Al: Assignment 2

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OUTPUT:

1. DFS: Depth First Search

Workflow:

- a) Data is read from the csv file and stored in the form a 2D list
- b) Preprocessing of this data to assert facts in form (city1, city2, distance)
- c) helper_dfs() takes source, destination, temporary path, final path, temporary cost, final cost as arguments to implement DFS.
- d) dfs() called by helper_dfs() . Handles edge cases if source is the destination or if source and destination are directly connected. If not connected directly, an Intermediate node is selected and dfs() is called recursively with this node as the source.
- e) Path and Cost found is returned

Source is same as destination

Directly connected cities

Cities not directly connected

2. Best First Search

A heuristic function f(n)=h(n) is chosen and assigned to each city to the destination.

The heuristic function chosen is:

Let n be a node,

h(n)=minimum(

for all intermediate nodes 'intermediate_node' of n and destination {distance(n,intermediate_node) + distance(intermediate_node, destination) }

This heuristic function is admissible and consistent as

- 1) It does not overestimate the distance from the source to destination.
- 2) For each node, $h(n) \le cost(n,n') + h(n')$

Workflow:

- a) Data is read from the csv file and stored in the form a 2D list
- b) Preprocessing of this data to assert facts in form (city1, city2, distance)
- c) bestfs() takes source, destination, final path, temporary cost and final cost as arguments.
- d) Heuristics are assigned from each city to the destination by assign heurestic()
- e) best_first() is used to calculate the best path from source to destination as per the heuristics.

- f) best_first() extends the source node and appends the child nodes at the end of the queue. The queue is sorted based on the heuristic values and a recursive call is made with the new queue.
- g) cost estimator() estimates the cost to travel on this path and the values are returned

Source is same as destination

Source and destination are directly connected

Source and destination are not directly connected

Source code:

```
%starts of the program
:-use module(library(csv)).
:-use module(library(lists)).
:-use module(library(apply)).
%Process the csv data in the form of a 2d list
get rows data(File, Lists):- %Stored in 'Lists'
 csv read file(File, Rows, []),
rows to lists(Rows, Lists):-
 maplist(row to list, Rows, Lists).
row to list(Row, List):-
 Row = .. [row|List].
main:-
  retractall(child(_,_,_)),
  write("----"),nl,
```

```
write(" Cities Distance Directory
    write("Source City: "),
    read(Src),
    assert (source (Src)),
    write("Destination City: "),
    read(Dst),
    assert(dest(Dst)),
    write("What algorithm do you wish to test: 1. Depth First Search 2.
Best First Search"),
    read (Choice),
    assert(is choice(Choice)),
   dfs menu(Src, Dst, Choice);
   bestfs menu(Src, Dst, Choice)
dfs menu(Src, Dst, Choice):-
              Choice is 1,
              get rows data("roaddistance.csv", List),
              List=[ |Tail], %First element is the CSV header
              Tail=[Head1|Tail1], %Head1 is the first row, Tail1 is the
              write ("Algorithm chosen is Depth First Search on source"),
              process(Head1, Tail1), %preprocessing of data stored in lists
to form facts
              helper dfs(Src, Dst, [] , Path, 0, Cost),
              nl, nl, write ("The Depth First Search path from
"),write(Src),write(" to "),write(Dst),write(" is "), write(Path),
              nl,nl,write("Estimated Cost from "),write(Src),write(" to
"),write(Dst),write(" is "),write(Cost).
bestfs menu(Src, Dst, Choice):-
```

```
get rows data("roaddistance.csv", List),
              Tail=[Head1|Tail1],
              write("Algorithm chosen is Best First Search on source"),
              process(Head1, Tail1),
              bestfs(Src, Dst, Path, 0, Cost),
              nl, nl, write ("The Best First Search path from
"), write(Src), write(" to "), write(Dst), write(" is "), write(Path),
              nl, nl, write("Estimated Cost from "), write(Src), write(" to
"),write(Dst),write(" is "),write(Cost).
process( ,[]).
process(Head1, Tail1):-
   Tail1=[Head2|Tail2],
   Head1=[ |FirstCol], %head has empty data
   FirstCol=[ |NeighbourCity], % here head is the first cell of the table
   Head2=[ |Distances], %head is empty data
   Distances=[CityName|Distance], %CityName is the name of first city in
    traverse and assert (CityName, NeighbourCity, Distance), %assert facts
for each CityName across the row
   process (Head1, Tail2).
traverse and assert(CityName, NeighbourCity, Distances):-
   list traverse(CityName, NeighbourCity, Distances).
list traverse( ,[H1],[H2]).
```

```
list traverse(CityName,[H1|T1],[H2|T2]):-
    assert(child(CityName, H1, H2)),
    assert(child(H1,CityName,H2)),
   assert(cities(CityName)),
    list traverse(CityName, T1, T2).
append list([], L2, L2).
append list([X | L1], L2, [X | L3]) :-
    append list(L1, L2, L3).
insert end(L, X, NewL) :-
   append list(L, [X], NewL).
minimal(X,Y,X) :- X < Y.
minimal(X,Y,Y) :- X > Y.
list min elem([X],X).
list min elem([X,Y|Rest],Mini) :-
  list min elem([Y|Rest], MiniRest),
  minimal(X,MiniRest,Mini).
helper dfs(Cur,Next, L, Path, Cost, NetCost):-
    insert end(L,Cur,NewList), %insert the source node in the list
dfs(Source,Source,[Source],[Source],0,0). %if Source is Dest
```

```
dfs(Cur, Next, L, Path, Cost, NetCost):-
 child(Cur, Next, Dist),
 insert end(L,Next,Path),
 NetCost is Cost+Dist,!
 );
   child(Cur, Inter, Dist),
  \+ member(Inter, L),
  NewCost is Cost + Dist,
  insert end(L, Inter, UpdatedList),
  dfs(Inter, Next, UpdatedList, Path, NewCost, NetCost)
best_first([[Goal|Path]|_], Goal, [Goal|Path]).
best first([Path|Queue], Goal, FinalPath):-
    extend and add(Path, NewPaths, Queue, NewQueue),
   sorter(NewQueue, NewerQueue),
   best first (NewerQueue, Goal, FinalPath).
extend and add([Node|Path], NewPaths, Queue, NewQueue):-
            (child(Node, NewNode, ),
            \+ member(NewNode, Path)),
            NewPaths),
    append list(Queue, NewPaths, NewQueue).
sorter(NewQueue, NewerQueue):-
```

```
swapping(NewQueue, AuxQueue), !,
    sorter(AuxQueue, NewerQueue).
sorter(NewQueue, NewQueue).
swapping([[A1|B1], [A2|B2]|T], [[A2|B2], [A1|B1]|T]):-
   htics(A1, W1),
    W1>W2.
swapping([X|T], [X|V]):-
    swapping (T, V).
bestfs(Source, Source,[Source], 0, 0).
bestfs(Source, Dest, Path, InitCost, NetCost):-
    findall(X, cities(X), CityDirectory),
    assign heuristic (Source, CityDirectory, Dest), nl,
    write("Calculated Heuristics from "), write(Source),nl,
   best first([[Source]], Dest, TempPath),
    reverse (TempPath, Path),
   cost estimator(Path, 0, NetCost).
comparator(City, Dest, Cost):-
    child(City, Inter, D1),
    child(Inter, Dest, D2),
   Cost is D1 + D2.
cost_estimator([A|[B|C]], CurCost, NetCost):-
  ( C==[] ->
   child(A, B, Dist),
   ( child(A, B, Dist),
```

```
NewCost is CurCost + Dist,
   cost_estimator([B|C], NewCost, NetCost)
).

% Assigns the heurestics

assign_heuristic(Source, [], Dest).
assign_heuristic(Source, [H|T], Dest):-
   findall(X, comparator(H, Dest, X), L),
   min_list(L,Min),
   forall(\+ htics(H,Min), assert(htics(H, Min))),
   assign_heuristic(Source, T, Dest).
```