

Part-B

Chapter-3: Matrix Algebra

1. Real matrix: $A = \bar{A}$

2. Imaginary matrix: $A = -\bar{A}$

3. Square matrix: Number of rows = number of columns.

4. Rectangular matrix: number of rows and columns not equal.

5. Diagonal matrix: $a_{ij} = 0$ when $i \neq j$. $(1,1), (2,2), (3,3)$ are not zero. $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$

6. Identity matrix: $a_{ij} = 0$ when $i \neq j$, $a_{ij} = 1$ when $i = j$. $(1,1), (2,2), (3,3)$ will be 1.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

7. Null matrix: Every element is zero. $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

8. Upper triangular matrix: For square matrix, $a_{ij} = 0$, when $i > j$. $(2,1), (3,1), (3,2)$ will be zero.

Example: $\begin{bmatrix} 2 & 3 & 5 \\ 0 & 1 & -2 \\ 0 & 0 & 7 \end{bmatrix}$

9. Lower triangular matrix: For square matrix, $a_{ij} = 0$ when $i < j$. (1,2), (1,3), (2,3) will be zero

Example:
$$\begin{bmatrix} 5 & 0 & 0 \\ -1 & 2 & 0 \\ 3 & 7 & 1 \end{bmatrix}$$

10. Symmetric matrix: $A^T = A$

Example:
$$\begin{bmatrix} 1 & 2 & -3 \\ 2 & 5 & 7 \\ -3 & 7 & 3 \end{bmatrix}$$

11. Skew-symmetric matrix: $A^T = -A$

Example: $B = \begin{bmatrix} 0 & 1 & -2 \\ -1 & 0 & 3 \\ 2 & -3 & 0 \end{bmatrix}$ $B^T = - \begin{bmatrix} 0 & +1 & -2 \\ -1 & 0 & +3 \\ +2 & -3 & 0 \end{bmatrix}$

12. Hermitian matrix: For a square matrix, $A^* = (\overline{A})^T = A$ the A is called Hermitian matrix.

A imaginary matrix হতে A ও imaginary part এর আগে sign বদলে থাকে (plus থাকলে minus এবং minus থাকলে plus).

$$A = \begin{bmatrix} 2 & 2-3i & 3 \\ 2+3i & 5 & 1+i \\ 3 & 1-i & 0 \end{bmatrix}$$

13. Skew-Hermitian matrix: $A^* = (\bar{A}^T) = -A$

Example: $A = \begin{bmatrix} 2i & 2-3i & 3 \\ -2-3i & 5i & 1+i \\ -3 & -1+i & 0 \end{bmatrix}$

14. Orthogonal matrix: For a square matrix $A \cdot A^T = A^T \cdot A = I$

15. Idempotent matrix: $A^2 = A$, for a square matrix.

16. Nilpotent matrix: For a square matrix, $A^n = 0$ and $A^{n-1} \neq 0$

Example: $B = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ -1 & -2 & -3 \end{bmatrix}$

17. Unitary matrix: For a complex square matrix, if

$AA^* = A^*A = I$ or $A^* = A^{-1}$, then A is a unitary matrix.

Example: $\begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \\ \frac{-i}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{bmatrix}$

3.9: Theorem-1: Prove that.

① $(A^T)^T = A$

Solve: Let $A = [a_{ij}]$ where $i = 1, 2, \dots, m$

By definition, $j = 1, 2, \dots, n$

$$A^T = [a_{ij}]^T = [a_{ji}]$$

$$\text{Now } (A^T)^T = [a_{ji}]^T$$

$$= a_{ij}$$

$$\therefore (A^T)^T = A$$

② $(A+B)^T = A^T + B^T$

Solve: Let, $A = [a_{ij}]$

where,

$$B = [b_{ij}]$$

$$i = 1, 2, \dots, m$$

$$j = 1, 2, \dots, n$$

Then,

$$C = A+B \text{ is defined as } [c_{ij}] = [a_{ij}] + [b_{ij}]$$

Now, by definition of the transpose matrix of C

$$\text{we have } (A+B)^T = C^T = [c_{ij}]^T = [c_{ji}] = [a_{ji}] + [b_{ji}]$$

$$= [a_{ij}]^T + [b_{ij}]^T$$

$$\therefore (A+B)^T = A^T + B^T$$

$$\textcircled{III} (AB)^T = B^T A^T$$

Solve: Let,

$$A = [a_{ij}]$$

$$B = [b_{jk}]$$

where,

$$i = 1, 2, \dots, m$$

$$j = 1, 2, \dots, n$$

$$k = 1, 2, \dots, p$$

Then, $A^T = [a_{ij}]^T = [a_{ji}]$ is an $n \times m$ matrix

$B^T = [b_{jk}]^T = [b_{kj}]$ is an $p \times n$ matrix

Thus, AB is a matrix of $m \times p$ so that $(AB)^T$ is a $p \times m$ matrix. also $B^T A^T$ is a $p \times m$ matrix. Therefore, $(AB)^T$ and $B^T A^T$ have same dimensions.

Now, $AB = [c_{ik}]$ where (i, k) th element of AB is

$$c_{ik} = \sum_{j=1}^n a_{ij} \cdot b_{jk}$$

where,

$$i = 1, 2, \dots, m$$

$$j = 1, 2, \dots, n$$

Therefore the (i, k) th element of $(AB)^T$

$$= \sum_{j=1}^n a_{ij} \cdot b_{jk}$$

$$= \sum_{j=1}^n a_{ji}^T \cdot b_{kj}^T$$

$$= \sum_{j=1}^n b_{kj}^T \cdot a_{ji}^T$$

$$= (k, i) \text{th element of } B^T A^T$$

Hence, $(AB)^T = B^T A^T$

$$\textcircled{iv} (\alpha A)^T = \alpha \cdot A^T$$

Solve: Let $A = [a_{ij}]$
 $\therefore A^T = [a_{ij}]^T = [a_{ji}]$

Now, $(\alpha A)^T = [\alpha a_{ij}]^T$
 $= [\alpha a_{ji}]$
 $= \alpha [a_{ji}]$
 $= \alpha A^T$

$$\therefore (\alpha A)^T = \alpha A^T$$

3.11

Theorem-1: Let A^* and B^* be the conjugate transpose of A and B respectively, then

$$\textcircled{i} (A^*)^* = A$$

Solve: Let, $A^* = B$
 then, $B = (\overline{A})^T = (\overline{A})^T$
 and $B^T = \{(\overline{A})^T\}^T = \overline{A}$

Again, $(B)^T = (\overline{B^T}) = \overline{\overline{A}} = A$

Therefore, $B^* = A$, since $B^* = (B)^T = \overline{(B^T)}$

Hence $(A^*)^* = A$, since $B = A^*$.

$$\textcircled{II} (A+B)^* = A^* + B^*$$

Solve: By definition,

$$\begin{aligned} (A+B)^* &= (\overline{A+B})^T \\ &= (\overline{A})^T + (\overline{B})^T && \text{since } (\overline{C+D})^T = \overline{C}^T + \overline{D}^T \\ &= A^* + B^* && \text{since } A^* = (\overline{A})^T \end{aligned}$$

$$\textcircled{III} (AB)^* = B^* \cdot A^*$$

$$\begin{aligned} \text{Solve: } (AB)^* &= (\overline{AB})^T \\ &= (\overline{A} \ \overline{B})^T \\ &= (\overline{B})^T \cdot (\overline{A})^T && \text{since } (\overline{CD})^T = \overline{D}^T \cdot \overline{C}^T \\ &= B^* \cdot A^* \end{aligned}$$

$$\textcircled{IV} (KA)^* = \overline{K} \cdot A^*$$

$$\begin{aligned} \text{Solve: } (KA)^* &= (\overline{KA})^T \\ &= (\overline{K} \cdot \overline{A})^T \\ &= \overline{K} \cdot (\overline{A})^T \\ &= \overline{K} \cdot A^* \end{aligned}$$

$$\therefore (KA)^* = \overline{K} \cdot A^*$$

Singular matrix: Let D be the determinant of the square matrix A , then if $D=0$ the matrix A is called the singular matrix and if $D \neq 0$, the matrix A is called non-singular matrix.

Inverse matrix: If $AB=BA=I$, then A and B are invertible and $A^{-1}=B$, $B^{-1}=A$.

Example-12(b)

Let D be the determinant of the matrix

$$\text{then } D = \begin{vmatrix} 2 & -1 & 3 \\ 4 & 0 & -1 \\ 3 & 3 & 2 \end{vmatrix}$$

$$= 2(0+3) + 1(8+3) + 3(12-0)$$

$$= 6 + 11 + 36$$

$$= 53 \neq 0$$

∴ So the matrix is non-singular and A^{-1} exists. Now the co-factors of D are:

$$A_{11} = \begin{vmatrix} 0 & -1 \\ 3 & 2 \end{vmatrix}$$

$$= (0+3)$$

$$= 3$$

$$A_{12} = (-1) \begin{vmatrix} 4 & -1 \\ 3 & 2 \end{vmatrix}$$

$$= -1(8+3)$$

$$= -11$$

$$A_{13} = \begin{vmatrix} 4 & 0 \\ 3 & 3 \end{vmatrix}$$

$$= 12$$

$$A_{21} = (-1) \begin{vmatrix} -1 & 3 \\ 3 & 2 \end{vmatrix}$$

$$= -1(-2 - 9)$$

$$= 11$$

$$A_{22} = \begin{vmatrix} 2 & 3 \\ 3 & 2 \end{vmatrix}$$

$$= (4 - 9)$$

$$= -5$$

$$A_{23} = (-1) \begin{vmatrix} 2 & -1 \\ 3 & 3 \end{vmatrix}$$

$$= -1(6 + 3)$$

$$= -9$$

$$A_{31} = \begin{vmatrix} -1 & 3 \\ 0 & -1 \end{vmatrix}$$

$$= (1 - 0)$$

$$= 1$$

$$A_{32} = \begin{vmatrix} 2 & 3 \\ 4 & -1 \end{vmatrix} \times (-1)$$

$$= -1(-2 - 12)$$

$$= 14$$

$$A_{33} = \begin{vmatrix} 2 & -1 \\ 4 & 0 \end{vmatrix}$$

$$= (0 + 4)$$

$$= 4$$

Therefore,

$$\text{Adj of } A = \begin{bmatrix} 3 & -11 & 12 \\ 11 & -5 & -9 \\ 1 & 14 & 4 \end{bmatrix}^T = \begin{bmatrix} 3 & 11 & 1 \\ -11 & -5 & 14 \\ 12 & -9 & 4 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{|A|} \text{Adj of } A$$

$$= \frac{1}{53} \begin{bmatrix} 3 & 11 & 1 \\ -11 & -5 & 14 \\ 12 & -9 & 4 \end{bmatrix}$$

Exercise-13: Row canonical form:

$$A = \begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \quad I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$AI_2 = \left[\begin{array}{cc|cc} 2 & 5 & 1 & 0 \\ 1 & 3 & 0 & 1 \end{array} \right]$$

Interchanging R_1 and R_2 we have:

$$\left[\begin{array}{cc|cc} 1 & 3 & 0 & 1 \\ 2 & 5 & 1 & 0 \end{array} \right]$$

$$R_2' = R_2 - 2R_1$$

$$\left[\begin{array}{cc|cc} 1 & 3 & 0 & 1 \\ 0 & -1 & 1 & -2 \end{array} \right]$$

$$R_1' = R_1 + 3R_2$$

$$\left[\begin{array}{cc|cc} 1 & 0 & 3 & -5 \\ 0 & -1 & 1 & -2 \end{array} \right]$$

$$R_2' = (-1) \times R_2$$

$$\left[\begin{array}{cc|cc} 1 & 0 & 3 & -5 \\ 0 & 1 & -1 & 2 \end{array} \right]$$

$$\therefore I_2 A^{-1} = \left[\begin{array}{cc|cc} 1 & 0 & 3 & -5 \\ 0 & 1 & -1 & 2 \end{array} \right]$$

Hence,

$$A^{-1} = \begin{bmatrix} 3 & -5 \\ -1 & 2 \end{bmatrix}$$

Example - 17:

$$\left. \begin{array}{l} 2x + y = 1 \\ x - 2y = 3 \end{array} \right\} \text{--- ①}$$

The system of linear equations can be written in matrix as:

$$\begin{bmatrix} 2 & 1 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \text{--- ②}$$

Let,

$$A = \begin{bmatrix} 2 & 1 \\ 1 & -2 \end{bmatrix} \quad X = \begin{bmatrix} x \\ y \end{bmatrix} \quad L = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

From ② we get,

$$AX = L \text{ --- ③}$$

Let D be the determinant of the matrix A , then

$$\begin{aligned} D &= \begin{vmatrix} 2 & 1 \\ 1 & -2 \end{vmatrix} = (-4 - 1) \\ &= -5 \neq 0 \end{aligned}$$

So the matrix A is non singular and A^{-1} exists.

Now, cofactors of D are:

$$A_{11} = -2 \quad A_{12} = -1$$

$$A_{21} = -1 \quad A_{22} = 2$$

$$\text{Therefore adj of } A = \begin{bmatrix} -2 & -1 \\ -1 & 2 \end{bmatrix}^T = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$\therefore A^{-1} = \frac{1}{-5} \text{ Adj of } A = \frac{1}{-5} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2/5 & 1/5 \\ 1/5 & -2/5 \end{bmatrix}$$

Multiplying both sides of eqn ③ by A^{-1}

$$A^{-1} \cdot AX = A^{-1}L$$

$$\text{or } IX = A^{-1}L$$

$$X = A^{-1}L$$

$$X = \begin{bmatrix} 2/5 & 1/5 \\ 1/5 & -2/5 \end{bmatrix} \times \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{2}{5} + \frac{3}{5} \\ \frac{1}{5} - \frac{6}{5} \end{bmatrix} = \begin{bmatrix} \frac{5}{5} \\ \frac{-5}{5} \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

Hence, $x = 1$

$$y = -1$$

Chapter-4: Rank of a matrix

Echelon matrix: An echelon matrix is a matrix which have the property that if in any of its rows the first element distinct from zero is in the k th position, then in all the following rows there are zeros in the first k positions, or equivalently.

Rank of a matrix: The rank of a matrix is the maximum number of linearly independent rows or columns in the matrix.

Example-4:

Given that,

$$A = \begin{bmatrix} 1 & 2 & -1 & 2 & 1 \\ 2 & 4 & 1 & -2 & 3 \\ 3 & 6 & 2 & -6 & 5 \end{bmatrix}$$

First let us reduce the matrix A to echelon form by the elementary row operations. We multiply 1st row by 2 and 3 then subtract from 2nd and 3rd rows respectively.

$$= \begin{bmatrix} 1 & 2 & -1 & 2 & 1 \\ 0 & 0 & 3 & -6 & 1 \\ 0 & 0 & 5 & -12 & 2 \end{bmatrix}$$

$$R_2' = R_2 - 2R_1$$

$$R_3' = R_3 - 3R_1$$

We multiply 3rd row by 3:

$$\begin{bmatrix} 1 & 2 & -1 & 2 & 1 \\ 0 & 0 & 3 & -6 & 1 \\ 0 & 0 & 15 & -36 & 6 \end{bmatrix}$$

We multiply 2nd row by 5 and subtract from 3rd row:

$$\begin{bmatrix} 1 & 2 & -1 & 2 & 1 \\ 0 & 0 & 3 & -6 & 1 \\ 0 & 0 & 0 & -6 & 1 \end{bmatrix}$$

This matrix is in row echelon form.

We subtract 3rd row from the second row:

$$\begin{bmatrix} 1 & 2 & -1 & 2 & 1 \\ 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & -6 & 1 \end{bmatrix}$$

$$R_2' = R_2 - R_3$$

Multiply 3rd row by $-1/6$:

$$\begin{bmatrix} 1 & 2 & -1 & 2 & 1 \\ 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1/6 \end{bmatrix}$$

We multiply 2nd row by $1/3$:

$$\begin{bmatrix} 1 & 2 & -1 & 2 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1/6 \end{bmatrix}$$

We add second row with the first row:

$$\begin{bmatrix} 1 & 2 & 0 & 2 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1/6 \end{bmatrix} \quad R_1' = R_1 + R_2$$

We multiply 3rd row by 2 and subtract from 1st row:

$$\begin{bmatrix} 1 & 2 & 0 & 0 & 4/3 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1/6 \end{bmatrix} \quad R_1' = R_1 - 3R_3$$

This matrix is in row ~~ee~~ reduced echelon form.

Example - 5:

We apply both elementary column and row operations to the matrix A for reducing it to the normal form.

$$A = \begin{bmatrix} 1 & 2 & 0 & -1 \\ 3 & 4 & 1 & 2 \\ -2 & 3 & 2 & 5 \end{bmatrix}$$

We replace C_2 and C_4 by $C_2 - 2C_1$ and $C_4 + C_1$:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 3 & -2 & 1 & 5 \\ -2 & 7 & 2 & 3 \end{bmatrix}$$

$$C_2' = C_2 - 2C_1$$

$$C_4' = C_4 + C_1$$

We replace C_2 and C_4 by $C_2 + 2C_3$ and $C_4 - 5C_3$:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 3 & 0 & 1 & 0 \\ -2 & 11 & 2 & -7 \end{bmatrix}$$

$$C_2' = C_2 + 2C_3$$

$$C_4' = C_4 - 5C_3$$

We replace C_1 by $C_1 + C_3$ and $C_4 + \frac{7}{11}C_2$.

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 4 & 0 & 1 & 0 \\ 0 & 11 & 2 & 0 \end{bmatrix}$$

We replace R_2 by $R_2 - 4R_1$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 11 & 2 & 0 \end{bmatrix}$$

$$R_2' = R_2 - 4R_1$$

We replace R_3 by $R_3 - 2R_2$:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 11 & 0 & 0 \end{bmatrix}$$

$$R_3' = R_3 - 2R_2$$

We interchange c_2 and c_3

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 11 & 0 \end{bmatrix}$$

We replace c_3 by $\frac{1}{11}c_3$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\sim [I_3 \ 0] \text{ where } I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ and } 0 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Hence the rank of matrix A is 3.