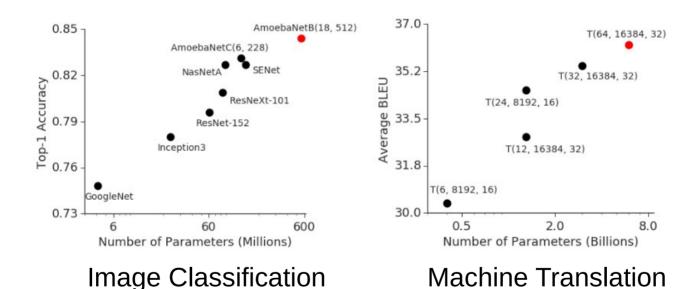
Data-Parallel Deep Learning Episode II, YSDA'21

Yandex Research





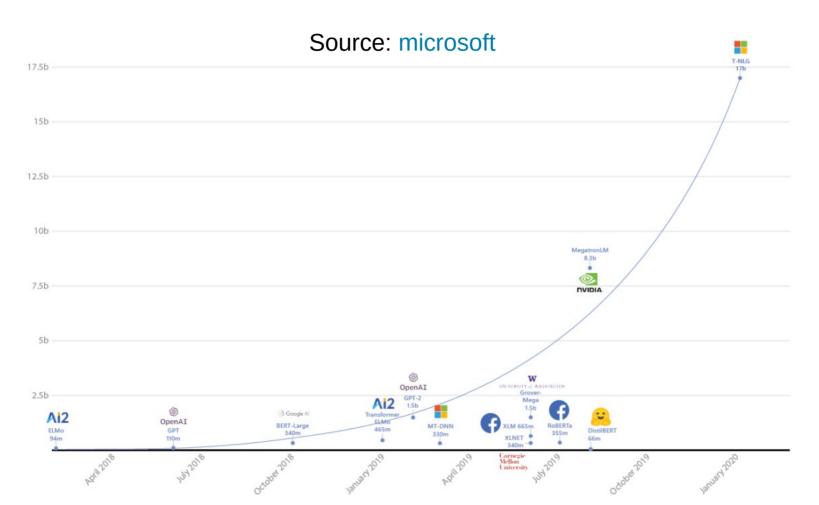
Large problems need large models



ImageNet average over WMT

Source: https://arxiv.org/abs/1811.06965

The transformer curve



Machine Learning Supertasks

Image classification – ImageNet, JFT300M

Generative models – ImageNet(biggan), the internet

Language Models – common crawl, BERT / MLM

Machine Translation – multilingual translation

Reinforcement Learning – playstation* & steam:)

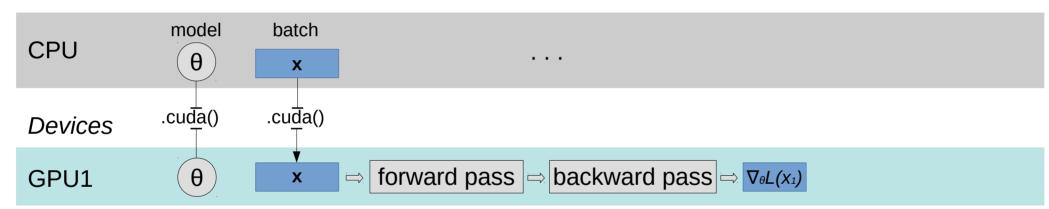
* playstation for RL: https://arxiv.org/abs/1912.06101

Meanwhile, exabytes of YouTube videos lay dormant across the web, waiting for someone who can make use of them

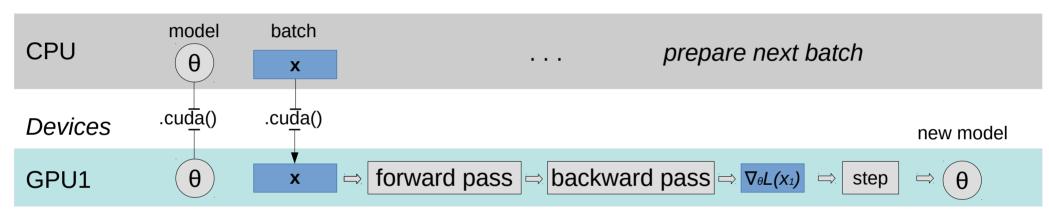
cs.cmu.edu/~muli/file/parameter_server_osdi14.pdf



cs.cmu.edu/~muli/file/parameter_server_osdi14.pdf

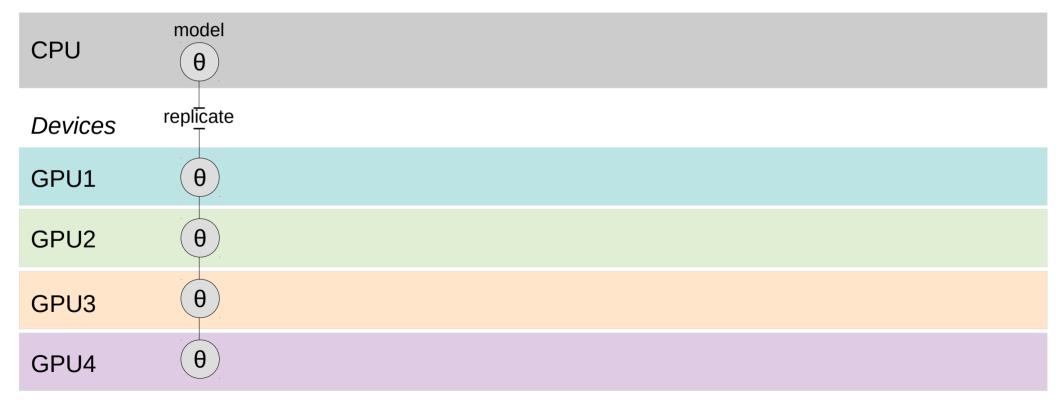


cs.cmu.edu/~muli/file/parameter_server_osdi14.pdf

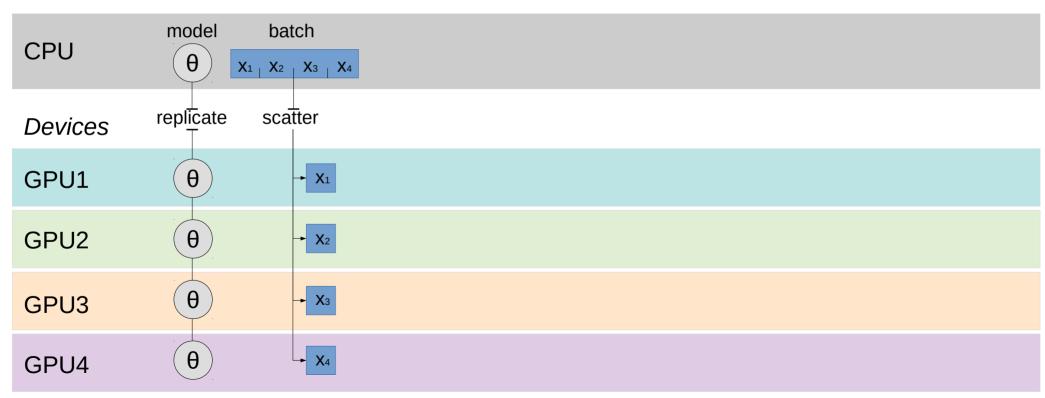


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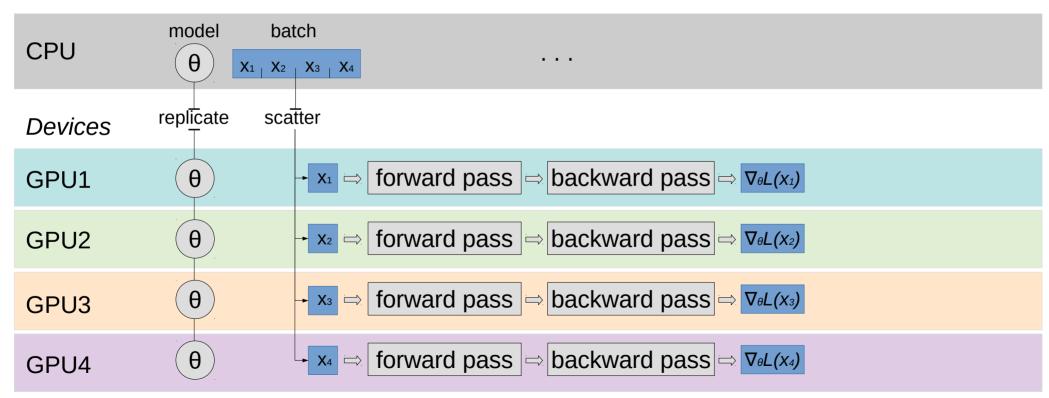




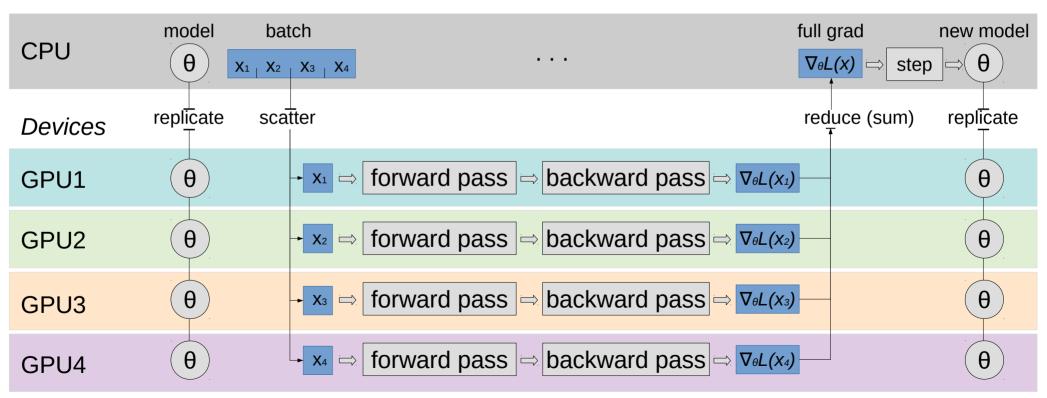
cs.cmu.edu/~muli/file/parameter_server_osdi14.pdf



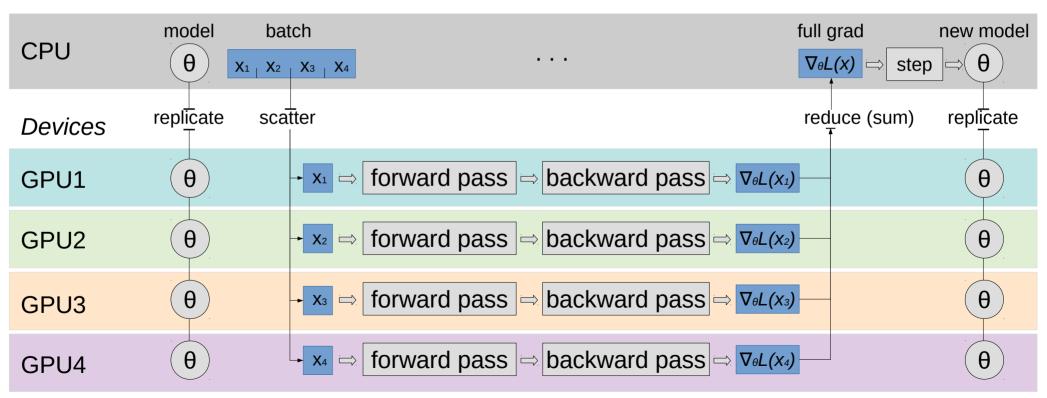
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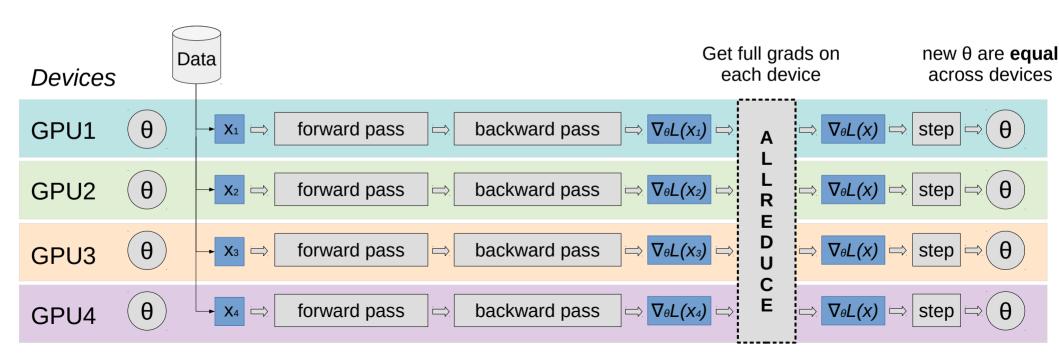
cs.cmu.edu/~muli/file/parameter_server_osdi14.pdf



All-Reduce data parallel

arxiv.org/abs/1706.02677

Idea: get rid of the host, each gpu runs its own computation Q: why will weights be equal after such step?



Input: each device has its its own vector

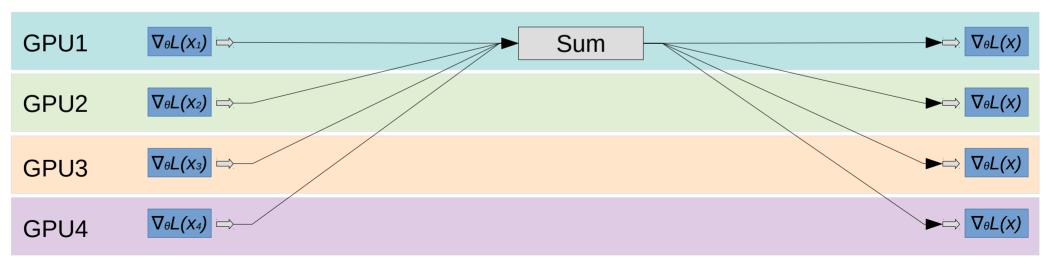
Output: each device gets a sum of all vectors



Input: each device has its its own vector

Output: each device gets a sum of all vectors

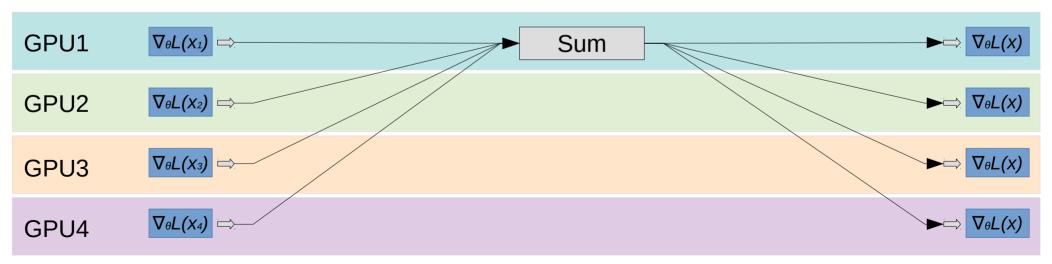
Naive implementation



Input: each device has its its own vector

Output: each device gets a sum of all vectors

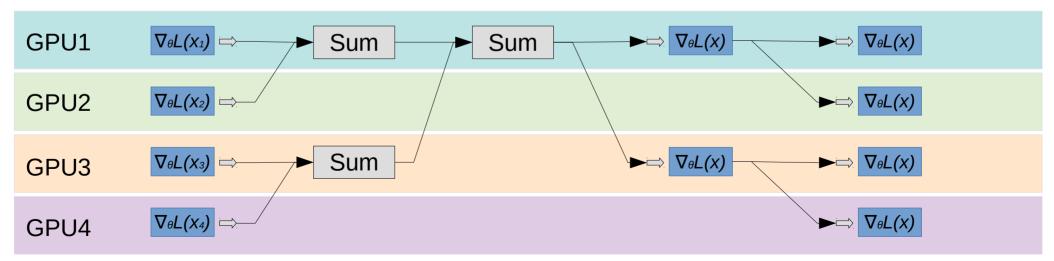
Q: Can we do better?



Input: each device has its its own vector

Output: each device gets a sum of all vectors

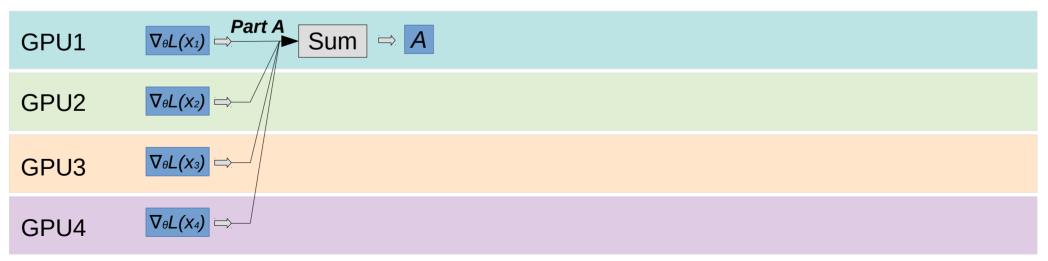
Tree-allreduce



Input: each device has its its own vector

Output: each device gets a sum of all vectors

Butterfly-allreduce – split data into chunks (ABCD)



Input: each device has its its own vector

Output: each device gets a sum of all vectors

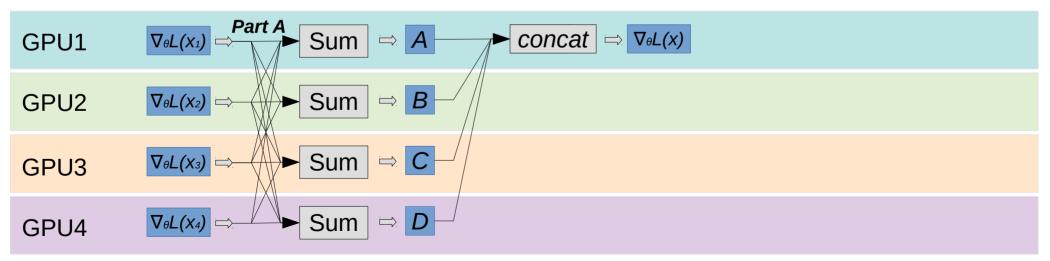
Butterfly-allreduce – split data into chunks (ABCD)



Input: each device has its its own vector

Output: each device gets a sum of all vectors

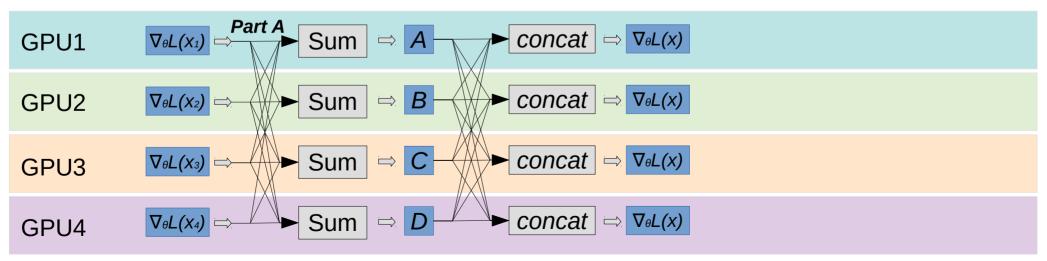
Butterfly-allreduce – split data into chunks (ABCD)



Input: each device has its its own vector

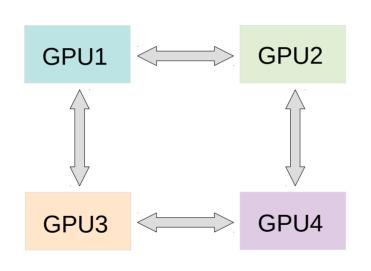
Output: each device gets a sum of all vectors

Ring-allreduce – split data into chunks (ABCD)



Ring allreduce

Bonus quest: you can only send data between adjacent gpus



Ring topology



Image: graphcore ipu server

Answer & more: tinyurl.com/ring-allreduce-blog

Ring allreduce

Bonus quest: you can only send data between adjacent gpus

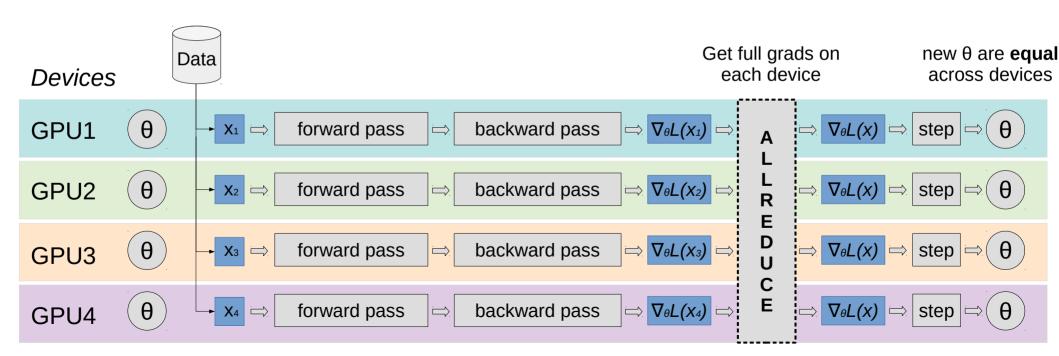
[Time to use the whiteboard]

Answer & more: tinyurl.com/ring-allreduce-blog

All-Reduce data parallel

arxiv.org/abs/1706.02677

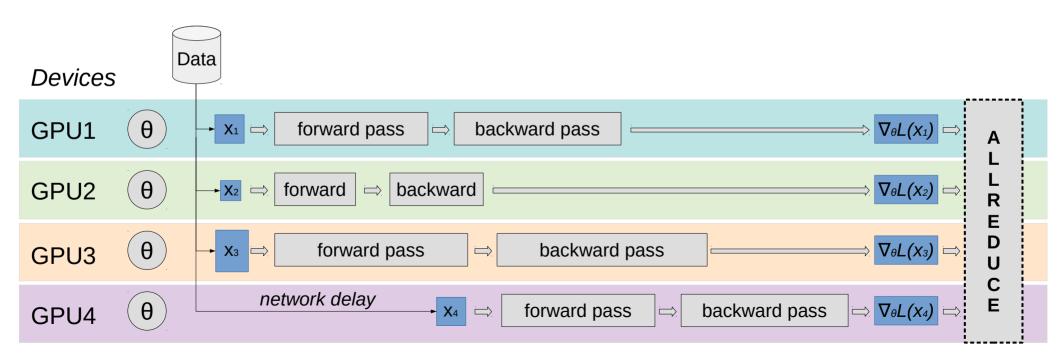
Idea: get rid of the host, each gpu runs its own computation Q: why will weights be equal after such step?



All-Reduce data parallel VS reality

arxiv.org/abs/1706.02677

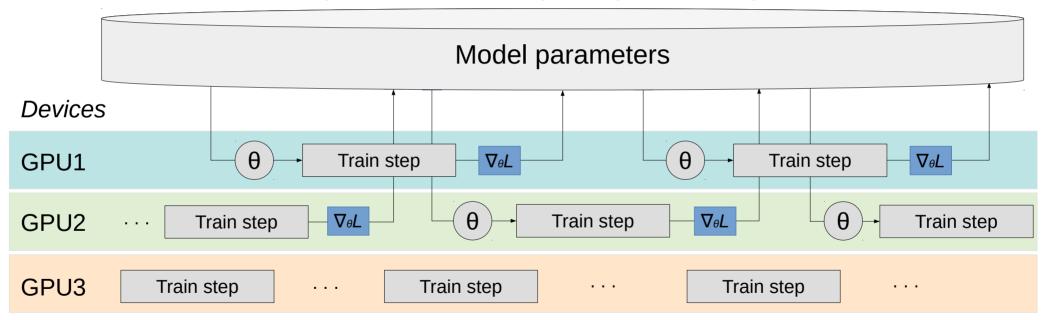
Each gpu has different processing time & delays **Q:** can we improve device utilization?



Recap: Parameter Server

HOGWILD! arxiv.org/abs/1106.5730

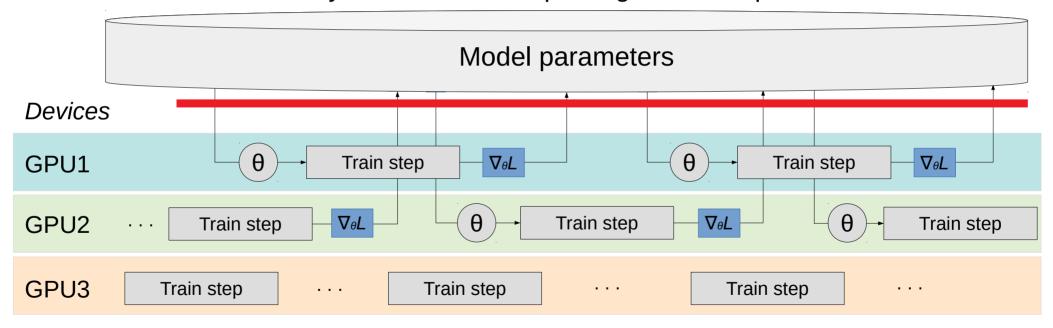
Idea: remove synchronization step alltogether, use parameter server



Recap: Parameter Server

HOGWILD! arxiv.org/abs/1106.5730

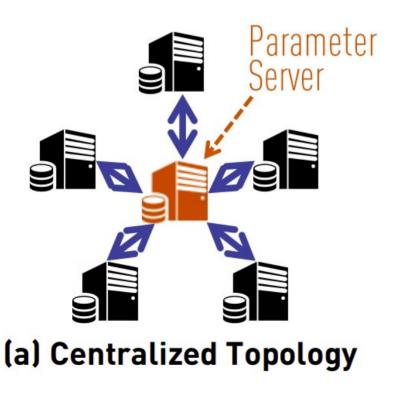
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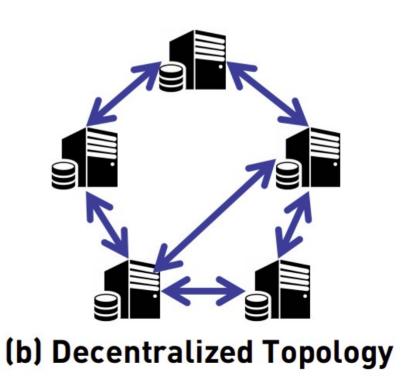


Problem: parameter servers need to ingest tons of data over training

Decentralized Training with Gossip

Gossip (communication): https://tinyurl.com/boyd-gossip-2006 Gossip outperforms All-Reduce: https://tinyurl.com/can-dsgd-outperform





Decentralized Training with Gossip

Source: https://tinyurl.com/can-dsgd-outperform

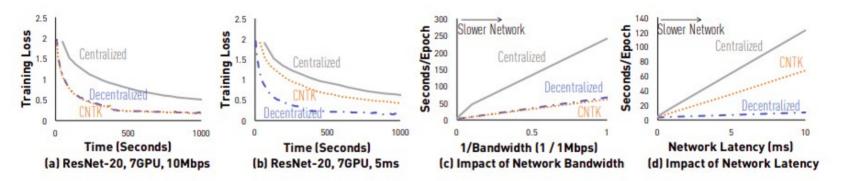


Figure 2: Comparison between D-PSGD and two centralized implementations (7 and 10 GPUs).

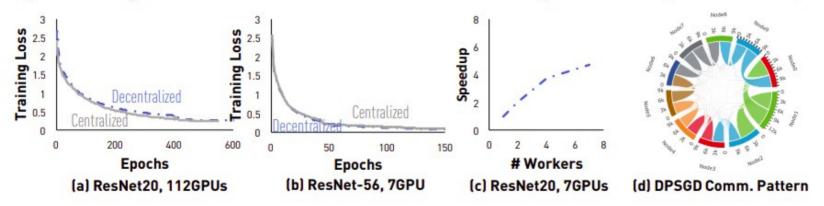
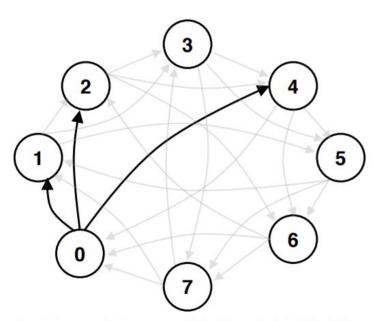


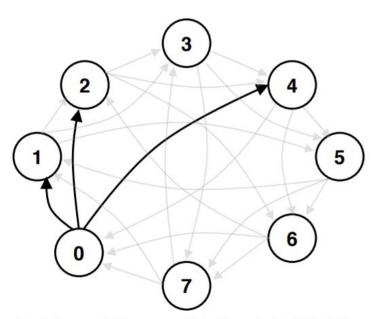
Figure 3: (a) Convergence Rate; (b) D-PSGD Speedup; (c) D-PSGD Communication Patterns.

Source: https://arxiv.org/abs/1811.10792



(a) Directed Exponential Graph highlighting node 0's out-neighbours

Source: https://arxiv.org/abs/1811.10792



(a) Directed Exponential Graph highlighting node 0's out-neighbours

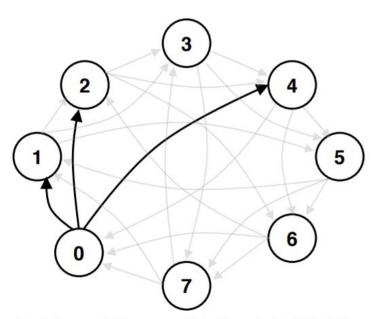
Algorithm 1 Stochastic Gradient Push (SGP)

Require: Initialize $\gamma>0$, $\boldsymbol{x}_i^{(0)}=\boldsymbol{z}_i^{(0)}\in\mathbb{R}^d$ and $w_i^{(0)}=1$ for all nodes $i\in\{1,2,\ldots,n\}$

- 1: **for** $k = 0, 1, 2, \dots, K$, at node i, **do**
- 2: Sample new mini-batch $\xi_i^{(k)} \sim \mathcal{D}_i$ from local distribution
- 3: Compute mini-batch gradient at $z_i^{(k)}$: $\nabla F_i(z_i^{(k)}; \xi_i^{(k)})$

<to be continued>

Source: https://arxiv.org/abs/1811.10792



(a) Directed Exponential Graph highlighting node 0's out-neighbours

Algorithm 1 Stochastic Gradient Push (SGP)

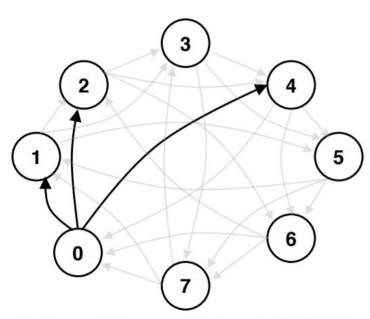
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- 4: $x_i^{(k+\frac{1}{2})} = x_i^{(k)} \gamma \nabla F_i(z_i^{(k)}; \xi_i^{(k)})$

normal GD step

<to be continued>

Source: https://arxiv.org/abs/1811.10792



(a) Directed Exponential Graph highlighting node 0's out-neighbours

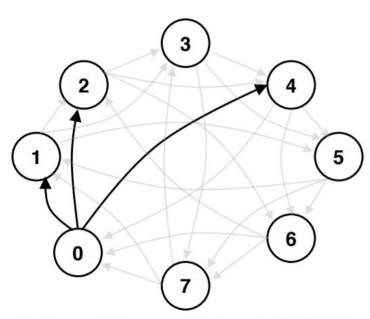
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- 5: Send $(p_{j,i}^{(k)} \boldsymbol{x}_i^{(k+\frac{1}{2})}, p_{j,i}^{(k)} w_i^{(k)})$ to out-neighbors; receive $(p_{i,j}^{(k)} \boldsymbol{x}_j^{(k+\frac{1}{2})}, p_{i,j}^{(k)} w_j^{(k)})$ from in-neighbors

<to be continued>

Source: https://arxiv.org/abs/1811.10792



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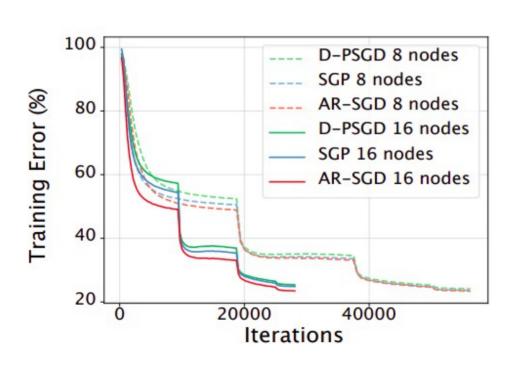
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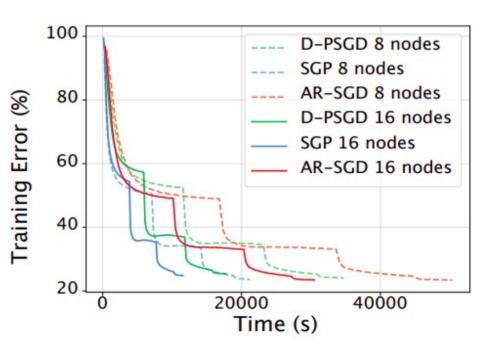
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- 6: $\boldsymbol{x}_{i}^{(k+1)} = \sum_{j} p_{i,j}^{(k)} \boldsymbol{x}_{j}^{(k+\frac{1}{2})}$ 7: $w_{i}^{(k+1)} = \sum_{j} p_{i,j}^{(k)} w_{j}^{(k)}$ 8: $\boldsymbol{z}_{i}^{(k+1)} = \boldsymbol{x}_{i}^{(k+1)} / w_{i}^{(k+1)}$ weighted average
- 9: end for

Source: https://arxiv.org/abs/1811.10792

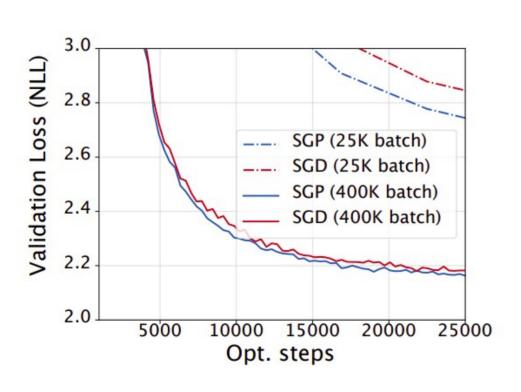
SGP vs ImageNet (ResNet50 + SGD w/ momentum)

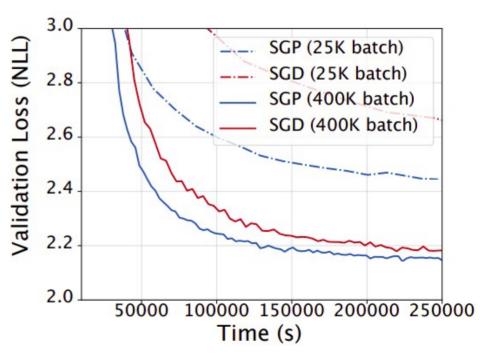




Source: https://arxiv.org/abs/1811.10792

SGP vs WMT English-German (Transformer, Adam)





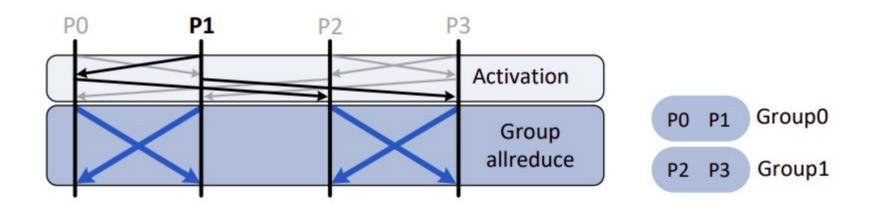
Gossip vs All-Reduce

Your thoughts?

Gossip + All-Reduce

Source: arxiv.org/abs/2005.00124

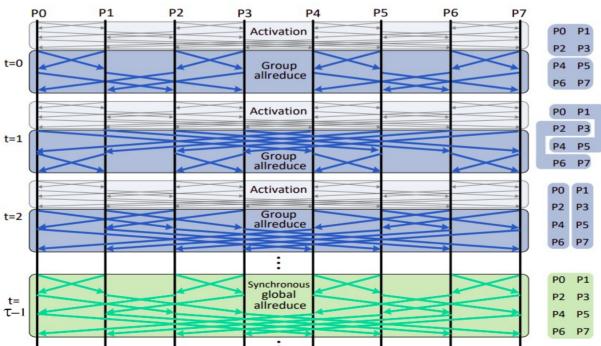
Core idea: run all-reduce in independent groups You only have to synchronize for your small group Swap groupmates between iterations



Gossip + All-Reduce

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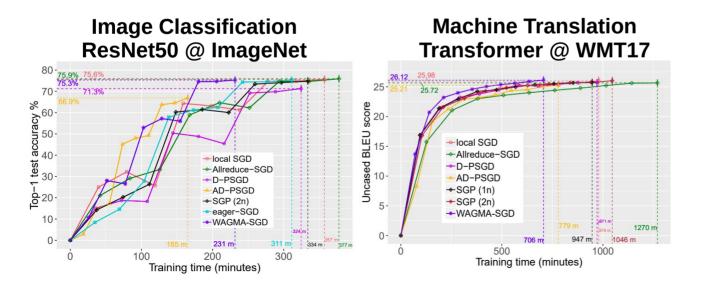
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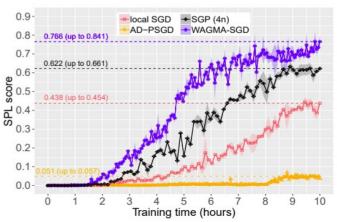
Gossip + All-Reduce

Source: arxiv.org/abs/2005.00124

Experiment setup: up to 1024 GPU, Natural (or emulated) network latency



Reinforcement Learning DDPO on Habitat



Side-quest: reducing network usage

Virtual batch / virtual pipeline

ёж, открой доску

</Data-parallel>

- + easy to implement
- + can scale to 100s of gpus
- + can be fault-tolerant
- model must fit in 1 gpu
- large batches aren't always good for generalization
- 2-4 GPUs & no time naive data parallel tinyurl.com/torch-data-parallel
- 4+ GPUs or multiple hosts horovod (allreduce) github.com/horovod/horovod
 - High-level distributed pytorch (allreduce): tinyurl.com/distributed-dp
- Somewhat faulty GPU/network: synchronous data parallel + drop stragglers
- Very faulty or uneven resources: asynchronous data parallel (more later)
- Efficient training with large batches: LAMB https://arxiv.org/abs/1904.00962
- Dynamically adding or removing resources: https://tinyurl.com/torch-elastic

"That's all Folks!"