# Kernel Ridge Regression and the Kernel Trick

Machine Learning Course - CS-433 Nov 2, 2021 Nicolas Flammarion



#### Equivalent formulation for Ridge regression

$$\min_{w} \frac{1}{2N} \sum_{n=1}^{N} (y_n - w^{\mathsf{T}} x_n)^2 + \frac{\lambda}{2} ||w||^2$$

The solution is given by

$$w_* = \frac{1}{N} \left( \underbrace{\frac{1}{N} \mathbf{X}^\mathsf{T} \mathbf{X}}_{N} + \lambda I_d \right)^{-1} \mathbf{X}^\mathsf{T} \mathbf{y}$$
$$\mathbf{X}^\mathsf{T} \in \mathbb{R}^{d \times N} \to d \times d$$

But it can be alternatively written as

$$w_* = \frac{1}{N} \mathbf{X}^{\mathsf{T}} \left( \frac{1}{N} \mathbf{X} \mathbf{X}^{\mathsf{T}} + \lambda I_N \right)^{-1} \mathbf{y}$$
$$\mathbf{X} \in \mathbb{R}^{N \times d} \to N \times N$$

Proof: let  $P \in \mathbb{R}^{m \times n}$  and  $Q \in \mathbb{R}^{n \times m}$ 

$$P(QP + I_n) = PQP + P = (PQ + I_m)P$$

Assume that  $QP + I_n$  and  $PQ + I_m$  are invertible

$$(PQ + I_m)^{-1}P = P(QP + I_n)^{-1}$$

We get the result with  $P = \mathbf{X}^{\mathsf{T}}$  and  $Q = \frac{1}{\lambda N} \mathbf{X}$ 

$$w_* = \frac{1}{N} \left( \frac{1}{N} \mathbf{X}^\mathsf{T} \mathbf{X} + \lambda I_d \right)^{-1} \mathbf{X}^\mathsf{T} \mathbf{y}$$
$$\mathbf{X}^\mathsf{T} \in \mathbb{R}^{d \times N} \to d \times d$$

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$$\mathbf{X} \in \mathbb{R}^{N \times d} \to N \times N$$

regression

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#### Usefulness of the alternative form

$$w_* = \frac{1}{N} \mathbf{X}^{\mathsf{T}} \left( \frac{1}{N} \mathbf{X} \mathbf{X}^{\mathsf{T}} + \lambda I_N \right)^{-1} \mathbf{y}$$

$$d \times N$$

- 1. Computational complexity:
  - For the original formulation  $\frac{1}{N}(\frac{1}{N}\mathbf{X}^{\mathsf{T}}\mathbf{X} + \lambda I_d)^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$ ,  $O(d^3 + Nd^2)$
  - For the new formulation  $\frac{1}{N}\mathbf{X}^{\mathsf{T}}(\frac{1}{N}\mathbf{X}\mathbf{X}^{\mathsf{T}}+\lambda I_N)^{-1}\mathbf{y},\ O(N^3+dN^2)$ 
    - ightharpoonup Depending on d,N one can be more efficient than the other
- 2. Structural difference:

$$w_* = \mathbf{X}^{\mathsf{T}} \alpha_*$$
 where  $\alpha_* = \frac{1}{N} (\frac{1}{N} \mathbf{X} \mathbf{X}^{\mathsf{T}} + \lambda I_N)^{-1} \mathbf{y}$ 

 $\rightarrow w_* \in \text{span}\{x_1, \dots, x_N\}$ 

These two points are the crucial ingredients of the kernel trick

# Representer Theorem

Claim: For any loss function  $\ell$ , if  $w_* = \arg\min_{w} \frac{1}{N} \sum_{n=1}^{N} \ell(x_n^{\mathsf{T}} w, y_n) + \frac{\lambda}{2} ||w||^2$  then there exists  $\alpha_* \in \mathbb{R}^N$  such that

$$w_* = \mathbf{X}^{\mathsf{T}} \alpha_*$$

Meaning: There exists an optimal solution that lies in span $\{x_1, \dots, x_N\}$ 

<u>Consequence</u>: It is far more general than LS and we will be able to use the kernel tricks for various problems such as: Kernel SVM, Kernel LS, Kernel Principal Component Analysis

# Proof of the representer theorem

We can always rewrite  $w_*$  as  $w_* = \sum_{n=1}^N \alpha_n x_n + u$  where  $u^{\mathsf{T}} x_n = 0$  for all n

Let's denote by  $w = w_* - u$ 

- $||w_*||^2 = ||w||^2 + ||u||^2$ , thus  $||w||^2 \le ||w_*||^2$
- For all n,  $w^{\mathsf{T}}x_n = (w_* u)^{\mathsf{T}}x_n = w_*^{\mathsf{T}}x_n$ , thus  $\ell(x_n^{\mathsf{T}}w, y_n) = \ell(x_n^{\mathsf{T}}w_*, y_n)$

Therefore

$$\frac{1}{N} \sum_{n=1}^{N} \mathcal{E}(x_n^{\mathsf{T}} w, y_n) + \frac{\lambda}{2} \|w\|^2 \le \frac{1}{N} \sum_{n=1}^{N} \mathcal{E}(x_n^{\mathsf{T}} w_*, y_n) + \frac{\lambda}{2} \|w_*\|^2$$

And w is an optimal solution for this problem. Since the objective is strongly convex, there is unicity of the solution and  $w_* = w$ 

# Kernelized ridge regression

#### Classical formulation in w:

$$w_* = \arg\min_{w} \frac{1}{2N} ||\mathbf{y} - \mathbf{X}w||^2 + \frac{\lambda}{2} ||w||^2$$

#### Alternative formulation in $\alpha$ :

$$\alpha_* = \arg\min_{\alpha} \frac{1}{2} \alpha^{\mathsf{T}} (\frac{1}{N} \mathbf{X} \mathbf{X}^{\mathsf{T}} + \lambda I_N) \alpha - \frac{1}{N} \alpha^{\mathsf{T}} \mathbf{y}$$

Claim: These two formulations are equivalent

<u>Proof</u>: Set the gradient to 0, to obtain  $\alpha_* = \frac{1}{N} (\frac{1}{N} \mathbf{X} \mathbf{X}^{\mathsf{T}} + \lambda I_N)^{-1} \mathbf{y}$ , and  $w_* = \mathbf{X}^{\mathsf{T}} \alpha_*$ 

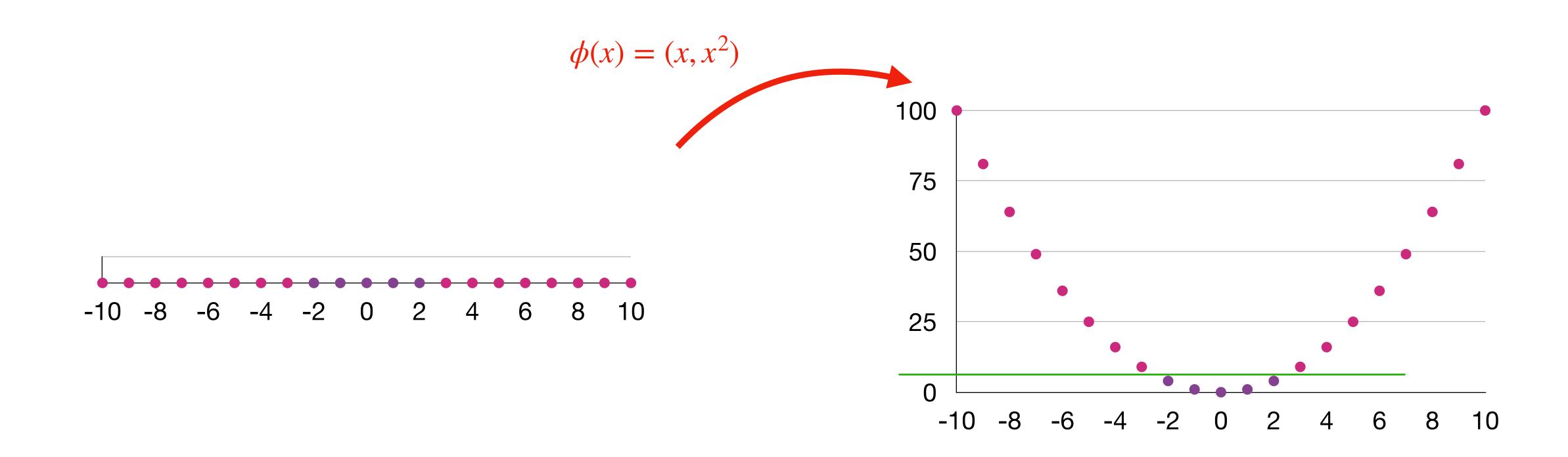
#### **Interest:**

- Computational complexity depending on d,N
- The dual formulation only uses  ${f X}$  through the kernel matrix  ${f K}={f X}{f X}^{\top}$

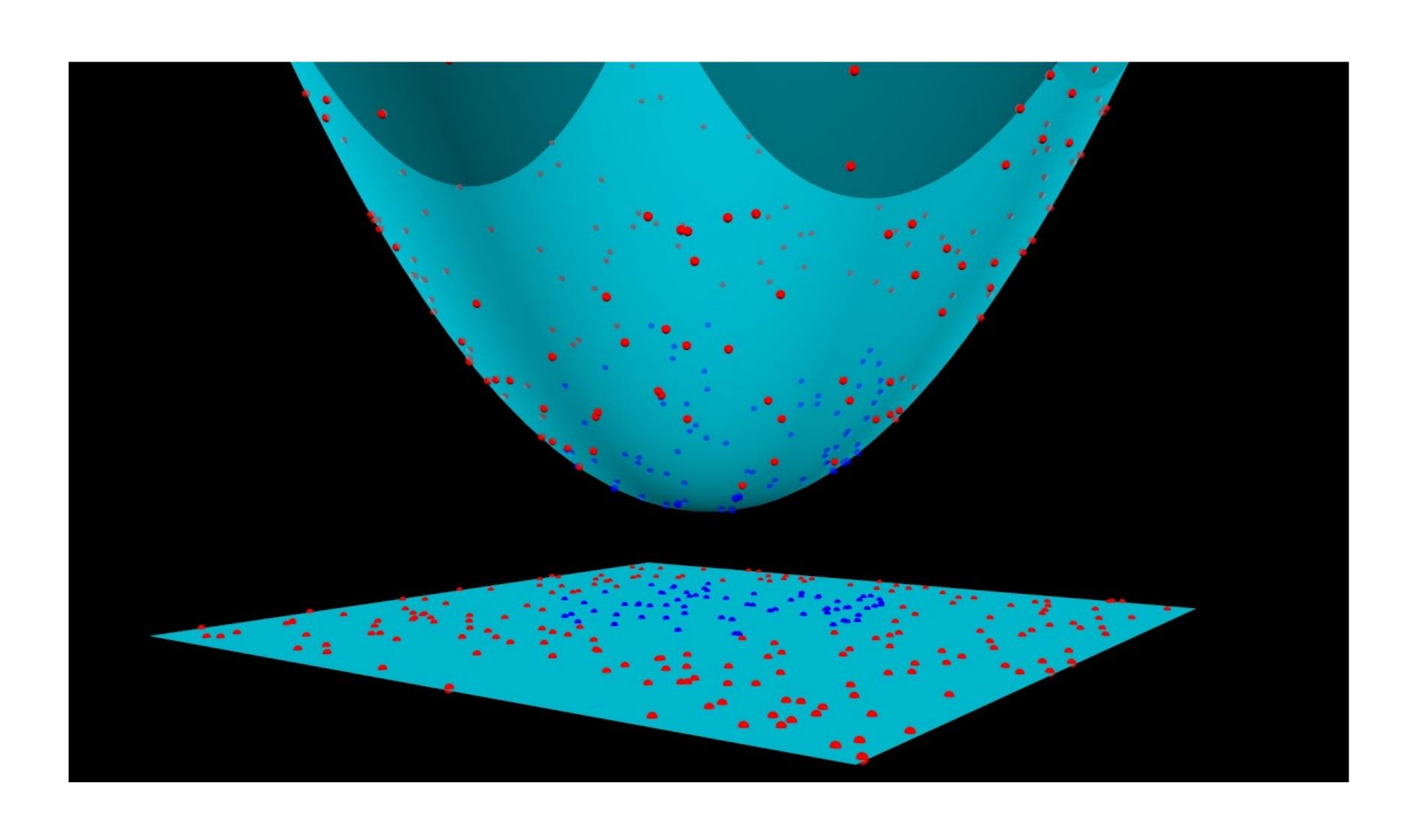
### Kernel matrix

$$\mathbf{K} = \mathbf{X}\mathbf{X}^{\top} = \begin{pmatrix} x_{1}^{\top}x_{1} & x_{1}^{\top}x_{2} & \cdots & x_{1}^{\top}x_{N} \\ x_{2}^{\top}x_{1} & x_{2}^{\top}x_{2} & \cdots & x_{2}^{\top}x_{N} \\ \vdots & \vdots & \ddots & \vdots \\ x_{N}^{\top}x_{1} & x_{N}^{\top}x_{2} & \cdots & x_{N}^{\top}x_{N} \end{pmatrix} = (x_{i}^{\top}x_{j})_{i,j} \in \mathbb{R}^{N \times N}$$

# Embedding into feature spaces



# Usefulness of feature spaces



### Kernel matrix with feature spaces

When a feature map  $\phi: \mathbb{R}^d \to \mathbb{R}^{\widetilde{d}}$  is used,

$$(x_n)_{n=1}^N \hookrightarrow (\phi(x_n))_{n=1}^N$$

The associated kernel matrix is

$$\mathbf{K} = \mathbf{\Phi} \mathbf{\Phi}^{\top} = \begin{pmatrix} \phi(x_1)^{\top} \phi(x_1) & \phi(x_1)^{\top} \phi(x_2) & \cdots & \phi(x_1)^{\top} \phi(x_N) \\ \phi(x_2)^{\top} \phi(x_1) & \phi(x_2)^{\top} \phi(x_2) & \cdots & \phi(x_2)^{\top} \phi(x_N) \\ \vdots & \vdots & \ddots & \vdots \\ \phi(x_N)^{\top} \phi(x_1) & \phi(x_N)^{\top} \phi(x_2) & \cdots & \phi(x_N)^{\top} \phi(x_N) \end{pmatrix} \in \mathbb{R}^{N \times N}$$

Problem: when  $d \ll \tilde{d}$  computing  $\phi(x)^{\top}\phi(x')$  costs  $O(\tilde{d})$  - too expensive

### Kernel trick

Kernel function:  $\kappa(x, x')$  such that

$$\kappa(x,x') = \phi(x)^{\mathsf{T}} \phi(x')$$
 Similarity between  $x_i$  and  $x_j$  Similarity realized as inner products in the feature space

It is equivalent to

- Directly compute  $\kappa(x, x')$
- First augment the features to  $\phi(x)$ , then compute  $\phi(x)^{T}\phi(x')$

Interest: enable computation of linear classifiers in high-dimensional space without having to do computation in this high-dimensional space.

# Examples of kernel (easy)

- 1. Linear kernel:  $\kappa(x, x') = x^{\mathsf{T}} x'$ 
  - $\rightarrow$  Feature map is  $\phi(x) = x$
- 2. Quadratic kernel:  $\kappa(x, x') = (xx')^2$  for  $x, x' \in \mathbb{R}$ 
  - $\rightarrow$  Feature map is  $\phi(x) = x^2$

# 3. Polynomial kernel

Let  $x, x' \in \mathbb{R}^3$ 

$$\kappa(x, x') = (x_1 x_1' + x_2 x_2' + x_3 x_3')^2$$

#### Feature map:

$$\phi(x) = [x_1^2, x_2^2, x_3^2, \sqrt{2}x_1x_2, \sqrt{2}x_1x_3, \sqrt{2}x_2x_3] \in \mathbb{R}^6$$

#### Proof:

$$\begin{split} \kappa(x,x') &= \phi(x)^{\top} \phi(x') \\ \kappa(x,x') &= (x_1 x_1' + x_2 x_2' + x_3 x_3')^2 \\ &= (x_1 x_1')^2 + (x_2 x_2')^2 + (x_3 x_3')^2 + 2x_1 x_2 x_1' x_2' + 2x_1 x_3 x_1' x_3' + 2x_2 x_3 x_2' x_3' \\ &= \left(x_1^2, x_2^2, x_3^2, \sqrt{2} x_1 x_2, \sqrt{2} x_1 x_3, \sqrt{2} x_2 x_3\right)^{\top} \left(x_1'^2, x_2'^2, x_3'^2, \sqrt{2} x_1' x_2', \sqrt{2} x_1' x_3', \sqrt{2} x_2' x_3'\right) \end{split}$$

We obtain  $\phi$  by identification

### 4. Radial basis function (RBF) kernel

Let  $x, x' \in \mathbb{R}^d$ 

$$\kappa(x,x') = e^{-(x-x')^{\mathsf{T}}(x-x')}$$

For  $x, x' \in \mathbb{R}$ 

$$\kappa(x,x')=e^{-(x-x')^2}$$

Feature map:

$$\phi(x) = e^{-x^2} \left( \cdots, \frac{2^{k/2} x^k}{\sqrt{k!}} \cdots \right)$$
 Infinite dimensional vector

Proof:  $\kappa(x, x') = e^{-x^2 - x'^2 + 2xx'}$   $= e^{-x^2} e^{-x'^2} \sum_{k=0}^{\infty} \frac{2^k x^k x'^k}{k!} \text{ by the Taylor expansion of exp}$   $\phi(x) = e^{-x^2} \left( \cdots, \frac{2^{k/2} x^k}{\sqrt{k!}} \cdots \right) \implies \phi(x)^{\top} \phi(x') = \kappa(x, x')$ 

Interest: it cannot be represented as an inner product in a finite-dimensional space

### Building new kernels from old kernels

Let  $\kappa_1$ ,  $\kappa_2$  be two kernel functions and  $\phi_1$ ,  $\phi_2$  the corresponding feature maps

Claim 1: Positive linear combinations of kernel are kernels

$$\kappa(x, x') = \alpha \kappa_1(x, x') + \beta \kappa_2(x, x') \text{ for } \alpha, \beta \ge 0$$

Claim 2: Products of kernels are kernels

$$\kappa(x, x') = \kappa_1(x, x')\kappa_2(x, x')$$

Interest: Building blocks to derive new kernels

#### Proof 1:

$$\kappa(x, x') = \alpha \kappa_1(x, x') + \beta \kappa_2(x, x')$$

$$= \alpha \phi_1(x)^{\mathsf{T}} \phi_1(x') + \beta \phi_2(x)^{\mathsf{T}} \phi_2(x')$$

$$= \phi(x)^{\mathsf{T}} \phi(x')$$

where 
$$\phi(x) = \begin{pmatrix} \sqrt{\alpha}\phi_1(x) \\ \sqrt{\beta}\phi_2(x) \end{pmatrix} \in \mathbb{R}^{d_1+d_2}$$

#### kernels from old kernel

s and  $\phi_1$ ,  $\phi_2$  the corresponding feature maps

Claim 1: Positive linear combinations of kernel are kernel

$$\kappa(x, x') = \alpha \kappa_1(x, x') + \beta \kappa_2(x, x')$$

Claim 2: Products of kernels are kernel

$$\kappa(x, x') = \kappa_1(x, x')\kappa_2(x, x')$$

#### Proof 2:

$$\kappa(x, x') = \kappa_1(x, x') \kappa_2(x, x')$$
  
=  $\phi_1(x)^{\mathsf{T}} \phi_1(x') \phi_2(x)^{\mathsf{T}} \phi_2(x')$ 

Let

$$\phi(x)^{\top} = \left( (\phi_1(x))_1 (\phi_2(x))_1, \cdots, (\phi_1(x))_1 (\phi_2(x))_{d_2}, \cdots, (\phi_1(x))_{d_1} (\phi_2(x))_1, \cdots, (\phi_1(x))_{d_1} (\phi_2(x))_{d_2} \right) \in \mathbb{R}^{d_1 d_2}$$

then

$$\phi(x)^{\top}\phi(x') = \sum_{i,j} (\phi_1(x))_i (\phi_2(x))_j (\phi_1(x'))_i (\phi_2(x'))_j$$

$$= \sum_i (\phi_1(x))_i (\phi_1(x'))_i \sum_j (\phi_2(x))_j (\phi_2(x'))_j$$

$$= \phi_1(x)^{\top}\phi_1(x')\phi_2(x)^{\top}\phi_2(x') = \kappa(x, x')$$

Claim 2: Products of kernels are kernel

$$\kappa(x, x') = \kappa_1(x, x')\kappa_2(x, x')$$

### Mercer's condition

Question: Given a kernel function  $\kappa$ , how can we ensure that there exists a feature map  $\phi$  such that

$$\kappa(x, x') = \phi(x)^{\mathsf{T}} \phi(x')$$

Answer: It is true if and only if the following Mercer's conditions are fulfilled:

• The kernel function is symmetric:

$$\forall x, x', \kappa(x, x') = \kappa(x', x)$$

The kernel matrix is psd for all possible input sets:

$$\forall n \geq 0, \ \forall (x_n)_{n=1}^N, \ \mathbf{K} = (\kappa(x_i, x_j))_{i,j=1}^N \geq 0$$

# Predicting with kernels

<u>Problem</u>: we predict with  $y = \phi(x)^{\top} w_*$  whereas  $\phi(x)$  can be expensive to compute

Question: How to do a prediction only using the kernel function, without computing  $\phi(x)$ ?

Answer: 
$$\phi(x)^{\mathsf{T}} w_* = \phi(x)^{\mathsf{T}} \phi(\mathbf{X})^{\mathsf{T}} \alpha_* = \sum_{n=1}^N \kappa(x, x_n) \alpha_{*i}$$
 We can do a prediction only using the kernel function

using the kernel function

Important remark:

$$y = \phi(x)^{\top} w_* = f_{\psi_*}(x)$$
 Linear prediction Non linear prediction

in the feature space

in the  ${\mathscr X}$  space

# Bonus: proof of Mercer theorem

• If  $\kappa$  implements an inner product then it is symmetric and the kernel matrix is psd:

$$v^{\mathsf{T}} \mathsf{K} v = \sum_{i,j} v_i v_j \phi(x_i)^{\mathsf{T}} \phi(x_j) = (\sum_i v_i \phi(x_i))^2$$

• Define  $\phi(x) = \kappa(\cdot, x)$ . Define a vector space of functions by taking all linear combinations  $\{\sum_i \alpha_i \kappa(\cdot, x_i)\}$ . Define an inner product on this vector space by

$$\langle \sum_{i} \alpha_{i} \kappa(\cdot, x_{i}), \sum_{j} \beta_{j} \kappa(\cdot, x_{j}) \rangle = \sum_{i,j} \alpha_{i} \beta_{j} \kappa(x_{i}, x_{j})$$

This is a valid inner product (symmetric, bilinear and positive definite, with equality only  $\phi(x)$  is the zero function)

We have

$$\langle \phi(x), \phi(x') \rangle = \langle \kappa(\cdot, x), \kappa(\cdot, x') \rangle = \kappa(x, x')$$