Noise: Depolarizing, [0.001, 0.001, 0.00]Title Simulation Mean Std -7.379092083216174 0.14051949985579798 vqe xyredundant (noise=6) -7.379092083216115 0.14051949985579046ху redundant (noise=18) -5.824916251047478 0.1477491400189833xy0.14316522047529734zne -8.156179999300434 xynoiseoff -8.369342611101047 0.15124979844206457хy -6.583152545992618 0.18915423038578477ising vqe ising redundant (noise=6) -6.583152545992628 0.1891542303858077redundant (noise=18) ising -5.380444453773971 0.2113251022452117ising zne -7.184506592101956 0.18074166336647968noiseoff -7.2800222505553736 0.24690963596051196ising -6.056457299952753 0.1806957231807042heisenberg vqe heisenberg redundant (noise=6) -6.056457299952717 0.18069572318071422-4.591528569882986 0.17227869097031923heisenberg redundant (noise=18) 0.19421201884782338heisenberg zne -6.788921664987581 noiseoff -6.9205461139528435 0.19766791757742266heisenberg heisenberg-ric3 -6.056457299952753 0.1806957231807042 vge -6.056457299952717 0.18069572318071436heisenberg-ric3 redundant (noise=6) redundant (noise=18) 0.17227869097031917heisenberg-ric3 -4.591528569882987 heisenberg-ric3 redundant (noise=26) -3.80869593495965 0.17433124795481902heisenberg-ric3 -6.919727564945707 0.19696437844337153zne

Anstze with noise-free time-evolution.

noiseoff -6.9205461139528435 0.19766791757742266heisenberg-ric3 -6.056457299952753 0.1806957231807042heisenberg-ricmul vge redundant (noise=(4, 2)) heisenberg-ricmul -6.056457299952716 0.1806957231807142

heisenberg-ricmul redundant (noise=(12,6)) -4.591528569882987 0.17227869097031925

-3.80869593495965

-6.788921664987581

-6.9205461139528435

redundant (noise=(20, 6))

zne

noiseoff

0.17433124795481897

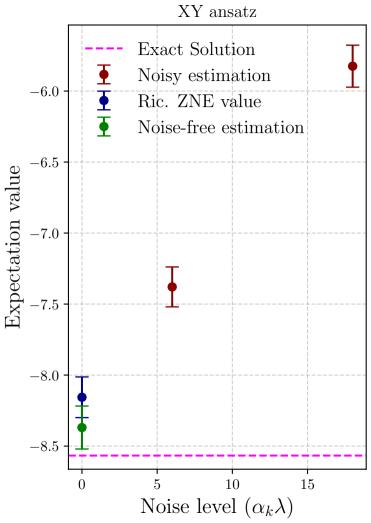
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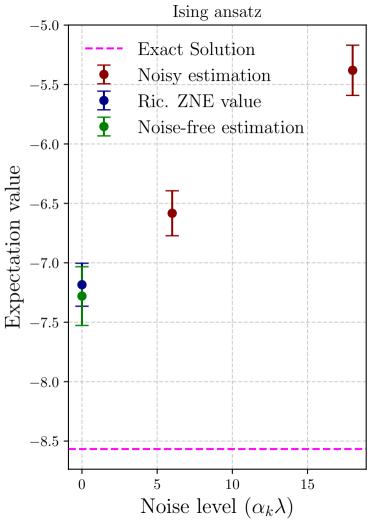
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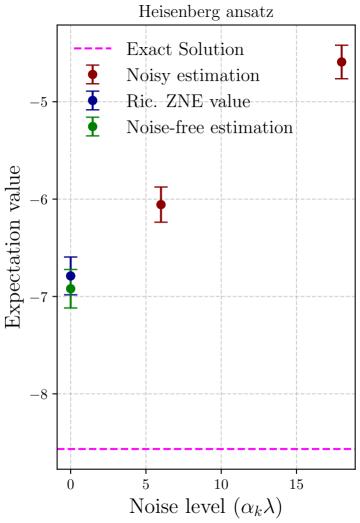
heisenberg-ricmul

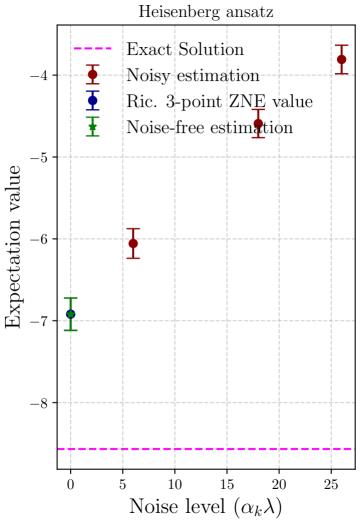
heisenberg-ricmul

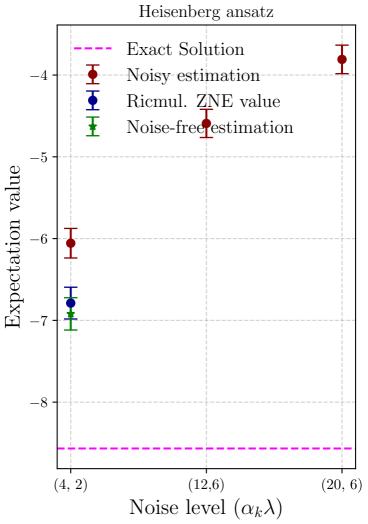
heisenberg-ricmul











## XY VQE CONFIGURATION

Parameter	Value
run	vqe
nqubits	7
state	dmatrix
output.file_name_prefix	xy_noisefree_time_evo
output.draw.status	True
output.draw.fig_dpi	100
output.draw.type	png
observable.def	ising
observable.coefficients.cn	[0.5,  0.5,  0.5,  0.5,  0.5,  0.5]
observable.coefficients.bn	[1.0, 1.0, 1.0, 1.0, 1.0, 1.0]
observable.coefficients.r	1
ansatz.layer	30
ansatz.gateset	1
ansatz.ugate.type	xy-iss
ansatz.ugate.coefficients.cn	[0.5,  0.5,  0.5,  0.5,  0.5,  0.5]
ansatz.ugate.coefficients.bn	[0, 0, 0, 0, 0, 0, 0]
ansatz.ugate.coefficients.r	0
ansatz.ugate.time.min	0.0
ansatz.ugate.time.max	10.0
vqe.iteration	10
vqe.optimization.status	True
vqe.optimization.algorithm	SLSQP
vqe.optimization.constraint	True
init_param.value	random
noise_profile.status	True
noise_profile.type	depolarizing
noise_profile.noise_prob	[0.001,0.001,0,0]
noise_profile.noise_on_init_param.status	False
noise_profile.noise_on_init_param.value	0
redundant.identity_factors	[[0, 0, 0, 0], [1, 1, 0, 0]]
zne.method	richardson
zne.degree	1
zne.sampling	default
zne.data_points	

## ISING VQE CONFIGURATION

Parameter	Value
run	vqe
nqubits	7
state	dmatrix
output.file_name_prefix	ising_noisefree_time_evo
output.draw.status	True
output.draw.fig_dpi	100
output.draw.type	png
observable.def	ising
observable.coefficients.cn	[0.5,  0.5,  0.5,  0.5,  0.5,  0.5]
observable.coefficients.bn	[1.0, 1.0, 1.0, 1.0, 1.0, 1.0]
observable.coefficients.r	1
ansatz.layer	30
ansatz.gateset	1
ansatz.ugate.type	ising
ansatz.ugate.coefficients.cn	[0.5,  0.5,  0.5,  0.5,  0.5,  0.5]
ansatz.ugate.coefficients.bn	[0, 0, 0, 0, 0, 0, 0]
ansatz.ugate.coefficients.r	0
ansatz.ugate.time.min	0.0
ansatz.ugate.time.max	10.0
vqe.iteration	10
vqe.optimization.status	True
vqe.optimization.algorithm	SLSQP
vqe.optimization.constraint	True
init_param.value	random
noise_profile.status	True
noise_profile.type	depolarizing
noise_profile.noise_prob	[0.001,0.001,0,0]
noise_profile.noise_on_init_param.status	False
noise_profile.noise_on_init_param.value	0
redundant.identity_factors	[[0, 0, 0, 0], [1, 1, 0, 0]]
zne.method	richardson
zne.degree	1
zne.sampling	default
zne.data_points	

## HEISENBERG VQE CONFIGURATION

Parameter	Value
run	vqe
nqubits	7
state	dmatrix
output.file_name_prefix	heisenberg_noisefree_time_evo
output.draw.status	True
output.draw.fig_dpi	100
output.draw.type	png
observable.def	ising
observable.coefficients.cn	[0.5,  0.5,  0.5,  0.5,  0.5,  0.5]
observable.coefficients.bn	[1.0, 1.0, 1.0, 1.0, 1.0, 1.0]
observable.coefficients.r	1
ansatz.layer	30
ansatz.gateset	1
ansatz.ugate.type	heisenberg
ansatz.ugate.coefficients.cn	[0.5,  0.5,  0.5,  0.5,  0.5,  0.5]
ansatz.ugate.coefficients.bn	[0,  0,  0,  0,  0,  0]
ansatz.ugate.coefficients.r	0
ansatz.ugate.time.min	0.0
ansatz.ugate.time.max	10.0
vqe.iteration	10
vqe.optimization.status	True
vqe.optimization.algorithm	SLSQP
vqe.optimization.constraint	True
init_param.value	random
noise_profile.status	True
noise_profile.type	depolarizing
noise_profile.noise_prob	[0.001, 0.001, 0, 0]
noise_profile.noise_on_init_param.status	False
noise_profile.noise_on_init_param.value	0
redundant.identity_factors	[[0, 0, 0, 0], [1, 1, 0, 0]]
zne.method	richardson
zne.degree	1
zne.sampling	default
zne.data_points	