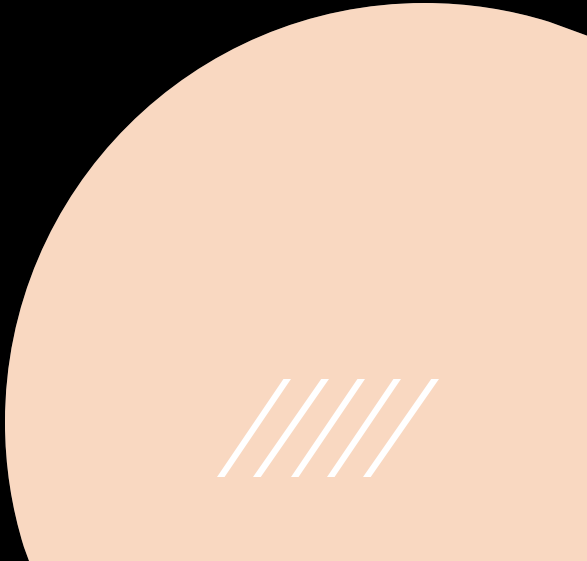
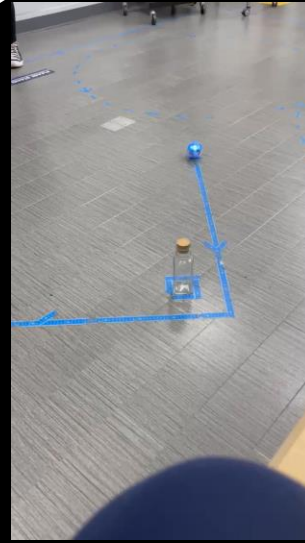


# Robot Triathlon

By: Kelly  
Gonzalez,  
Arizona  
Reynoso, Bajon  
Wilkins



Block Code for  
Sprint 3  
Agility/Video  
of your robot  
doing the  
Agility sprint



```
on start program
roll 0° at 58 speed for 1.6s
stop
delay for 1.5s
roll 90° at 58 speed for 1.8s
stop
delay for 1.5s
roll 0° at 58 speed for 2.1s
stop
delay for 1.5s
roll 90° at 140 speed for 2.2s
stop
delay for 2s
roll 225° at 151 speed for 2.6s
stop
exit program
```

# What would you do differently/Challenges



- Practice more with the code for specific actions
- More examples of the code
- Used our online resources
- Try a few different ways to see what works best


////////////////////////////////////



- Never worked with Sphero before
- Learning how to do a figure 8
- Understanding "aim"
- Speed and time relationship
- 'Drunk' robot
- The robot's battery



## Roles of Each Team Member

- Arizona: worked on block coding, made the github repositories, got the sensory data diagram, worked on the design documents, created the flowchart
  - Kelly: worked on block coding, made the gantt chart, videoed the robot, worked on the design documents, created the algorithm
  - Bajon: worked on block coding, made the requirements table, created the staffing table, worked on the test table, worked on the design documents
- 

# What have you learned about software engineering



- Time consuming
- One wrong move, has a big impact
- It is a language
- Programming can be used in many different ways
- You have to test out many possibilities before finding the one that worked the best
- Planning to stay within the timelines given