ARJAN GUPTA

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EDUCATION

Worcester Polytechnic Institute

Master of Science in Robotics Engineering, GPA: 4.00/4.00

August 2022 — Present

Autonomous Vehicles Specialization

University of Kansas

Bachelor of Science in Computer Engineering, Mathematics Minor

August 2013 — May 2017

Projects

- 6 DoF Robotic Arm assembled arm, wrote its controller and kinematics in Python, and moved it using servos and a Raspberry Pi. Designing a computer-vision based localization system for it
- Path Planning in Lung designed a path planning algorithm for a capsule robot to navigate through a human lung, then simulated it in MATLAB

WORK EXPERIENCE

Lev Technologies

Remote

Co-Founder & Engineering Expert

June 2023 — present

- Helped launch the usage of custom-trained YOLOv7 object detection model to help daycare workers
- Designing the edge strategy to deploy the system on a Jetson Nano for real-time inference
- Collaborating with other founders to develop the technical road-map

Lindsay Corporation

Olathe, KS (Hybrid)

Embedded Software Engineer II

December 2021 — present

- Enhanced the firmware on the Smart Pivot system to use GPS-path planning over MQTT
- Mentored entry level engineers and interns, guided them with debugging and profiling tools
- Served as a technical lead on Smart Pivot main UI panel, responsible for the entire software stack
- Collaborated in board-bring up, developed wrappers for low-level drivers
- Completed a hardware & firmware replacement of Sub-GHz mesh network on a legacy product

AGI SureTrack

Lenexa, KS (Hybrid)

Embedded Software Engineer I & II

October 2019 — December 2021

- Helped maintain LiDAR product with a 3 DoF robotic arm for grain inventory management
- Coordinated engineering work as a team lead, guided productivity and helped meet milestones
- Owned the product development and commercial launch of a new IoT Gateway product
- Designed and implemented backend web-services for automated firmware updates

ZOLOZ

Kansas City, MO

Software Engineer

June 2017 — October 2019

- Developed and maintained biometric matching systems for a 2 DoF camera (pan-tilt)
- Aided board-bring up and firmware development for Portable Auger product
- Implemented and optimized C++ image scaling and compression algorithms
- Supported the R&D department to fine-tune several computer vision models for object detection

TECHNICAL SKILLS

Programming Languages: C, C++, Python, TypeScript/JavaScript, URDF, Bash, MATLAB Microcontrollers: NXP (MK70, IMXRT1064), PIC18, ATmega2560, ATTiny85

Protocols: UART, SPI, I2C, MQTT, TCP/IP, NTP, HTTPS

Operating Systems: Linux, Windows, FreeRTOS, Android, mbedOS

Robotics/AI Frameworks: ROS, Gazebo, OpenCV, PyTorch, Foxglove Studio, YOLOv7

Course Certificates

Coursera

Neural Networks and Deep Learning

Issued May 2023 | Credential ID R6Q353L77JC6

Machine Learning

Issued Aug 2022 | Credential ID KKFMWZ7WZCF7

Udemy

YOLOv7 YOLOv8: Deep Learning — Computer Vision 2023

In-progress