Multiple Resources









Officials often need to interfere in the process (Goldfrank, 2007)

MRPB has been recognized as an important challenge (Haris Aziz & Nisarg Shah, 2020)

Usual PB framework

The 'usual' PB framework often looks like this:

- Set P of projects
- Cost function $c: P \to \mathbb{N}$
- Budget limit $b \in \mathbb{Z}_+$
- Each voter i submits some sort of ballot A_i , making a profile $\mathbf{A} = (A_1, \dots, A_n)$

Project set $S \subseteq P$ is *Feasible* if $\sum_{p \in S} c(p) \le b$

Our framework

A *d-resource PB scenario* is a tuple $\langle P, \mathbf{c}, \mathbf{b} \rangle$:

- P is a set of projects
- **c** is a vector of cost functions $c_k: P \to \mathbb{N} \cup \{0\}$ for $k = 1 \dots d$
- **b** is a vector of budget limits $b_k \in \mathbb{N}$ for $k = 1 \dots d$

A set $S \subseteq P$ is feasible if $\sum_{p \in S} c_k(p) \leqslant b_k$ for all $k = 1 \dots d$.

Voters $i \in \{1, ..., N\}$ submit approval ballots $A_i \subseteq P$ Approval ballots make up a profile $\mathbf{A} = (A_1, ..., A_n)$

Other constraints & relations to other frameworks

Distributional: spend at most $\alpha \in [0,1]$ of b_k on $X \subseteq P$

Incompatibility: not all projects in $X \subseteq P$ can be realised simultaneously

Dependency: p can only be realised if all projects in X are realised

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Add k* with $b_{k*} = \lfloor \alpha \cdot b_k \rfloor$, and $c_{k*}(p) = \mathbb{1}_{p \in X} \cdot c_k(p)$

Add k* with $b_{k*} = |X| - 1$ and $c_{k*}(p) = \mathbb{1}_{p \in X}$

Add k* with $b_{k*}=1$, $c_{k*}(p)=|X|+1$, and $c_{k*}(q)=-1$ for all $q\in X$

Mechanisms

A mechanism is a function F that takes as input scenarios $\langle P, \mathbf{c}, \mathbf{b} \rangle$ and profiles \mathbf{A} and returns feasible set $F(P, \mathbf{c}, \mathbf{b}, \mathbf{A}) \subseteq P$

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- F_{max} returns feasible set with maximal approval score
- F_{load} proceeds in steps: at each step, chooses the project minimizing the load (cost) carried by the worst-off voter

Axioms

Proportionality

All projects in set *S* are selected if for all $k \in R$:

$$\frac{|\{i \in N; A_i = S\}|}{n} \ge \frac{c_k(S)}{b_k}$$

Weak axiom only guarantees this if |S| = 1

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(Approximate) Strategyproofness

For truthful ballot S_i^* , $F(\mathbf{A}) \not\succ_i F(A_{-i}, S_i^*)$

Approximate: for some $p \in P$: $F(\mathbf{A}) \not\succ_i F(A_{-i}, S_i^*) \cup \{p\}$

Here we define different preferences \succ_i : prefer a Superset, or also an outcome that is better w.r.t. all resources (Paretian)

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Actually, our definitions are parameterized by a set *R* of relevant resources, giving more fine-grained analysis (and slightly different definitions)

Results

	Subset Preferences	Paretian Preferences	Paretian Preferences if $R = \{1 \dots d\}$
Greedy	V	X	V
Max	X	X	×
Load Balancing	X	X	×

Approximate Strategyproofness

	Strong	Weak
Greedy	X	X
Max	X	×
Load Balancing	V	V

Proportionality

No mechanisms are strategyproof (even for d=1)

Results

An impossibility result:

Theorem

Let $d \ge 1$, $m > b_k \ge 3$ for some resource k, then no mechanism can guarantee both weak proportionality and strategyproofness against Paretian voters for d-resource PB scenarios with budgets $(b_1, \ldots, b_k, \ldots b_d)$ and m projects.

Basecase is generated using a SAT-solving approach

Computational analysis

 F_{greedy} and F_{load} are polytime computable

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For F_{max} multiple decision problems:

Definition (MaxAppScore)

Instance: PB scenario $\langle P, \mathbf{c}, \mathbf{b} \rangle$, profile **A**, target $K \in \mathbb{N}$

Question: Is there feasible $S \subseteq P$ with approval score at least K?

 $(MaxAppScore_d restricts to d-resource scenarios)$

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 $(MaxAppScore_d restricts to d$ -resource scenarios)

MaxAppScore₁ (and F_{max} in single-resource case) is polytime computable per Talmon & Faliszewski (2019);

MaxAppScore is strongly NP-hard;

MaxAppScore_d for $d \ge 2$ is weakly NP-hard, and F_{max} is pseudo-polytime computable with restriction to d

Wrapping up

Summing up:

- Initiated the systematic study of PB with multiple resources
- New setting has significantly increased expressive power
- Mechanisms from single-resource setting largely carry over nice axiomatic & algorithmic properties

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What's next?

- Strengthen the results to e.g. other voter preferences, and other notions of proportionality
- Explore the introduction of negative costs
- Eventually implement multi-resource PB in real-world PB exercises

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Thank you!

The load-balancing mechanism

For set $R \subseteq \{1, \dots, d\}$ of relevant resources

Build outcome S in rounds. At each round, add a project that maintains feasibility of outcome S and minimises $\max_{k \in R} y_k$, where y_k is computed by linear program with variables $x_{i,k,p}$

$$\min y_k$$
 where $y_k\geqslant rac{1}{b_k}\cdot \sum_{p\in S} x_{i,k,p}$ for all $i\in N$ with
$$\sum_{i\in N}\mathbb{1}_{p\in A_i}\cdot x_{i,k,p}=c_k(p) \text{ for all } p\in S, \text{ and } x_{i,k,p}\geqslant 0$$

Intuitively, $x_{i,k,p}$ is the part of the cost $c_k(p)$ 'shouldered' by voter i