# NUMERICAL LINEAR ALGEBRA

HW - 4.1

HW - 4.2

HW - 4.3

HW - 4.4

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# HW - 4.1

Explain the difference between accuracy and precision.

# **Explanation**

We can explain with this example (from Wikipedia).

Imagine a study evaluating a new test that screens people for a disease. Each person taking the test either has or does not have the disease. The test outcome can be positive (classifying the person as having the disease) or negative (classifying the person as not having the disease). The test results for each subject may or may not match the subject's actual status. In that setting:

True positive: Sick people correctly identified as sick

False positive: Healthy people incorrectly identified as sick

True negative: Healthy people correctly identified as healthy

False negative: Sick people incorrectly identified as healthy

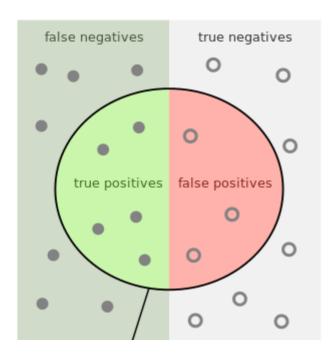
In general, Positive = identified and negative = rejected. Therefore:

True positive = correctly identified

False positive = incorrectly identified

True negative = correctly rejected

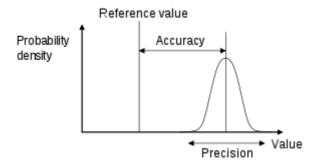
False negative = incorrectly rejected



$$\text{Precision} = \frac{tp}{tp + fp}$$

$$\label{eq:accuracy} \text{Accuracy} = \frac{tp + tn}{tp + tn + fp + fn}$$

Accuracy indicates proximity of measurement results to the true value, precision to the repeatability or reproducibility of the measurement.



### HW - 4.2

Write a Matlab program to solve a set of nonlinear equations by Newton-Ramphson Method.

# **Explanation**

```
function result= newton raphson(func,initial,max count, tolerance)
% Purpose: To solve the non-linear equation using newton raphson
% Input(func): non-linear function (f = @(x))
% Input(initial): initial value of f(x)
% Input(max_count) : maximum iteration
% Input(tolerance): acceptable tolerance for result
% Output: result
% Remarks : %sample func = f = @(x) x^3 - x - 1;
%call sample : t = newton raphson(f, 1, 10, 0.01)
syms x;
myFunc = func(x)
diffFunc = diff(myFunc);
y = initial;
y old=0;
tolerance new = tolerance+1;
count = 0;
while tolerance_new > tolerance && count < max_count</pre>
  tolerance new = 0; % in the begining we suppose our result is correct
  count = count + 1;
  a = subs(myFunc,x,y);
  b = subs(diffFunc,x,y);
  y_old = y;
  y = y - double(a)/double(b); % Newton Raphson
  % if difference between new result and old is not really clouse to zero
  if((abs((v old(1))-(v(1)))) > (1e-4))
  tolerance new = abs((y_old(1))-(y(1)))
  end
result = y;
end
```

# HW - 4.3

Write a Matlab program to compare all splitting methods.

X = mySplittingMethods(A,b,X,i)

#### **Answers**

There are two functions.

### - mySplittingMethods(A,b,x\_init,tolerance, maxcount)

this function tries to solve our problem in three method (jacobian, seidel and relaxation).

For Ax=b

A: Sequare Matrix

b: Result Vector

x\_init: initial vector

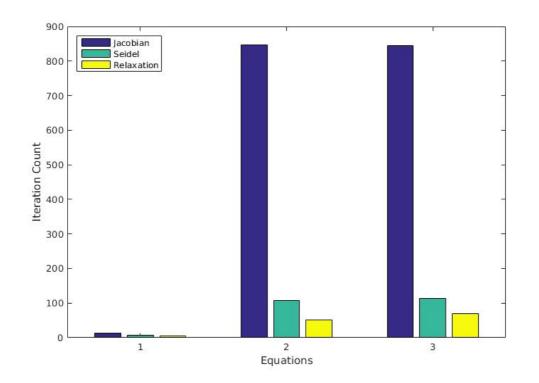
tolerance: acceptable error (float)

maxcount : maximum iteration (integer)

# -mySplittingMethodsTest()

this function tests our function and crates a plot.

As you can see jacobian always takes long time.



# mySplittingMethodsTest.m

```
function mySplittingMethodsTest()
A=[2,1,0;
   1,3,1;
   0,1,1];
b=[7,8,5];
x_{init}=[0;0;0]
[time1 count1]= mySplittingMethods(A,b,x_init,0.01,20000)
A=[-1,1,0,3,5,6;
 -2,3,1,-2,3,4;
  0,1,1,-5 2,4;
 -1,1,0, 3,5,6;
 -2,3,1,-2,3,4;
  0,1,1,-5 2,4];
x_init=[-1;-2;-3;2;5;6]
b=[7;8;5;6;4;3]
[time2 count2]=mySplittingMethods(A,b,x init,0.01,20000)
x_{init}=[-4;0;-3;-10;4;5]
[time3 count3]=mySplittingMethods(A,b,x init,0.01,20000)
y=[count1;count2;count3];
t=[time1 time2 time3]
bar1 = bar(y);
xlabel('Equations');
ylabel('Iteration Count');
set(bar1(3),'DisplayName','Jacobian');
set(bar1(2),'DisplayName','Seidel');
set(bar1(1), 'DisplayName', 'Relaxation');
legend('Jacobian','Seidel','Relaxation','Location','northwest');
```

# mySplittingMethods.m

```
function [time,count] = mySplittingMethods(A,b,x init,tolerance, maxcount)
x0=x_init;
jacobi_count = 0;
seidel_count = 0;
relaxation_count = 0;
tic;
%
                            Jacobi method
xnew=x0;
error=1:
while error>tolerance
  xold=xnew;
  jacobi count = jacobi count + 1;
  for i=1:length(xnew)
     off diag = [1:i-1 i+1:length(xnew)];
     xnew(i) = 1/A(i,i)*(b(i)-sum(A(i,off_diag)*xold(off_diag)));
  error=norm(xnew-xold)/norm(xnew);
x_jacobian = xnew
jacobian time = toc;
tic;
                                            Gauss Seidel
relax parameter=1;
n=length(x0);
x=x0;
error=1;
iter = 0;
while (error>tolerance & iter<maxcount)</pre>
  xold=x;
  seidel_count = seidel_count + 1;
  for i=1:n
     I = [1:i-1 i+1:n];
     x(i) = (1-relax parameter)*x(i)+relax parameter/A(i,i)*(b(i)-A(i,I)*x(I));
  error = norm(x-xold)/norm(x);
  iter = iter + 1;
end
x \text{ seidel}=x
seidel time=toc;
tic;
                                               relaxation
relax parameter=1.2;
n=length(x0);
x=x0;
error=1;
iter = 0;
while (error>tolerance & iter<maxcount)</pre>
```

```
xold=x;
relaxation_count = relaxation_count + 1;

for i=1:n
    I = [1:i-1 i+1:n];
    x(i) = (1-relax_parameter)*x(i)+relax_parameter/A(i,i)*( b(i)-A(i,I)*x(I) );
end
error = norm(x-xold)/norm(x);
iter = iter+1;
end

x_relaxation=x;
relaxation_time = toc;
time(1)=jacobian_time;
time(2)=seidel_time;
time(3)=relaxation_time;
count(1)= jacobi_count;
count(2)=seidel_count;
count(3)=relaxation_count;
```

return