

Arkadeep Narayan Chaudhury

<https://arkadeepnc.github.io>

[LinkedIn](#), [GitHub](#), [ResearchGate](#)

Email: arkadeec@alumni.cmu.edu

Cell: +1 412-626-4231

Pittsburgh, Pennsylvania

EDUCATION

Carnegie Mellon University, Robotics Institute

PhD in Robotics

Pittsburgh, PA, USA

Nov. 2019 – Oct. 2024

Indian Institute of Science

Master of Science in Mechanical Engineering

Bangalore, Karnataka, India

Aug. 2015 – Dec. 2017

RESEARCH EXPERIENCE

3D capture and reconstruction systems, sensor fusion, photometric stereo, prototyping low-level computer vision systems, computational photography, geometric and photometric camera calibration.

EXPERIENCE

Epic Games, Inc.

Research Scientist : Human Capture

Pittsburgh, PA

Nov. 2024 – present

Responsibilities: Co-led development of a high-performance, multi-modal human capture system integrating 30+ heterogeneous cinema cameras, MOCAP, and an electromagnetic articulograph. Achieved $\sim 15\%$ faster and higher-fidelity facial reconstruction (sub-0.5 mm RMSE) compared to internal and commercial baselines, enabling sub-millimeter accurate multi-modal tracking. Designed calibration pipelines to substitute internal and commercial systems by matching the accuracy. Developed a human-scale photometric stereo system for dense facial geometry and reflectance acquisition. Prototyped scalable pipelines for aggregating terabyte-scale, time-synchronized multi-modal datasets to support training of large ML models.

Toyota Research Institute

Research Scientist Intern

Los Altos, CA

May 2023 – Aug. 2023

Physically based 3D representations: Developed a robot-mounted, multi-flash stereo rig to capture physically based 3D assets of small objects. Enabled multimodal sensing under constrained capture environments. Filed a [US Patent](#) on novel capture hardware and pipeline.

The Robotics Institute, CMU

Graduate Research Assistant

Pittsburgh, PA

Nov. 2019 – Oct 2024

Doctoral thesis:

[Moving Lights and Cameras for Better 3D Perception of Indoor Scenes](#)

Moving cameras: Developed one of the first co-located RGB-D-tactile sensor ensembles for visual servoing and object localization. [ICRA & RA-L'22](#)

Moving lights: Designed mm-accurate, real-time photometric stereo system for surface perception in robot workspaces. [WACV'24](#)

Moving lights and cameras: Created portable multi-flash stereo camera enabling geometry + appearance recovery with just 10 views. [SIGGRAPH Asia Tech. Comm.](#), 3DV'25.

Early PhD work (08/2018 – 10/2019): Computer vision for medical robots ([Hamlyn Symposium 2019](#), pp. 107). Transitioned to the Robotics Institute from Mechanical Engineering PhD program.

Robotics and Design Lab, IISc

Graduate Research Assistant

Bangalore, India

Jul. 2015 - Jun. 2018

Advisor:

[Prof. Ashitava Ghosal](#)

Design of Parallel Robots: Designed Monte Carlo simulations to model workspaces of parallel robots. Modeled the human 3-fingered grasp and proposed techniques for optimal design of parallel robots. [Thesis](#), [MMT](#), [JMR](#).

Motion planning for snake-like robots: Co-designed and implemented optimal formulations for planning motion of snake-like robots (e.g. endoscopes) through narrow paths. [Elsevier CAD](#)

SELECTED PUBLICATIONS. [\[GOOGLE SCHOLAR PAGE\]](#)

- [1] **Chaudhury, A. N.**, Vasiljevic I., Zakharov S., Guizilini V., Ambrus R., Narasimhan S., Atkeson C. (2024) “Incorporating dense depth into neural 3D representations for view synthesis and relighting” *Proc. of the 3DV ‘25* [Link](#), [arXiv](#)
- [2] **Chaudhury, A. N.**, Vasiljevic I., Zakharov S., Guizilini V., Ambrus R., Narasimhan S., Atkeson C. (2024) “A Multi-flash Stereo Camera for Photo-realistic Capture of Small Scenes” *SIGGRAPH Asia 2024 Technical Communications* [Link](#)
- [3] **Chaudhury, A. N.**, Keselman, L. & Atkeson, C. (2024) “Shape from Shading for Robotic Manipulation” *Proc. of the WACV ‘24* [Link](#)
- [4] **Chaudhury, A. N.**, Man, T. Yuan, W. & Atkeson, C. (2022) “Using Collocated Vision and Tactile Sensors for Visual Servoing and Localization.” *IEEE RA-L & ICRA 2022* [Link](#)

PATENTS

- [1] **Chaudhury, A. N.**, Vasiljevic I., Zakharov S., Guizilini V., Ambrus R., Narasimhan S., Atkeson C. (2024) “Multi-flash stereo camera for photorealistic capture of small scenes” [US Patent Application no.: 19/042,629](#).

SKILLS

Programming Languages: Python, C++, CUDA
Robot platforms: Universal Robots UR5, Franka Emika FR3, XArm-7
Camera platforms: PointGrey(FLIR), Arducam, V4L2 devices, Emergent Vision Tech.(EVT), Red Digital Cinema
Computing Environments: Linux [Ubuntu]
Machine Learning Toolboxes: PyTorch, TensorFlow, SciKit-Learn
Software Libraries: ROS, OpenCV, PCL, GTSAM
Languages: English (full proficiency), Bengali (native proficiency) and Hindi (bi-lingual proficiency)

AWARDS AND SERVICE

DST-SERB Overseas PhD fellowship (Govt. of India) [Declined]	08/2018 – 08/2023
DST Graduate Scholarship (Govt. of India)	08/2015 – 12/2017

Reviewer: WACV, 3DV, AAAI, ICRA, IEEE Sensors, IEEE-RA-L, Elsevier CAD, Elsevier MMT, and ASME JMR.