

Bayesian Decision theory with continuous features

- Consider more than one feature through feature vector \mathbf{x} , where \mathbf{x} is in d-dimensional Euclidean space \mathbb{R}^d , called the feature space.
- Consider c (more than two) states of nature as in $\{w_1, \dots, w_c\}$.
- Consider a actions, more than merely deciding the state of nature $\{\alpha_1, \dots, \alpha_a\}$
- Introduce a loss function, more general than the probability of error, $\lambda(\alpha_i | w_j)$, describing the loss incurred for taking action α_i when the state of nature is w_j .

$P(w_j | \mathbf{x}) = p(\mathbf{x} | w_j) * P(w_j) / p(\mathbf{x})$ where the evidence is now

where the evidence is now

$$p(\mathbf{x}) = \sum p(\mathbf{x} | w_j) * P(w_j), j = 1, \dots, c.$$

If we have observed a particular \mathbf{x} and we intend to take action α_i but the true state of nature is w_j then we incur loss $\lambda(\alpha_i | w_j)$.

Because $P(w_j | \mathbf{x})$ is the probability that the true state of nature is w_j , the expected loss associated with taking action α_i is

$$R(\alpha_i | \mathbf{x}) = \sum \lambda(\alpha_i | w_j) * P(w_j | \mathbf{x}), j = 1, \dots, c.$$

It is called the risk and our objective is to minimize the risk. A general decision rule is a function $\alpha(\mathbf{x})$. For every \mathbf{x} , the decision function $\alpha(\mathbf{x})$ assumes one of the a values $\alpha_1, \dots, \alpha_a$. The overall risk is then given by

$$R = \int R(\alpha(\mathbf{x}) | \mathbf{x}) p(\mathbf{x}) d\mathbf{x}.$$

To minimize the overall risk, we compute the risk

$R(\alpha_i | \mathbf{x}) = \sum \lambda(\alpha_i | w_j) * P(w_j | \mathbf{x}), j = 1, \dots, c$ and select the action α_i for which $R(\alpha_i | \mathbf{x})$ is minimum. The resulting minimum overall risk is called the Bayes risk and is the best performance that can be achieved.

Special case of two-category classification problem:

Here, action α_1 corresponds to deciding that the true state of nature is w_1 and action α_2 corresponds to deciding that it is w_2 .

Simplifying, write λ_{ij} for $\lambda(\alpha_i | w_j)$, the loss incurred for deciding w_i when the true nature is w_j .

So, $R(\alpha_1 | \mathbf{x}) = \lambda_{11}P(w_1 | \mathbf{x}) + \lambda_{12}P(w_2 | \mathbf{x})$ and

$$R(\alpha_2 | \mathbf{x}) = \lambda_{21}P(w_1 | \mathbf{x}) + \lambda_{22}P(w_2 | \mathbf{x}).$$

Our rule would be to decide w_1 if $R(\alpha_1 | \mathbf{x}) < R(\alpha_2 | \mathbf{x})$.

That is, in terms of posterior probabilities, we decide w_1 if $(\lambda_{21} - \lambda_{11}) P(w_1 | \mathbf{x}) > (\lambda_{12} - \lambda_{22}) P(w_2 | \mathbf{x})$.

This can also be expressed in terms of prior probabilities, by Bayes formula, as, decide w_1 if

$$(\lambda_{21} - \lambda_{11})p(\mathbf{x} | w_1)P(w_1) > (\lambda_{12} - \lambda_{22})p(\mathbf{x} | w_2)P(w_2) \text{ else decide } w_2.$$