

Lecture 20, Thu Nov 6

GAUSS MARKOV THEOREM

Assume a linear model with fixed covariates, i.e. Φ is deterministic:

$$Y = \Phi \beta^* + \varepsilon$$

$n \times 1$ $n \times d$ $d \times 1$ $n \times 1$

\hookrightarrow iid errors $\sim (0, \sigma^2)$
 \downarrow
 deterministic \rightarrow homoscedastic errors

Any estimator of β^* of the form AY is a linear unbiased estimator of β^* if

$$E[AY] = \beta^* \quad (\text{for all } \beta^* \in \mathbb{R}^d)$$

$\hookrightarrow \hat{\beta} = (\Phi^T \Phi)^{-1} \Phi^T Y$ is a linear unbiased estimator.

How good is $\hat{\beta}$ compared to all linear unbiased estimators?

Gauss-Markov Thm $\hat{\beta}$ is the BLUE! \rightarrow Best Linear Unbiased estimator

Remark: "Best" means that, for any other linear unbiased estimator

$$AY, \quad \text{Var}[\hat{\beta}] \preceq \text{Var}[AY]$$

where for 2 psd matrices M_1 and M_2 of the same size

$$M_1 \preceq M_2 \iff M_2 - M_1 \succeq 0$$

\nwarrow psd order \searrow "is positive semi-definite"

This means that, for any $x \in \mathbb{R}^d$,

$$x^T \text{Var}[\hat{\beta}] x \leq x^T \text{Var}[AY] x$$

choose x to be the i^{th} standard basis vector $e_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \rightarrow i^{\text{th}} \text{ position}$

to conclude that

the i^{th} element of diagonal of $\text{Var}[\hat{\beta}]$ is

smaller than i^{th} element $\text{Var}[AY]$

$$\hookrightarrow \text{Var}[\hat{\beta}_i] \leq \text{Var}[\tilde{\beta}_i] \quad \tilde{\beta} = AY$$

In fact this implies

$$\underbrace{\text{Var}[c^T \hat{\beta}]}_{\text{contrast}} \leq \text{Var}[c^T \tilde{\beta}] \quad \text{for all } c \in \mathbb{R}^d$$

PF/ Let $\tilde{\beta} = AY$ s.t. $\mathbb{E}[\tilde{\beta}] = \beta^*$. Then

$$\beta^* = \mathbb{E}_{d \times n}[AY] = \mathbb{E}[A\Phi\beta^* + A\epsilon] = A\Phi\beta^* \quad \nmid \beta^*$$

\Downarrow

$$A\Phi = I_{d \times d}$$

$$\text{Next} \quad \text{Var}[\tilde{\beta}] = A \underbrace{\text{Var}[Y]}_{\sigma^2 I_n} A^T = \sigma^2 AA^T$$

$$\text{Let } D = A - (\Phi^T \Phi)^{-1} \Phi^T \quad \text{so}$$

$$\text{Var}[\tilde{\beta}] = \text{Var}[AY] = \sigma^2 (D + (\Phi^T \Phi)^{-1} \Phi^T) (D + (\Phi^T \Phi)^{-1} \Phi^T)^T$$

$$\text{But } \underbrace{(D + (\Phi^T \Phi)^{-1} \Phi^T)}_A \Phi = I_d \quad \text{so}$$

$$\text{Var}[\tilde{\beta}] = \underbrace{\sigma^2 D D^T}_{\geq 0} + \underbrace{\sigma^2 (\Phi^T \Phi)^{-1} \Phi^T \Phi (\Phi^T \Phi)^{-1}}_{\sigma^2 (\Phi^T \Phi)^{-1} = \text{Var}[\hat{\beta}]}$$

↓

$$\text{Var}[\tilde{\beta}] \geq \text{Var}[\hat{\beta}]$$

- *fw* : extension to random Φ !

RIDGE REGRESSION

- Chapter 3 for Bach's book Learning theory from first principles

- Suppose d is large compared to n , almost close to n

in this case $\Phi^T \Phi$ may not be well-conditioned

i.e. $\frac{\lambda_{\max}(\Phi^T \Phi)}{\lambda_{\min}(\Phi^T \Phi)}$ is large and $(\Phi^T \Phi)^{-1}$ is unstable

$$\hookrightarrow \text{Var}[\hat{\beta}] = \sigma^2 (\Phi^T \Phi)^{-1} \text{ is unstable}$$

- One approach is to regularize, to solve a penalized least squares problem that includes a penalty for not choosing "good" solutions.

- The ridge regression estimator arises as the solution to this problem:

for a value $\lambda \geq 0$, let
 \hookrightarrow penalty parameter

ridge estimator $\leftarrow \hat{\beta}_\lambda = \underset{\beta \in \mathbb{R}^d}{\operatorname{argmin}} \underbrace{\frac{\|y - \Phi\beta\|^2}{n}}_{f(\beta)} + \lambda \|\beta\|^2$

$$= \left(\frac{\Phi^T \Phi}{n} + \lambda I_d \right)^{-1} \frac{\Phi^T}{n} y = \left(\hat{\Sigma} + \lambda I_d \right)^{-1} \frac{\Phi^T}{n} y$$

when $\lambda = 0$ this reduces to OLS $\hat{\beta}$ (if $\hat{\Sigma}$ is invertible)
or the min-norm estimator $\Phi^+ y$ if it is not)

PA/ The objective function is strictly convex so the first order optimality conditions are

$$0 = \nabla f(\hat{\beta}_\lambda) = \frac{2}{n} \Phi^T (\Phi \hat{\beta}_\lambda - y) + 2\lambda \hat{\beta}_\lambda$$

\hookrightarrow solve for $\hat{\beta}_\lambda$

This solution exists, is unique even if $d > n$ and regardless of how poorly conditioned $\Phi^T \Phi$ is!

Remarks

1) if $\lambda \rightarrow 0$ then

$\hat{\beta}_\lambda \rightarrow \hat{\beta}_{\text{min-norm}}$ or $\hat{\beta}$ if $\Phi^T \Phi$ is invertible

2) Alternative expression:

$$\hat{\beta}_\lambda = \left(\frac{\Phi^T \Phi}{n} + \lambda I_d \right)^{-1} \frac{\Phi^T}{n} y = \frac{\Phi^T}{n} \left(\frac{\Phi \Phi^T}{n} + \lambda I_n \right)^{-1} y$$

3) Let $\Phi = U \Sigma V^T$ Then

$$\hat{Y} = \Phi \hat{\beta}_\lambda = \sum_{j=1}^{\text{rank}(\Phi)} u_j \underset{\substack{\downarrow \\ j\text{th column of } U}}{\langle Y, u_j \rangle} \frac{\sigma_j^2}{\sigma_j^2 + \lambda} \quad \sigma_j \text{ } j\text{th singular value of } \Phi$$

in contrast $\Phi \hat{\beta} = \sum_{j=1}^{\text{rank}(\Phi)} u_j \langle Y, u_j \rangle$

• Thm 3.7 The excess risk of $\hat{\beta}_\lambda$ is

$$\begin{aligned} \mathbb{E} [R(\hat{\beta}_\lambda)] - \underbrace{R(\beta^*)}_{\sigma^2} &= \lambda^2 \beta^{*T} (\hat{\Sigma} + \lambda I_d)^{-2} \hat{\Sigma} \beta^* + \\ &\quad \frac{\sigma^2}{\lambda} \text{tr} \left(\hat{\Sigma}^2 (\hat{\Sigma} + \lambda I_d)^{-2} \right) \\ &\quad \underbrace{\sum_j \frac{\hat{\lambda}_j^2}{(\hat{\lambda}_j + \lambda)^2}}_{\text{Bias term}} \underbrace{\hat{\lambda}_j}_{j\text{th eigenvalue of } \hat{\Sigma}} \\ &= \text{Bias term} + \text{Variance term} \end{aligned}$$

• Bias is \uparrow in λ variance is \downarrow in λ .

• Task: choose optimal λ ! In Prop 3.8 of

Bach's book you will see a convenient choice of λ

that minimizes an upper bound on the excess risk

In particular with $\lambda = \frac{\sigma \text{tr}(\hat{\Sigma})}{\|\beta^*\| \sqrt{n}}$

$$\mathbb{E} [R(\hat{\beta}_\lambda)] - R(\beta^*) \leq \frac{\sigma \text{tr}(\hat{\Sigma}) \|\beta^*\|_2}{\sqrt{n}}$$

• Remark: 1) this is a "slow" rate

2) we do not know σ or $\|\beta^*\|$

in) ∇ in practice you will do cross validation

- MIN(MAX
LOWER BOUND ON EXCESS RISK (Section 3.7 in Bach's book)