ECE368: Probabilistic Reasoning

Lab 3: Hidden Markov Model

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You should hand in: 1) A scanned .pdf version of this sheet with your answers (file size should be under 2 MB); 2) one Python file inference.py that contains your code. The files should be uploaded to Quercus.

1. (a) Write down the formulas of the forward-backward algorithm to compute the marginal distribution $p(\mathbf{z}_i|(\hat{x}_0,\hat{y}_0),\ldots,(\hat{x}_{N-1},\hat{y}_{N-1}))$ for $i=0,1,\ldots,N-1$. Your answer should contain the initializations of the forward and backward messages, the recursion relations of the messages, and the computation of the marginal distribution based on the messages. (1.5 **pt**)

(b) After you run the forward-backward algorithm on the data in test.txt, write down the obtained marginal distribution of the state at i = 99 (the last time step), i.e., $p(\mathbf{z}_{99}|(\hat{x}_0, \hat{y}_0), \dots, (\hat{x}_{99}, \hat{y}_{99}))$. Only include states with non-zero probability in your answer. (2.5 **pt**)

$$\rho(z_{99} | (y_{0}, y_{0}), ...(y_{99}, y_{19})) = \begin{cases}
0.8103 & (11, 0, 'stay') \\
0.1796 & (11, 0, 'right') \\
0.0101 & (10, 1, 'down')
\end{cases}$$

2. Modify your forward-backward algorithm so that it can handle missing observations. After you run the modified forward-backward algorithm on the data in test_missing.txt, write down the obtained marginal distribution of the state at i = 30, i.e., $p(\mathbf{z}_{30}|(\hat{x}_0, \hat{y}_0), \dots, (\hat{x}_{99}, \hat{y}_{99}))$. Only include states with non-zero probability in your answer. (2 **pt**)

$$\rho(z_{30}|(50,90),...(500,90)) = \begin{cases} 0.9130 & (6,7,'right') \\ 0.0435 & (5,7,'right') \\ 0.0435 & (5,7,'stug') \end{cases}$$

3. (a) Write down the formulas of the Viterbi algorithm using \mathbf{z}_i and $(\hat{x}_i, \hat{y}_i), i = 0, 1, \dots, N-1$. Your answer should contain the initialization of the messages and the recursion of the messages in the Viterbi algorithm. (2 **pt**)

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W_0(z_0) = \ln \rho(z_0) + \ln \rho(|x_0, y_0| | z_0)

\forall i \in [1, N-1] : W_1(z_1) = \ln \rho(|x_0, y_0| | z_0)) + \max_{z_{i-1}} [\ln \rho(z_i| z_{i-1}) + W_{i-1}(z_{i-1})]

U_0(z_0) = \lim_{z \to \infty} |y_0| + \lim_{z \to
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(b) After you run the Viterbi algorithm on the data in test_missing.txt, write down the last 10 hidden states of the most likely sequence (i.e., $i = 90, 91, 92, \ldots, 99$) based on the MAP estimate. (3 **pt**)

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290 = (11, 5, 'down')

291 = (11, 6, 'down')

292 = (11, 7, 'down')

293 = (11, 7, 'stung')

294 = (11, 7, 'stung')

295 = (10, 7, 'left')

296 = (9, 7, 'left')

297 = (8, 7, 'left')

298 = (7, 7, 'left')

299 = (6, 7, 'left')
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- 4. Compute and compare the error probabilities of $\{\tilde{\mathbf{z}}_i\}$ and $\{\tilde{\mathbf{z}}_i\}$ using the data in test_missing.txt. The error probability of $\{\tilde{\mathbf{z}}_i\}$ is $\boxed{\mathbf{0.02}}$. (1 pt)
- 5. Is sequence $\{\check{\mathbf{z}}_i\}$ a valid sequence? If not, please find a small segment $\check{\mathbf{z}}_i, \check{\mathbf{z}}_{i+1}$ that violates the transition model for some time step i. You answer should specify the value of i as well as the corresponding states $\check{\mathbf{z}}_i, \check{\mathbf{z}}_{i+1}$. (1 **pt**)

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i=64: 264: (3,7, 'stug')
265: (1,7, 'stug')

Since the action from 264 to 265 is 'stug', the robot's position should be the sume, however, it is apparent that the robot has moreal lett
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