

# RBE 501 Week 7 Assignment

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**Abstract**—This is the abstract

**Index Terms**—robotics

## I. INTRODUCTION

We are asked to solve problem x and y.

## II. MATERIALS AND METHODS

We know from the textbook [1] that,

$$\frac{1}{2}\dot{q}^T \left\{ I_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + I_2 \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \right\} \dot{q}$$

is the same as,

$$\frac{1}{2}I_1\dot{\theta}_1^2 + \frac{1}{2}I_1(\dot{\theta}_1 + \dot{\theta}_2)^2$$

## III. RESULTS

These are the results.

## IV. DISCUSSION

Place author's opinions here.

## REFERENCES

- [1] M. W. Spong, S. Hutchinson, and M. Vidyasagar, "Robot modeling and control," 2006.