HorizonNet 코드 분석

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https://github.com/sunset1995/HorizonNet 참고.

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Estimating Layout with HorizonNet Layout 3D Viewer

python preprocess.py --img_glob ssu_dataset/train/img/pic424_1.png --output_dir ssu_dataset/preprocessed --rgbonly

preprocess.py

이미지 조정(정렬)



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python train.py --train_root_dir ssu_dataset/train --valid_root_dir ssu_dataset/valid --batch_size_train 1 --num_workers 0 --id model_bs1

train.py

데이터 세트에 대해 학습 Batch_size, epochs, num_workers 기정



 $python\ preprocess. py\ --img_glob\ ssu_dataset/train/img/pic424_1.png\ --output_dir\ ssu_dataset/preprocessed\ --rgbonly$

```
# Process each input
    for i_path in paths:
        print('Processing', i_path, flush=True)
        # Load and cat input images
        img_ori = np.array(Image.open(i_path).resize((1024, 512), Image.BICUBIC))[..., :3]
        # VP detection and line segment extraction
                                                                                                             파노라마 사진에서
        _, vp, _, _, panoEdge, _, _ = panoEdgeDetection(img_ori,
                                                                                                           edge와 소실점을 찾음
60
                                                     qError=args.q error,
                                                     refineIter=args.refine iter)
        panoEdge = (panoEdge > 0)
        # Align images with VP
64
                                                                                                            소실점 가진 이미지를 align
        i_img = rotatePanorama(img_ori / 255.0, vp[2::-1])
                                                                                                              (구부려진 사진이 펴짐)
        l img = rotatePanorama(panoEdge.astype(np.float32), vp[2::-1])
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python train.py --train_root_dir ssu_dataset/train --valid_root_dir ssu_dataset/valid --batch_size_train 1 --num_workers 0 --id model_bs1

```
# Create dataloader
dataset train = PanoCorBonDataset(
   root_dir=args.train_root_dir,
    flip=not args.no_flip, rotate=not args.no_rotate, gamma=not args.no_gamma,
    stretch=not args.no_pano_stretch)
loader_train = DataLoader(dataset_train args.batch_size_train,
                          shuffle=True, drop_last=True,
                         num_workers=args.num_workers,
                                                                                                             # Start training
                         pin_memory=not args.no_cuda,
                                                                                                             for ith_epoch in trange(1, args.epochs + 1, desc='Epoch', unit='ep'):
                          worker_init_fn=lambda x: np.random.seed())
                                                                                                                 # Train phase
                                                                                                                 net.train()
                                                                                                                 if args.freeze earlier blocks != -1:
                                                                                                                     b0, b1, b2, b3, b4 = net.feature_extractor.list_blocks()
                                                                                                                     blocks = [b0, b1, b2, b3, b4]
                                                                                                                     for i in range(args.freeze_earlier_blocks + 1):
                                                                                                                         for m in blocks[i]:
                                                                                                                             m.eval()
                                                                                                                 iterator_train = iter(loader_train)
                                                                                                                 for _ in trange(len(loader_train),
                       Epoch만큼 for문 돌립.
                                                                                                                                 desc='Train ep%s' % ith_epoch, position=1):
                                                                                                                     # Set learning rate
                                                                                                                     adjust_learning_rate(optimizer, args)
                                                                                                                     args.cur_iter += 1
                                                                                                                     x, y_bon, y_cor = next(iterator_train)
                                                                                                                     losses = feed_forward(net, x, y_bon, y_cor)
                                                                                                                     for k, v in losses.items():
                                                                                                                         k = 'train/%s' % k
                                                                                                                         tb writer.add scalar(k, v.item(), args.cur iter)
                                                                                                                     tb_writer.add_scalar('train/lr', args.running_lr, args.cur_iter)
                                                                                                                     loss = losses['total']
                                                                                                                     # backprop
                                                                                                                     optimizer.zero_grad()
                                                                                                                     loss.backward()
                                                                                                                     nn.utils.clip_grad_norm_(net.parameters(), 3.0, norm_type='inf')
                                                                                                                     optimizer.step()
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결과

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preprocess.py

이미지 조정(정렬)



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train.py

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https://velog.io/@arittung/%EC%A1%B8%EC%97%85%EC%9E%91%ED%92%88-3D-Room-Reconstruction-Using-HorizonNet-%EC%A7%81%EC%A0%91-%EB%8D%B0%EC%9D%B4%ED%84%B0-%ED%9B%88%EB%A0%A8-%ED%9B%84-%EC%8B%A4%ED%96%89

감사합니다.

The End