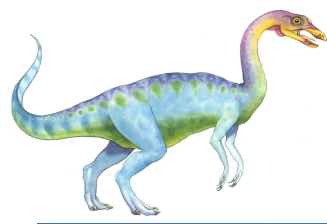


Chapter 3: Processes



Schedulers (Cont.)

- Short-term scheduler is invoked very frequently (milliseconds) \Rightarrow (must be fast)
- Long-term scheduler is invoked very infrequently (seconds, minutes) \Rightarrow (may be slow)
- The long-term scheduler controls the *degree of multiprogramming*
- Processes can be described as either:
 - **I/O-bound process** – spends more time doing I/O than computations, many short CPU bursts
 - **CPU-bound process** – spends more time doing computations; few very long CPU bursts

Degree of multiprogramming:
nr. of processes in the memory



Process Creation

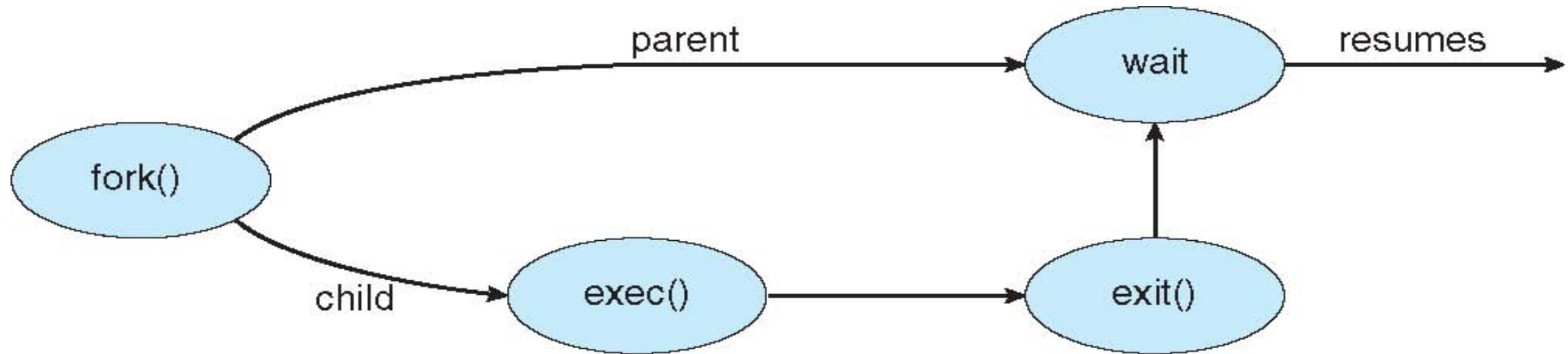
- **Parent** process create **children** processes, which, in turn create other processes, forming a tree of processes
 - Run
 - `:~$ps tree -p` // with names and PIDs
 - `:~$ps tree -np` // arranged in ascending PID
 - To see the list of processes on your linux machine
- Generally, process identified and managed via **a process identifier (pid)**
- Resource sharing
 - Parent and children share all resources
 - Children share subset of parent's resources
 - Parent and child share no resources
- Execution
 - Parent and children execute concurrently
 - Parent waits until children terminate

Process Creation (Cont.)

- Address space
 - Child duplicate of parent
 - Child has a program loaded into it

- UNIX examples
 - **fork** system call creates new process
 - **exec** system call used after a **fork** to replace the process' memory space with a new program

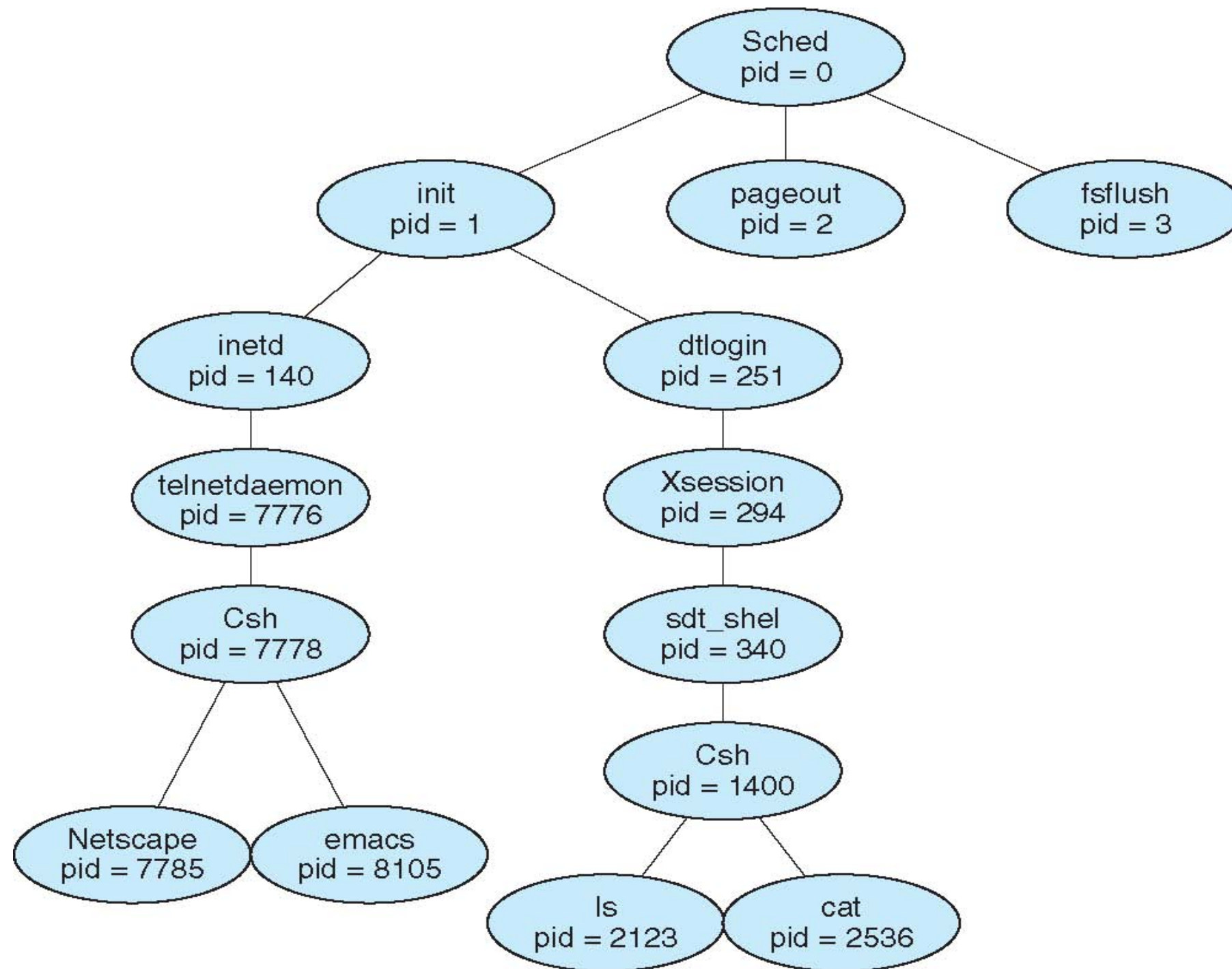
Process Creation



C Program Forking Separate Process

```
#include <sys/types.h>
#include <stdio.h>
#include <unistd.h>
int main()
{
    pid_t pid;
    /* fork another process */
    pid = fork();
    if (pid < 0) { /* error occurred */
        fprintf(stderr, "Fork Failed");
        return 1;
    }
    else if (pid == 0) { /* child process */
        execlp("/bin/ls", "ls", NULL);
    }
    else { /* parent process */
        /* parent will wait for the child */
        wait (NULL);
        printf ("Child Complete");
    }
    return 0;
}
```

A Tree of Processes on Solaris



Process Termination

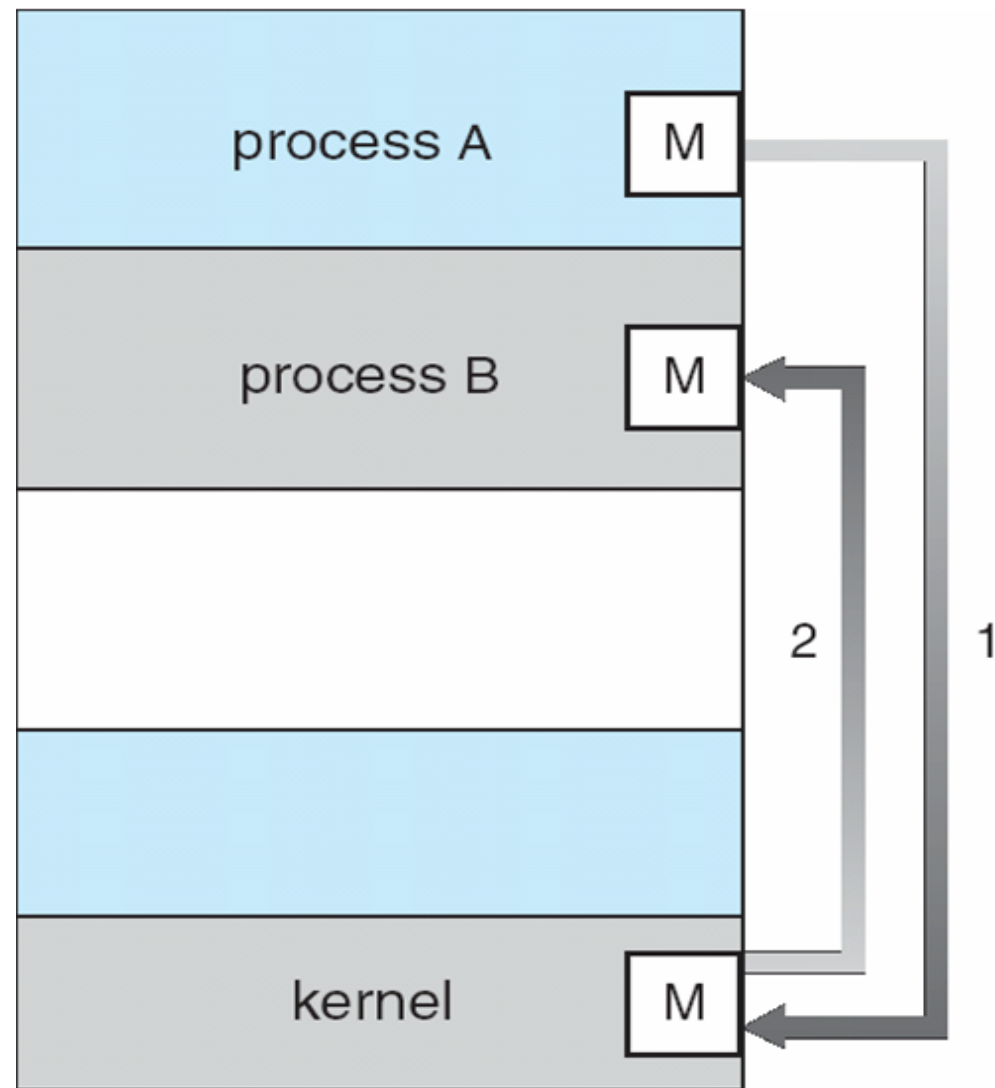
- Process executes last statement and asks the operating system to delete it (**exit**)
 - Output data from child to parent (via **wait**)
 - Process' resources are deallocated by operating system

- Parent may terminate execution of children processes (**abort**)
 - Child has exceeded allocated resources
 - Task assigned to child is no longer required
 - If parent is exiting
 - ▶ Some operating system do not allow child to continue if its parent terminates
 - All children terminated - **cascading termination**

Interprocess Communication

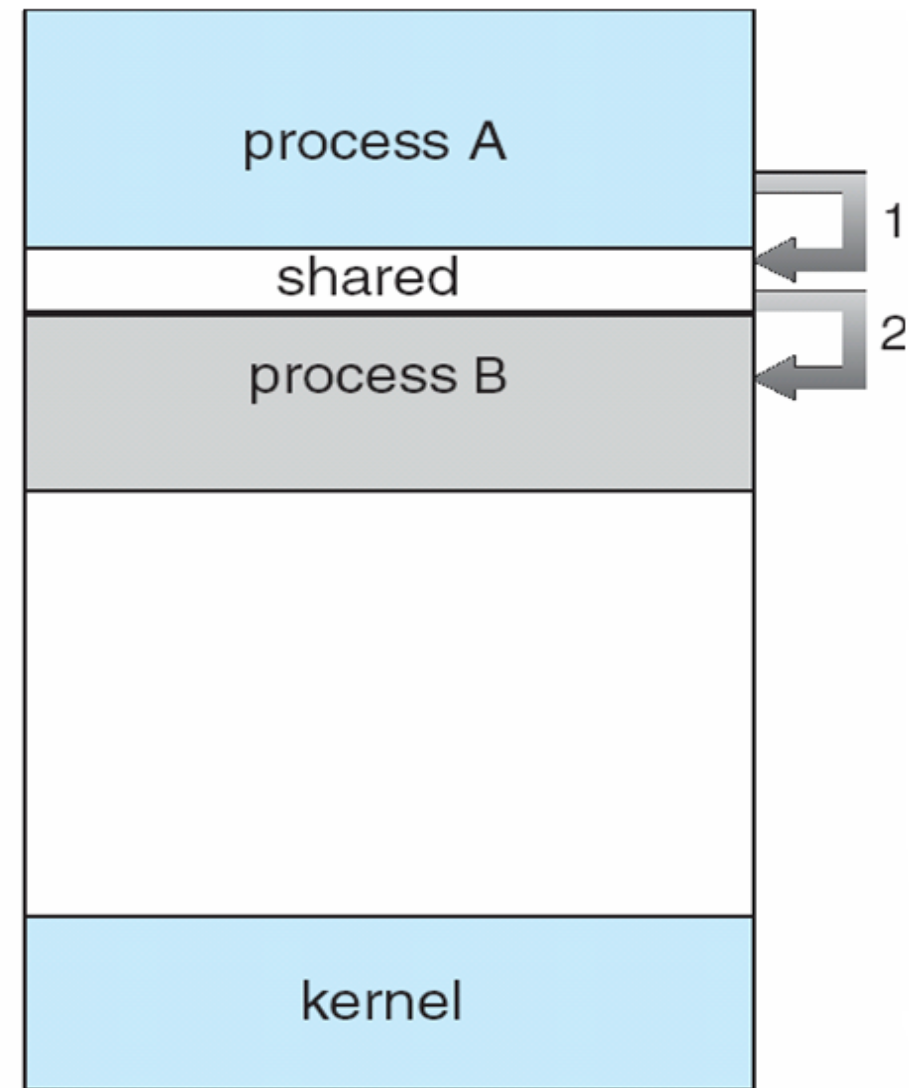
- Processes within a system may be **independent** or **cooperating**
- Cooperating process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes:
 - Information sharing
 - Computation speedup
 - Modularity
- Cooperating processes need **interprocess communication (IPC)**
- Two models of IPC
 - Shared memory
 - Message passing

Communications Models



(a)

Message Passing



(b)

Shared Memory

Vs.

Cooperating Processes

- **Independent** process cannot affect or be affected by the execution of another process
- **Cooperating** process can affect or be affected by the execution of another process
- Advantages of process cooperation
 - Information sharing
 - Computation speed-up
 - Modularity
 - Convenience

Producer-Consumer Problem

- Paradigm for cooperating processes, *producer* process produces information that is consumed by a *consumer* process
 - *unbounded-buffer* places no practical limit on the size of the buffer
 - *bounded-buffer* assumes that there is a fixed buffer size

Bounded-Buffer – Shared-Memory Solution

- Shared data

```
#define BUFFER_SIZE 10  
typedef struct {  
    . . .  
} item;  
  
item buffer[BUFFER_SIZE];  
int in = 0;  
int out = 0;
```

- Solution is correct, but can only use BUFFER_SIZE-1 elements

Bounded-Buffer – Producer

```
item nextProduced;
while (true) {
    /* Produce an item */
    while (((in + 1) % BUFFER SIZE) == out);
                                     /* if buffer is full do nothing
*/
    buffer[in] = item;
    in = (in + 1) % BUFFER SIZE;
}
```

Bounded Buffer – Consumer

```
item nextConsumed;
```

```
while (true) {
```

```
    while (in == out);
```

```
        // if buffer empty do nothing --  
        //nothing to consume
```

```
    // else remove an item from the buffer
```

```
    item = buffer[out];
```

```
    out = (out + 1) % BUFFER SIZE;
```

```
    return item;
```

```
}
```

Interprocess Communication – Message Passing

- Mechanism for processes to communicate and to synchronize their actions
- Message system – processes communicate with each other without resorting to shared variables
- IPC facility provides two operations:
 - **send**(*message*) – message size fixed or variable
 - **receive**(*message*)
- If processes *P* and *Q* wish to communicate, they need to:
 - establish a *communication link* between them
 - exchange messages via send/receive
- Implementation of communication link
 - physical (e.g., shared memory, hardware bus)
 - logical (e.g., logical properties)

Direct Communication

- Processes must name each other explicitly:
 - **send** ($P, message$) – send a message to process P
 - **receive**($Q, message$) – receive a message from process Q

- Properties of communication link
 - Links are established automatically
 - A link is associated with exactly one pair of communicating processes
 - Between each pair there exists exactly one link
 - The link may be either unidirectional or bi-directional

Indirect Communication

- Messages are sent to and received from mailboxes (also referred to as ports)
 - Each mailbox has a unique id
 - Processes can communicate only if they share a mailbox

- Properties of communication link
 - Link established only if processes share a common mailbox
 - A link may be associated with many processes
 - Each pair of processes may share several communication links
 - Link may be unidirectional or bi-directional

Indirect Communication

- Operations
 - create a new mailbox
 - send and receive messages through mailbox
 - destroy a mailbox

- Primitives are defined as:
 - send**(*A, message*) – send a message to mailbox A
 - receive**(*A, message*) – receive a message from mailbox A

Synchronization

- Message passing may be either blocking or non-blocking
- **Blocking** is considered **synchronous**
 - **Blocking send** has the sender block until the message is received
 - **Blocking receive** has the receiver block until a message is available
- **Non-blocking** is considered **asynchronous**
 - **Non-blocking send** has the sender send the message and continue
 - **Non-blocking receive** has the receiver receive a valid message or null

Buffering

- Queue of messages attached to the link; implemented in one of three ways
 1. Zero capacity – 0 messages
Sender must wait for receiver (rendezvous)
 2. Bounded capacity – finite length of n messages
Sender must wait if link full
 3. Unbounded capacity – infinite length
Sender never waits

Examples of IPC Systems - POSIX

- POSIX Shared Memory STEPS: create, attach, use and detach
 - Process first creates shared memory segment
`segment id = shmget(IPC PRIVATE, size, S_IRUSR | S_IWUSR);`
 - Process wanting access to that shared memory must attach to it
`shared memory = (char *) shmat(id, NULL, 0);`
 - Now the process could write to the shared memory
`sprintf(shared memory, "Writing to shared memory");`
 - When done a process can detach the shared memory from its address space
`shmdt(shared memory);`

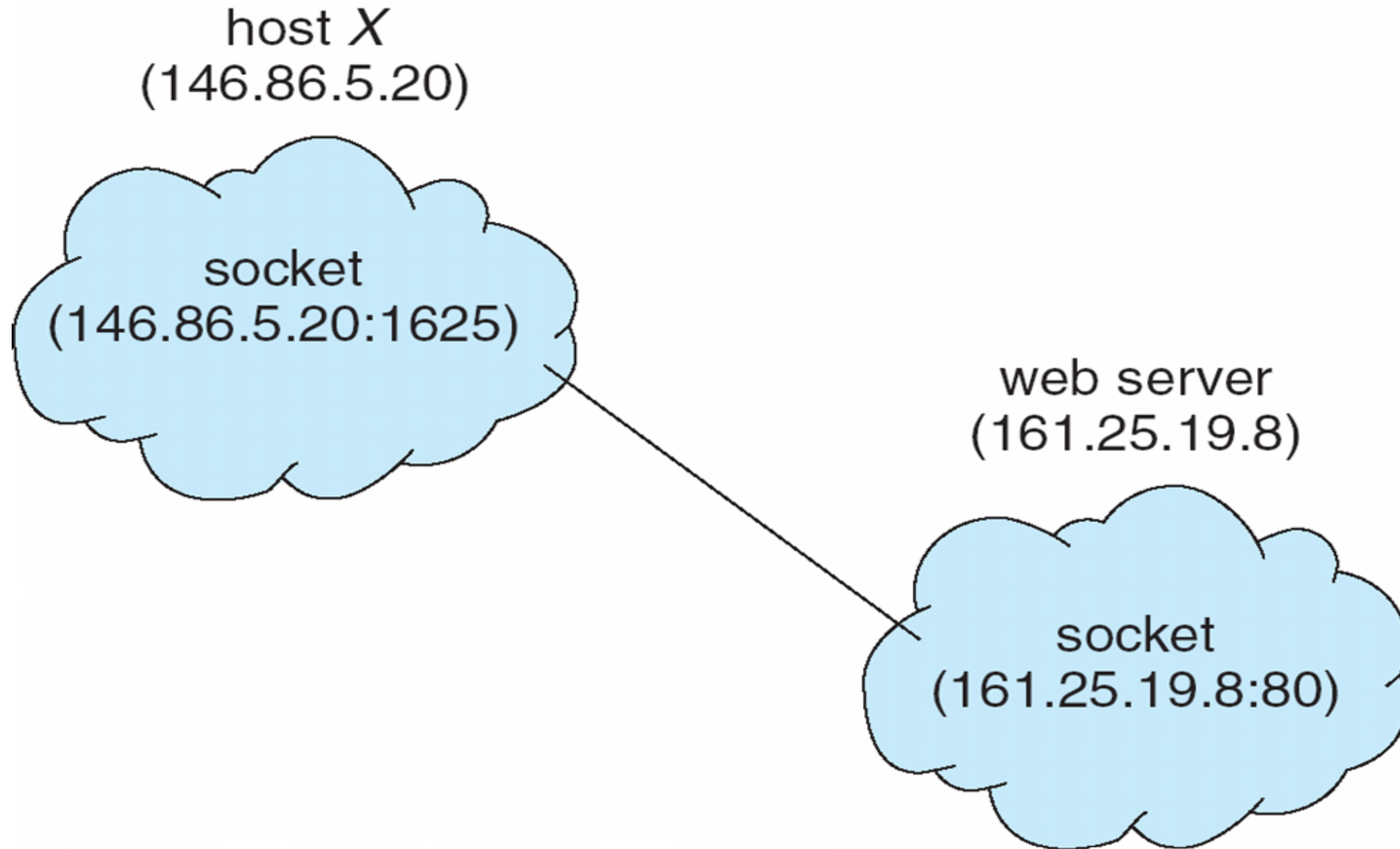
Communications in Client-Server Systems

- Sockets
- Remote Procedure Calls
- Pipes
- Remote Method Invocation (Java)

Sockets

- A **socket** is defined as an *endpoint for communication*
- Concatenation of IP address and port
- The socket **161.25.19.8:1625** refers to port **1625** on host **161.25.19.8**
- Communication consists between a pair of sockets

Socket Communication



Remote Procedure Calls

- Remote procedure call (RPC) abstracts procedure calls between processes on networked systems
- **Stubs** – client-side proxy for the actual procedure on the server
- The client-side stub locates the server and *marshalls* the parameters
- The server-side stub receives this message, unpacks the marshalled parameters, and performs the procedure on the server

Pipes

- Acts as a conduit allowing two processes to communicate

Ordinary Pipes

- **Ordinary Pipes** allow communication in standard producer-consumer style
- Producer writes to one end (the *write-end* of the pipe)
- Consumer reads from the other end (the *read-end* of the pipe)
- Ordinary pipes are therefore unidirectional
- Require parent-child relationship between communicating processes

End of Chapter 3