

```

#include "sphfluidsystem.h"
#include "PhysicsUtilities.h"
#include "kernelutilities.h"

using namespace std;

SPHFluidSystem::SPHFluidSystem()
{
    SPHFluidSystem(5000);
}

SPHFluidSystem::SPHFluidSystem(int numParticles) : ParticleSystem(numParticles)
{
    initConstants();
    //buildTestSystem2();
    testOneInitializeSystem();
    //buildTestSystem2();
    Vector3f origin = Vector3f::ZERO;
    particleGrid = ParticleGrid(origin, 0.5 , 0.9, 0.5);
    vecParticleDensities = vector<float>();
    vecParticlePressures = vector<float>();
}

void SPHFluidSystem::initConstants()
{
    PARTICLE_MASS = 0.02;
    GRAVITY_CONSTANT = 6.5;
    REST_DENSITY = 1000.0;
    GAS_CONSTANT = 1.0;
    VISCOSITY_CONSTANT = 6.0;
    TENSION_CONSTANT = 0.10;
    TENSION_THRESHOLD = 6.0;
    SELF_DENSITY_CONSTANT = PARTICLE_MASS *
KernelUtilities::polySixKernel(Vector3f::ZERO);
    SELF_LAPLACIAN_COLOR_FIELD = PARTICLE_MASS *
KernelUtilities::laplacianPolySixKernel(Vector3f::ZERO);
}

SPHFluidSystem::~SPHFluidSystem()
{
}

vector<Vector3f> SPHFluidSystem::evalF(vector<Vector3f> state)
{
    vector<Vector3f> particlePositionsInState =
PhysicsUtilities::getParticlePositions(state);
    particleGrid.initializeGrid(particlePositionsInState);
    calculateDensitiesAndPressures(state);

    vector<Vector3f> derivative;
    for (int particleIndex = 0; particleIndex < m_numParticles; ++particleIndex)
    {
        Vector3f positionOfParticle = PhysicsUtilities::getPositionOfParticle(state,
particleIndex);
        Vector3f velocityOfParticle = PhysicsUtilities::getVelocityOfParticle(state,
particleIndex);
        float densityAtParticleLoc = vecParticleDensities[particleIndex];
        float pressureAtParticleLoc = vecParticlePressures[particleIndex];

        // CALCULATE PRESSURE AND VISCOSITY FORCES
        // ALSO CALCULATE PIECES OF THE SURFACE TENSION FORCE
        Vector3f totalPressureForce = Vector3f::ZERO;
        Vector3f totalViscosityForce = Vector3f::ZERO;
        Vector3f totalGradColorField = Vector3f::ZERO;
        float totalLaplacianColorField = 0.0f;

        vector<int> neighborIndexes =

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particleGrid.getNeighborParticleIndexes(particleIndex, positionOfParticle);
    for (int neighborI : neighborIndexes)
    {
        Vector3f positionOfNeighbor = PhysicsUtilities::getPositionOfParticle(state,
neighborI);

        float densityAtNeighborLoc = vecParticleDensities[neighborI];
        float pressureAtNeighborLoc = vecParticlePressures[neighborI];

        Vector3f spikyKernelGradForDebugging;

        Vector3f pressureContribution;
        Vector3f viscosityContribution;
        Vector3f gradColorFieldContribution;
        float laplacianColorFieldContribution;

        Vector3f rForKernel = positionOfParticle - positionOfNeighbor;

        float rEpsilon = 0.0005;
        if (rForKernel.abs() < rEpsilon)
        {

            pressureContribution = Vector3f::ZERO;
            viscosityContribution = Vector3f::ZERO;
            gradColorFieldContribution = Vector3f::ZERO;
            laplacianColorFieldContribution = 0.0f;

            //rForKernel = Vector3f(0.003, 0.003, 0.003);
        }
        else
        {
            // CALCULATE PRESSURE CONTRIBUTION FROM THE NEIGHBOR
            Vector3f spikyKernelGrad = KernelUtilities::gradSpikyKernel(rForKernel);
            spikyKernelGradForDebugging = spikyKernelGrad;

            if (isNaN(spikyKernelGrad))
            {
                cout << "NAN spiky kernel gradient" << endl;
                cout << "Spiky kernel gradient: ";
DebugUtilities::printVector3f(spikyKernelGrad);
                cout << "ri - rj magnitude: " << rForKernel.abs() << endl;
            }

            pressureContribution = PhysicsUtilities::getPressureForce(
PARTICLE_MASS,
ticleLoc,
ghborLoc,
hborLoc,
ad );

            // CALCULATE VISCOSITY CONTRIBUTION FROM THE NEIGHBOR
            float laplacianKernel =
KernelUtilities::laplacianViscosityKernel(rForKernel);
            Vector3f velocityOfNeighbor =
PhysicsUtilities::getVelocityOfParticle(state, neighborI);
            viscosityContribution =
PhysicsUtilities::getViscosityForce(PARTICLE_MASS,
NSTANT,
ghborLoc,
nel,
pressureAtPar
pressureAtNei
densityAtNeig
spikyKernelGr
VISCOSITY_CO
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velocityOfNe

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ighbor,
rticle);

// CALCULATE GRAD COLOR FIELD CONTRIBUTION FROM NEIGHBOR
Vector3f gradPolySixKernel =
KernelUtilities::gradPolySixKernel(rForKernel);
gradColorFieldContribution = (PARTICLE_MASS / densityAtNeighborLoc) *
gradPolySixKernel; // Eq(15);

// CALCULATE LAPLACIAN COLOR FIELD CONTRIBUTION FROM NEIGHBOR
float laplacianPolySixKernel =
KernelUtilities::laplacianPolySixKernel(rForKernel);
laplacianColorFieldContribution = (PARTICLE_MASS / densityAtNeighborLoc)
* laplacianPolySixKernel; // Eq(15)

totalViscosityForce += viscosityContribution;
totalPressureForce += pressureContribution;
totalGradColorField += gradColorFieldContribution;

//cout << "Grad color field contribution: ";
DebugUtilities::printVector3f(gradColorFieldContribution);

// For debugging
if(isNan(viscosityContribution))
{
    cout << "Encountered NAN viscosity contribution" << endl;
    cout << "Viscosity contribution: ";
DebugUtilities::printVector3f(viscosityContribution);

    cout << "Particle loc: ";
DebugUtilities::printVector3f(positionOfParticle);
    cout << "Particle velocity: ";
DebugUtilities::printVector3f(velocityOfParticle);

    cout << "NeighborI: " << neighborI << endl;
    cout << "Neighbor loc: ";
DebugUtilities::printVector3f(positionOfNeighbor);
    Vector3f velocityNeighbor =
PhysicsUtilities::getVelocityOfParticle(state, neighborI);
    cout << "Neighbor velocity: ";
DebugUtilities::printVector3f(velocityNeighbor);
    cout << "Density at neighbor loc: " << densityAtNeighborLoc << endl;

    float laplacianKernel =
KernelUtilities::laplacianViscosityKernel(positionOfParticle - positionOfNeighbor);
    cout << "Laplacian Kernel: " << laplacianKernel << endl;

    assert(false); // Kill execution of the program
}

if(isNan(pressureContribution))
{
    cout << "Encountered NAN pressure contribution" << endl;
    cout << "Pressure contribution: ";
DebugUtilities::printVector3f(pressureContribution);

    cout << "Particle loc: ";
DebugUtilities::printVector3f(positionOfParticle);
    cout << "Pressure at particle loc: " << pressureAtParticleLoc <<
endl;

    cout << "NeighborI: " << neighborI << endl;
    cout << "Neighbor loc: ";
DebugUtilities::printVector3f(positionOfNeighbor);
    cout << "Density at neighbor loc: " << densityAtNeighborLoc << endl;
    float pressureAtNeighborLoc =
PhysicsUtilities::getPressureAtLocation(densityAtNeighborLoc, REST_DENSITY,
GAS_CONSTANT);

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        cout << "Pressure at neighbor loc: " << pressureAtNeighborLoc <<
endl;

        cout << "Spiky kernel grad: ";
DebugUtilities::printVector3f(spikyKernelGradForDebugging);

        assert(false); // Kill execution of the program
    }

    if (isNaN(gradColorFieldContribution))
    {
        cout << "Encountered NAN grad color field contribution" << endl;
        cout << "Grad color field contribution: ";
DebugUtilities::printVector3f(gradColorFieldContribution);
        assert(false);
    }

    if (isNaN(laplacianColorFieldContribution))
    {
        cout << "Encountered NAN laplacian color field contribution" <<
endl;
        cout << "Laplacian color field contribution: " <<
laplacianColorFieldContribution << endl;
        assert(false);
    }
}

totalViscosityForce += viscosityContribution;
totalPressureForce += pressureContribution;
totalGradColorField += gradColorFieldContribution;
totalLaplacianColorField += laplacianColorFieldContribution;

}

totalLaplacianColorField += (SELF_LAPLACIAN_COLOR_FIELD / densityAtParticleLoc);

// CALCULATE TOTAL SURFACE TENSION FORCE FROM COMPONENTS
Vector3f surfaceNormal = totalGradColorField;
float surfaceNormalMag = surfaceNormal.abs();

Vector3f totalSurfaceTensionForce;

if (surfaceNormalMag > TENSION_THRESHOLD)
{
    float constant = (-1.0 * TENSION_CONSTANT * totalLaplacianColorField) /
surfaceNormalMag;
    totalSurfaceTensionForce = constant * surfaceNormal;
}

else
{
    //cout << "Surface normal mag: " << surfaceNormalMag << endl;
    totalSurfaceTensionForce = Vector3f::ZERO;
}

if (totalSurfaceTensionForce.abs() > 0.0f)
{
    //cout << "Total surf tension force: ";
DebugUtilities::printVector3f(totalSurfaceTensionForce);
    //cout << "Total grad color field: ";
DebugUtilities::printVector3f(totalGradColorField);
    //cout << "Total laplacian color field: " << totalLaplacianColorField <<
endl;
}

// COMPUTE TOTAL ACCELERATION OF PARTICLE
Vector3f accelPressure = totalPressureForce / densityAtParticleLoc;
Vector3f accelViscosity = totalViscosityForce / densityAtParticleLoc;
Vector3f accelSurfaceTension = totalSurfaceTensionForce / densityAtParticleLoc;
Vector3f accelGravity = PhysicsUtilities::getGravityForce(PARTICLE_MASS,

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```
GRAVITY_CONSTANT) / PARTICLE_MASS;
```

```
    Vector3f accelTotal = accelPressure + accelViscosity + accelGravity +  
    accelSurfaceTension;
```

```
    derivative.push_back(velocityOfParticle);  
    derivative.push_back(accelTotal);
```

```
}
```

```
    return derivative;
```

```
}
```

```
void SPHFluidSystem::draw()
```

```
{
```

```
    int numNanPositions = 0;
```

```
    for (int i = 0; i < m_numParticles; i++)
```

```
    {
```

```
        // Draw the particles
```

```
        Vector3f posParticle = PhysicsUtilities::getPositionOfParticle(m_vVecState, i);
```

```
        if (isNan(posParticle))
```

```
        {
```

```
            cout << "Encountered NAN position: " << "(" << posParticle.x() << " , " <<  
posParticle.y() << " , " << posParticle.z() << " )" << endl;
```

```
            //++numNanPositions;
```

```
        }
```

```
        glPushMatrix();
```

```
        glTranslatef(posParticle[0], posParticle[1], posParticle[2] );
```

```
        glutSolidSphere(0.015f, 10.0f, 10.0f);
```

```
        glPopMatrix();
```

```
    }
```

```
    //cout << "Num nans: " << numNanPositions << endl;
```

```
}
```

```
void SPHFluidSystem::reinitializeSystem()
```

```
{
```

```
}
```

```
// Helper functions
```

```
void SPHFluidSystem::calculateDensitiesAndPressures(vector<Vector3f> &state)
```

```
{
```

```
    vecParticleDensities = vector<float>();
```

```
    vecParticlePressures = vector<float>();
```

```
    for (int i = 0; i < m_numParticles; ++i)
```

```
    {
```

```
        float density = 0;
```

```
        Vector3f pos = PhysicsUtilities::getPositionOfParticle(state, i);
```

```
        vector<int> neighborIndexes = particleGrid.getNeighborParticleIndexes(i, pos);
```

```
        for (int neighborI : neighborIndexes)
```

```
        {
```

```
            Vector3f neighborPos = PhysicsUtilities::getPositionOfParticle(state,  
neighborI);
```

```
            density += PARTICLE_MASS * KernelUtilities::polySixKernel(pos -  
neighborPos);
```

```
        }
```

```
        density += SELF_DENSITY_CONSTANT;
```

```
        vecParticleDensities.push_back(density);
```

```
        float pressure = PhysicsUtilities::getPressureAtLocation(density, REST_DENSITY,  
GAS_CONSTANT);
```

```
        vecParticlePressures.push_back(pressure);
```

```
    }
```

```
}
```

```
bool SPHFluidSystem::isNan(float val)
```

```

{
    return val != val;
}

bool SPHFluidSystem::isNaN(Vector3f vec)
{
    return isNaN(vec.x()) || isNaN(vec.y()) || isNaN(vec.z());
}

// Different system initializations
void SPHFluidSystem::buildTwoParticleSystemNotNeighbors()
{
    Vector3f pos1(0.3, 0.5, 0.1);
    Vector3f pos2(0.1, 0.5, 0.1);

    m_vVecState.push_back(pos1);
    m_vVecState.push_back(Vector3f::ZERO);
    m_vVecState.push_back(pos2);
    m_vVecState.push_back(Vector3f::ZERO);

    m_numParticles = 2;
}

void SPHFluidSystem::buildTwoParticleSystemNeighbors()
{
    Vector3f pos1(0.3, 0.5, 0.1);
    Vector3f pos2(0.305, 0.5, 0.1);

    m_vVecState.push_back(pos1);
    m_vVecState.push_back(Vector3f::ZERO);
    m_vVecState.push_back(pos2);
    m_vVecState.push_back(Vector3f::ZERO);

    m_numParticles = 2;
}

void SPHFluidSystem::testOneInitializeSystem()
{
    for (int k = 0; k < 20; k++)
    {
        for (int i = 0; i < 15; i++)
        {
            for (int j = 0; j < 20; j++) {
                Vector3f point(0.14 + .01 * i + .005 * (i % 2), 0.24 + j * .01 + .005 *
(j % 2), 0.1 + k * .01 + .005 * (k % 2));
                m_vVecState.push_back(point);
                m_vVecState.push_back(Vector3f::ZERO);
            }
        }

        m_numParticles = 6000;
    }
}

void SPHFluidSystem::build2DTestSystem()
{
    float k = 0.4;
    for (int i = 0; i < 10; ++i)
    {
        for (int j = 0; j < 10; ++j)
        {
            Vector3f point(0.04 * (i + 1), 0.04 * (j + 1), k);
            m_vVecState.push_back(point);
            m_vVecState.push_back(Vector3f::ZERO);
        }
    }

    m_numParticles = 100;
}

```

```
}  
  
void SPHFluidSystem::buildTestSystem2()  
{  
    for (float x = 0.1; x <= 0.384; x += 0.02)  
    {  
        for (float y = 0.1; y <= 0.576; y += 0.02)  
        {  
            for (float z = 0.1; z <= 0.384; z+= 0.02)  
            {  
                Vector3f point(x, y, z);  
                m_vVecState.push_back(point);  
                m_vVecState.push_back(Vector3f::ZERO);  
            }  
        }  
    }  
  
    m_numParticles = m_vVecState.size() / 2;  
}
```