## Rademacher\_F1

June 12, 2020

```
[596]: import numpy as np
       import matplotlib.pyplot as plt
       import compute_parameters
       import pandas as pd
       import statsmodels.api as sm
       from scipy.stats import norm
       from scipy.optimize import curve_fit
       import pylab
[597]: def get_actual_predicted(trace, trace_name, jvm, hidden_size, history_size=40,
                                  model_type="fcn", output_file_location="/media/arjun/
        ⇔Shared/chaos/output_files"):
           start_point = 10000
           n_points = 5000
           if jvm == "jikes":
               jvm_name = "JikesRVM"
           elif jvm == "j9":
               jvm_name = "J9"
           else:
               jvm_name = "HotSpot"
           data = []
           predictions = np.load(
                            '{}/{}/predictions_{}_{}_{}.npy'.
        →format(output_file_location,
                                                                           trace_name,_
        →jvm, history_size,
                                                                           1,<sub>U</sub>
       →hidden_size, 1))
           predictions = np.argsort(predictions)
             print(predictions.shape)
             print(trace.shape)
           for idx, point in enumerate(trace):
                 print("{}: {}".format(np.argmax(point),__
        \rightarrow predictions[history_size-1+idx, -1]))
```

```
actual = bin_to_val(int(np.argmax(point)))
predicted = bin_to_val(predictions[history_size-1+idx, -1])
data.append((actual, predicted))
return data
```

```
[598]: def mse_function(y, y1):
           return np.mean((y-y1)**2)
       ## precision and recall
       def relevance_function(x, sigma=1.0, mu=0):
           return np.exp(-((x-mu)**2)/(2*(sigma**2)))/(sigma*np.sqrt(2*np.pi))
       def relevance_function1(x, mu=0):
          return 1
       def alpha(y, y_pred, loss_function=mse_function, threshold=1e-2):
           return loss_function(y, y_pred) < threshold</pre>
       def recall(data, y_ref, loss_function=mse_function, relevance_threshold=0.3):
           num = 0
           din = 0
           for y_actual, y_pred in data:
               phi_y = relevance_function(y_actual, mu=y_ref)
               if phi_y >= relevance_threshold:
                   num += alpha(y_actual, y_pred, loss_function) * phi_y
                   din += phi_y
           if din > 0:
               return num/din
           else:
              return 0
       def existance_check(data, y_ref, loss_function=mse_function,_
        →relevance_threshold=0.3):
           num = 0
           din = 0
           exists = False
           for y_actual, y_pred in data:
               phi_y = relevance_function(y_actual, mu=y_ref)
               if phi_y >= relevance_threshold:
```

```
return False
       def precision(data, y_ref, loss_function=mse_function, relevance_threshold=0.3):
           num = 0
           din = 0
           for y_actual, y_pred in data:
               phi_y1 = relevance_function(y_pred, mu=y_ref)
               if phi_y1 >= relevance_threshold:
                   num += alpha(y_actual, y_pred, loss_function) * phi_y1
                   din += phi_y1
           if din > 0:
               return num/din
           else:
               return 0
       def f1_score(precision, recall, beta=1):
           if precision+recall > 0:
               return ((1+beta**2)*precision*recall)/(precision+recall)
           else:
               return 0
       def bin_to_val(bin_idx):
           g_max = 1
           g_min = 3 * np.exp(-8)
           feature_dimension = 100
           \verb| multiplier = (np.log(g_max) - np.log(g_min))/feature\_dimension # values_{\sqcup}|
        → from preprocess cache file
           return bin_idx*multiplier + np.log(g_min)
[599]: def sup(arr, mode="max"):
           if mode == "max":
               return (np.max(arr))
           elif mode == "999percentile":
               return np.mean(arr) + 5 * np.std(arr)
       def get_rademacher(loss_array):
           rademacher = []
           n_sigma = 2000
```

return True

```
for i in range(n_sigma):
    sigma_arr = np.random.choice([1, -1], size=loss_array.shape)

f = sigma_arr*loss_array
    f = np.sum(f, axis=1)/loss_array.shape[1]
# print(f)
    rademacher.append(sup(f))
return np.mean(rademacher)
```

```
[600]: def get_loss_dict1(trace, output_file_location, hidden_sizes=None,__
        →trace_name="pmd", plot_graphs=False):
           if hidden_sizes is None:
               hidden_sizes = [ 10, 50, 100, 500, 1000, 2000, 3000, 4000, 5000, 6000, U
        →7000. 8000 T
           history_sizes = [ 5, 10, 15, 20, 25, 30, 35, 40, 45, 50 ]
           history_size = 40
           n seeds = 30
           n_sets = 1
           n points = 5000
           chunk_size = int(n_points/n_sets)
           relevance threshold = relevance function(1e-1)
           loss dict = {}
           min val = np.log(3e-8)
           \max val = 0
          n_steps = 50
           print("relevance threshold: {}".format(relevance_threshold))
           for hidden_size in hidden_sizes:
               loss_array = np.zeros((n_seeds, n_sets))
               print("hidden_size: {}".format(hidden_size))
               if hidden_size in loss_dict.keys():
                   continue
               for seed in range(n seeds):
                   data1 = get_actual_predicted(trace, trace_name, "jikes", __
        →hidden_size=hidden_size, history_size=40,
                                 model_type="lstm",_
        →output_file_location=output_file_location)
                   indices = np.arange(0, n_points, chunk_size)
```

```
for index in indices:
   #
                 print(index, index+chunk_size)
   #
                 print(np.linspace(0, n_points, n_sets))
               data = data1[index:index+chunk_size]
               recall_vals = []
               precision_vals = []
               f1 \text{ vals} = []
               for val in np.linspace(min_val, max_val, n_steps):
                    recall_val = recall(data, val, u
→relevance_threshold=relevance_threshold)
                    precision_val = precision(data, val, __
→relevance_threshold=relevance_threshold)
                    recall_vals.append(recall_val)
                    precision_vals.append(precision_val)
                      print("precision: {}, recall: {}".format(precision_val,__
\rightarrow recall_val))
                    f1_vals.append(f1_score(precision_val, recall_val))
               f1_avg_list=[]
               for idx, val in enumerate(np.linspace(min_val, max_val, u
\rightarrown_steps)):
                    if existance_check(data, val, u
→relevance_threshold=relevance_threshold):
                        f1_avg_list.append(f1_vals[idx])
               if plot_graphs and index==0 and seed==1:
                    ax1=plt.subplot(1, 3, 1)
                    ax2=plt.subplot(1, 3, 2)
                    ax3=plt.subplot(1, 3, 3)
                    ax1.figure.set_size_inches(10, 3)
                    ax2.figure.set_size_inches(10, 3)
                    ax3.figure.set_size_inches(10, 3)
                    ax1.set_title("precision")
                    ax2.set_title("recall")
                    ax3.set_title("f1")
                    ax1.plot(np.linspace(min_val, max_val, n_steps),__
→precision_vals, label="precision")
                    ax2.plot(np.linspace(min_val, max_val, n_steps),__
→recall vals, label="recall")
                    ax3.plot(np.linspace(min_val, max_val, n_steps), f1_vals,__
→label="f1")
```

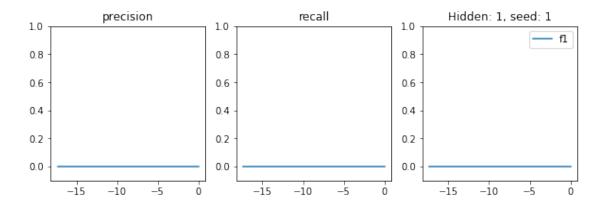
```
ax1.set_ylim((-0.1, 1))
                           ax2.set_ylim((-0.1, 1))
                           ax3.set_ylim((-0.1, 1))
                           plt.title("Hidden: {}, seed: {}".format(hidden_size, seed))
                           plt.legend()
                           plt.show()
                       chunk_idx = int(index/chunk_size)
                       loss_array[seed, chunk_idx] = 1-np.average(f1_avg_list)
               loss_dict[hidden_size] = loss_array
           return loss_dict
[601]: trace_name = "pmd"
       start point = 10000
       n_points = 5000
       jvm = "jikes"
       if jvm == "jikes":
           jvm_name = "JikesRVM"
       elif jvm == "j9":
           jvm_name = "J9"
       else:
           jvm_name = "HotSpot"
       trace = pd.read_pickle(
                       '../data/{}-small-{}-d-164-p4096-w100000i.analyzed-1.pkl'.
        →format(trace_name, jvm_name)
```

```
[602]: loss_main = {} hidden_sizes=[ 1, 10, 100, 1000, 2000, 3000, 4000, 5000, 6000, 7000, 8000 ]
```

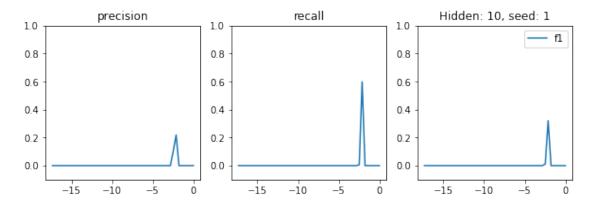
).to\_numpy()[start\_point:start\_point+n\_points]

```
[603]: loss_main["fcn"] = get_loss_dict1(trace, "/media/arjun/Shared/chaos/
output_files",
hidden_sizes=hidden_sizes, plot_graphs=True)
```

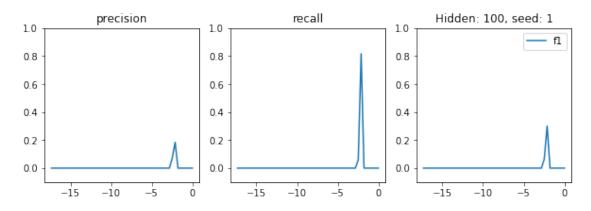
relevance threshold: 0.3969525474770118
hidden\_size: 1

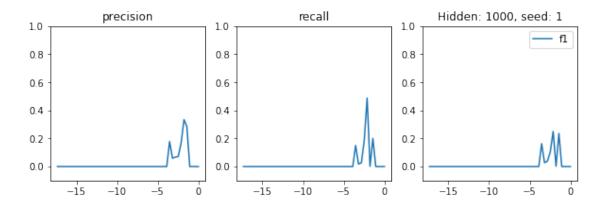


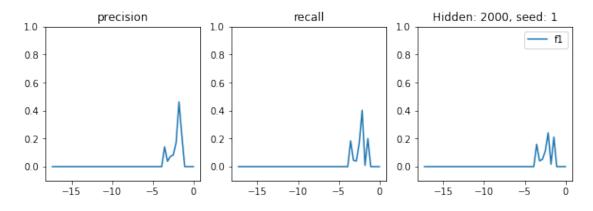
hidden\_size: 10



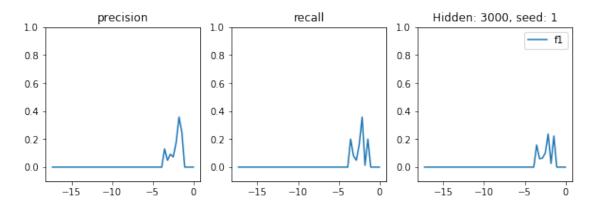
hidden\_size: 100

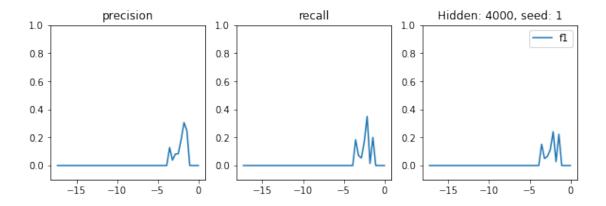


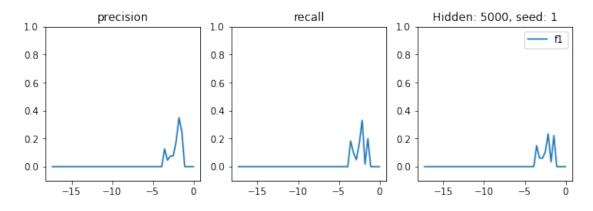




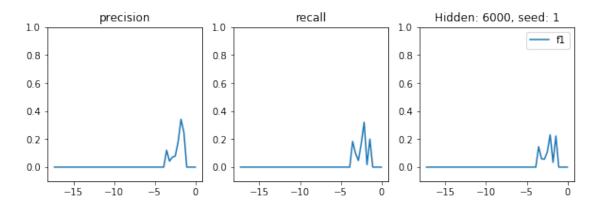
hidden\_size: 3000

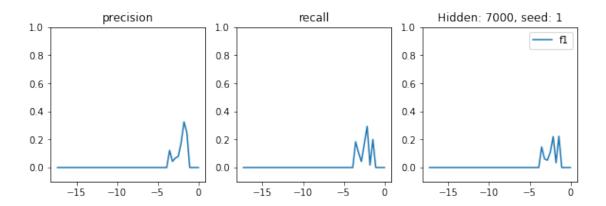


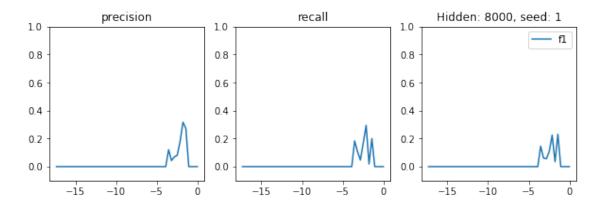




hidden\_size: 6000

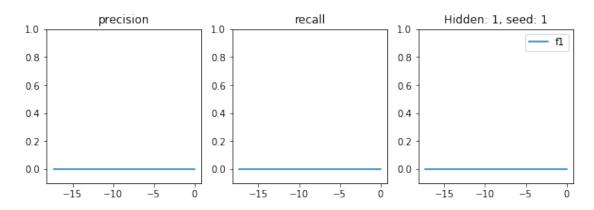




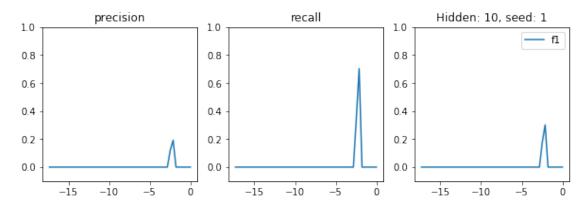


[604]: loss\_main["lstm"] = get\_loss\_dict1 (trace, "/media/arjun/Shared/chaos/
output\_files/lstm",
hidden\_sizes=hidden\_sizes, plot\_graphs=True)

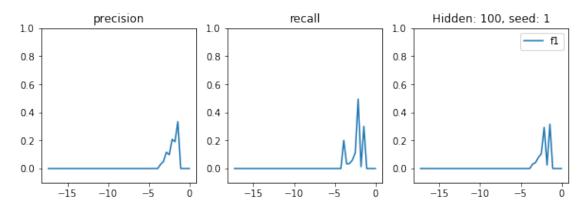
relevance threshold: 0.3969525474770118
hidden\_size: 1



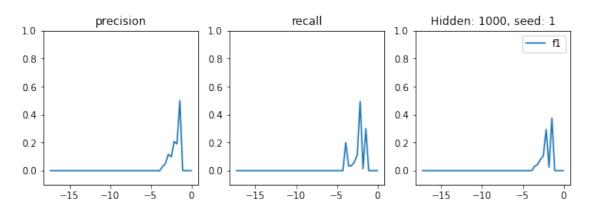
hidden\_size: 10



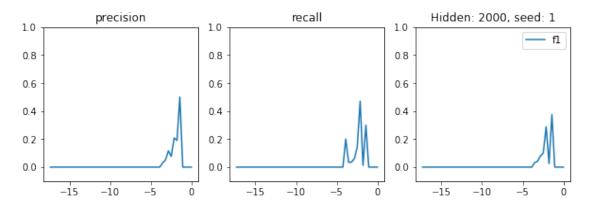
hidden\_size: 100



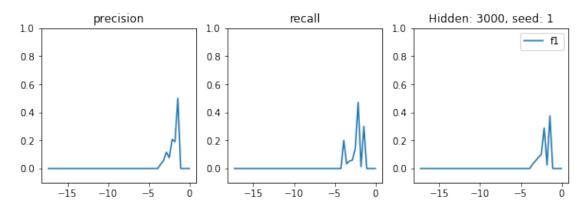
hidden\_size: 1000



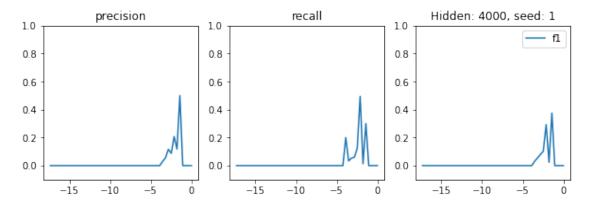
hidden\_size: 2000



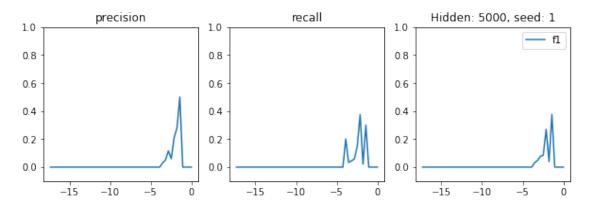
hidden\_size: 3000

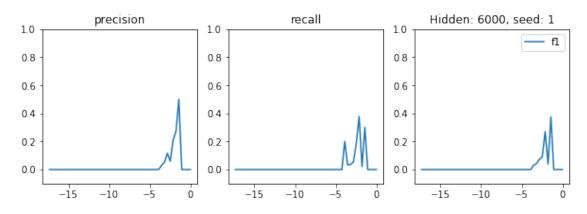


hidden\_size: 4000

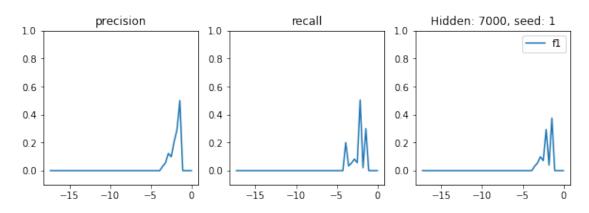


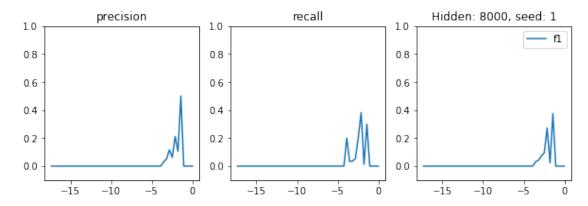
hidden\_size: 5000



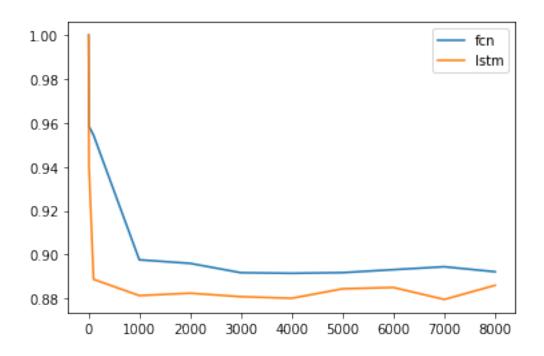


hidden\_size: 7000





```
[605]: rademacher_list_fcn = []
       rademacher_list_lstm = []
       for hidden_size in hidden_sizes:
           loss_array = loss_main["fcn"][hidden_size]
           rademacher_list_fcn.append(get_rademacher(loss_array))
           loss_array = loss_main["lstm"][hidden_size]
           rademacher list lstm.append(get rademacher(loss array))
[606]: # compute number of parameters
       fcn_param_list = []
       lstm param list = []
       for hidden_size in hidden_sizes:
           fcn_param_list.append(compute_parameters.get_count(4000, 100, [ hidden_size_
        →], [ 'fcn' ]))
           lstm_param_list.append(compute_parameters.get_count(100, 100, [1000, __
        →hidden_size], ["lstm", "fcn"]))
[607]: plt.plot(hidden_sizes, rademacher_list_fcn, label="fcn")
       plt.plot(hidden_sizes, rademacher_list_lstm, label="lstm")
       plt.legend()
       # plt.ylim((0.36, 0.42))
       # plt.xlim((-0.1e7, 1e7))
       plt.show()
```



[608]: [<matplotlib.lines.Line2D at 0x7f9b5ebd62e8>]

