Model assisted (1+1)ES

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- 1 Algorithms
- 1.1 Algorithm 1

Normal (1+1) ES

```
1: N \leftarrow 400
 2: function FIT(x)
         y \leftarrow \Sigma_{i < N} (x_i - 1)^2
         return(y)
 5: end function
 6: function DIST(x)
         y \leftarrow \sqrt{\Sigma_{i < N}(x_i - 1)^2}
         return(y)
9: end function
10: Initialize(ind, \sigma^*, prate^* \leftarrow 0)
11: for i \leq MAXGen do
        i + + \atop \sigma \leftarrow \frac{\sigma^* * ||ind - y||)}{N} \atop ind2 \leftarrow ind + \sigma * N(0, I)
12:
13:
14:
         newfit \leftarrow FIT(ind2)
15:
         if newfit \leq bestfit then
16:
             prate^* \leftarrow prate^* - N * \log \frac{DIST(ind2)}{DIST(ind)}
17:
              ind \leftarrow ind2
18:
              bestfit \leftarrow newfit
19:
20:
          end if
21: end for
22: prate^* \leftarrow prate^*/i
```

1.2 Algorithm 2

Model Assisted (1+1)ES

```
1: N \leftarrow 400
 2: function FIT(x)
         y \leftarrow \Sigma_{i < N} (x_i - 1)^2
         return(y)
 4:
 5: end function
 6: function DIST(x)
         y \leftarrow \sqrt{\sum_{i < N} (x_i - 1)^2}
         return(y)
 9: end function
10: initialize(ind, \sigma^*, \sigma_e^*, prate^* \leftarrow 0)
11: for i \leq MAXGen do
        i + +
12:
         ind2 \leftarrow ind
13:
         while j \leq MAXModel do
14:
15:
                     \frac{\sigma^* \! * \! Dist(ind)}{N}
16:
              ind3 \leftarrow ind2 + \sigma * N(0, I)
17:
              \sigma_e \leftarrow \frac{2*\sigma_e^**Dist(ind)^2}{N}fit3 \leftarrow FIT(ind2) + \sigma_e * N(0, 1)
18:
19:
              if fit3 \leq bestfit then
20:
                  ind2 \leftarrow ind3
21:
                   Break
22:
              end if
23:
          end while
24:
         newfit = FIT(ind2)
25:
         if newfit \leq bestfit then
26:
                                                                            3
              prate^* \leftarrow prate^* - N * \log \frac{DIST(ind2)}{DIST(ind)}
27:
              ind \leftarrow ind2
28:
              bestfit \leftarrow new fit
29:
30:
          end if
31: end for
32: prate^* \leftarrow prate^*/i
```

1.3 Algorithm 3

Model Assisted (1+1)ES without model generation limit

```
1: N \leftarrow 400
 2: function FIT(x)
         y \leftarrow \Sigma_{i < N} (x_i - 1)^2
         return(y)
 4:
 5: end function
 6: function DIST(x)
         y \leftarrow \sqrt{\sum_{i < N} (x_i - 1)^2}
         return(y)
 9: end function
10: initialize(ind, \sigma^*, \sigma_e^*, prate^* \leftarrow 0)
11: for i \leq MAXGen do
         i + +
12:
         ind2 \leftarrow ind
13:
14:
          while true do
15:
                     \frac{\sigma^* \! * \! Dist(ind)}{N}
16:
              ind3 \leftarrow ind2 + \sigma * N(0, I)
17:
              \sigma_e \leftarrow \frac{2*\sigma_e^**Dist(ind)^2}{N}fit3 \leftarrow FIT(ind2) + \sigma_e * N(0, 1)
18:
19:
              if fit3 \leq bestfit then
20:
                  ind2 \leftarrow ind3
21:
                   Break
22:
              end if
23:
         end while
24:
         newfit = FIT(ind2)
25:
         if newfit \leq bestfit then
26:
                                                                            4
              prate^* \leftarrow prate^* - N * \log \frac{DIST(ind2)}{DIST(ind)}
27:
              ind \leftarrow ind2
28:
              bestfit \leftarrow new fit
29:
30:
          end if
31: end for
32: prate^* \leftarrow prate^*/i
```

1.4 Algorithm 4

Step-size Adaptive Model Assisted (1+1)ES

```
1: N \leftarrow 400
 2: function FIT(x)
         y \leftarrow \Sigma_{i < N} (x_i - 1)^2
         return(y)
 4:
 5: end function
 6: function DIST(x)
         y \leftarrow \sqrt{\Sigma_{i < N}(x_i - 1)^2}
         return(y)
 9: end function
10: initialize(ind, \sigma_e^*, prate^* \leftarrow 0)
11: for i \leq MAXGen do
         i + +
12:
         ind2 \leftarrow ind
13:
         flag \leftarrow 0
14:
         for j \leq MAXModel do
15:
              j + +
16:
              ind3 \leftarrow ind2 + \sigma * N(0, I)
17:
              \sigma_e \leftarrow \frac{2*\sigma_e^**Dist(ind)^2}{N}
18:
              fit3 \leftarrow FIT(ind2) + \sigma_e * N(0,1)
19:
              if fit3 \leq bestfit then
20:
                  flag \leftarrow 1
21:
                  ind2 \leftarrow ind3
22:
                  Break
23:
              end if
24:
         end for
25:
         newfit = FIT(ind2)
26:
                                                                          5
         \sigma \leftarrow \sigma * \exp^{\frac{1}{N}}(flag - \alpha)
27:
         if newfit \leq bestfit then
28:
             prate^* \leftarrow prate^* - N * \log \frac{DIST(ind2)}{DIST(ind)}
29:
              ind \leftarrow ind2
30:
              bestfit \leftarrow newfit
31:
32:
         end if
33: end for
34: prate^* \leftarrow prate^*/i
```

2 Results

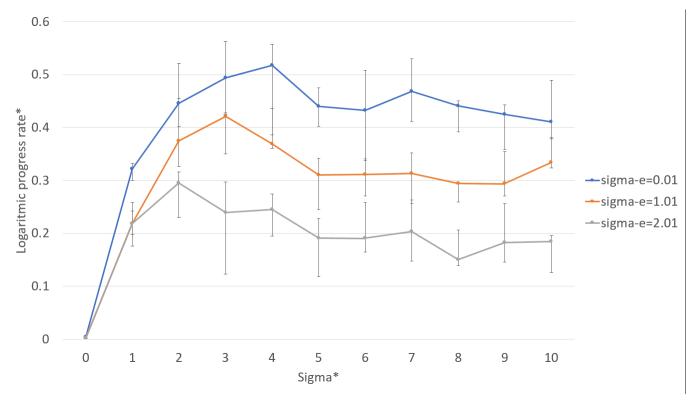


Figure 1: Normalized logarithmic progress rate as a function of normalized mutation strength. Algorithm 3 - Model assisted (1+1)ES without model generation limit, 4 Dimensions, $Y = (X-1)^2$. Each point represents the median result of 5 trails, error bars show the range of results for each point. (5 trails) (100 original fitness generations)

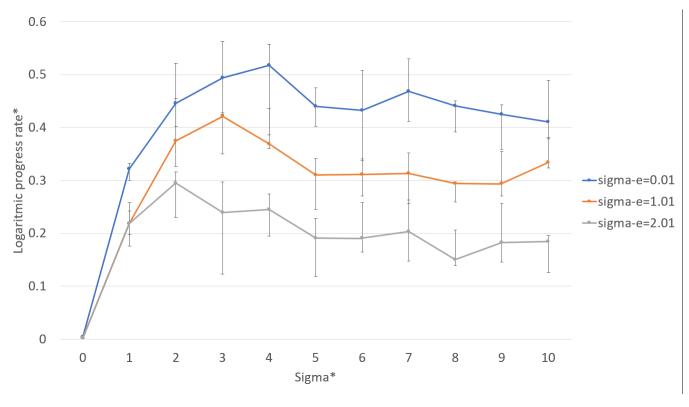


Figure 2: Normalized logarithmic progress rate as a function of normalized mutation strength. Algorithm 3 - Model assisted (1+1)ES without model generation limit, 40 Dimensions, $Y = (X-1)^2$. Each point represents the median result of 5 trails, error bars show the range of results for each point. (5 trails) (900 original fitness generations)

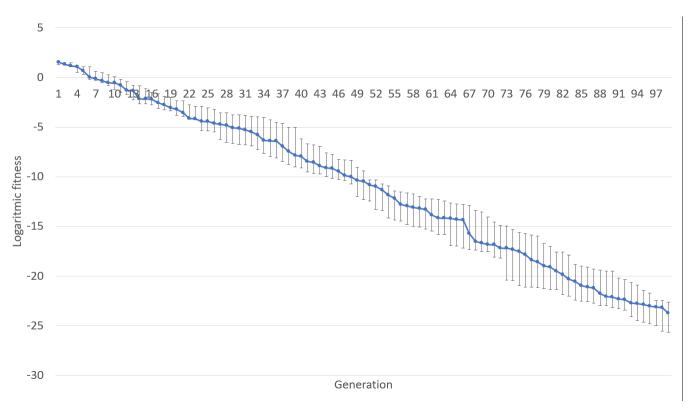


Figure 3: Normalized fitness as a function of normalized mutation strength. Algorithm 3- Model assisted (1+1)ES without model generation limit, 4 Dimensions, $Y = (X - 1)^2$. Each point represents the median result of 5 trails, error bars show the range of results for each point. (5 trails) (100 original fitness generations)

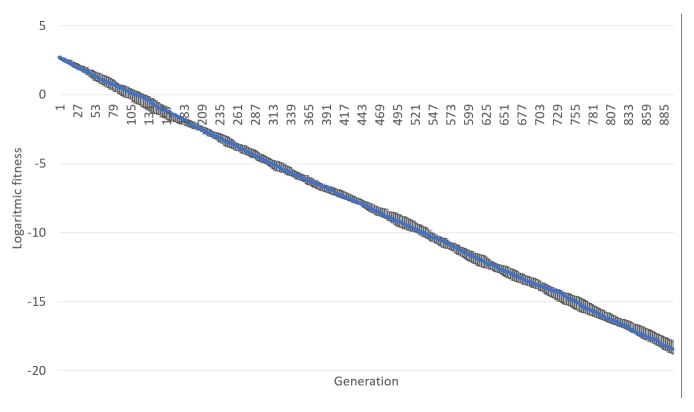


Figure 4: Normalized fitness as a function of normalized mutation strength. Algorithm 3- Model assisted (1+1)ES without model generation limit, 40 Dimensions, $Y = (X - 1)^2$. Each point represents the median result of 5 trails, error bars show the range of results for each point. (5 trails) (900 original fitness generations)

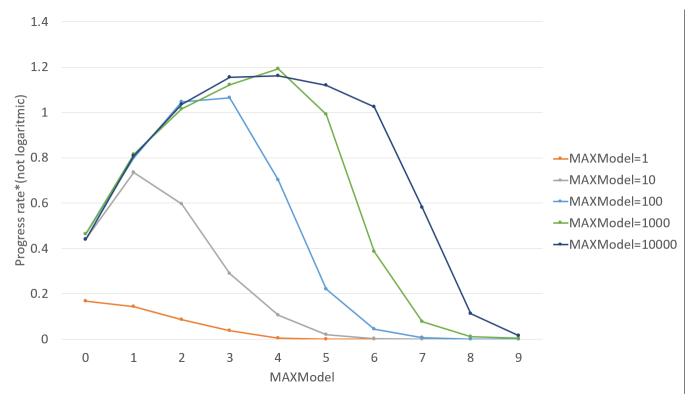


Figure 5: Normalized progress rate as a function of maximum number of model generations. Algorithm 2-Model assisted (1+1)ES, 40 Dimensions, $Y = (X-1)^2$. Each point represents the median result of 5 trails, error bars show the range of results for each point. (5 trails) (900 original fitness generations)

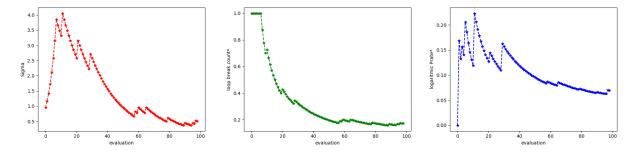


Figure 6: Sigma, logarithmic progress rate and number of generations that in less than 1000 model generations the algorithm finds a better model and exits the modeling loop in proportion to the number of original fitness generations. Model assisted (1+1)ES, 4 Dimensions, $Y = (X-1)^2$. $(\sigma_{initial value}^* = 1)(\alpha = 0.2)(100 \text{ original fitness generations})$ (1000 model-generation)

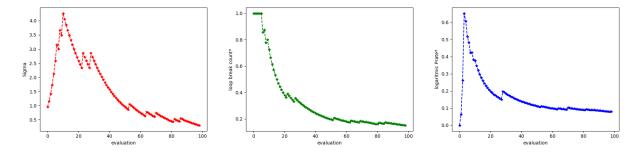


Figure 7: Sigma, logarithmic progress rate and number of generations that in less than 10000 model generations the algorithm finds a better model and exits the modeling loop in proportion to the number of original fitness generations. Model assisted (1+1)ES, 4 Dimensions, $Y = (X-1)^2$. $(\sigma_{initial value}^* = 1)(\alpha = 0.2)(100$ original fitness generations)

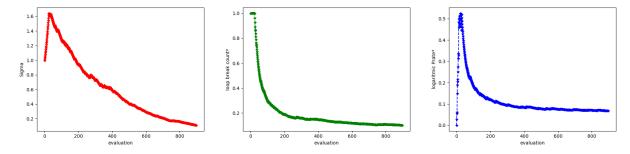


Figure 8: Sigma, logarithmic progress rate and number of generations that in less than 1000 model generations the algorithm finds a better model and exits the modeling loop in proportion to the number of original fitness generations. Model assisted (1+1)ES, 40 Dimensions, $Y = (X - 1)^2$. $(\sigma_{initial value}^* = 1)(\alpha = 0.2)(100 \text{ original fitness generations})(1000 \text{ model-generation})$

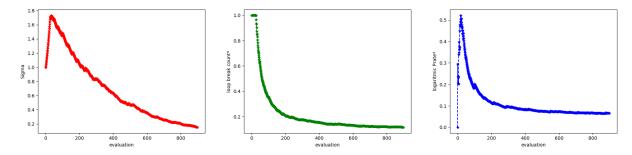


Figure 9: Sigma, logarithmic progress rate and number of generations that in less than 10000 model generations the algorithm finds a better model and exits the modeling loop in proportion to the number of original fitness generations. Model assisted (1+1)ES, 40 Dimensions, $Y = (X-1)^2$. $(\sigma_{initial value}^* = 1)(\alpha = 0.2)(100$ original fitness generations)(10000 model-generation)