Closed-Loop Active Compensation for Needle Deflection and Target Shift During Cooperatively Controlled Robotic Needle Insertion

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Abstract—The abstract by Will goes here.

Index Terms—IEEE, IEEEtran, journal, \LaTeX , paper, template.

I. INTRODUCTION

THIS demo file will be edited by Will. It is intended to serve as a "starter file" for IEEE journal papers produced under LATEX using IEEEtran.cls version 1.8b and later. I wish you the best of success.

mds February 7, 2023

A. Subsection Heading Here

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II. METHODS AND MATERIALS

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III. RESULTS

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IV. DISCUSSION

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APPENDIX A
PROOF OF THE FIRST ZONKLAR EQUATION
Appendix one text goes here.

APPENDIX B

Appendix two text goes here.

All authors are software engineers in their professional life.

ACKNOWLEDGMENT

The authors would like to thank...

REFERENCES

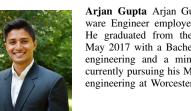
 H. Kopka and P. W. Daly, A Guide to ETEX, 3rd ed. Harlow, England: Addison-Wesley, 1999.

Patrick Donelan Biography text here.

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Debbie Guenthner Biography text here.

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Will Yingling Biography text here.

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