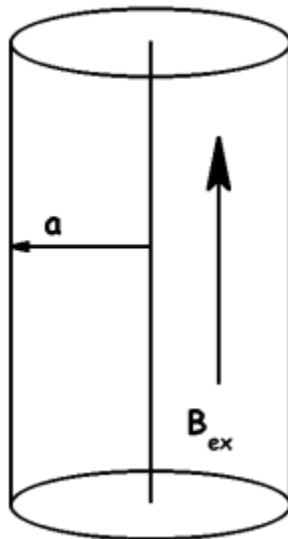
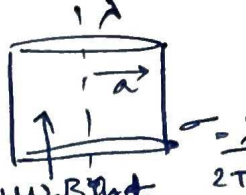


An infinitely long wire with linear charge density $-\lambda$ lies along the z -axis. An insulating cylindrical shell of radius a and moment of inertia I per unit length is concentric with the wire and can rotate freely about the z -axis. The areal charge density on the cylinder is $\sigma = \lambda/2\pi a$ and is uniformly distributed. The cylinder is immersed in an external magnetic field $B_{\text{ex}} \hat{z}$, and is initially at rest. Starting at $t = 0$ the external magnetic field is slowly reduced to zero over a time $T \gg a/c$, where c is the speed of light. What is the final angular velocity ω of the cylinder?



Given, $\sigma = \frac{\lambda}{2\pi a}$; radius = a ; length is infinite



As we know that,

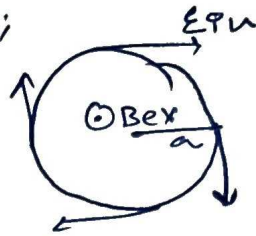
$$\vec{\nabla} \times \vec{E} = -\frac{dB}{dt} ; \text{ Faradays law. But}$$

$$\int E \cdot dl = -\frac{d\Phi}{dt} ; \Phi = \int B \cdot dA ; \text{ lenz law.}$$

Now for a circular loop of radius a ;

$$E_{\text{in}} \cdot 2\pi a = -\frac{d(B \cdot \pi a^2)}{dt}$$

$$E_{\text{in}} = -\frac{dB}{dt} \cdot \frac{a}{2} \dots\dots (1)$$



As we know;

force per unit length = charge per unit $\times E_{\text{in}}$

$$F_L = (\sigma \cdot 2\pi a) \times E_{\text{in}}$$

$$\text{Torque} = \vec{a} \times \vec{F}$$

$$T_L = \vec{a} \times \vec{F}_L$$

$$= \sigma \cdot 2\pi a \times E_{\text{in}} \times a$$

$$I \frac{d\omega}{dt} = \sigma \cdot 2\pi a^2 \left(-\frac{dB}{dt} \right) \frac{a}{2} ,$$

$$\text{given } \sigma = \frac{\lambda}{2\pi a}$$

$$\therefore I \frac{d\omega}{dt} = \frac{\lambda}{2\pi a} \frac{a^3 \times 2\pi}{2} \left(-\frac{dB}{dt} \right)$$

Integration on both sides

$$\int I \cdot \frac{d\omega}{dt} = -\frac{\lambda a^2}{2} \int \frac{dB}{dt}$$

$$I \cdot \int \frac{d\omega}{dt} = -\frac{\lambda a^2}{2} \int \frac{dB}{dt}$$

$$\int \frac{d\omega}{dt} = -\frac{\lambda a^2}{2I} \int \frac{dB}{dt}$$

$$(\omega_{\text{final}} - \omega_{\text{int}}^0) = \frac{\lambda a^2}{2I} (B_{\text{final}} - B_{\text{int}})$$

$$\omega_{\text{final}} = \frac{\lambda a^2}{2I} (B_{\text{int}} - B_{\text{final}});$$

in general people assume B_{final} shall be "zero" but not; because, at the time B_{induced} becomes zero but the cylinder rotates with an angular velocity ω , can cause an magnetic field.

Induced current I ; per unit length I_L is

$$\text{current } I_L = \frac{\text{charge per unit length}}{\text{time period}}$$

$$\text{current } I_L = \frac{\sigma \cdot 2\pi a \cdot \omega}{2\pi}, \quad \therefore T = \frac{2\pi}{\omega}$$

$$\text{current } I_L = \sigma a \omega; \quad \sigma = \frac{\lambda}{2\pi a}$$

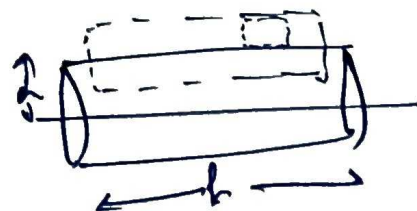
$$\text{current } I_L = \frac{\lambda}{2\pi} \omega; \quad \omega \text{ is } \omega_{\text{final}} \text{ at } B_{\text{induced}} = 0$$

\therefore magnetic field due to cylinder B_{final} .

$$B_{\text{final}} \cdot L = \mu_0 I_L \cdot L$$

$$B_{\text{final}} = \mu_0 \frac{\lambda \omega_{\text{final}}}{2\pi}$$

Assume an Amperian



$$\omega_f = \frac{\lambda a^2}{2I} \left(B_{int} - \frac{\mu_0 \lambda \omega_{final}}{2\pi} \right)$$

$$\omega_f = \frac{\lambda a^2}{2I} (B_{int})$$

$$1 + \frac{\mu_0 \lambda^2 a^2}{4\pi I}$$