

(a) For the cylinder the unit normal is

$$(\cos u, \sin u, 0)$$

$$\Rightarrow \text{let } e_1 = (0, 0, 1)$$

by 1.3 $S(e_1) = 0 \cdot e_1 \Rightarrow e_1$ is an eigenvector of S with the eigenvalue $\kappa_1 = 0$

$$\text{let } e_2 = (-\sin u, \cos u, 0)$$

by 1.3 $S(e_2) = -\frac{1}{r} e_2 \Rightarrow e_2$ is an eigenvector of S with the eigenvalue $\kappa_2 = -\frac{1}{r}$

\Rightarrow Principal directions $e_1 = (0, 0, 1)$, $e_2 = (-\sin u, \cos u, 0)$
 Principal curvatures $\kappa_1 = 0$, $\kappa_2 = -\frac{1}{r}$

at every point

(b) For the saddle surface $z = xy$ at $(0, 0, 0)$

and take $u_1 = (1, 0, 0)$, $u_2 = (0, 1, 0)$.

$$\text{let } e_1 = \frac{1}{\sqrt{2}}(u_1 + u_2) \quad \text{as in Example 1.3}$$

$$S(e_1) = \frac{1}{\sqrt{2}} [S(u_1) + S(u_2)] = \frac{1}{\sqrt{2}} [u_2 + u_1] = e_1$$

$\Rightarrow e_1$ is an eigenvector with eigenvalue 1

$$\text{let } e_2 = \frac{1}{\sqrt{2}}(u_1 - u_2)$$

$$\begin{aligned} \text{by Example 1.3} \\ \Rightarrow S(e_2) &= \frac{1}{\sqrt{2}} [S(u_1) - S(u_2)] = \frac{1}{\sqrt{2}} (u_2 - u_1) \\ &= -e_2 \end{aligned}$$

$\Rightarrow e_2$ is an eigenvector with eigenvalue -1

\Rightarrow Principal directions $e_1 = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0)$, $e_2 = (\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0)$
 Principal curvatures $\kappa_1 = 1$, $\kappa_2 = -1$ } at $(0, 0, 0)$

At an umbilical point the shape operator S is $K = \det \begin{bmatrix} k & 0 \\ 0 & k \end{bmatrix} = k^2 \geq 0$. Hence, if $k < 0$ umbilics are impossible.

If $K = 0 \Rightarrow$ Both principal curvatures are 0, so every normal curvature is 0. therefore the surface is flat at that point.

$$a) x_u = (1, 0, t_u)$$

$$x_v = (0, 1, t_v)$$

$$E = x_u \cdot x_u = 1 + t_u^2$$

$$F = x_u \cdot x_v = t_u t_v$$

$$G = x_v \cdot x_v = 1 + t_v^2$$

$$U = (-t_u, -t_v, 1) / \sqrt{1+t_u^2+t_v^2}$$

note:

$$EG - F^2 = 1 + t_u^2 + t_v^2 + t_u^2 t_v^2 - (t_u t_v)^2$$

$$= 1 + t_u^2 + t_v^2$$

$$\Rightarrow U = (-t_u, -t_v, 1) / \sqrt{EG - F^2}$$

$$= (-t_u, -t_v, 1) / w$$

$$L = x_{uu} \cdot U = (0, 0, t_{uu}) \cdot \vec{U} = \frac{t_{uu}}{w}$$

$$M = x_{uv} \cdot U = (0, 0, t_{uv}) \cdot \vec{U} = \frac{t_{uv}}{w}$$

$$N = x_{vv} \cdot U = (0, 0, t_{vv}) \cdot \vec{U} = \frac{t_{vv}}{w}$$

$$K = \frac{LN - M^2}{EG - F^2} = \frac{\frac{t_{uu} t_{vv} - t_{uv}^2}{w^2}}{\frac{1 + t_u^2 + t_v^2}{w^2}} = \frac{t_{uu} t_{vv} - t_{uv}^2}{w^4}$$

$$H = \frac{GL + GN - 2FM}{2(EG - F^2)} = \frac{(1+t_v^2) \frac{t_{uu}}{w} + (1+t_u^2) \frac{t_{vv}}{w} - 2 t_u t_v \frac{t_{uv}}{w}}{2w^2}$$

$$= \frac{(1+t_v^2) t_{uu} + (1+t_u^2) t_{vv} - 2 t_u t_v t_{uv}}{2w^3}$$

$$b) \text{ flat} \Leftrightarrow K=0 \Leftrightarrow \frac{t_{uu} t_{vv} - t_{uv}^2}{w^4} = 0 \Leftrightarrow t_{uu} t_{vv} - t_{uv}^2 = 0$$

$$\text{minimed} \Leftrightarrow H=0 \Leftrightarrow (1+t_v^2) t_{uu} + (1+t_u^2) t_{vv} - 2 t_u t_v t_{uv} = 0$$