

REQUIREMENTS NOT MET

N/A

PROBLEMS ENCOUNTERED

I had a vast amount of problems writing my code because I could not figure out how to get my program to work even though my logic seemed correct. Since I did not initially write to the high bytes of the CCx registers or clear them, the RGB LED would not turn on at all, and I did not account for this because I thought the register values were configured to 0x00 in the hardware. Additionally, I had some issues with remapping the pins and outputting the PWM values to the LED. It took me many hours of debugging to realize what the issues were.

HOMEWORK EXERCISES

- i. How many TC0 channels are necessary to control all three of the LEDs within the on-board RGB LED package?
 - a. Three channels because you need one PWM channel per LED (R, G, B), so three TC0 compare channels (CCA/CCB/CCC) are sufficient. A TC0 block provides four compare channels total, so using three covers all LEDs independently.

- ii. In the context of the program specified above, would any difference (theoretically) result from setting the RGB period to be \$FFFF, instead of \$FF?
 - a. If the period were set to \$FFFF instead of \$FF, the theoretical difference is that the PWM would have much higher duty-cycle resolution (16-bit vs. 8-bit) but a frequency 256 times lower. In practice, this slower frequency could cause visible flicker, which is why \$FF is preferred for smooth LED control.

PSEUDOCODE/FLOWCHARTS

SECTION 1

hw2.asm:

;define constants

;assembler directives

.org 0

Rjmp MAIN

.org 0x100

MAIN:

;init stack

Rcall IO_INIT

Rcall TC_INIT

LOOP:

;check S1 on SLB and read values

;if pressed (low)

;write value into TCD0_CCA (red duty)

;clear TCD0_CCB and TCD0_CCC (green and blue)

;else continue

;check S1 on MB and read values

;if pressed (low)

;write value into TCD0_CCB (green duty)

;clear TCD0_CCA and TCD0_CCC (red and blue)

;else continue

;check S2 on SLB and read values

```
;if pressed (low)
;write value into TCD0_CCC (Blue duty)
;clear TCD0_CCA and TCD0_CCB (red and green)
;else continue
```

```
;if no switch pressed
;Clear all three compare registers to turn RGBs off
```

```
Rjmp LOOP
```

```
*****
```

- * Name: INIT_IO
- * Purpose: Configure RGB LEDs on PD4–PD6 as outputs (inverted, OFF by default),
 - * DIP switches as inputs, and tactile switches as inputs with pull-ups.
- *
- * Inputs: None
- * Outputs: I/O configured for LEDs, DIP switches, and tactile switches

- * Affected: PORTD_DIRSET, PORTD_PINnCTRL, PORTD_OUTSET,
 - * PORTA_DIR, PORTF_DIRCLR, PORTE_DIRCLR,
 - * PORTF_PINnCTRL, PORTE_PINnCTRL

```
******/
```

```
INIT_IO:
```

```
;push registers
```

```
;configure PD4-PD6 as outputs (RGB) (off at first HIGH)
```

```
;enable inversion on PD4-PD6 in PORTD_PINnCTRL to ensure duty cycle logic matches brightness
```

```
;configure DIP switches as inputs (PORT A)
```

;Configure tactile switches as inputs

;slb s1 = PF2, slb s2 = PF3

;mb s1 = PE0

;pop registers

Ret

* Name: TC_INIT

* Purpose: Configure TCD0 for single-slope PWM on PD4–PD6 (RGB LEDs).

*

* Inputs: None

* Outputs: PWM channels initialized on PD4–PD6 (all LEDs OFF by default)

* Affected: PORTD_REMAP, TCD0_PER, TCD0_CCA/CCB/CCC,

* TCD0_CTRLB, TCD0_CTRLA

TC_INIT:

;push registers

;enable remap so TC0 outputs go to pd4-pd7 to access the rgb leds

;write to portd_REMAP

;set the bits TC0A, TC0B, TC0C

;configure PWM mode (single slope)

;enable compare channels A, B, C in CTRLB

;set period to 0xFF in TCD0

;initialize duty cycles to 0 (write 0 to TCD0_CCA, TCD0_CCB, TCD0_CCC)

;Start the timer with PRE = div 8

;pop registers

ret

PROGRAM CODE

SECTION 2

```
;  
; hw2.asm  
;  
; Created: 9/29/2025 11:44:13 PM  
; Author : arist  
;  
  
;define constants  
;assembler directives  
.include "ATxmega128A1Udef.inc"  
  
.org 0  
Rjmp MAIN  
  
.org 0x100  
MAIN:  
;init stack  
ldi r16, low (0xFFFF)  
sts CPU_SPL, r16  
ldi r16, high (0xFFFF)  
sts CPU_SPH, r16  
  
Rcall INIT_IO  
Rcall TC_INIT  
  
clr r17  
  
LOOP:  
;output dip to leds for debugging  
lds r18, PORTA_IN  
sts PORTC_OUT, r18  
com r18  
  
;check S1 on SLB and read values  
lds r16, PORTF_IN  
;if pressed (low)  
sbrc r16, 2  
rjmp NOT_S1_SLB  
    ;write value into TCD0_CCA (red duty)  
  
    sts TCD0_CCA, r18  
    sts TCD0_CCA+1, r17  
    ;clear TCD0_CCB and TCD0_CCC (green and blue)  
    sts TCD0_CCB, r17  
    sts TCD0_CCB+1, r17  
    sts TCD0_CCC, r17  
    sts TCD0_CCC+1, r17  
  
rjmp loop  
  
;else continue  
  
NOT_S1_SLB:  
;check S1 on MB and read values
```



```
;enable inversion on PD4-PD6 in PORTD_PINnCTRL to ensure duty cycle logic matches brightness
ldi r16, PORT_INVEN_bm
sts PORTD_PIN4CTRL, r16
sts PORTD_PIN5CTRL, r16
sts PORTD_PIN6CTRL, r16

;configure PD4-PD6 as outputs (RGB) (off at first HIGH)
ldi r16, 0b01110000
sts PORTD_OUTCLR, r16
sts PORTD_DIRSET, r16

;configure DIP switches as inputs (PORT A)
ldi r16, 0xFF
sts PORTA_DIRCLR, r16

;Configure tactile switches as inputs
;slb s1 = PF2, slb s2 = PF3
ldi r16, (1<<2 | 1<<3)
sts PORTF_DIRCLR, r16
; mb s1 = PE0
ldi r16, (1<<0)
sts PORTE_DIRCLR, r16

;set slb leds for debuggin purposes
ldi r16, 0xFF
sts PORTC_OUTSET, r16
sts PORTC_DIRSET, r16
;pop registers
pop r16

Ret

/******************
* Name:      TC_INIT
* Purpose:  Configure TCD0 for single-slope PWM on PD4-PD6 (RGB LEDs).
*
* Inputs:    None
* Outputs:   PWM channels initialized on PD4-PD6 (all LEDs OFF by default)
* Affected:  PORTD_REMAP, TCD0_PER, TCD0_CCA/CCB/CCC,
*            TCD0_CTRLB, TCD0_CTRLA
********************/
TC_INIT:
;push registers
push r16

;enable remap so TC0 outputs go to pd4-pd7 to access the rgb leds
;write to portd_REMAP
;set the bits TC0A, TC0B, TC0C

;ldi r16, (PORT_TC0C_bm | PORT_TC0B_bm | PORT_TC0A_bm)
ldi r16, 0b00000111
sts PORTD_REMAP, r16

;configure PWM mode (single slope) in CTRLB
; enable compare channels A, B, C in CTRLB
ldi r16, (TC_WGMODE_SINGLE_SLOPE_gc | TC0_CCAEN_bm | TC0_CCBEN_bm | TC0_CCCEN_bm)
sts TCD0_CTRLB, r16
;set period to 0xFF in TCD0
```

```
ldi r16, low(0xFF)
sts TCD0_PER, r16
ldi r16, high (0xFF)
sts TCD0_PER + 1, r16

;initialize duty cycles to 0 (write 0 to TCD0_CCA, TCD0_CCB, TCD0_CCC)
ldi r16, 0x00
sts TCD0_CCA, r16
sts TCD0_CCA + 1, r16
sts TCD0_CCB, r16
sts TCD0_CCB + 1, r16
sts TCD0_CCC, r16
sts TCD0_CCC + 1, r16

;Start the timer with PRE = div 8
ldi r16, TC_CLKSEL_DIV8_gc
sts TCD0_CTRLA, r16

;pop registers
pop r16

ret
```

APPENDIX

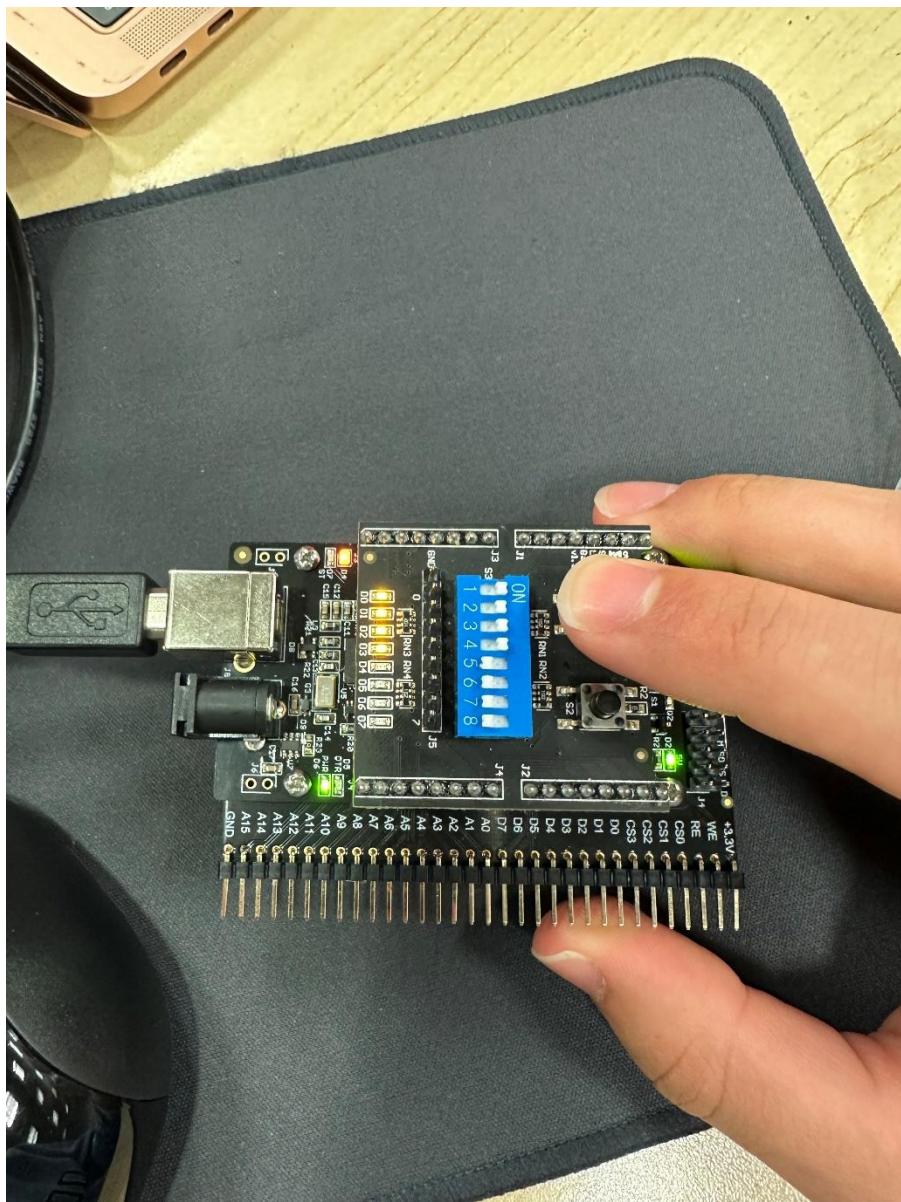


Figure 1: The red LED at about 50% duty cycle with the other LEDs at a very low duty cycle

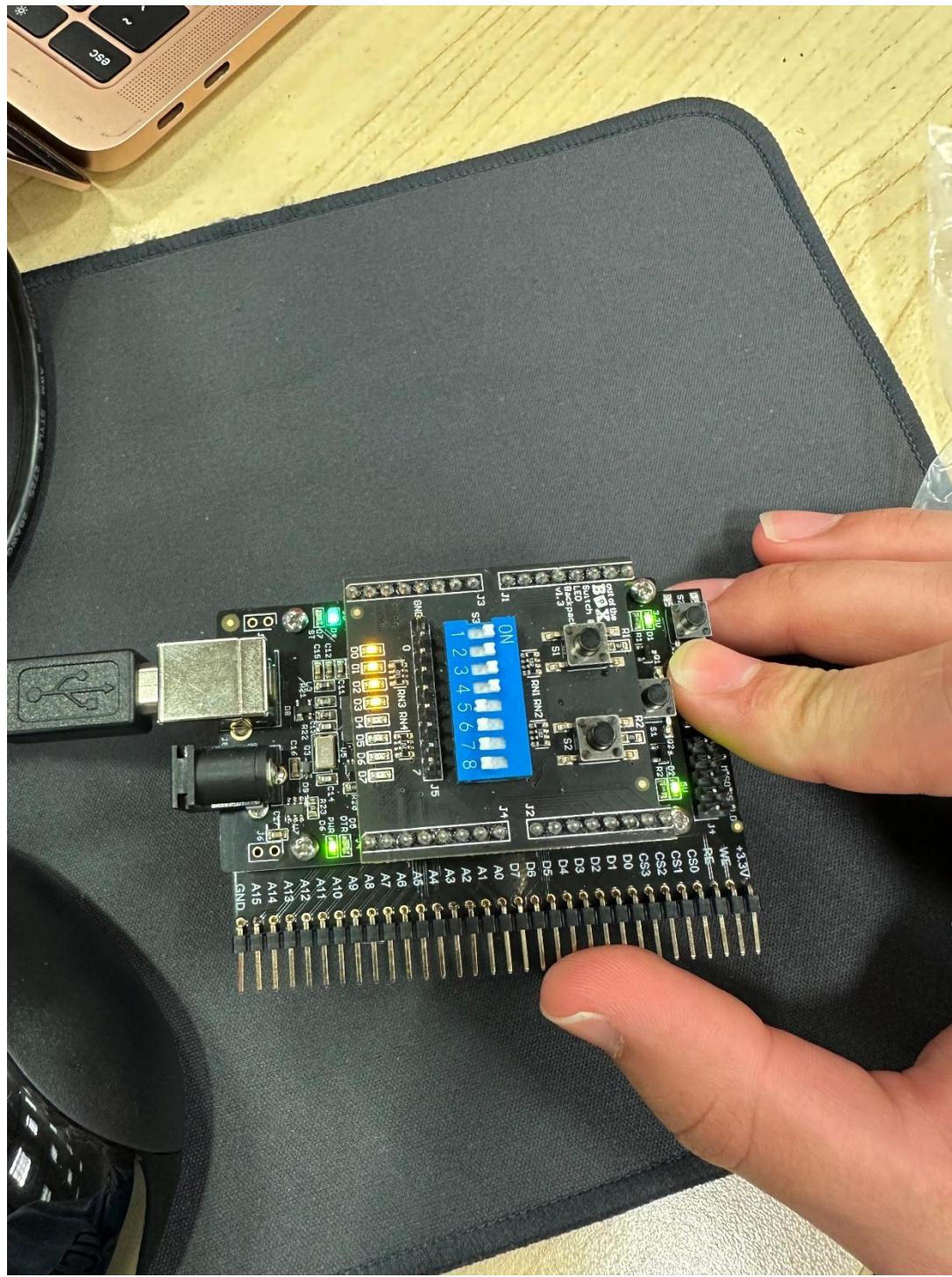


Figure 2: The green LED at about 50% duty cycle with the other LEDs at a very low duty cycle



Figure 1: The blue LED at about 50% duty cycle with the other LEDs at a very low duty cycle