



arm

Bit:Bot Race Car Project

One Lap test

Lesson 14



arm School Program

Objectives

- Apply what you have learned to make the car complete one lap autonomously
- Complete one safe lap as quickly as possible
- Create a section plan for each race section
- Combine to create a complete **algorithm** for the racetrack

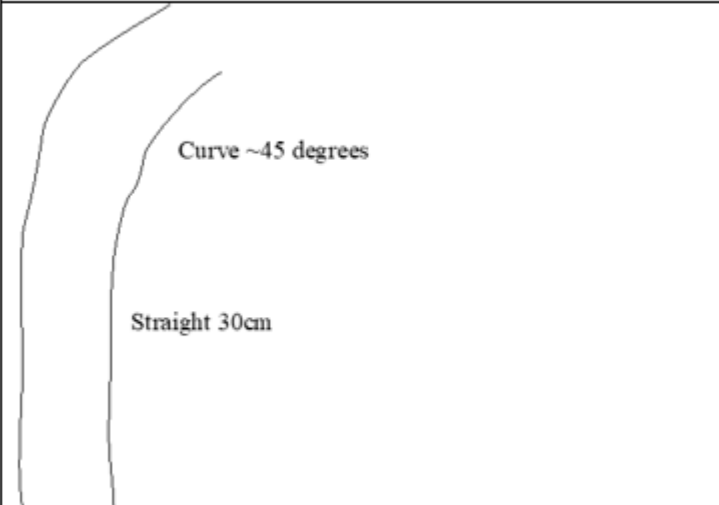
Self-driving Vehicles

- Companies like Waymo and Google have been developing self-driving (or **autonomous**) cars for several years
- Self-driving cars could: reduce the stress of driving, reduce accidents and improve traffic flow in major cities
- Autonomous cars combine a variety of sensors to understand their surroundings, such as radar, computer vision, sonar and GPS
- By utilising sensors and accurate mapping the self-driving car could pick you up from your home and deliver you to your location



Algorithm Plan

- Apply what you've learned from the previous lessons
- Look at the track and break it down into small sections (**decomposition**)
- Consider how far / fast the car travels with different settings
- Consider the angles you will need to get round the bends and curves
- Expect the get it wrong – fail early, fail often

Section	Commands
 <p>The diagram shows a track layout within a rectangular frame. On the left, there is a vertical line representing the start of a section. From this line, a curved path leads to the right, labeled 'Curve ~45 degrees'. After the curve, the path becomes a straight vertical line, labeled 'Straight 30cm'.</p>	<p>Drive Forward at 600 for time 1 second Spin 600 for time 100ms</p>

Thank You

Danke

Merci

谢谢

ありがとう

Gracias

Kiitos

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