

Chapter 4: Threads

CS303

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Motivation

- Threads run within an application
- An “Application” if running typically involves following tasks on the same set of data:
 - Being rendered on the display, style, face, etc.
 - Data access/modification locally
 - Data access/modification across network
 - Additional tasks on the same data

These “Multiple tasks” with the application can be implemented by separate threads

- Update display
- Fetch data
- Spell checking
- Answer a network request

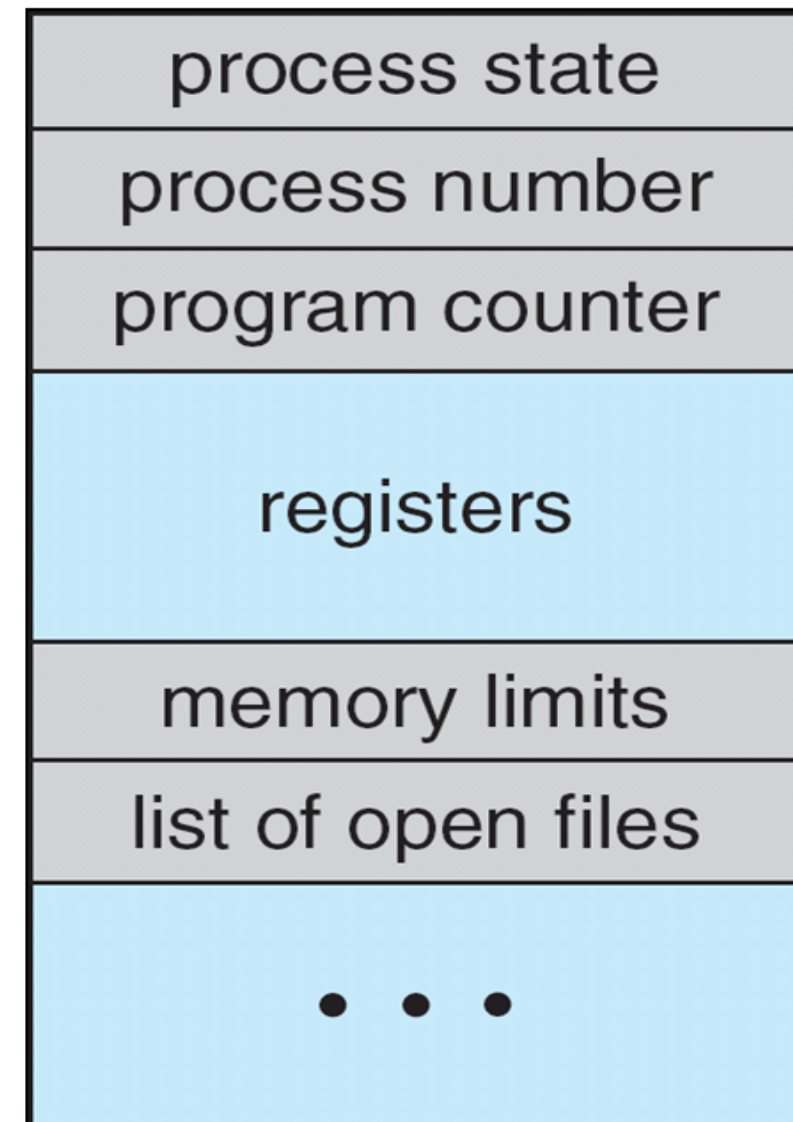
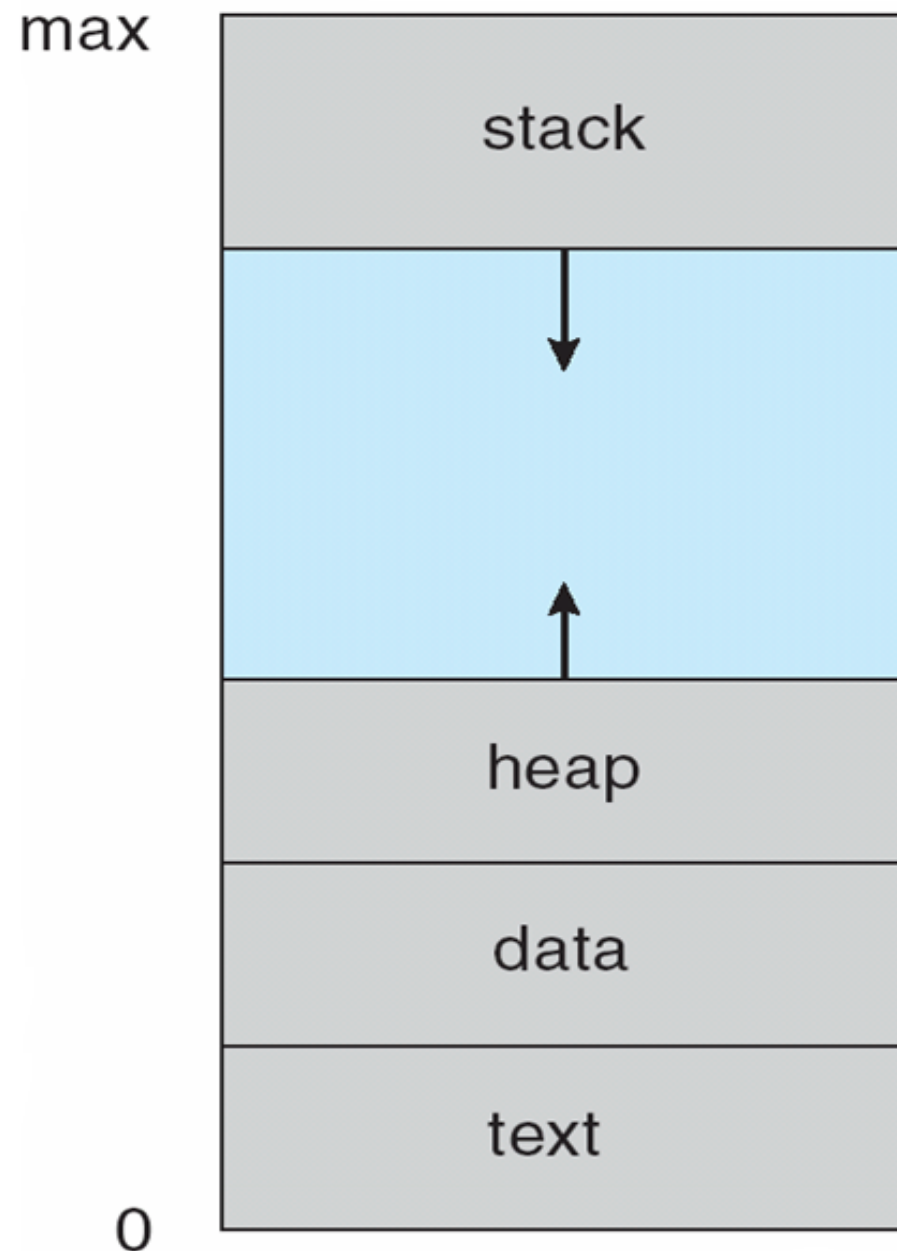
- ▶ We could achieve similar multitasking with the paradigm of interacting processes
 - All sharing the same data set

- But: Process creation is heavy-weight while thread creation is light-weight
- Can simplify code, increase efficiency
- Kernels are generally multithreaded

Motivation (2)

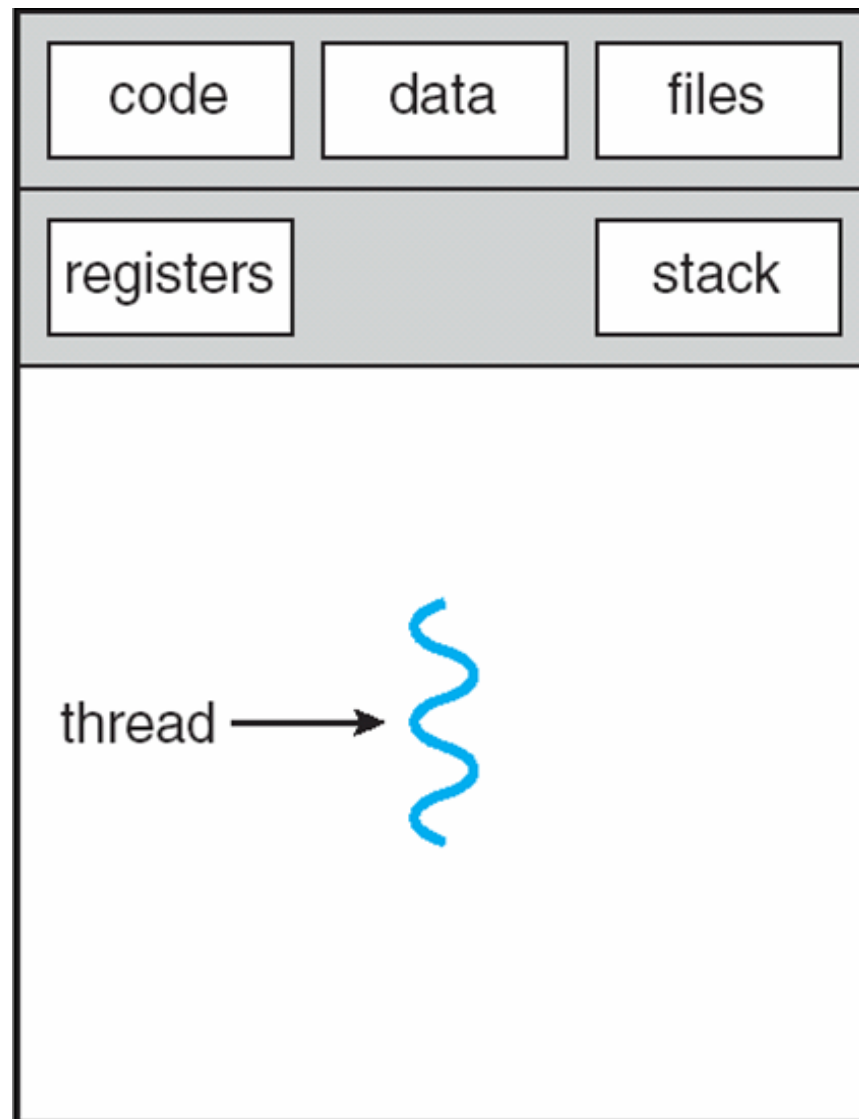
- We could gain in terms of performance, if exploit:
 - Data parallelism: to carryout same operation on different sets of data
 - Task parallelism: sto carryout different operations on the same set of data

Recall Process Memory Map and PCB

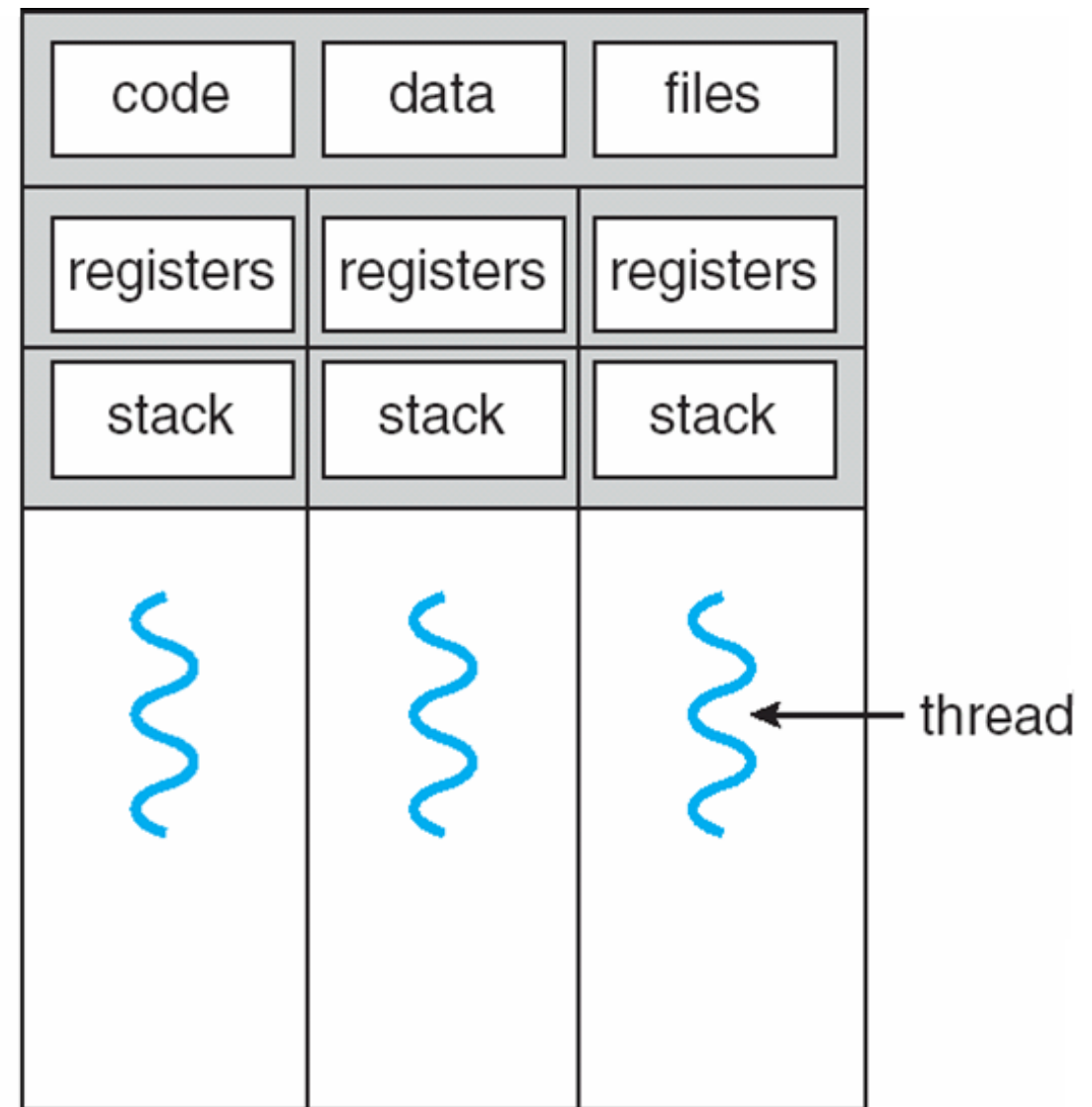


CPU Registers: GPR, Segment registers, SPR, Flag registers

Single and Multithreaded Processes

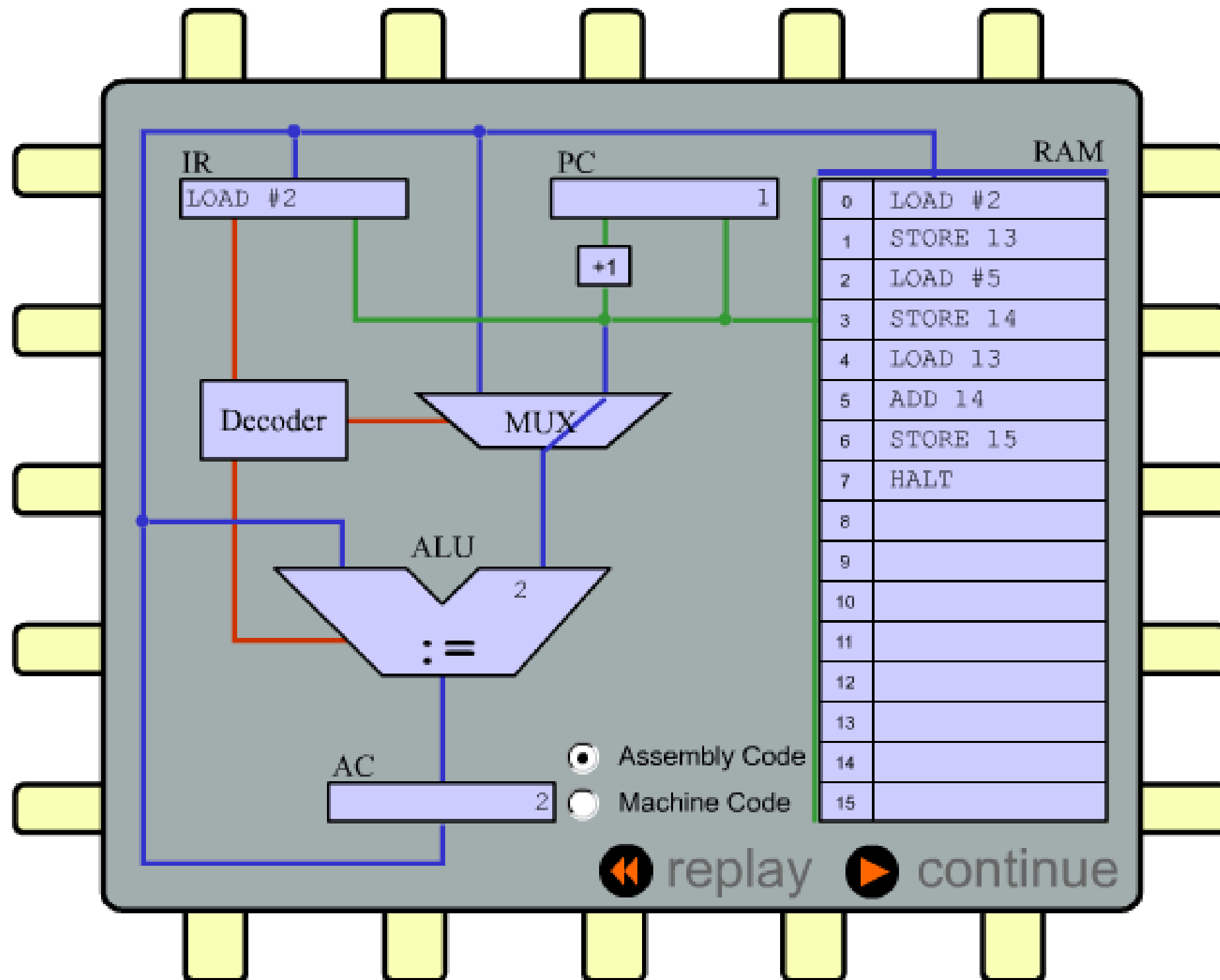


single-threaded process



multithreaded process

Recall Process Execution inside the CPU



Thread Control Block

TCB: a data structure in the operating system kernel which contains thread-specific information needed to manage it

■ **TCB contents:**

- **Status: specific to the Thread State Transition Diagram**
 - **Running on CPU**
 - **Ready**
 - **Suspended**
 - **Blocked**
 - **...**
- **Attributes: ...**
- **Context: stores the context as contained in the thread registers**
- **Thread parameters: start functions, parameters stack size, ..**
- **Stack address: pointer to the stack for this thread**
- **...**

Thread Libraries

- **Thread library** provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS

Pthreads

- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Solaris, Linux, Mac OS X)

Pthreads Example

```
#include <pthread.h>
#include <stdio.h>

int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* the thread */

int main(int argc, char *argv[])
{
    pthread_t tid; /* the thread identifier */
    pthread_attr_t attr; /* set of thread attributes */

    if (argc != 2) {
        fprintf(stderr, "usage: a.out <integer value>\n");
        return -1;
    }
    if (atoi(argv[1]) < 0) {
        fprintf(stderr, "%d must be >= 0\n", atoi(argv[1]));
        return -1;
    }
}
```

Pthreads Example (Cont.)

```
/* get the default attributes */
pthread_attr_init(&attr);
/* create the thread */
pthread_create(&tid,&attr,runner,argv[1]);
/* wait for the thread to exit */
pthread_join(tid,NULL);

printf("sum = %d\n",sum);
}

/* The thread will begin control in this function */
void *runner(void *param)
{
    int i, upper = atoi(param);
    sum = 0;

    for (i = 1; i <= upper; i++)
        sum += i;

    pthread_exit(0);
}
```

Figure 4.9 Multithreaded C program using the Pthreads API.

Java Threads

- Java threads are managed by the JVM
- Typically implemented using the threads model provided by underlying OS
- Java threads may be created by:
 - Extending Thread class
 - Implementing the Runnable interface

Java Multithreaded Program

```
class Sum
{
    private int sum;

    public int getSum() {
        return sum;
    }

    public void setSum(int sum) {
        this.sum = sum;
    }
}

class Summation implements Runnable
{
    private int upper;
    private Sum sumValue;

    public Summation(int upper, Sum sumValue) {
        this.upper = upper;
        this.sumValue = sumValue;
    }

    public void run() {
        int sum = 0;
        for (int i = 0; i <= upper; i++)
            sum += i;
        sumValue.setSum(sum);
    }
}
```

Java Multithreaded Program (Cont.)

```
public class Driver
{
    public static void main(String[] args) {
        if (args.length > 0) {
            if (Integer.parseInt(args[0]) < 0)
                System.err.println(args[0] + " must be >= 0.");
            else {
                // create the object to be shared
                Sum sumObject = new Sum();
                int upper = Integer.parseInt(args[0]);
                Thread thrd = new Thread(new Summation(upper, sumObject));
                thrd.start();
                try {
                    thrd.join();
                    System.out.println
                        ("The sum of " + upper + " is " + sumObject.getSum());
                } catch (InterruptedException ie) { }
            }
        }
        else
            System.err.println("Usage: Summation <integer value>");
    }
}
```

Figure 4.11 Java program for the summation of a non-negative integer.

Threading Issues

- Semantics of **fork()** and **exec()** system calls
- Thread cancellation of target thread
 - Asynchronous or deferred
- Signal handling
 - Synchronous and asynchronous

Threading Issues (Cont.)

- Thread pools
- Thread-specific data
 - Create Facility needed for data private to thread
- Scheduler activations

Semantics of `fork()` and `exec()`

- Does **`fork()`** duplicate only the calling thread or all threads?

Thread Cancellation

- Terminating a thread before it has finished
- Two general approaches:
 - **Asynchronous cancellation** terminates the target thread immediately.
 - **Deferred cancellation** allows the target thread to periodically check if it should be cancelled.
 - At cancellation points!

Signal Handling

- Signals are used in UNIX systems to notify a process that a particular event has occurred.
- A **signal handler** is used to process signals
 1. Signal is generated by particular event
 2. Signal is delivered to a process
 3. Signal is handled
- Options:
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals for the process

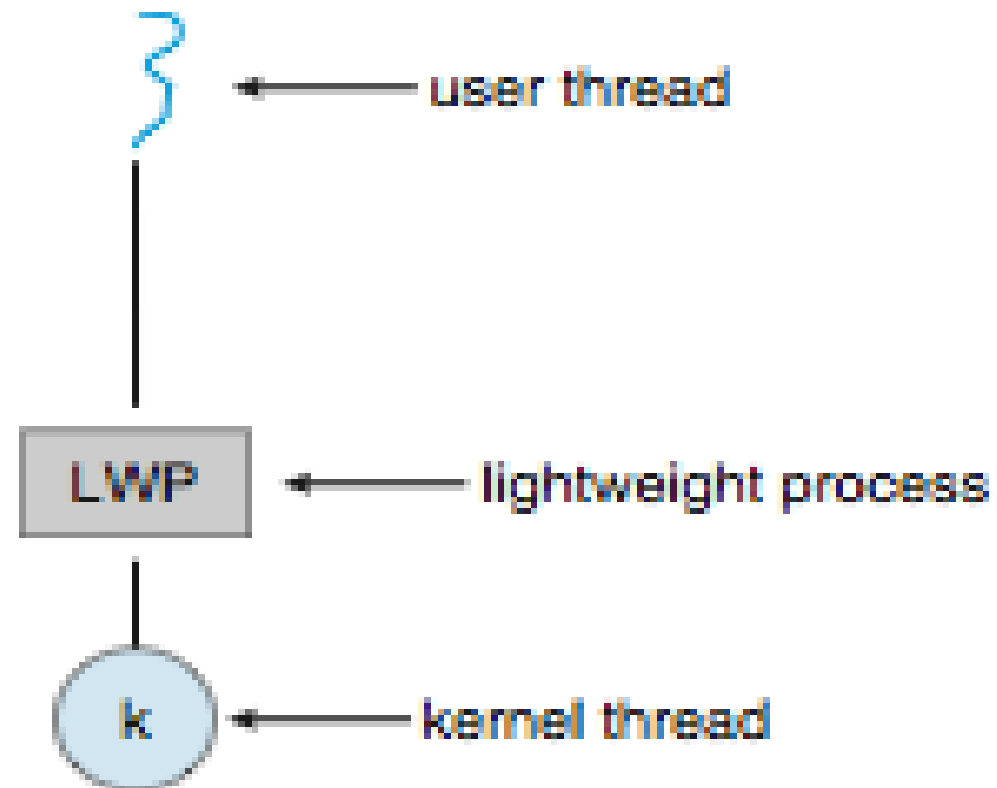
Thread Pools

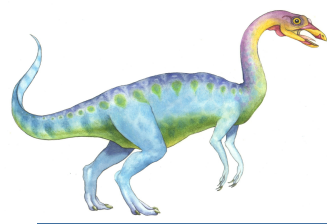
- Create a number of threads in a pool where they await work
- Typically, there are two paradigms: fixed pool-size vs. dynamic pool-size
 - Stable load
 - Dynamic load
- This number of threads is dependent on the:
 - Hardware
 - Number of CPUs/cores in the system
 - The amount of Physical memory
 - Anticipated load
- Advantages:
 - Usually slightly faster to service a request with an existing thread than create a new thread
 - Allows the number of threads in the application(s) to be bound to the size of the pool

Scheduler Activations

- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- User-threading library schedules user-threads onto available LWPs
- Kernel schedules k-threads on the available hardware threads/cores
- If both schedulers coordinate/communicate optimal resource utilisation is possible
 - Scheduler activation is a coordination technique between UTL and Kernel
- Scheduler activations provide **upcalls** - a communication mechanism from the kernel to the thread library
- This communication allows an application to maintain the correct number kernel threads
 - How?

Lightweight Processes





Operating System Examples

- Linux Thread



Linux Threads

- Linux refers to them as *tasks* rather than *threads*
- Thread creation is done through `clone()` system call
- `clone()` allows a child task to share the address space of the parent task (process)
- `struct task_struct` points to process data structures (shared or unique)

Linux Threads

- `fork()` and `clone()` system calls
- Doesn't distinguish between process and thread
 - Uses term *task* rather than thread
- `clone()` takes options to determine sharing on process create
- `struct task_struct` points to process data structures (shared or unique)

flag	meaning
<code>CLONE_FS</code>	File-system information is shared.
<code>CLONE_VM</code>	The same memory space is shared.
<code>CLONE_SIGHAND</code>	Signal handlers are shared.
<code>CLONE_FILES</code>	The set of open files is shared.