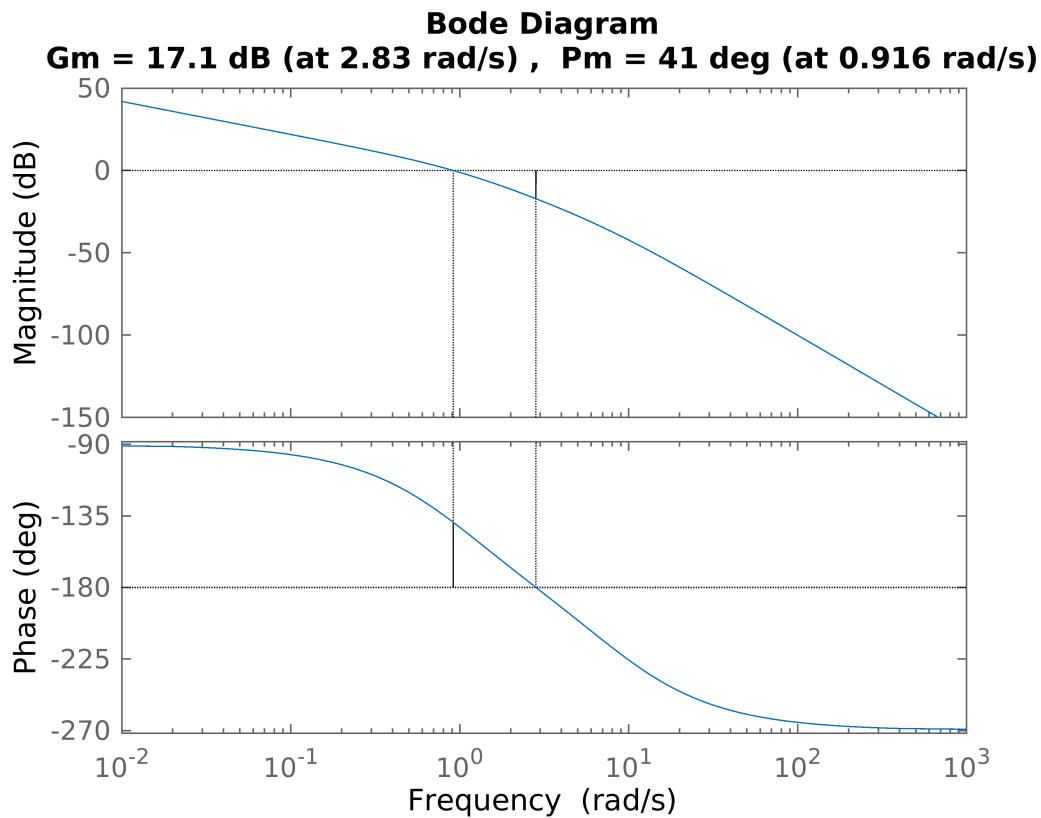


Question 1

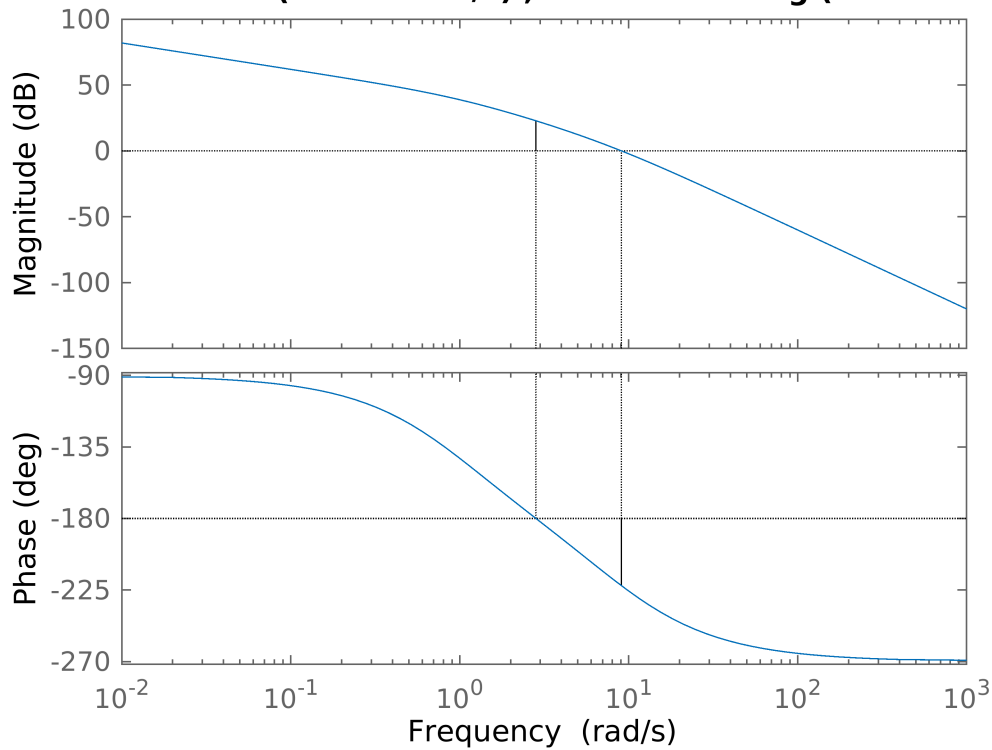
```
clear;
close all;
s = tf('s');
gain_list = [10 1000];
G = 1/(s*(s+1)*(s+8));
hold off;
for k = gain_list
    margin(k*G)
    [~,~,phase_crossover,gain_crossover] = margin(k*G)
end
```



```
phase_crossover = 2.8284
gain_crossover = 0.9158
```

Bode Diagram

Gm = -22.9 dB (at 2.83 rad/s) , Pm = -42.3 deg (at 9.06 rad/s)



Warning: The closed-loop system is unstable.

phase_crossover = 2.8284

gain_crossover = 9.0643

Question 2

```
clear;
sympref('FloatingPointOutput',true);
syms K s w real;
G(s) = K/(s*(s^2+s+4))
```

G(s) =

$$\frac{K}{s(s^2 + s + 4)}$$

H = 1

H = 1

GH=G(w*1i)*H

GH =

$$-\frac{1 K i}{w(-w^2 + 1 w i + 4)}$$

```
[num,den]=numden(GH);
```

```
den = expand(den);
```

```
a = real(num)
```

$$a = -K$$

$$b = \text{imag}(\text{num})$$

$$b = 0$$

$$c = \text{real}(\text{den})$$

$$c = w^2$$

$$d = \text{imag}(\text{den})$$

$$d = w^3 - 4w$$

$$\text{amp} = \text{simplify}(\sqrt{a^2+b^2}/\sqrt{c^2+d^2})$$

$$\text{amp} =$$

$$\frac{|K|}{|w| (w^4 - 7w^2 + 16)^{0.5000}}$$

$$\text{phase} = \text{simplify}(\text{atan}(b/a) - \text{atan}(d/c))$$

$$\text{phase} =$$

$$-\text{atan}\left(\frac{w^2 - 4}{w}\right)$$

$$\text{phase_eq} = \text{phase} == \text{deg2rad}(-180 + 50) + \pi \text{ \% the + pi here is so the eq solves between}$$

$$\text{phase_eq} =$$

$$-\text{atan}\left(\frac{w^2 - 4}{w}\right) = 0.8727$$

$$S = \text{eval}(\text{solve}(\text{phase_eq}));$$

$$\text{wn} = S(2)$$

$$\text{wn} = 1.4910$$

$$\text{gain_eq} = \text{subs}(\text{amp}, w, \text{wn}) == 1$$

$$\text{gain_eq} = 0.2891 |K| = 1$$

$$S = \text{eval}(\text{solve}(\text{gain_eq}));$$

$$\text{Kn} = S(2)$$

$$\text{Kn} = 3.4585$$

```
phase_crossover_eq = phase == deg2rad(-180) + pi
```

```
phase_crossover_eq =
```

$$-\operatorname{atan}\left(\frac{w^2-4}{w}\right) = 0$$

```
S = eval(solve(phase_crossover_eq));
phase_crossover = S(2)
```

```
phase_crossover = 2
```

```
amp
```

```
amp =
```

$$\frac{|K|}{|w| (w^4 - 7w^2 + 16)^{0.5000}}$$

```
gain_margin = eval(subs(amp,[K, w], [Kn, phase_crossover]))
```

```
gain_margin = 0.8646
```

```
gain_margin_decibels = 20*log(gain_margin)
```

```
gain_margin_decibels = -2.9091
```

Question 3

```
clear;
sympref('FloatingPointOutput',true);
syms K s w real;
G1(s)= K*(s+.1)/(s+.5)
```

```
G1(s) =
```

$$\frac{K (s + 0.1000)}{s + 0.5000}$$

```
G2(s)=10/(s*(s+1))
```

```
G2(s) =
```

$$\frac{10}{s (s + 1)}$$

```
H = 1
```

```
H = 1
```

```
GH = G1(w*1i)* G2(w*1i)*H
```

```
GH =
```

$$-\frac{10 K (0.1000 + 1 w i) i}{w (1 + 1 w i) (0.5000 + 1 w i)}$$

```
[num,den]=numden(GH);
```

```
den = expand(den);
a = real(num)
```

$$a = 20 K w$$

$$b = \text{imag}(\text{num})$$

$$b = -2 K$$

$$c = \text{real}(\text{den})$$

$$c = w - 2 w^3$$

$$d = \text{imag}(\text{den})$$

$$d = 3 w^2$$

$$\text{amp} = \text{simplify}(\sqrt{a^2+b^2}/\sqrt{c^2+d^2})$$

$$\text{amp} = \frac{2 |K| \sqrt{100 w^2 + 1}}{|w| (4 w^4 + 5 w^2 + 1)^{0.5000}}$$

$$\text{phase} = \text{simplify}(\text{atan}(b/a) - \text{atan}(d/c))$$

$$\text{phase} = \text{atan}\left(\frac{3 w}{2 w^2 - 1}\right) - \text{atan}\left(\frac{0.1000}{w}\right)$$

$$\text{phase_eq} = \text{phase} == \text{deg2rad}(-180 + 50) + \text{pi} \quad \% \text{ the } + \text{pi here is so the eq solves between}$$

$$\text{phase_eq} = \text{atan}\left(\frac{3 w}{2 w^2 - 1}\right) - \text{atan}\left(\frac{0.1000}{w}\right) = 0.8727$$

$$S = \text{eval}(\text{solve}(\text{phase_eq}));$$

$$wn = S$$

$$wn = 1.4384$$

$$\text{gain_eq} = \text{subs}(\text{amp}, w, wn) == 1$$

$$\text{gain_eq} = 3.7577 |K| = 1$$

```
S = eval(solve(gain_eq));  
Kn = S(2)
```

$$Kn = 0.2661$$

Phase margin lies above phase = -180 so gain margin is infinity