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EPISODIC LEARNING FOR SAFE BIPEDAL LOCOMOTION WITH CONTROL BARRIER FUNCTIONS  
AND PROJECTION TO STATE SAFETY

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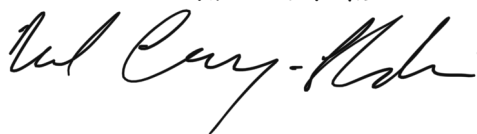
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