

## Linear Regression MLE

As a starting point for linear regression, we assume that the labels  $y_i$  are a linear function of the corresponding features  $\mathbf{x}_i$  with additive Gaussian noise **€**:

$$y_i = \mathbf{w}^{ op} \mathbf{x}_i + \epsilon$$

The Gaussian noise  $\epsilon$  is mathematically drawn from a Gaussian (Normal) random variable  $\epsilon \sim \mathcal{N}(0,\sigma)$ . This means that the noise is sampled from a Gaussian probability distribution with mean 0 and standard deviation  $\sigma$ .

## Key Points

The maximum likelihood estimator maximizes the likelihood of the observed data given the model assumptions.

The MLE expression is mathematically equivalent to the minimization of the mean squared error.

If  $\epsilon$  is sampled with mean 0 and standard deviation  $\sigma$ , then  $y_i$  (given  $\mathbf{x}_i, \mathbf{w}$ ) must be sampled from a Gaussian random variable with mean  $\mathbf{w}^{\mathsf{T}}\mathbf{x}_i$  and standard deviation  $\sigma$ . This follows directly from the definition of  $y_i = \mathbf{w}^{\mathsf{T}} \mathbf{x}_i + \epsilon$  (mean of  $\epsilon$  gets shifted by  $+\mathbf{w}^{\mathsf{T}} \mathbf{x}_i$ ). We can then get the exact conditional probability distribution of  $y_i | \mathbf{x}_i$ ; w:

$$P(y_i|\mathbf{x}_i|\mathbf{w}) = rac{1}{2\pi\sigma^2}e^{rac{(y_i-(w)^2\mathbf{x}_i)^2}{2\sigma^2}}$$

Given such a probability distribution, we need to find the parameter vector w that best explains our data. To this end, we can deploy MLE, which will seek the w that maximizes the likelihood of our observed labels (given their feature vectors):

$$\begin{aligned} \mathbf{w} &= \arg\max_{\mathbf{w}} \prod_{i=1}^{n} \mathrm{P}(y_{i}|\mathbf{x}_{i};\mathbf{w}) \\ &= \arg\max_{\mathbf{w}} \sum_{i=1}^{n} \log[\mathrm{P}(y_{i}|\mathbf{x}_{i};\mathbf{w})] \qquad \qquad (\log \text{converts a product of probabil} \\ &= \arg\max_{\mathbf{w}} \sum_{i=1}^{n} \left[ \log\left(\frac{1}{\sqrt{2\pi\sigma^{2}}}\right) + \log\left(e^{\frac{(\mathbf{x}_{i}^{\top}\mathbf{w} - y_{i})^{2}}{2\sigma^{2}}}\right) \right] \qquad \qquad (\mathrm{P}) \\ &= \arg\max_{\mathbf{w}} - \frac{1}{2\sigma^{2}} \sum_{i=1}^{n} (\mathbf{x}_{i}^{\top}\mathbf{w} - y_{i})^{2} \qquad \qquad (\mathrm{First tr}) \\ &= \arg\min_{\mathbf{w}} \frac{1}{n} \sum_{i=1}^{n} (\mathbf{x}_{i}^{\top}\mathbf{w} - y_{i})^{2} \qquad \qquad \left(\frac{1}{n} \text{ makes the loss interpretent} \right) \end{aligned}$$

This derivation shows that the MLE estimate of  $\mathbf{w}$  is the minimizer of the following loss function:

$$l(\mathbf{w}) = rac{1}{n} \sum_{i=1}^n (\mathbf{x}_i^ op \mathbf{w} - y_i)^2$$

This particular loss function is also known as the squared loss or **ordinary least squares (OLS)**. OLS can be optimized with gradient descent, Newton's method, or in closed form (i.e. solving for the exact analytical solution). It has a nice explanation: the linear prediction  $\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i}$  should minimize the squared error from the true label  $y_{i}$ .