Features:

1. We have added two metallic clamps to add rigidity and stability to the bot while keeping the added weight to a minimum.
2. We also added a switch to the sender esp so that in case the bot topples, we can invert the controls of the bot by flipping the switch thereby rendering the bot functional without loss of time.
3. We attached rubber bands to our tyres to increase traction and grip. In addition to this, we cleaned the rubber bands before using them as dust on the rubber band decreases the friction between the bot and the ground.

Resources used:

1. GrabCad
2. AutoDesk Fusion 360
3. Tinkerer’s Lab