



Information

1. *reference dimension
2. Dimension tolerance accrding ISO 2768 medium class
3. For other details see attached 3d model
4. Guides and bearings have to be lubricated
5. Machine should be operated on flat level and rigid surface.
6. Part names are given seperately
7. Not to use above 12 voltage of supply

File No.	Additional information	Material	Scale
ME	General drawing	Technical drawing	1:4
Owner	Compiled	General view of Delta robot	
VG TU	Checked		
MP luc-15	Prof., Sigitas Petkivicius	Edit	Date
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