Logistic Regression

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Naïve Bayes Recap

• Classifier:

$$f^*(x) = \arg \max_{y} P(y|x)$$

• NB Assumption:

$$P(X_1 ... X_d | Y) = \prod_{i=1}^d P(X_i | Y)$$

NB Classifier:

$$f_{NB}(x) = \arg \max_{y} \prod_{i=1}^{d} P(x_i|y)P(y)$$

- Assume parametric form for $P(X_i|Y)$ and P(Y)
 - Estimate parameters using MLE/MAP and plug in

Generative vs. Discriminative Classifiers

Generative classifiers (e.g. Naïve Bayes)

- Assume some functional form for P(X,Y) (or P(X|Y) and P(Y))
- Estimate parameters of P(X|Y), P(Y) directly from training data
- Use Bayes rule to calculate P(Y|X)

Why not learn P(Y|X) directly? Or better yet, why not learn the decision boundary directly?

Discriminative classifiers (e.g. Logistic Regression)

- Assume some functional form for P(Y|X) or for the decision boundary
- Estimate parameters of P(Y|X) directly from training data

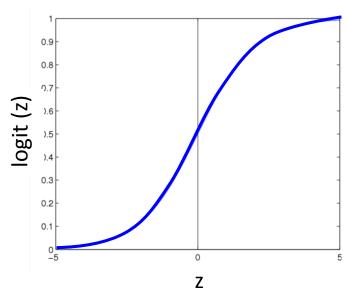
Logistic Regression

Assumes the following functional form for P(Y|X):

$$P(Y = 1 | X) = \frac{1}{1 + \exp(-(w_0 + \sum_i w_i X_i))} = \frac{\exp(w_0 + \sum_i w_i X_i)}{\exp(w_0 + \sum_i w_i X_i) + 1}$$

Logistic function applied to a linear function of the data

Logistic function $\frac{1}{1+\exp(-z)}$



Features can be discrete or continuous!

Logistic Regression is a Linear Classifier!

Assumes the following functional form for P(Y|X):

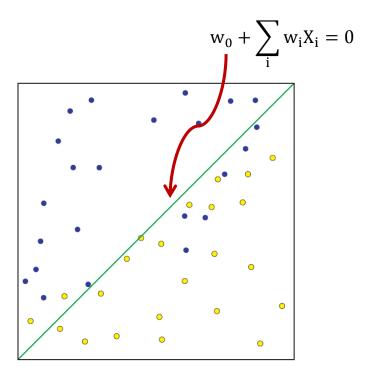
$$P(Y = 1|X) = \frac{1}{1 + \exp(-(w_0 + \sum_i w_i X_i))} = \frac{\exp(w_0 + \sum_i w_i X_i)}{\exp(w_0 + \sum_i w_i X_i) + 1}$$

Decision boundary:

$$P(Y = 1|X) > P(Y = 0|X)$$
?

$$w_0 + \sum_i w_i X_i > 0?$$

(Linear Decision Boundary)



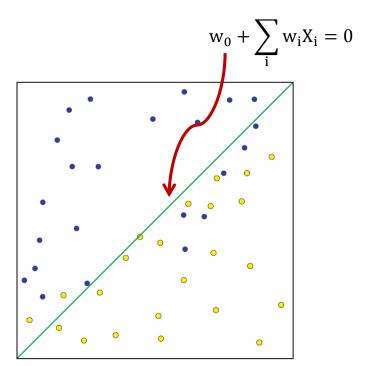
Logistic Regression is a Linear Classifier!

Assumes the following functional form for P(Y|X):

$$P(Y = 1 | X) = \frac{1}{1 + \exp(-(w_0 + \sum_i w_i X_i))} = \frac{\exp(w_0 + \sum_i w_i X_i)}{\exp(w_0 + \sum_i w_i X_i) + 1}$$

Assumes a linear decision boundary: there are weights w_i s.t. when $w_0 + \sum_i w_i X_i > 0$, the example is more likely to be positive, and when this linear function is negative ($w_0 + \sum_i w_i X_i < 0$) the example is more likely to be negative.

$$\begin{split} w_0 + \sum_i w_i X_i &= 0, P(Y = 1 | X) = \frac{1}{2} \\ w_0 + \sum_i w_i X_i &\to \infty, P(Y = 1 | X) \to 1 \\ w_0 + \sum_i w_i X_i &\to -\infty, P(Y = 1 | X) \to 0 \end{split}$$



Logistic Regression is a Linear Classifier!

Assumes the following functional form for P(Y|X):

$$P(Y = 1|X) = \frac{1}{1 + \exp(-(w_0 + \sum_i w_i X_i))} = \frac{\exp(w_0 + \sum_i w_i X_i)}{\exp(w_0 + \sum_i w_i X_i) + 1}$$

$$\Rightarrow P(Y = 0|X) = \frac{1}{\exp(w_0 + \sum_i w_i X_i) + 1}$$

$$\Rightarrow \frac{P(Y = 1|X)}{P(Y = 0|X)} = \exp(w_0 + \sum_i w_i X_i) > 1?$$

$$\Rightarrow w_0 + \sum_i w_i X_i > 0?$$

Training Logistic Regression

We'll focus on binary classification:

$$P(Y = 0|X, w) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$P(Y = 1|X, w) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

How to learn the parameters $w_0, w_1, ..., w_d$?

Training data:
$$\left\{\left(X^{(j)},Y^{(j)}\right)\right\}_{j=1}^{n} \qquad X^{(j)} = \left(X_{1}^{(j)},\ldots,X_{d}^{(j)}\right)$$

$$X^{(j)} = (X_1^{(j)}, ..., X_d^{(j)})$$

Maximum Likelihood Estimates:

$$\widehat{\mathbf{w}}_{\text{MLE}} = \arg \max_{\mathbf{w}} \prod_{j=1}^{n} P(X^{(j)}, Y^{(j)} | \mathbf{w})$$

But there's a problem...

Don't have a model for P(X) or P(X|Y) - only for P(Y|X)

Training Logistic Regression

How to learn the parameters w_0 , w_1 , ... w_d ?

Training data:
$$\left\{\left(X^{(j)},Y^{(j)}\right)\right\}_{j=1}^{n} \qquad X^{(j)}=\left(X_{1}^{(j)},\ldots,X_{d}^{(j)}\right)$$

Maximum (Conditional) Likelihood Estimates

$$\widehat{\mathbf{w}}_{\text{MCLE}} = \arg \max_{\mathbf{w}} \prod_{j=1}^{n} P(Y^{(j)}|X^{(j)},\mathbf{w})$$

Discriminative philosophy – Don't waste effort learning P(X), focus on P(Y|X) – that's all that matters for classification!

Expressing Conditional log Likelihood

$$P(Y = 0 | X, w) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)} \qquad P(Y = 1 | X, w) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$l(\mathbf{w}) \equiv \ln \prod_{j} P(y^{j} | \mathbf{x}^{j}, \mathbf{w})$$

$$= \sum_{j} \left[y^{j} \left(w_{0} + \sum_{i=1}^{d} w_{i} x_{i}^{j} \right) - \ln \left(1 + \exp \left(w_{0} + \sum_{i=1}^{d} w_{i} x_{i}^{j} \right) \right) \right]$$

Maximizing Conditional log Likelihood

$$\begin{aligned} \max_{\mathbf{w}} l(\mathbf{w}) &\equiv \ln \prod_{j} P(y^{j} | \mathbf{x}^{j}, \mathbf{w}) \\ &= \sum_{j} \left[y^{j} \left(w_{0} + \sum_{i=1}^{d} w_{i} x_{i}^{j} \right) - \ln \left(1 + \exp \left(w_{0} + \sum_{i=1}^{d} w_{i} x_{i}^{j} \right) \right) \right] \end{aligned}$$

Good news: $l(\mathbf{w})$ is concave in w. Local optimum = global optimum

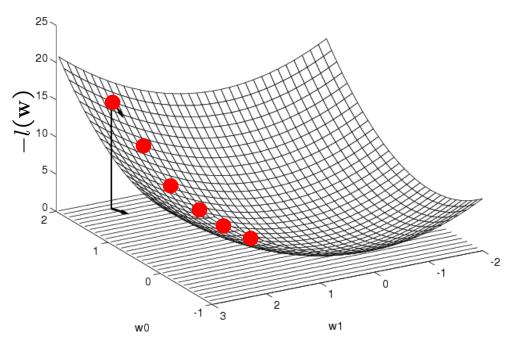
Bad news: no closed-form solution to maximize $l(\mathbf{w})$

Good news: concave functions easy to optimize (unique maximum)

Optimizing concave/convex function

- Conditional likelihood for Logistic Regression is concave
- Maximum of a concave function = minimum of a convex function

Gradient Ascent (concave)/ Gradient Descent (convex)



Gradient:

$$\nabla_{\mathbf{w}} \mathbf{l}(\mathbf{w}) = \left[\frac{\partial \mathbf{l}(\mathbf{w})}{\partial \mathbf{w}_0}, \dots, \frac{\partial \mathbf{l}(\mathbf{w})}{\partial \mathbf{w}_d} \right]$$

Update rule: Learning rate,
$$\eta>0$$

$$\Delta \mathbf{w} = \eta \nabla_{\mathbf{w}} l(\mathbf{w})$$

$$w_i^{(t+1)} = w_i^{(t)} + \eta \frac{\partial l(\mathbf{w})}{\partial w_i} \Big|_t$$

Gradient Ascent for Logistic Regression

Gradient ascent algorithm: iterate until change $< \epsilon$

$$w_0^{(t+1)} = w_0^{(t)} + \eta \sum_j [y^j - \widehat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w}^{(t)})]$$

For i = 1, ..., d:

$$w_i^{(t+1)} = w_i^{(t)} + \eta \sum_j x_i^j [y^j - \widehat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w}^{(t)})]$$

repeat

Predict what current weight thinks label Y should be

look at actual labels of the examples, compare them to our current predictions, and then for each example j we multiply that difference by the feature value x_i^j and then add them up.

Gradient Ascent for Logistic Regression

Gradient ascent algorithm: iterate until change $< \epsilon$

$$w_0^{(t+1)} = w_0^{(t)} + \eta \sum_{j} [y^j - \widehat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w}^{(t)})]$$

For i = 1, ..., d:

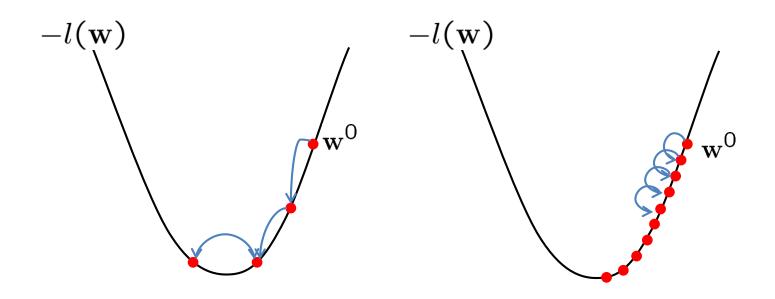
$$\mathbf{w}_{i}^{(t+1)} = \mathbf{w}_{i}^{(t)} + \eta \sum_{j} \mathbf{x}_{i}^{j} \left[\mathbf{y}^{j} - \widehat{\mathbf{P}} \left(\mathbf{Y}^{j} = 1 | \mathbf{x}^{j}, \mathbf{w}^{(t)} \right) \right]$$

repeat

Predict what current weight thinks label Y should be

- Gradient ascent is simplest of optimization approaches
 - e.g., Newton method, Conjugate gradient ascent, IRLS (see Bishop 4.3.3)

Effect of step-size η



Large $\eta \Rightarrow$ Fast convergence but larger residual error Also possible oscillations

Small $\eta \Rightarrow$ Slow convergence but small residual error

That's all M(C)LE. How about MAP?

$$p(\mathbf{w} \mid Y, \mathbf{X}) \propto P(Y \mid \mathbf{X}, \mathbf{w})p(\mathbf{w})$$

- One common approach is to define priors on w
 - Normal distribution, zero mean, identity covariance
 - "Pushes" parameters towards zero
- Corresponds to Regularization
 - Helps avoid very large weights and overfitting
 - More on this later in the semester
- M(C)AP estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[p(\mathbf{w}) \prod_{j=1}^{n} P(y^j \mid \mathbf{x}^j, \mathbf{w}) \right]$$

What you should know

- LR is a linear classifier: decision rule is a hyperplane
- LR optimized by conditional likelihood
 - no closed-form solution
 - concave ⇒ global optimum with gradient ascent
 - Maximum conditional a posteriori corresponds to regularization