A Simple Genetic Algorithm for the Geometric Connected Dominating Set Problem

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ABSTRACT

For this project, I created a custom genetic algorithm engine from scratch in Java and used it to collect data and compare results from various combinations of standard genetic algorithm operators for selection, crossover, and mutation including the N4N hypermutation proposed by Alkhalifah and Wainwright^[2]. These results were also compared with results from the simulated annealing and foolish hill climbing algorithms, with various perturbation functions.

INTRODUCTION

The geometric connected dominating set problem (GCDSP) is formally defined as follows: Given a set of points in a plane, P, and a constant B, find the minimum |P'| such that all points P - P' are within euclidean distance of B of some point in P' and such that the graph G = (P', E) with an edge between two points in P' if and only if they are within distance B of each other is connected^[1].

This problem is also informally refered to as the "radar" problem and can be stated as follows: given a set of cities, we need to select the minumum number of cities in which to install a range limited radar transmitter such that all cities receive radar

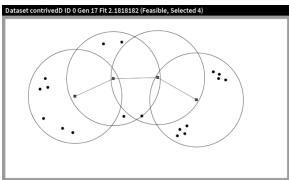


Figure 1- A valid solution to the GCDSP

coverage and all transmitters are within range of another transmitter.

An example dataset and solution is shown in Figure 1. Each point represents a city. Square points are considered "selected" and will contain a transmitter whose range is represented by the surrounding circle. In order to be a feasible solution, all points must be within a circle and all selected points must have a path to all other selected points.

CHROMOSOME & FITNESS

The chromosome is a simple bit string of length |P|. For each point i, $c_i = 1$ if it is selected; Otherwise, $c_i = 0$.

The fitness function is composed of three factors:

- 1) Percent covered points (P_c)
- 2) Percent selected points (P_s)
- 3) Connectedness of selected points (C)

Factors 1 and 3 are to be maximized and factor 2 is to be minimized. The SGA was set up to minimize fitness, so the inverses of factors 1 and 3 were taken. The complete fitness function has the form:

$$Fitness = \alpha * \frac{1}{P_C} + \beta * P_S + \gamma * \frac{1}{C}$$

where alpha, beta, and gamma are variable weights for each respective factor. To select appropriate weights, all other variables were held constant and 10 trials were run for each value of alpha, beta, and gamma shown in Table 1 using datasets E100, E250, and F100. The average number of selected points in each case is given, except when a solution was not always found. Ignoring schemes where a solution was not always found, the best performing weighting schemes based on the average of the three datasets

average number of selected points were number 1 and 6. Since both of these schemes had the same average performance in these trials, I went with the simpler choice, number 1, where $\alpha=\beta=\gamma=1$. It should also be noted that while scheme number 1 was not always the best choice for all datasets, it was always able to find a solution and performed well on average.

				Avg. number of selected points		
id	а	β	Υ	E250	E100	F100
1	1	1	1	22.8	12	22.1
2	1	10	10			
3	1	100	10			
4	3	2	1	22.5	11.6	23
5	5	10	1			
6	10	1	10	22.7	11.7	22.5
7	10	5	1	22	12.2	
8	10	10	1	21.1	11.6	
9	10	100	1			
10	100	1	10	22.8	12.1	23.2
11	100	10	1	21.7		

Table 1- a comparison of various weighting schemes (a "--" indicates a solution was not always found)

OPERATORS

Three standard selection methods were implemented in this SGA: roulette, rank, and tournament. The tournament selection used a tournament parameter of 0.75.

Four crossover methods were implemented: single point, double point, n-point, and uniform. For the n-point crossover, a random number of crossover points were selected between 1 and the number of points divided by 2 and the location of each crossover point was randomly selected.

Three mutation methods were implemented: single invert, double invert, and N4N hypermutation[2]. When the dataset is loaded, the nearest four points are calculated for each point. When a chromosome is selected for N4N hypermutation, the fitness for every combination of selecting the nearest four points is calculated, and the combination with the best fitness is imposed upon the original chromosome.

PARAMETERS

The basic parameters for the generational SGA are population size, crossover rate, and mutation rate. Their values were 100, 1.0, and 0.01 respectively. These parameter values remained constant throughout all runs of the SGA. Elitism was used. Ten trials were run of each combination of selection, crossover, and mutation operators. The initial population was generated randomly.

The algorithm was terminated when any one of the following conditions occured:

- Out of time- The SGA has run of more than 10 minutes of wall clock time
- Maximum number of generations was reached- The SGA completed over 10,000 generations
- 3) The population has stagnated no improvement to the best fitness value of the population has occurred in over 2000 generations

DATASETS

The contrived datasets were constructed so that the correct answer is very easily seen by a human, but the search space is still large enough to provide a challenge to the SGA. Three contrived datasets were used to verify the algorithm: "contrived1" with 41 points, "contrived90" with 91 points and "contrived150" with 150 points. These datasets and their respective solutions are shown in Figure 2.

Two types of random datasets were also used, E and F. E type datasets had a larger maximum distance (radar range) than F type datasets, making them generally solvable with fewer selections. Random datasets with 100, 250, and 500 points of each type were used. These datasets and their possible solutions are shown in Figures 3 and 4.

SIMULATED ANNEALING & FOOLISH HILL CLIMBING

The parameters for the SA were as follows: $\alpha = 0.95, \beta = 1.05, T_0 = 10, i = 1000.$ The

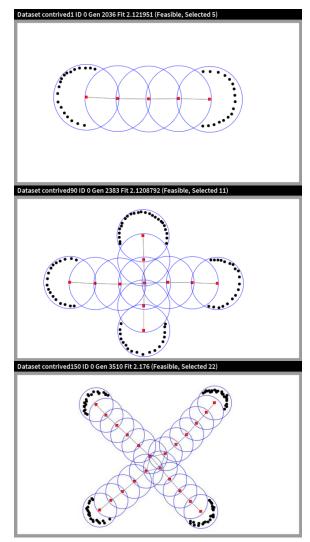


Figure 2: contrived datasets and their solutions

perturbation functions used were the same as the three mutation operators used for the SGA: single invert, double invert, and N4N hypermutation. Elitism was used. The SA and FHC were terminated after 5 minutes of wall clock time.

COMPUTATIONAL RESULTS

The data table is shown in Table 2. For each dataset, the minimum (best) selected number of points, the average of the number of selected points, the standard deviation of the number of selected points, and the average number of generations is shown from all runs. Any run that did not result in a feasible result was discarded. This only occurred in the simulated annealing runs with F-type datasets. For each average selected column, the lowest 10%

values are highlighted in green and the highest 10% values are highlighted in red.

CONCLUSIONS

All combinations of operators for the SGA were able to find feasible and correct (if contrived) solutions in all runs on both the contrived and random datasets. The best performing combination of parameters was (rank, N-point, double invert). This combination was in the top 10% in 5 out of 6 datasets and had the best average number of selected points in the most difficult dataset F500. Another notable combination is (rank, N-point, N4N). This combination performed very well when the number of points was highest (in the E500 and F500 datasets).

The simulated annealing algorithm performed well with the smaller datasets (E100 and F100), but did very poorly with increasing dataset size. The foolish hill climbing algorithm did suprisingly well with the E and smaller F datasets. I'm not sure why.

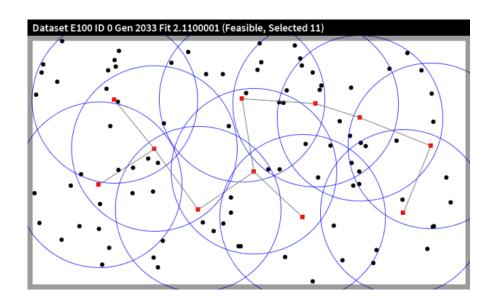
One possible thing to try in the future is to allow the alpha, beta, and gamma factors in the fitness function to vary dynamically. This could produce better results, since different combinations of values performed better for different datasets (as seen in Table 1).

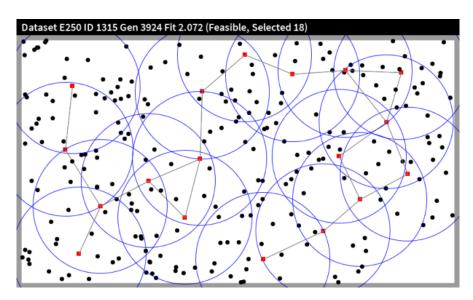
The most difficult part of this project was data collection, so I made a GUI to simplify things (Figure 5). Also to save time, I ran three different runs at a time on different threads.

SOURCES

- [1] Garey, Michael R., and David S. Johnson. *Computers and Intractability: A Guide to the Theory of NP-Completeness*. San Fransisco: W.H. Freeman, 1979.
- [2] Alkhalifah, Yaser and Roger. L. Wainwright. "A Genetic Algorithm Applied to Graph Problems Involving Subsets of Vertices", Proceedings of the 2004 IEEE Congress on Evolutionary Computation (CEC 2004), 2004.

Table 2: results





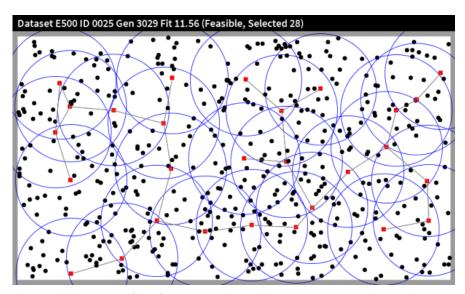
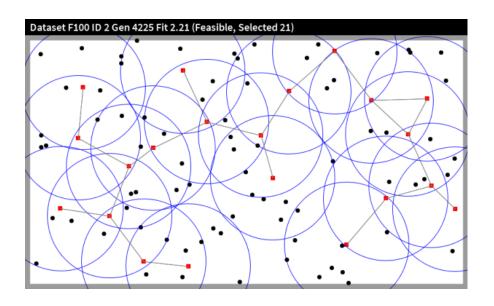
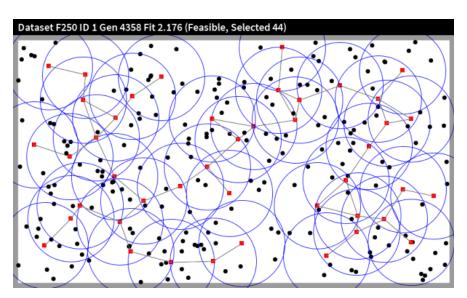


Figure 3: E type random datasets





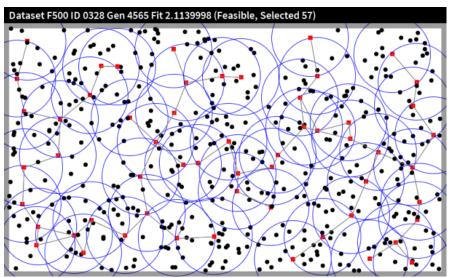
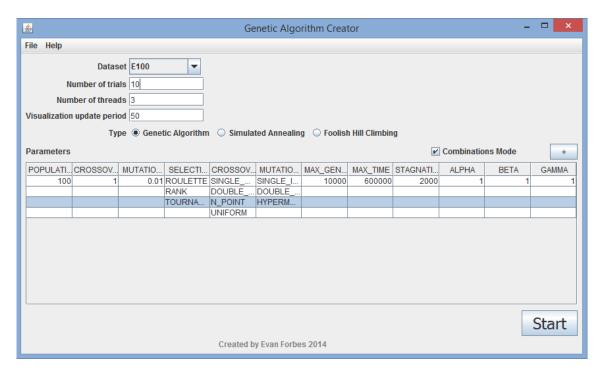


Figure 4: F type random datasets



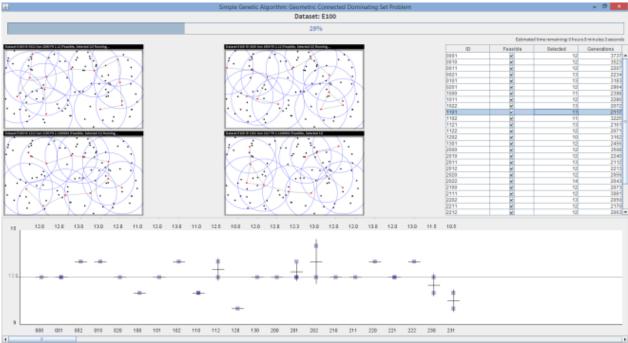


Figure 5: Custom SGA engine GUI