

# Arkadeep Narayan Chaudhury

Homepage

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Carnegie Mellon University, Pittsburgh, PA, ZIP: 15232

## EDUCATION

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### Carnegie Mellon University

*PhD in Computer Science (Robotics)*

Pittsburgh, PA

*Aug. 2020 – Now*

### Carnegie Mellon University

*PhD in Mechanical Engineering (Robotics)*

Pittsburgh, PA

*Aug. 2018 – Aug 2020*

### Indian Institute of Science

*Master of Science in Mechanical Engineering*

Bangalore, India

*Aug. 2015 – Dec. 2017*

### Indian Institute of Engineering Science and Technology

*Bachelor of Engineering in Mechanical Engineering*

Shibpur, India

*Jul. 2011 – May 2015*

## EXPERIENCE

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### Atkeson Lab & Robotouch Lab, CMU RI

*Graduate Research Assistant*

Pittsburgh, PA

*Nov. 2019 – Present*

#### Advisor:

Prof. Christopher Atkeson

**FingerVision II:** Developing FingerVision II – an ensemble of collocated vision, depth and touch sensors and a set of algorithms to viually servo robots to workspace goals and localize objects through vision and touch. [Link](#)

**Active Lighting:** Developing a robot workspace scale shape-from-shading setup for object scale and articulation agnostic depth, normal and motion perception.

### CI2CV Lab, CMU RI

*Graduate Research Assistant*

Pittsburgh, PA

*July. 2019 – Nov. 2019*

#### Advisor:

Prof. Simon Lucey

**Learning Based Registration:** Researched learning based algorithms for registration of human organ models. A summary my work: [Link](#).

### Biorobotics Lab, CMU RI

*Graduate Research Assistant*

Pittsburgh, PA

*Aug. 2018 - Jul. 2019*

#### Advisor:

Prof. Howie Choset

**Medical device prototype:** Co-developed and prototyped a hand held soft tissue investigation device for low-cost tumor diagnosis.

**Non-rigid registration:** Surveyed algorithms for human organ registration and proposed faster algorithms with comparable accuracy to handle larger volumes of data. [Link](#)

### Robotics and Design Lab, IISc

*Research Staff*

Bangalore, India

*Jan. 2018 - Jul. 2018*

#### Advisor:

Prof. Ashitava Ghosal

**Optimal Motion Planning:** Derived optimal, polynomial time motion plans for snake-like robots in confined spaces such as endoscopes, pipe inspection robots and robots in cluttered search and rescue scenarios.

### Robotics and Design Lab, IISc

*Graduate Research Assistant*

Bangalore, India

*Jul. 2015 - Dec. 2017*

#### Advisor:

Prof. Ashitava Ghosal

**Design of Parallel Robots:** Designed Monte Carlo simulations to model workspaces of parallel robots. Modeled the human 3-fingered grasp and proposed techniques for optimal design of parallel robots.

### Solid Mechanics Lab, IIST

*Undergraduate Researcher*

Shibpur, India

*Jul. 2014 - Apr. 2015*

#### Advisor:

Prof. Debasis Datta

**Computational Design of Springs:** Formulated closed form expressions for design of springs of un-conventional shapes to estimate their stresses, natural frequencies, buckling loads etc.

## SELECTED COURSE PROJECTS

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**Planning on Manifolds:** Devised algorithms for path planning of collaborative robot arms to manipulate ultra-sound probes on a human body phantom. The algorithm may be used to automate femoral artery catheterization. [Video]  
**SLAM for Legged Robots:** Used GTSAM and OpenCV to co-develop a framework for visual state estimation in legged robots using their gait information. [Report]

## PUBLICATIONS. [GOOGLE SCHOLAR PAGE]

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- [1] **Chaudhury, A. N.**, Man, T. Yuan, W. & Atkeson, C. (2021) “Using Collocated Vision and Tactile Sensors for Visual Servoing and Localization.” *In Submission to IEEE RA-L* [Link](#)
- [2] Ashwin K.P., **Chaudhury A.N.**, and Ashitava Ghosal. (2020) “Efficient representation of ducts and cluttered spaces for realistic motion planning of hyper-redundant robots through confined paths.” *J. Computer-Aided Design*, 119, 102777. [Link](#)
- [3] **Chaudhury, A. N.**, & Ghosal, A. (2017). “Optimum design of multi-degree-of-freedom closed-loop mechanisms and parallel manipulators for a prescribed workspace using Monte Carlo method”. *Mechanism and Machine Theory*, 118, 115-138. [Link](#)
- [4] **Chaudhury, A. N.**, & Ghosal, A. (2018). “Workspace of Multi-fingered Hands Using Monte Carlo Method”. *Journal of Mechanisms and Robotics*, 10(4), 041003. [Link](#)
- [5] **Chaudhury, A. N.**, & Datta, D. (2017). “Analysis of prismatic springs of non-circular coil shape and non-prismatic springs of circular coil shape by analytical and finite element methods”. *Journal of Computational Design and Engineering*, 4(3), 178-191. [Link](#)

## SKILLS

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**Programming Languages:** Python, C++ and CUDA  
**Modelling Tools:** Matlab, Maple (Symbolic Mathematics)  
**Computing Environments:** Windows, Ubuntu  
**Machine Learning Toolboxes:** PyTorch, TensorFlow, SciKit-Learn  
**Software Libraries:** ROS, OpenCV, PCL, GTSAM  
**Languages:** English (full proficiency), Bengali (native proficiency) and Hindi (bi-lingual proficiency)

## RELEVANT COURSES

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**At CMU:** Computer Vision (16-720), Advanced Nonlinear Control Theory (16-748), Robot Localization (16-833), Geometric Methods in Computer Vision (16-822), Linear Systems (18-771), Statistical Techniques in Robotics (16-831), Deep Reinforcement Learning (10-703), Machine Learning (10-701)  
**At IISc:** Robotics (Kinematics, Dynamics and Control), Numerical Linear Algebra, Geometric Modelling, Linear and Non-Linear Optimization,

## AWARDS

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DST-SERB Overseas PhD fellowship [Declined]	08/2018 – 08/2023
Graduate Research Fellowship (CMU)	08/2018 – 08/2019
DST Graduate Scholarship (at IISc)	08/2015 – 12/2017

## REFERENCES

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**Dr. Christopher Atkeson** Professor, CMU, [cga@cmu.edu](mailto:cga@cmu.edu) [advisor]  
**Dr. Ashitava Ghosal** Professor, IISc Bangalore. [asitava@iisc.ac.in](mailto:asitava@iisc.ac.in) [ex. advisor]  
**Dr. Wenzhen Yuan** Assistant Professor, CMU RI, [yuanwz@cmu.edu](mailto:yuanwz@cmu.edu) [collaborator]